### **ABSOLUTE MAXIMUM RATINGS**

VDD to AGND, DGND	-0.3V to +6V
AGND to DGND.	
Digital Inputs to DGND	-0.3V to +6V
Digital Outputs (DOUT, UPO) to DGN	D0.3V to $(V_{DD} + 0.3V)$
FB, OUT to AGND	0.3V to $(V_{DD} + 0.3V)$
REF, REFADJ to AGND	0.3V to (V <sub>DD</sub> + $0.3V$ )

Maximum Current into Any Pin	50mA
Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )	
16-Pin QSOP (derate 8.00mW/°C above +70°C)	667mW
Operating Temperature Range40°C	to +85°C
Storage Temperature Range65°C to	
Lead Temperature (soldering, 10sec)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ELECTRICAL CHARACTERISTICS—MAX5132 (+5V)

 $(V_{DD} = +5V \pm 10\%, AGND = DGND, 33nF$  capacitor at REFADJ, internal reference,  $R_L = 5k\Omega$ ,  $C_L = 100pF$ , output amplifier connected in unity-gain,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
STATIC PERFORMANCE		•					
Resolution	Ν		13			Bits	
Integral Nanlinegrity (Nate 1)	INU	MAX5132A	-0.5		0.5	– LSB	
Integral Nonlinearity (Note 1)	INL -	MAX5132B	-1		1		
Differential Nonlinearity	DNL		-1		1	LSB	
Offset Error (Note 2)	Vos		-10		10	mV	
Gain Error	GE		-3	-0.2	3	mV	
Full-Scale Temperature	TOVES	MAX5132A		3	10	/°C	
Coefficient (Note 3)	TCV <sub>FS</sub>	MAX5132B		10	30	- ppm/°C	
Power-Supply Rejection Ratio	PSRR	$4.5V \le V_{DD} \le 5.5V$		20	250	μV/V	
REFERENCE			·				
Output Voltage	Vref	$T_A = +25^{\circ}C$	2.475	2.5	2.525	V	
Output Voltage Temperature	TOVALE	MAX5132A		3		ppm/°C	
Coefficient	TCVREF	MAX5132B		10			
Reference External Load Regulation	Vout/Iout	$0 \le I_{OUT} \le 100 \mu A$ (sourcing)			50	μ٧/μΑ	
Reference Short-Circuit Current				4		mA	
REFADJ Current		REFADJ = V <sub>DD</sub>		3.3	7	μA	
DIGITAL INPUT							
Input High Voltage	VIH		3			V	
Input Low Voltage	VIL				0.8	V	
Input Hysteresis	Vhys			200		mV	
Input Leakage Current	I <sub>IN</sub>	$V_{IN} = 0 \text{ or } V_{DD}$	-1	0.001	1	μA	
Input Capacitance	CIN			8		pF	
DIGITAL OUTPUTS			·			•	
Output High Voltage	Voh	I <sub>SOURCE</sub> = 2mA	V <sub>DD</sub> - 0.	5		V	
Output Low Voltage	Vol	I <sub>SINK</sub> = 2mA		0.13	0.4	V	



### ELECTRICAL CHARACTERISTICS—MAX5132 (+5V) (continued)

 $(V_{DD} = +5V \pm 10\%, AGND = DGND, 33nF$  capacitor at REFADJ, internal reference,  $R_L = 5k\Omega$ ,  $C_L = 100pF$ , output amplifier connected in unity-gain,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DYNAMIC PERFORMANCE						1
Voltage Output Slew Rate	SR			0.6		V/µs
Output Settling Time		To $\pm 0.5$ LSB, V <sub>STEP</sub> = 2.5V		20		μs
Output Voltage Swing (Note 4)				0 to V <sub>DD</sub>		V
Current into FB			-0.1	0	0.1	μA
Time Required to Exit Shutdown				2		ms
Digital Feedthrough		$\overline{CS} = V_{DD}$ , fsclk = 100kHz, Vsclk = 5Vp-p		5		nV-s
POWER REQUIREMENTS						
Power-Supply Voltage (Note 5)	Vdd		4.5		5.5	V
Power-Supply Current (Note 5)	IDD			500	600	μA
Power-Supply Current in Shutdown	ISHDN			3	20	μA

### **ELECTRICAL CHARACTERISTICS—MAX5133 (+3V)**

 $(V_{DD} = +3V \pm 10\%, AGND = DGND, 33nF$  capacitor at REFADJ, internal reference,  $R_L = 5k\Omega$ ,  $C_L = 100pF$ , output amplifier connected in unity-gain,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
STATIC PERFORMANCE	1		I				
Resolution	Ν		13			Bits	
Integral Naplinearity (Note 1)	INL	MAX5133A	-1		1	LSB	
Integral Nonlinearity (Note 1)	IINL	MAX5133B	-2		2	LSD	
Differential Nonlinearity	DNL		-1		1	LSB	
Offset Error (Note 2)	Vos		-10		10	mV	
Gain Error	GE		-5	-0.2	5	mV	
Full-Scale Temperature	TCVro	MAX5133A		3	10	nnm/°C	
Coefficient (Note 3)	TCV <sub>FS</sub>	MAX5133B		10	30	ppm/°C	
Power-Supply Rejection Ratio	PSRR	$2.7V \le V_{DD} \le 3.3V$		20	250	μV/V	
REFERENCE							
Output Voltage	Vref	$T_{A} = +25^{\circ}C$	1.237	1.25	1.263	V	
Output Voltage Temperature	TCVREF	MAX5133A		3		ppm/°C	
Coefficient	ICVREF	MAX5133B		10			
Reference External Load Regulation	Vout/Iout	$0 \le I_{OUT} \le 100 \mu A$ (sourcing)		0.1	1	μ٧/μΑ	
Reference Short-Circuit Current				4		mA	
REFADJ Current		$REFADJ = V_{DD}$		3.3	7	μA	
DIGITAL INPUT							
Input High Voltage	VIH		2.2			V	
Input Low Voltage	VIL				0.8	V	
Input Hysteresis	V <sub>HYS</sub>			200		mV	

