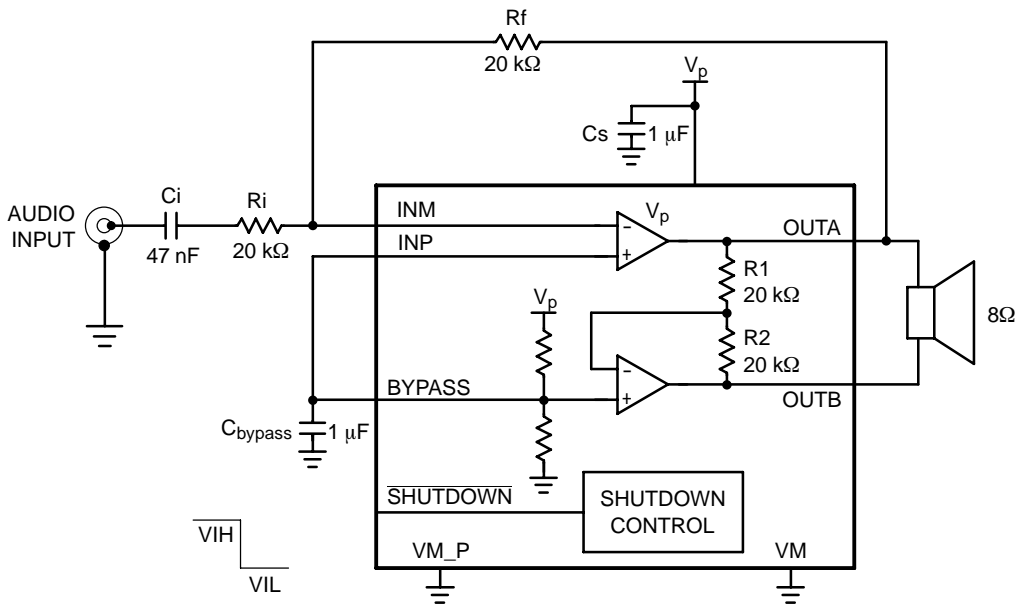
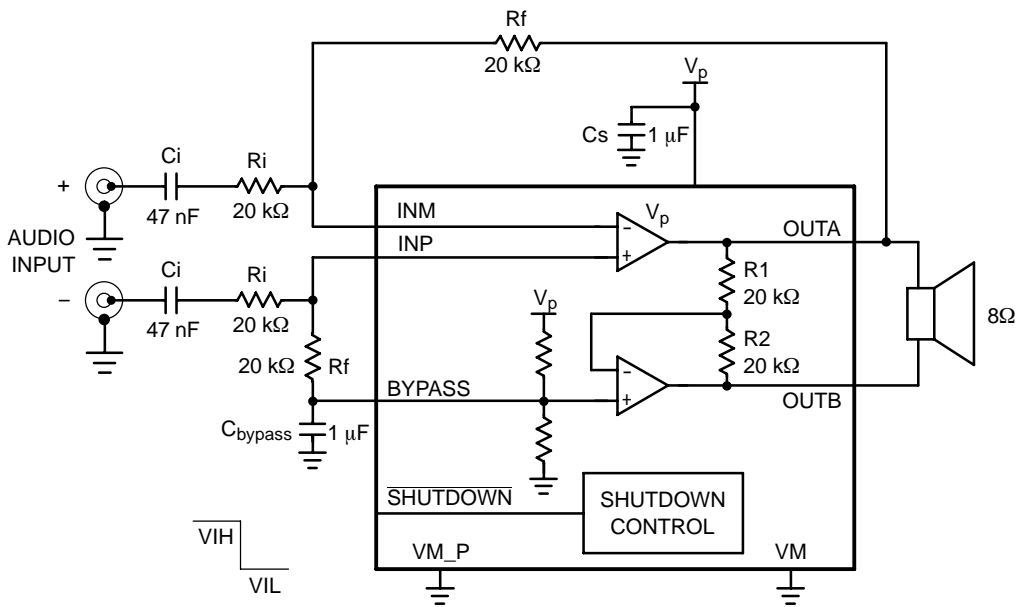


## NCP2892 Series



**Figure 1. Typical Audio Amplifier Application Circuit with Single Ended Input**



**Figure 2. Typical Audio Amplifier Application Circuit with a Differential Input**

This device contains 671 active transistors and 1899 MOS gates.

## NCP2892 Series

### PIN DESCRIPTION

Pin	Type	Symbol	Description
A1	I	INM	Negative input of the first amplifier, receives the audio input signal. Connected to the feedback resistor $R_f$ and to the input resistor $R_{in}$ .
A2	O	OUTA	Negative output of the NCP2892. Connected to the load and to the feedback resistor $R_f$ .
A3	I	INP	Positive input of the first amplifier, receives the common mode voltage.
B1	I	VM_P	Power Analog Ground.
B2	I	VM	Core Analog Ground.
B3	I	$V_p$	Positive analog supply of the cell. Range: 2.2 V–5.5 V.
C1	I	BYPASS	Bypass capacitor pin which provides the common mode voltage ( $V_p/2$ ).
C2	O	OUTB	Positive output of the NCP2892. Connected to the load.
C3	I	SHUTDOWN	The device enters in shutdown mode when a low level is applied on this pin.