# ELECTRICAL CHARACTERISTICS—MAX5133 (+3V) (continued)

 $(V_{DD} = +3V \pm 10\%, AGND = DGND, 33nF$  capacitor at REFADJ, internal reference,  $R_L = 5k\Omega$ ,  $C_L = 100pF$ , output amplifier connected in unity-gain,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input Leakage Current	lin	VIN = 0 or VDD	-1	0.001	1	μA
Input Capacitance	CIN			8		pF
DIGITAL OUTPUTS			L.			
Output High Voltage	Voh	ISOURCE = 2mA	V <sub>DD</sub> - 0.	5		V
Output Low Voltage	Vol	I <sub>SINK</sub> = 2mA		0.13	0.4	V
DYNAMIC PERFORMANCE		•				•
Voltage Output Slew Rate	SR			0.6		V/µs
Output Settling Time		To $\pm 0.5$ LSB, V <sub>STEP</sub> = 1.25V		20		μs
Output Voltage Swing (Note 4)				0 to V <sub>DD</sub>		V
Current into FB			-0.1	0	0.1	μA
Time Required to Exit Shutdown				2		ms
Digital Feedthrough		$\label{eq:cs} \begin{array}{l} \overline{\text{CS}} = \text{V}_{\text{DD}},  \text{f}_{\text{SCLK}} = 100 \text{kHz}, \\ \text{V}_{\text{SCLK}} = 3 \text{Vp-p} \end{array}$		5		nV-s
POWER REQUIREMENTS						
Power-Supply Voltage (Note 5)	Vdd		2.7		3.6	V
Power-Supply Current (Note 5)	IDD			500	600	μA
Power-Supply Current in Shutdown	ISHDN			3	20	μA

### TIMING CHARACTERISTICS—MAX5132 (+5V)

 $(V_{DD} = +5V \pm 10\%, AGND = DGND, 33nF$  capacitor at REFADJ, internal reference,  $R_L = 5k\Omega$ ,  $C_L = 100pF$ , output amplifier connected in unity-gain,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SCLK Clock Period	t <sub>CP</sub>		100			ns
SCLK Pulse Width High	t <sub>CH</sub>		40			ns
SCLK Pulse Width Low	tcL		40			ns
CS Fall to SCLK Rise Setup Time	tcss		40			ns
SCLK Rise to CS Rise Hold Time	tCSH		0			ns
SDI Setup Time	t <sub>DS</sub>		40			ns
SDI Hold Time	t <sub>DH</sub>		0			ns
SCLK Rise to DOUT Valid Propagation Delay Time	t <sub>DO1</sub>	C <sub>LOAD</sub> = 200pF			80	ns
SCLK Fall to DOUT Valid Propagation Delay Time	t <sub>DO2</sub>	C <sub>LOAD</sub> = 200pF			80	ns
SCLK Rise to CS Fall Delay Time	t <sub>CS0</sub>		10			ns
CS Rise to SCLK Rise Hold Time	tcs1		40			ns
CS Pulse Width High	tcsw		100			ns

## TIMING CHARACTERISTICS—MAX5133 (+3V)

 $(V_{DD} = +3V \pm 10\%, AGND = DGND, 33nF$  capacitor at REFADJ, internal reference,  $R_L = 5k\Omega$ ,  $C_L = 100pF$ , output amplifier connected in unity-gain,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SCLK Clock Period	tcp		150			ns
SCLK Pulse Width High	t <sub>CH</sub>		75			ns
SCLK Pulse Width Low	tcL		75			ns
CS Fall to SCLK Rise Setup Time	tcss		60			ns
SCLK Rise to $\overline{CS}$ Rise Hold Time	tcsh		0			ns
SDI Setup Time	t <sub>DS</sub>		60			ns
SDI Hold Time	t <sub>DH</sub>		0			ns
SCLK Rise to DOUT Valid Propagation-Delay Time	tDO1	C <sub>LOAD</sub> = 200pF			200	ns
SCLK Fall to DOUT Valid Propagation-Delay Time	t <sub>DO2</sub>	C <sub>LOAD</sub> = 200pF			200	ns
SCLK Rise to CS Fall Delay Time	t <sub>CS0</sub>		10			ns
CS Rise to SCLK Rise Hold Time	tcs1		75			ns
CS Pulse Width High	tcsw		150			ns

Note 1: Accuracy is guaranteed by following the table:

V <sub>DD</sub>	Accuracy Guaranteed					
(V)	From Code:	To Code:				
5	32	8191				
3	65	8191				

Note 2: Offset is measured at the code closest to 10mV.

**Note 3:** The temperature coefficient is determined by the "box" method in which the maximum  $\Delta V_{OUT}$  over the temperature range is divided by  $\Delta T$  and the typical reference voltage.

Note 4: Accuracy is better than 1.0LSB for V<sub>OUT</sub> = 10mV to V<sub>DD</sub> - 180mV. Guaranteed by PSR test on end points.

**Note 5:**  $R_{LOAD} = \infty$  and digital inputs are at either  $V_{DD}$  or DGND.

MAX5132/MAX5133 wise noted.) MAX5132 MAX5132 INTEGRAL NONLINEARITY vs. DIFFERENTIAL NONLINEARITY vs. DIGITAL INPUT CODE DIGITAL INPUT CODE 2.510 0.20 0.20 0.15 0.15 ≥ 2.505 0.10 0.10 REFERENCE VOLTAGE 0.05 0.05 INL (LSB) DNL (LSB) 2.500 0 0 -0.05 -0.05 2.495 -0.10 -0.10 -0.15 -0.15 -0.20 -0.20 2.490 0 2,000 4,000 6,000 8,000 10,000 0 2,000 4,000 6,000 8,000 10,000 -60 DIGITAL INPUT CODE DIGITAL INPUT CODE MAX5132 MAX5132 SUPPLY CURRENT vs. TEMPERATURE SUPPLY CURRENT vs. SUPPLY VOLTAGE 500 500 3.0 450 2.5 450 SHUTDOWN CURRENT (µA) SUPPLY CURRENT (µA) (CODE = 1555 HEX) SUPPLY CURRENT (MA) (CODE = 1555 HEX) 400 2.0 400 1.5 350 350 (CODE = 0000 HEX)300 1.0 (CODE = 0000 HEX) 300 250 05 200 250

4

0.25

-0.50

-1.25

-2.00

-275

-3.50

0.1

1

4.5

5

SUPPLY VOLTAGE (V)

MAX5132

10

 $R_L(k\Omega)$ 

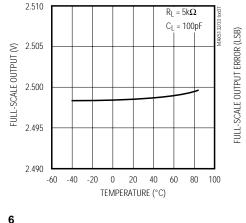
100



TEMPERATURE (°C)

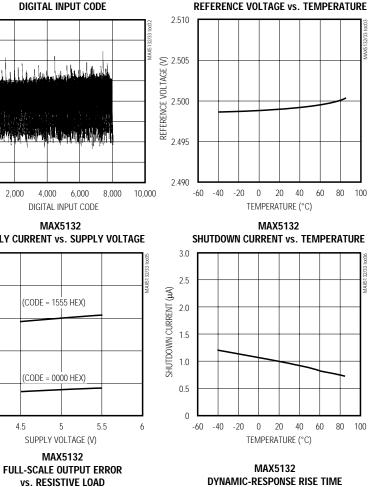
-60 -40 -20 0 20 40

60 80 100



### **Typical Operating Characteristics**

MAX5132



 $(V_{DD} = +5V, R_{L} = 5k\Omega, C_{L} = 100pF, OS = AGND, T_{A} = +25^{\circ}C$ , output amplifier connected in unity-gain configuration, unless other-

///XI//

2µs/div

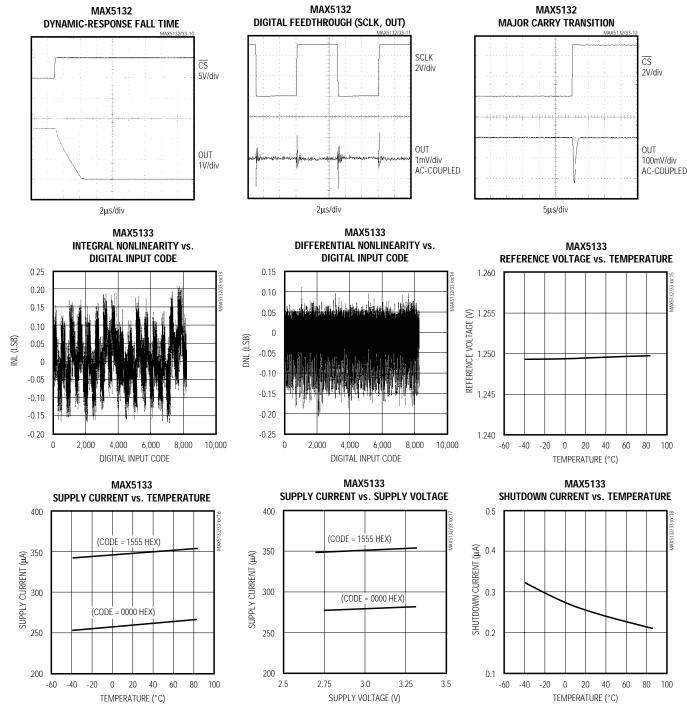
 $\overline{CS}$ 

5V/div

OUT 1V/div

### \_Typical Operating Characteristics (continued)

 $(V_{DD} = +5V, R_L = 5k\Omega, C_L = 100pF, OS = AGND, T_A = +25^{\circ}C$ , output amplifier connected in unity-gain configuration, unless otherwise noted.)

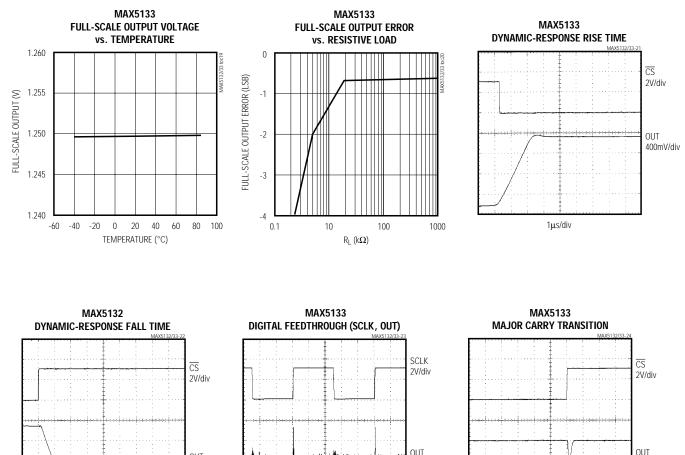


7

MAX5132/MAX5133

### Typical Operating Characteristics (continued)

 $(V_{DD} = +5V, R_L = 5k\Omega, C_L = 100pF, OS = AGND, T_A = +25^{\circ}C$ , output amplifier connected in unity-gain configuration, unless otherwise noted.)