### MAXIMUM RATINGS (Note 1)

Rating	Symbol	Value	Unit
Supply Voltage	$V_p$	6.0	V
Operating Supply Voltage	Op $V_p$	2.2 to 5.5 V 2.0 V = Functional Only	–
Input Voltage	$V_{in}$	–0.3 to $V_{cc} + 0.3$	V
Max Output Current	$I_{out}$	500	mA
Power Dissipation (Note 2)	$P_d$	Internally Limited	–
Operating Ambient Temperature	$T_A$	–40 to +85	°C
Max Junction Temperature	$T_J$	150	°C
Storage Temperature Range	$T_{stg}$	–65 to +150	°C
Thermal Resistance Junction-to-Air	$R_{\theta JA}$	(Note 3)	°C/W
ESD Protection	Human Body Model (HBM) (Note 4) NCP2892A NCP2892B Machine Model (MM) (Note 5)	– 8000 6000 >250	V
Latchup Current at $T_A = 85^\circ\text{C}$ (Note 6)	–	$\pm 100$	mA

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

- Maximum electrical ratings are defined as those values beyond which damage to the device may occur at  $T_A = +25^\circ\text{C}$ .
- The thermal shutdown set to  $160^\circ\text{C}$  (typical) avoids irreversible damage on the device due to power dissipation. For further information see page 10.
- The  $R_{\theta JA}$  is highly dependent of the PCB Heatsink area. For example,  $R_{\theta JA}$  can equal  $195^\circ\text{C/W}$  with  $50\text{ mm}^2$  total area and also  $135^\circ\text{C/W}$  with  $500\text{ mm}^2$ . For further information see page 10. The bumps have the same thermal resistance and all need to be connected to optimize the power dissipation.
- Human Body Model, 100 pF discharge through a  $1.5\text{ k}\Omega$  resistor following specification JESD22/A114.
- Machine Model, 200 pF discharged through all pins following specification JESD22/A115.
- Maximum ratings per JEDEC standard JESD78.

## NCP2892 Series

**ELECTRICAL CHARACTERISTICS** Limits apply for  $T_A$  between  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$  (Unless otherwise noted).

Characteristic	Symbol	Conditions	Min (Note 7)	Typ	Max (Note 7)	Unit
Supply Quiescent Current	$I_{dd}$	$V_p = 2.6\text{ V}$ , No Load	–	1.5	4	mA
		$V_p = 5.0\text{ V}$ , No Load	–	1.7		
		$V_p = 2.6\text{ V}$ , $8\ \Omega$ $V_p = 5.0\text{ V}$ , $8\ \Omega$	– –	1.7 1.9	5.5	
Common Mode Voltage	$V_{cm}$	–	–	$V_p/2$	–	V
Shutdown Current	$I_{SD}$	$T_A = +25^{\circ}\text{C}$ $T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$	–	0.01	0.5 1.0	$\mu\text{A}$
Shutdown Voltage High	$V_{SDIH}$	–	1.2	–	–	V
Shutdown Voltage Low	$V_{SDIL}$	–	–	–	0.4	V
Turning On Time (Note 9)	$T_{WU}$	$C_{by} = 1\ \mu\text{F}$	–	90	–	ms
Turning Off Time	$T_{OFF}$	–	–	1.0	–	$\mu\text{s}$
Output Impedance in Shutdown Mode NCP2892A NCP2892B	$Z_{SD}$	–	–	100	–	$\Omega$
			–	10	–	k $\Omega$
Output Swing NCP2892A	$V_{loadpeak}$	$V_p = 2.6\text{ V}$ , $R_L = 8.0\ \Omega$	1.6	2.12	–	V
		$V_p = 5.0\text{ V}$ , $R_L = 8.0\ \Omega$ (Note 8) $T_A = +25^{\circ}\text{C}$	4.0	4.15	–	
		$T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$	3.85			
Output Swing NCP2892B	$V_{loadpeak}$	$V_p = 2.6\text{ V}$ , $R_L = 8.0\ \Omega$	1.6	2.20	–	V
		$V_p = 5.0\text{ V}$ , $R_L = 8.0\ \Omega$ (Note 8) $T_A = +25^{\circ}\text{C}$	4.0	4.50	–	
		$T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$	3.85			
Rms Output Power NCP2892A	$P_O$	$V_p = 2.6\text{ V}$ , $R_L = 4.0\ \Omega$ THD + N < 0.1%	–	0.36	–	W
		$V_p = 2.6\text{ V}$ , $R_L = 8.0\ \Omega$ THD + N < 0.1%	–	0.28	–	
		$V_p = 5.0\text{ V}$ , $R_L = 8.0\ \Omega$ THD + N < 0.1%	–	1.08	–	
Rms Output Power NCP2892B	$P_O$	$V_p = 2.6\text{ V}$ , $R_L = 4.0\ \Omega$ THD + N < 0.1%	–	0.40	–	W
		$V_p = 2.6\text{ V}$ , $R_L = 8.0\ \Omega$ THD + N < 0.1%	–	0.30	–	
		$V_p = 5.0\text{ V}$ , $R_L = 8.0\ \Omega$ THD + N < 0.1%	–	1.20	–	
Maximum Power Dissipation (Note 9)	$P_{Dmax}$	$V_p = 5.0\text{ V}$ , $R_L = 8.0\ \Omega$	–	–	0.65	W
Output Offset Voltage	$V_{OS}$	$V_p = 2.6\text{ V}$ $V_p = 5.0\text{ V}$	–30		30	mV
Signal-to-Noise Ratio	SNR	$V_p = 2.6\text{ V}$ , $G = 2.0$ $10\text{ Hz} < F < 20\text{ kHz}$	–	84	–	dB
		$V_p = 5.0\text{ V}$ , $G = 10$ $10\text{ Hz} < F < 20\text{ kHz}$	–	77	–	
Positive Supply Rejection Ratio	PSRR $V_+$	$G = 2.0$ , $R_L = 8.0\ \Omega$ $V_{Pripple\_pp} = 200\text{ mV}$ $C_{by} = 1.0\ \mu\text{F}$ Input Terminated with $10\ \Omega$ $F = 217\text{ Hz}$				dB
		$V_p = 5.0\text{ V}$	–	–64	–	
		$V_p = 3.0\text{ V}$	–	–72	–	
		$V_p = 2.6\text{ V}$	–	–73	–	
		$F = 1.0\text{ kHz}$				
		$V_p = 5.0\text{ V}$	–	–64	–	
$V_p = 3.0\text{ V}$	–	–74	–			
$V_p = 2.6\text{ V}$	–	–75	–			
Efficiency	$\eta$	$V_p = 2.6\text{ V}$ , $P_{orms} = 320\text{ mW}$	–	48	–	%
		$V_p = 5.0\text{ V}$ , $P_{orms} = 1.0\text{ W}$	–	63	–	