OUT OUT 500mV/div 400mV/div AC-COUPLED 5µsV/div 2µs/div

100mV/div

AC-COUPLED

1µs/div

MAX5132/MAX5133

# Pin Description

PIN	NAME	FUNCTION
1	FB	Amplifier Inverting Sense Input (Analog Input)
2	OUT	Analog Output Voltage. High impedance if part is in shutdown.
3	RSTVAL	Reset Value Input (Digital Input) 1: Connect to VDD to select midscale as the output reset value. 0: Connect to DGND to select 0V as the output reset value.
4	PDL	Power-Down Lockout (Digital Input). 1: Normal operation. 0: Disallows shutdown (device cannot be powered down).
5	CLR	Reset DAC Input (Digital Input). Clears the DAC to its predetermined (RSTVAL) output state. Clearing the DAC will cause it to exit a software shutdown state.
6	CS	Active-Low Chip-Select Input (Digital Input)
7	DIN	Serial Data Input. Data is clocked in on the rising edge of SCLK.
8	SCLK	Serial Clock Input
9	DGND	Digital Ground
10	DOUT	Serial Data Output
11	UPO	User-Programmable Output (Digital Output)
12	PD	Power-Down Input (Digital Input). Pulling PD high when PDL = $V_{DD}$ places the IC into shutdown with a maximum shutdown current of 20µA.
13	AGND	Analog Ground
14	REF	Buffered Reference Output/Input. In internal reference mode, the reference buffer provides a +2.5V (MAX5132) or +1.25V (MAX5133) nominal output, externally adjustable at REFADJ. In external reference mode, disable the internal reference by pulling REFADJ to V <sub>DD</sub> and applying the external reference to REF.
15	REFADJ	Analog Reference Adjust Input. Bypass with a 33nF capacitor to AGND. Connect to $V_{DD}$ when using an external reference.
16	V <sub>DD</sub>	Positive Power Supply. Bypass with a $0.1\mu$ F capacitor in parallel with a $4.7\mu$ F capacitor to AGND.



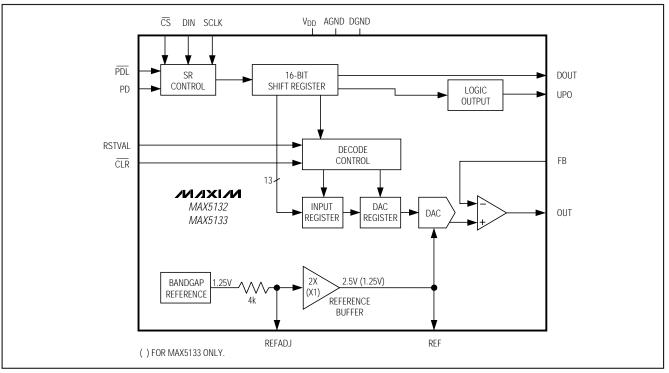


Figure 1. Simplified Functional Diagram

### **Detailed Description**

The MAX5132/MAX513313-bit, force/sense DACs are easily configured with a 3-wire serial interface. They include a 16-bit data-in/data-out shift register and have a double-buffered digital input consisting of an input register and a DAC register. In addition, these devices employ precision bandgap references, as well as an output amplifier with accessible feedback and output pins that can be used for setting the gain externally (Figure 1) or for forcing and sensing applications. These DACs are designed with an inverted R-2R ladder network (Figure 2) that produces a weighted voltage proportional to the digital input code.

#### Internal Reference

Both devices use an on-board precision bandgap reference with a low temperature coefficient of only 10ppm/°C (max) to generate an output voltage of +2.5V (MAX5132) or +1.25V (MAX5133). The REF pin can source up to 100µA and may become unstable with capacitive loads exceeding 100pF. REFADJ can be used for minor adjustments to the reference voltage. The circuits in Figures 3a and 3b achieve a nominal reference adjustment range of  $\pm$ 1%. Connect a 33nF capacitor from REFADJ to AGND to establish low-noise

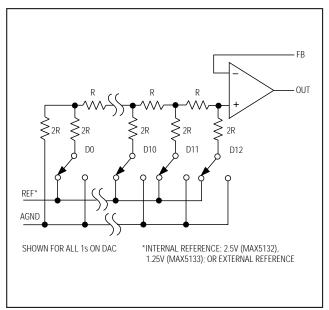


Figure 2. Simplified Inverted R-2R DAC Structure



operation of the DAC. Larger capacitor values may be used but will result in increased start-up delay. The time constant  $\tau$  for the start-up delay is determined by the REFADJ input impedance of 4k $\Omega$  and C<sub>REFADJ</sub>:

#### $\tau = 4k \Omega \bullet \mathsf{C}_{\mathsf{REFADJ}}$

#### **External Reference**

An external reference may be applied to the REF pin. Disable the internal reference by pulling REFADJ to  $V_{DD}$ . This allows an external reference signal (AC- or DC-based) to be fed into the REF pin. For proper operation, **do not** exceed the input voltage range limits of 0V to ( $V_{DD}$  - 1.4V) for  $V_{REF}$ .

Determine the output voltage using the following equation (REFADJ = VDD):

#### $V_{OUT} = V_{REF}(NB / 8192)G$

where NB is the numeric value of the MAX5132/ MAX5133 input code (0 to 8191), V<sub>REF</sub> is the external reference voltage, and G is the gain of the output amplifier, set by an external resistor-divider. The REF pin has a minimum input resistance of  $40k\Omega$  and is code dependent.

#### **Output Amplifier**

The MAX5132/MAX5133's DAC output is internally buffered by a precision amplifier with a typical slew rate of 0.6V/µs. Access to the output amplifier's inverting input (FB) provides the user greater flexibility with amplifier gain setting and signal conditioning (see *Applications Information*).

The output amplifier typically settles to  $\pm 0.5$ LSB from a full-scale transition within 20µs when it is connected in

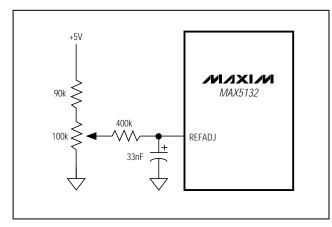


Figure 3a. MAX5132 Reference Adjust Circuit

unity gain and loaded with  $5k\Omega \parallel 100pF$ . Loads less than  $1k\Omega$  may result in degraded performance.

#### Power-Down Mode

The MAX5132/MAX5133 feature software- and hardware-programmable (PD pin) shutdown modes that reduce the typical supply current to 3µA. To enter software shutdown mode, program the control sequence for the DAC as shown in Table 1.

In shutdown mode, the amplifier output becomes high impedance and the serial interface remains active. Data in the input registers is saved, allowing the MAX5132/MAX5133 to recall the output state prior to entering shutdown when returning to normal operation. To exit shutdown mode, load both input and DAC registers simultaneously or update the DAC register from the input register. When returning from shutdown to normal operation, wait 2ms for the reference to settle. When using an external reference, the DAC requires only 20µs for the output to stabilize.

#### Power-Down Lockout Input (PDL)

The power-down lockout (PDL) pin disables shutdown when low. When in shutdown mode, a high-to-low transition on PDL will wake up the DAC with its output still set to the state prior to power-down. PDL can also be used to wake up the device asynchronously.

#### Power-Down Input (PD)

Pulling PD high places the MAX5132/MAX5133 in shutdown. Pulling PD low will not return the MAX5132/ MAX5133 to normal operation. A high-to-low transition on PDL or appropriate commands (Table 1) via the serial interface are required to exit power-down.

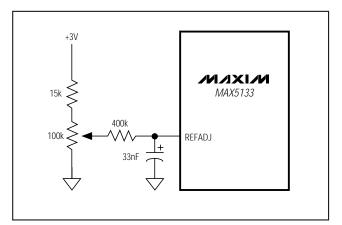


Figure 3b. MAX5133 Reference Adjust Circuit

	16-	BIT SERIAL	WORD	FUNCTION
C2	C1	C0	D12 D0	- FUNCTION
0	0	0	XXXXXXXXXXXXXX	No operation.
0	0	1	13-Bit DAC Data	Load input register; DAC register unchanged.
0	1	0	13-Bit DAC Data	Simultaneously load input and DAC registers; exit shutdown.
0	1	1	XXXXXXXXXXXXXXX	Update DAC register from input register; exit shutdown.
1	0	1	XXXXXXXXXXXXXX	Shutdown DAC (provided $\overline{PDL} = 1$ ).
1	0	0	XXXXXXXXXXXXXXX	UPO goes low (default).
1	1	0	XXXXXXXXXXXXXX	UPO goes high.
1	1	1	1XXXXXXXXXXXXXX	Mode 1: DOUT clocked out on SCLK's rising edge.
1	1	1	00XXXXXXXXXXXX	Mode 0: DOUT clocked out on SCLK's falling edge (default).

### Table 1. Serial-Interface Programming Commands

X = Don't care

#### Serial-Interface Configuration (SPI/QSPI/MICROWIRE/PIC16/PIC17)

The MAX5132/MAX5133 3-wire serial interface is compatible with SPI, QSPI, PIC16/PIC17 (Figure 4) and MICROWIRE (Figure 5) interface standards. The 2byte-long serial input word contains three control bits and 13 data bits in MSB-first format (Table 2).

The MAX5132/MAX5133's digital inputs are double buffered, which allows the user to:

- load the input register without updating the DAC register,
- update the DAC register with data from the input register,
- update the input and DAC registers concurrently.

The 16-bit input word may be sent in two 1-byte packets (SPI-, MICROWIRE- and PIC16/PIC17-compatible), with CS low during this period. The control bits C2, C1, and C0 (Table 1) determine:

- the clock edge on which DOUT transitions,
- the state of the user-programmable logic output,
- the configuration of the device after shutdown.

The general timing diagram in Figure 6 illustrates how data is acquired.  $\overline{CS}$  must be low for the part to receive data. With  $\overline{CS}$  low, data at DIN is clocked into the register on the rising edge of SCLK. When  $\overline{CS}$  transitions high, data is latched into the input and/or DAC registers, depending on the setting of the three control bits C2, C1, and C0. The maximum serial-clock frequency guaranteed for proper operation is 10MHz for the MAX5132 and 6.6MHz for the MAX5133. Figure 7 depicts a more detailed timing diagram of the serial interface.