## NCP2892 Series

**ELECTRICAL CHARACTERISTICS** Limits apply for  $T_A$  between  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$  (Unless otherwise noted).

Characteristic	Symbol	Conditions	Min (Note 7)	Typ	Max (Note 7)	Unit
Thermal Shutdown Temperature (Note 10)	$T_{sd}$		140	160	180	$^{\circ}\text{C}$
Total Harmonic Distortion	THD	$V_p = 2.6$ , $F = 1.0$ kHz $R_L = 4.0 \Omega$ , $A_V = 2.0$ $P_O = 0.32$ W	–	–	–	%
		$V_p = 5.0$ V, $F = 1.0$ kHz $R_L = 8.0 \Omega$ , $A_V = 2.0$ $P_O = 1.0$ W	–	0.04	–	
			–	–	–	
			–	0.02	–	
			–	–	–	

7. Min/Max limits are guaranteed by design, test or statistical analysis.
8. This parameter is guaranteed but not tested in production in case of a 5.0 V power supply.
9. See page 12 for a theoretical approach of this parameter.
10. For this parameter, the Min/Max values are given for information.

# NCP2892 Series

## TYPICAL PERFORMANCE CHARACTERISTICS

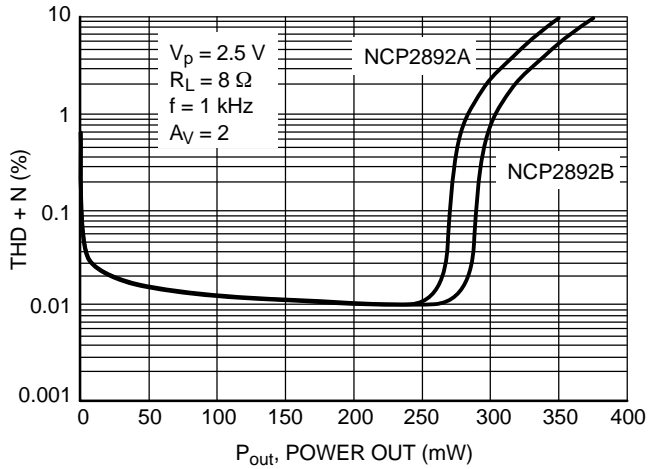


Figure 3. THD + N versus Power Out

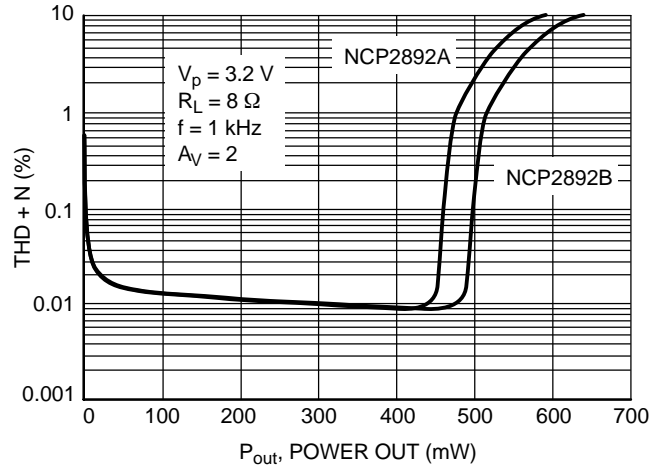


Figure 4. THD + N versus Power Out

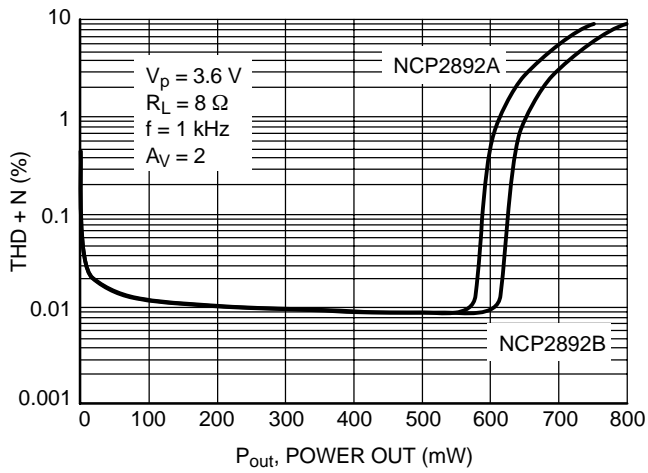


Figure 5. THD + N versus Power Out

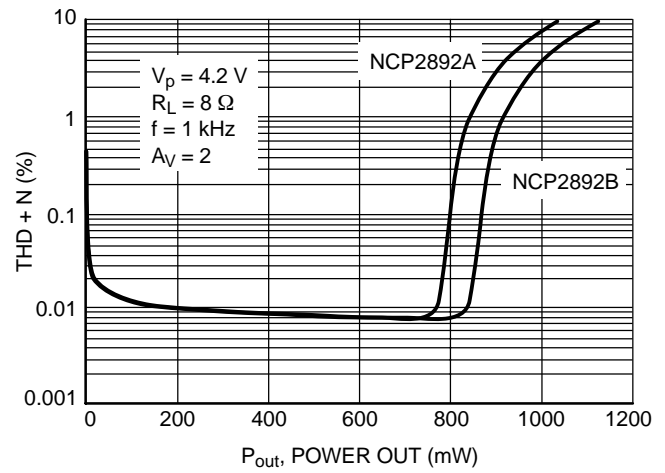


Figure 6. THD + N versus Power Out

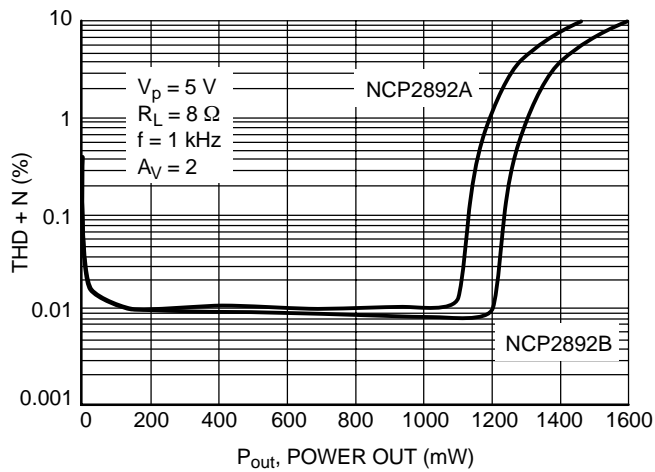


Figure 7. THD + N versus Power Out

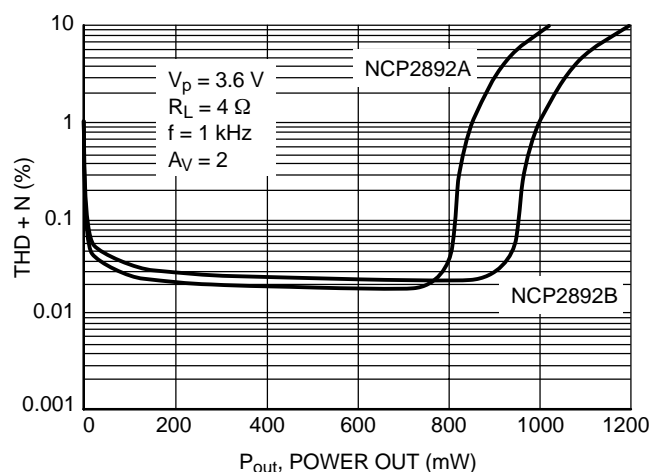


Figure 8. THD + N versus Power Out

# NCP2892 Series

## TYPICAL PERFORMANCE CHARACTERISTICS

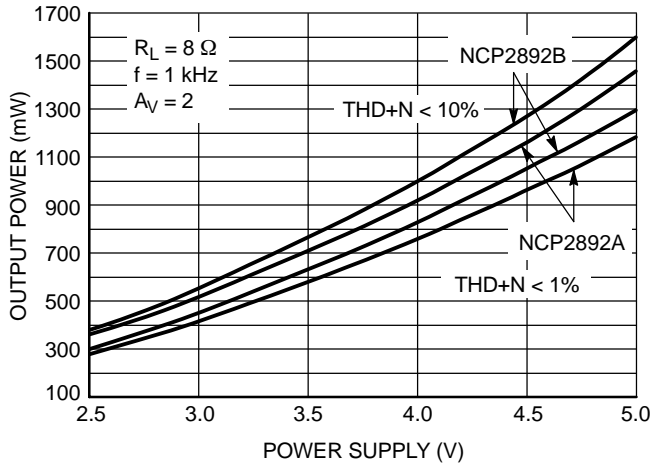


Figure 9. Output Power versus Power Supply

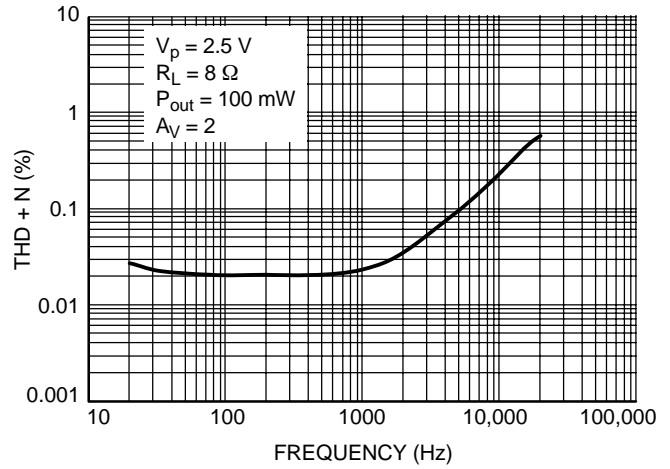


Figure 10. THD + N versus Frequency

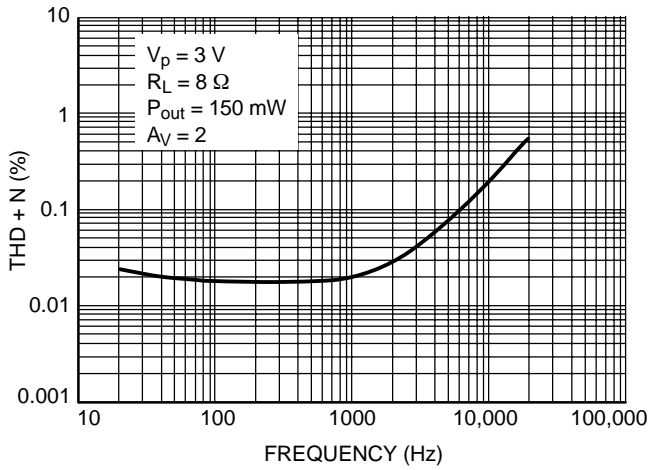


Figure 11. THD + N versus Frequency

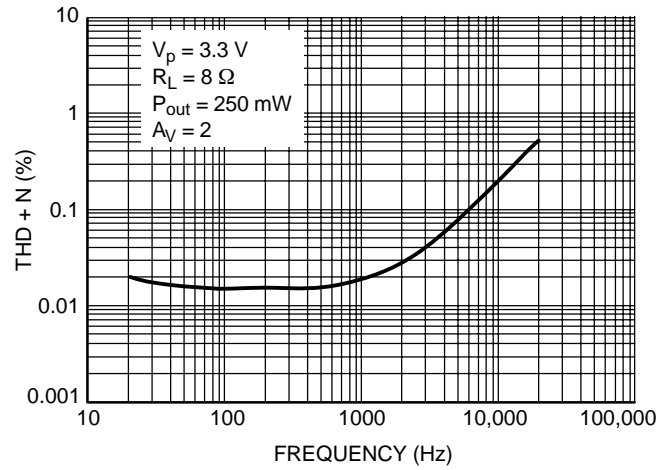


Figure 12. THD + N versus Frequency