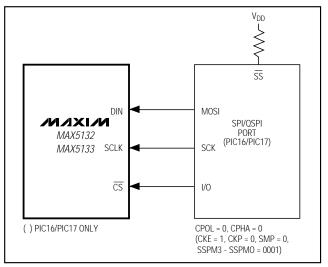


Figure 4. SPI/QSPI Interface Connections (PIC16/PIC17)

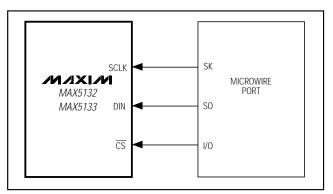


Figure 5. MICROWIRE Interface Connections



#### PIC16 with SSP Module and PIC17 Interface

The MAX5132/MAX5133 are compatible with a PIC16/PIC17 microcontroller ( $\mu$ C), using the synchronous serial port (SSP) module. To establish SPI communication, connect the controller as shown in Figure 4 and configure the PIC16/PIC17 as system master by initializing its synchronous serial-port control register (SSPCON) and synchronous serial-port status register (SSPSTAT) to the bit patterns shown in Tables 3 and 4.

In SPI mode, the PIC16/PIC17  $\mu$ Cs allow eight bits of data to be synchronously transmitted and received simultaneously. Two consecutive 8-bit writings (Figure 6) are necessary to feed the DAC with three control bits and 13 data bits. DIN data transitions on the serial clock's falling edge and is clocked into the DAC on SCLK's rising edge. The first eight bits of DIN contain

### Table 2. Serial Data Format

MSB	MSBLSB						
⇒	16 BITS OF	SERIAL DATA $\Rightarrow$					
	Control Bits	MSB Data Bits LSB					
	C2, C1, C0	D12D0					

the three control bits (C2, C1, C0) and the first five data bits (D12–D8). The second 8-bit data stream contains the remaining bits, D7–D0.

#### Serial Data Output

The contents of the internal shift-register are output serially on DOUT, which allows for daisy-chaining (see *Applications Information*) of multiple devices as well as data readback. The MAX5132/MAX5133 may be programmed to shift data out of DOUT on the serial clock's rising edge (Mode 1) or on the falling edge (Mode 0). The latter is the default during power-up and provides a lag of 16 clock cycles, maintaining SPI, QSPI, MICROWIRE, and PIC16/PIC17 compatibility. In Mode 1, the output data lags DIN by 15.5 clock cycles. During power-down, DOUT retains its last digital state prior to shutdown.

#### User-Programmable Output (UPO)

The UPO feature allows an external device to be controlled through the serial-interface setup (Table 1), thereby reducing the number of microcontroller I/O ports required. During power-down, this output will retain the last digital state before shutdown. With CLR pulled low, UPO will reset to the default state after wake-up.

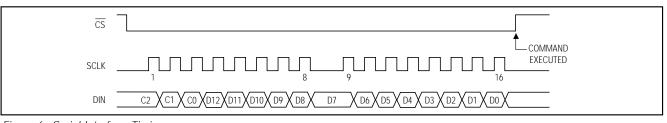


Figure 6. Serial-Interface Timing

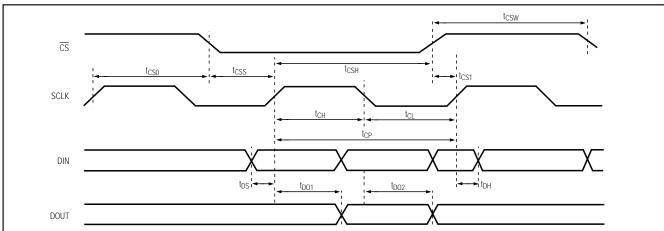


Figure 7. Detailed Serial-Interface Timing

### Table 3. Detailed SSPCON Register Contents

CONTROL BIT		MAX5132/MAX5133 SETTINGS	SYNCHRONOUS SERIAL-PORT CONTROL REGISTER (SSPCON)	
WCOL	BIT7	Х	Write-Collision Detection Bit	
SSPOV	BIT6	Х	Receive-Overflow Detection Bit	
SSPEN	BIT5	1	Synchronous Serial Port Enable Bit 0: Disables serial port and configures these pins as I/O port pins. 1: Enables serial port and configures SCK, SDO, and SCI as seri- al-port pins.	
СКР	BIT4	0	Clock-Polarity Select Bit. CKP = 0 for SPI master-mode selection.	
SSPM3	BIT3	0	Synchronous Serial-Port Mode Select Bit. Sets SPI master mode and selects $f_{CLK} = f_{OSC} / 16$ .	
SSPM2	BIT2	0		
SSPM1	BIT1	0		
SSPM0	BITO	1		

X = Don't care

### Table 4. Detailed SSPSTAT Register Contents

CONTROL BIT		MAX5132/MAX5133 SETTINGS	SYNCHRONOUS SERIAL-PORT STATUS REGISTER (SSPSTAT)	
SMP	BIT7	0	SPI Data-Input Sample Phase. Input data is sampled at the mid dle of the data-output time.	
CKE	BIT6	1	SPI Clock-Edge Select Bit. Data will be transmitted on the rising edge of the serial clock.	
D/A	BIT5	Х	Data-Address Bit	
Р	BIT4	Х	Stop Bit	
S	BIT3	Х	Start Bit	
R/W	BIT2	Х	Read/Write Bit Information	
UA	BIT1	Х	Update Address	
BF	BITO	Х	Buffer Full-Status Bit	

X = Don't care

# Applications Information

### Definitions

### Integral Nonlinearity (INL)

Integral nonlinearity (Figure 8a) is the deviation of the values on an actual transfer function from a straight line. This straight line can be either a best-straight-line fit (closest approximation to the actual transfer curve) or a line drawn between the endpoints of the transfer function, once offset and gain errors have been nullified. For a DAC, the deviations are measured at every single step.

### Differential Nonlinearity (DNL)

Differential nonlinearity (Figure 8b) is the difference between an actual step height and the ideal value of 1LSB. If the magnitude of the DNL is less than or equal to 1LSB, the DAC guarantees no missing codes and is monotonic.