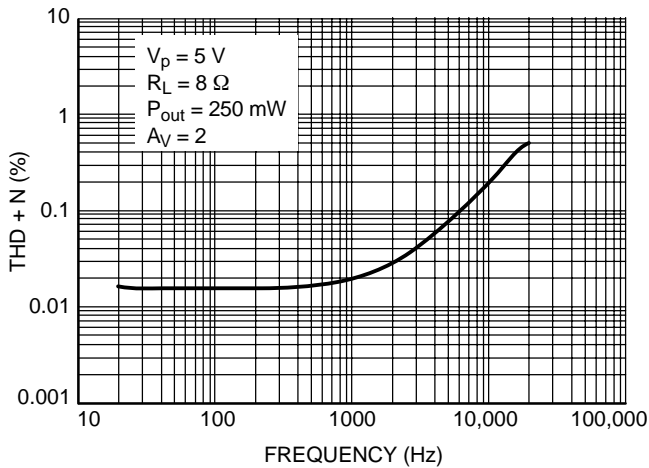


Figure 13. THD + N versus Frequency

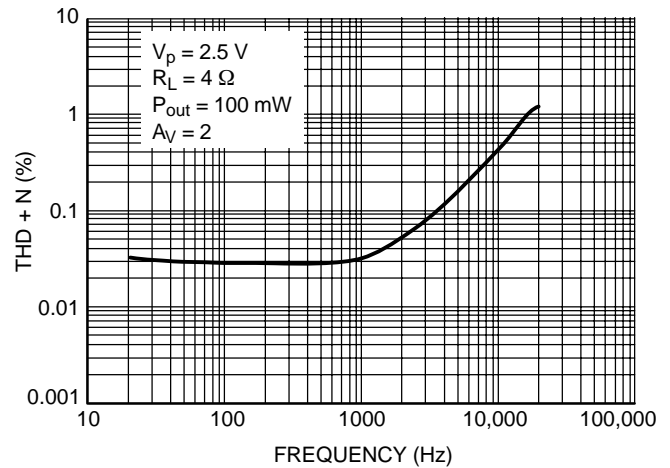


Figure 14. THD + N versus Frequency

TYPICAL PERFORMANCE CHARACTERISTICS

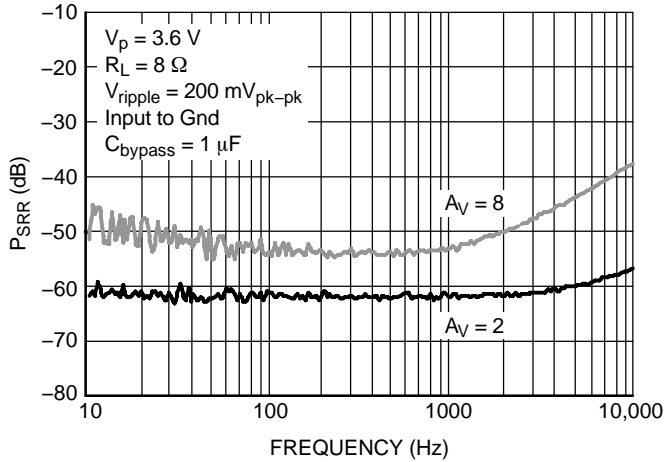


Figure 15.  $P_{SRR}$  @  $V_p = 3.6\text{ V}$   
Single Ended Audio Input to Ground

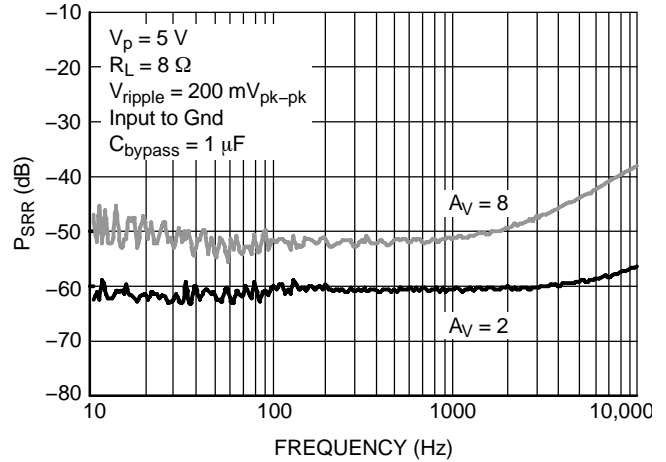


Figure 16.  $P_{SRR}$  @  $V_p = 5\text{ V}$   
Single Ended Audio Input to Ground

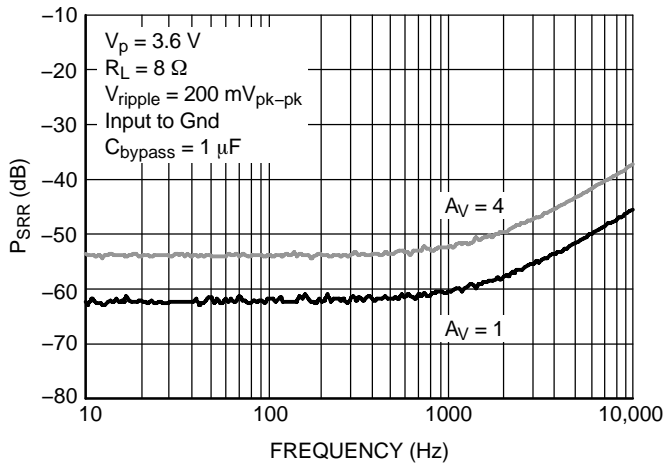


Figure 17.  $P_{SRR}$  @  $V_p = 3.6\text{ V}$   
Differential Audio Input to Ground

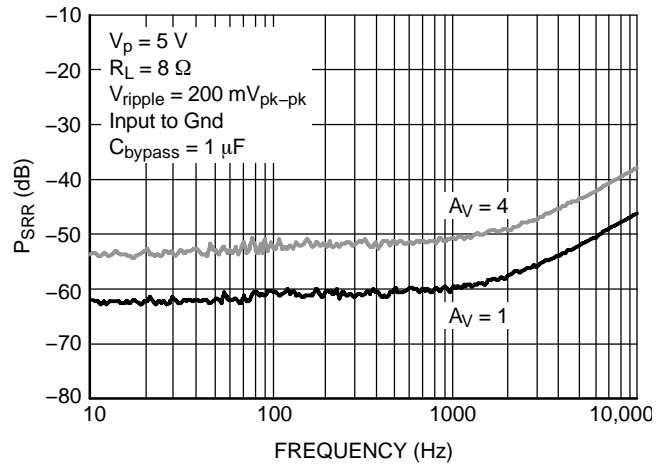


Figure 18.  $P_{SRR}$  @  $V_p = 5\text{ V}$   
Differential Audio Input to Ground

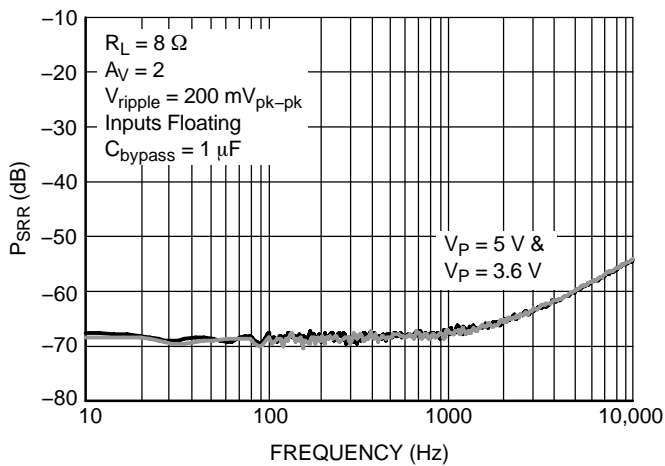


Figure 19.  $P_{SRR}$  @  $V_p = 3.6\text{ V}$   
Single Ended Audio Input Floating

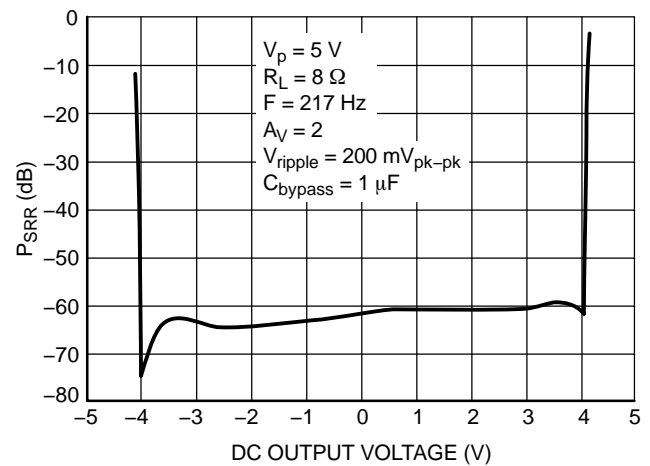


Figure 20.  $P_{SRR}$  @ DC Output Voltage

TYPICAL PERFORMANCE CHARACTERISTICS

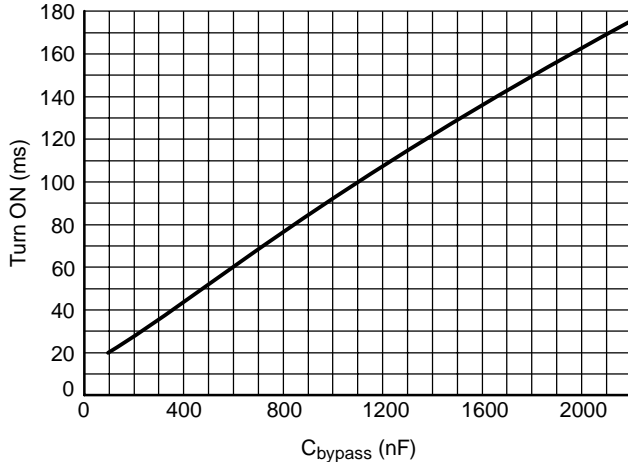


Figure 21.  $T_{ON}$  versus  $C_{bypass}$  @  $V_{bat} = 3.6$  V,  $T_A = +25^\circ\text{C}$