#### Offset Error

The offset error (Figure 8c) is the difference between the ideal and the actual offset point. For a DAC, the offset point is the step value when the digital input is zero. This error affects all codes by the same amount and can usually be compensated for by trimming.



#### Gain Error

Gain error (Figure 8d) is the difference between the ideal and the actual full-scale output voltage on the transfer curve, after nullifying the offset error. This error alters the slope of the transfer function and corresponds to the same percentage error in each step.

#### Settling Time

The settling time is the amount of time required from the start of a transition until the DAC output settles to its new output value within the converter's specified accuracy.

#### Digital Feedthrough

Digital feedthrough is noise generated on the DAC's output when any digital input transitions. Proper board layout and grounding will significantly reduce this noise, but there will always be some feedthrough caused by the DAC itself.

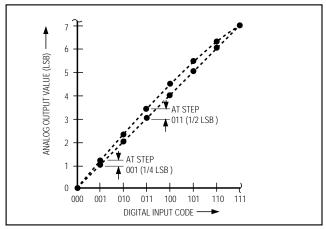


Figure 8a. Integral Nonlinearity

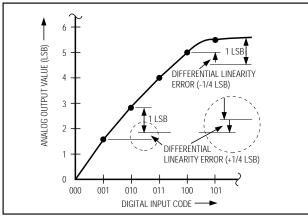


Figure 8b. Differential Nonlinearity

Rail-to-Rail is a registered trademark of Nippon Motorola, Ltd.



#### **Unipolar Output**

Figure 9 shows the MAX5132/MAX5133 setup for unipolar, Rail-to-Rail<sup>™</sup> operation with a closed-loop gain of 2V/V. With its internal reference of +2.5V, the MAX5132 provides a convenient unipolar output range of 0 to +4.99939V, while the MAX5133 offers an output range of 0 to +2.499695V with its on-board +1.25V reference. Table 5 lists example codes for unipolar output voltages.

#### **Bipolar Output**

The MAX5132/MAX5133 can be configured for unitygain bipolar operation (FB = OUT) using the circuit shown in Figure 10. The output voltage  $V_{OUT}$  is then given by the following equation:

Vout = V<sub>REF</sub> [G (NB / 8192) - 1]

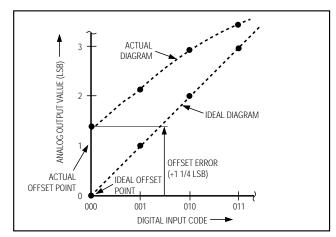


Figure 8c. Offset Error

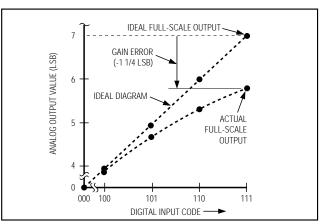


Figure 8d. Gain Error

where NB is the numeric value of the DAC's binary input code, VREF is the voltage of the internal (or external) precision reference, and G is the overall gain. The application circuit in Figure 10 uses a low-cost op amp (MAX4162) external to the MAX5132/MAX5133. Together with the MAX5132/MAX5133, this circuit offers an overall gain of 2V/V. Table 6 lists example codes for bipolar output voltages.

#### Reset (RSTVAL) and Clear (CLR) Functions

The MAX5132/MAX5133 DACs feature a clear pin  $(\overline{CLR})$ , which resets the output to a certain value, depending upon how RSTVAL is set. RSTVAL = DGND selects an output of 0, and RSTVAL = V<sub>DD</sub> selects a midscale output when  $\overline{CLR}$  is pulled low.

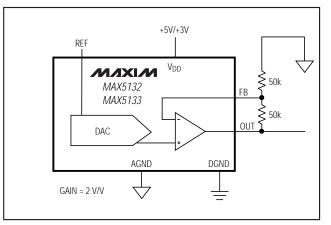
The  $\overline{\text{CLR}}$  pin has a minimum input resistance of 40k $\Omega$  in series with a diode to the supply voltage (V\_DD). If the digital voltage is higher than the supply voltage for the part, a small input current may flow, but this current will be limited to (V\_{\overline{\text{CLR}}} - V\_{DD} - 0.5V) / 40k\Omega.

**Note:** Clearing the DAC will also cause the part to exit software shutdown (PD = 0).

#### **Daisy-Chaining Devices**

Any number of MAX5132/MAX5133s may be daisychained simply by connecting the serial data output pin (DOUT) of one device to the serial data input pin (DIN) of the following device in the chain (Figure 11).

Another configuration (Figure 12) allows several MAX5132/MAX5133 DACs to share one common DIN signal line. In this configuration, the data bus is common to all devices; data is not shifted through a daisy chain. However, more I/O lines are required in this configuration because each IC needs a dedicated  $\overline{\text{CS}}$  line.





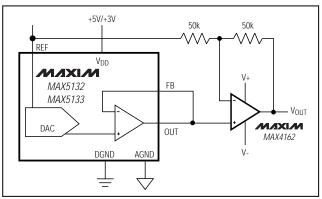


Figure 10. Unity-Gain Bipolar Output Circuit Using Internal (+1.25V/+2.5V) or External Reference. With external reference, pull REFADJ to  $V_{DD}$ .

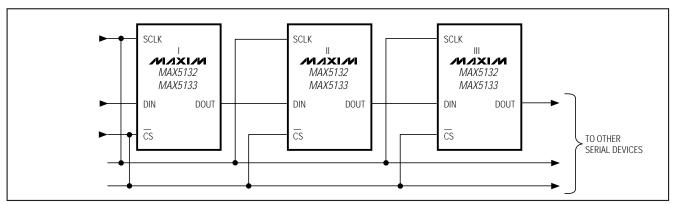


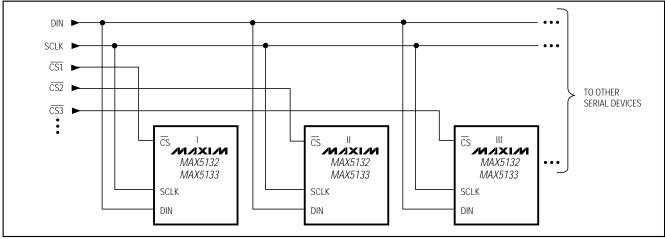
Figure 11. Daisy-Chaining Multiple Devices with the Digital I/Os DIN/DOUT

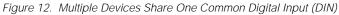
### Table 5. Unipolar Code Table (Gain = +2V/V)

DAC CONTENTS	ANALOG OUTPUT			
MSB LSB	INTERNAL REFERENCE		EXTERNAL REFERENCE	
MISB LSB	MAX5132	MAX5133	MAX5132/MAX5133	
1 1111 1111 1111	4.99939V	2.49969V	V <sub>REF</sub> (8191 / 8192) 2	
1 0000 0000 0001	2.50061V	1.25031V	V <sub>REF</sub> (4097 / 8192) 2	
1 0000 0000 0000	2.5V	1.25V	V <sub>REF</sub> (4096 / 8192) 2	
0 1111 1111 1111	2.49939V	1.24969V	V <sub>REF</sub> (4095 / 8192) 2	
0 0000 0000 0001	610.35µV	305.18µV	V <sub>REF</sub> (1 / 8192) 2	
0 0000 0000 0000	OV	OV	OV	

### Table 6. Bipolar Code Table for Figure 10

DAC CONTENTS		ANALOG OUTPUT			
MSB	LSB -	INTERNAL REFERENCE		EXTERNAL REFERENCE	
		MAX5132	MAX5133	MAX5132/MAX5133	
1 1111 1111 1111		2.49939V	1.24969V	V <sub>REF</sub> [2 (8191 / 8192) - 1]	
1 1000 0000 0001		610.35µV	305.18µV	V <sub>REF</sub> [2 (4097 / 8192) - 1]	
1 1000 0000 0000		OV	OV	V <sub>REF</sub> [2 (4096 / 8192) - 1]	
0 1111 1111 1111		-610.35µV	-305.18µV	V <sub>REF</sub> [2 (4095 / 8192) - 1]	
0 0000 0000 0001		-2.49939V	-1.24969V	V <sub>REF</sub> [ 2 (1 / 8192) - 1]	
0 0000 0000 0000		-2.5V	-1.25V	-VREF	





#### Using an External Reference with AC Components

The MAX5132/MAX5133 have multiplying capabilities within the reference input voltage range specifications. Figure 13 shows a technique for applying a sinusoidal input to REF, where the AC signal is offset before being applied to the reference input.

#### Power-Supply and Bypassing Considerations

On power-up, the input and DAC registers are cleared to either zero (RSTVAL = DGND) or midscale (RSTVAL =  $V_{DD}$ ). Bypass the power supply ( $V_{DD}$ ) with a 4.7µF capacitor in parallel with a  $0.1\mu F$  capacitor to AGND. Minimize lead lengths to reduce lead inductance.

#### Layout Considerations

Digital and AC signals coupling to AGND can create noise at the output. Connect AGND to the highest quality ground available. Use proper grounding techniques, such as a multilayer board with a low-inductance ground plane. Wire-wrapped boards and sockets are not recommended. If noise becomes an issue, shielding may be required.

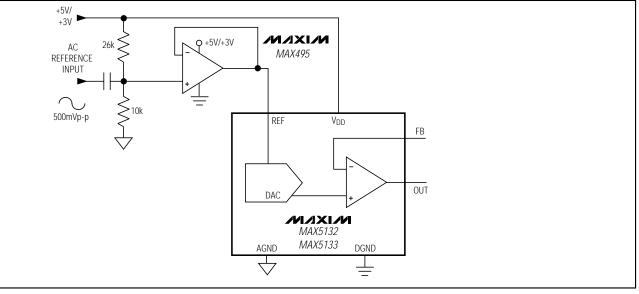
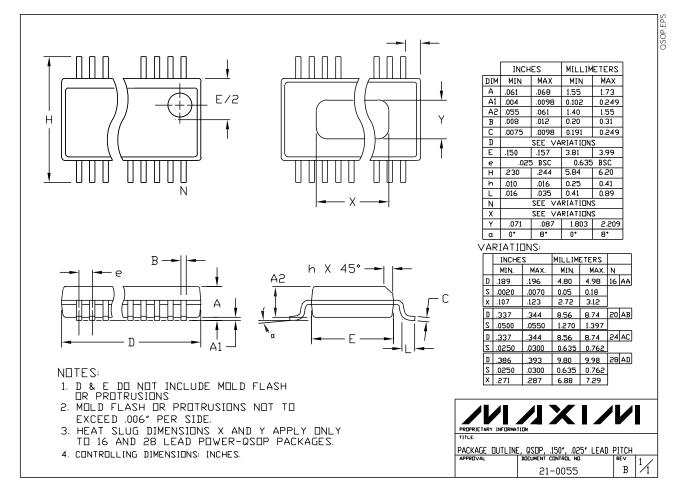


Figure 13. External Reference with AC Components

Chip Information

TRANSISTOR COUNT: 3308 SUBSTRATE CONNECTED TO AGND.

### \_Package Information



MAX5132/MAX5133

NOTES

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20

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