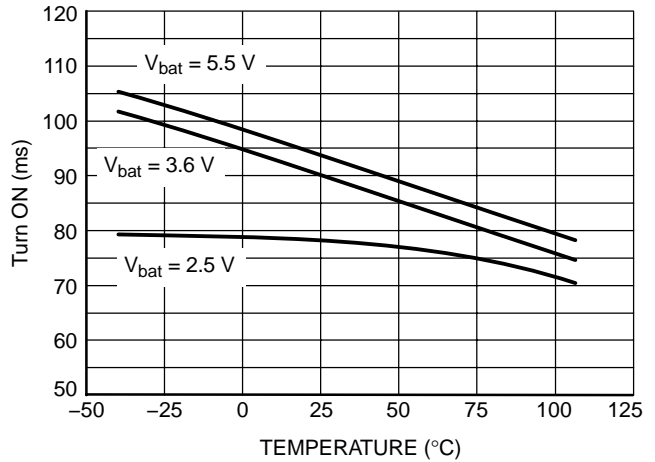


Figure 22.  $T_{ON}$  versus Temperature @  $V_{bat} = 3.6$  V,  $C_{bypass} = 1 \mu\text{F}$

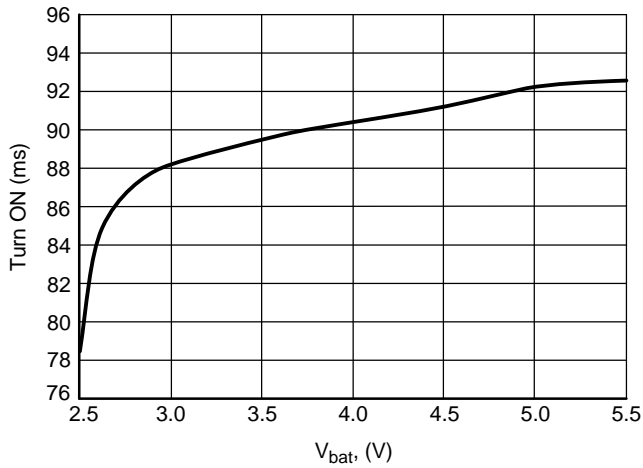


Figure 23.  $T_{ON}$  vs.  $V_{bat}$  @  $C_{bypass} = 1 \mu\text{F}$ ,  $T_A = +25^\circ\text{C}$

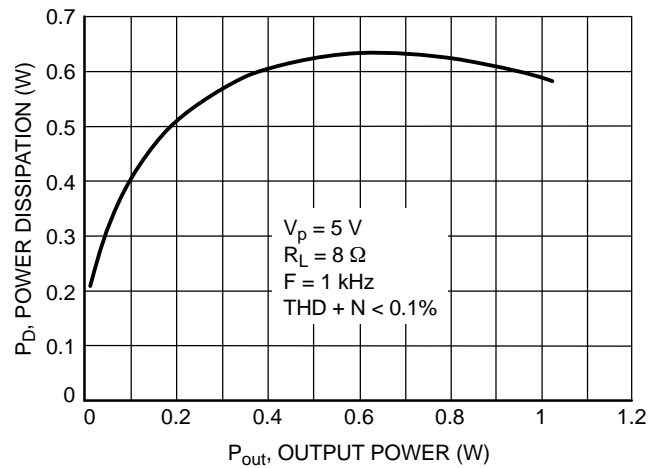


Figure 24. Power Dissipation versus Output Power

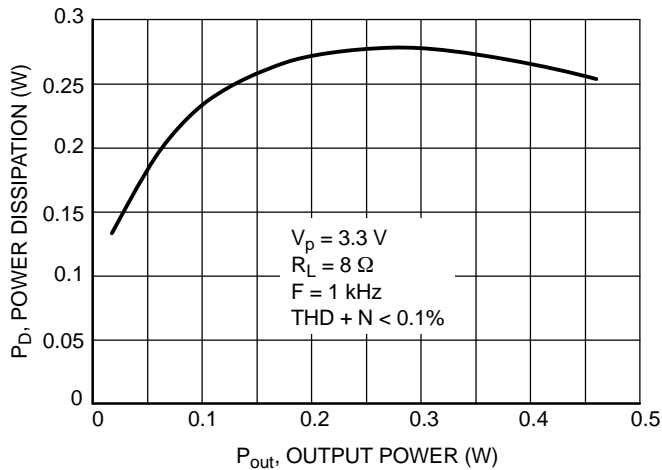


Figure 25. Power Dissipation versus Output Power

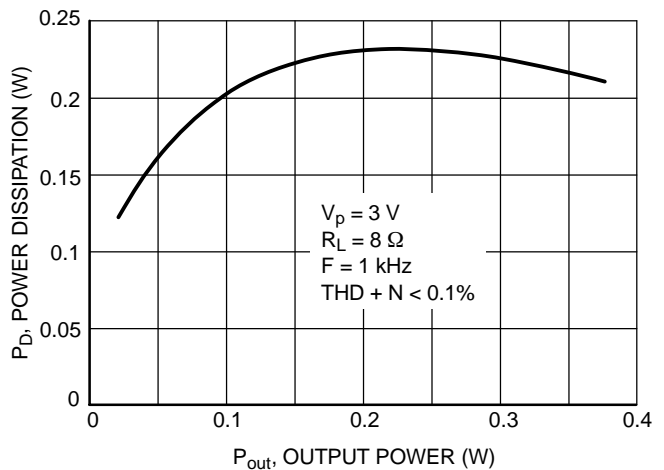
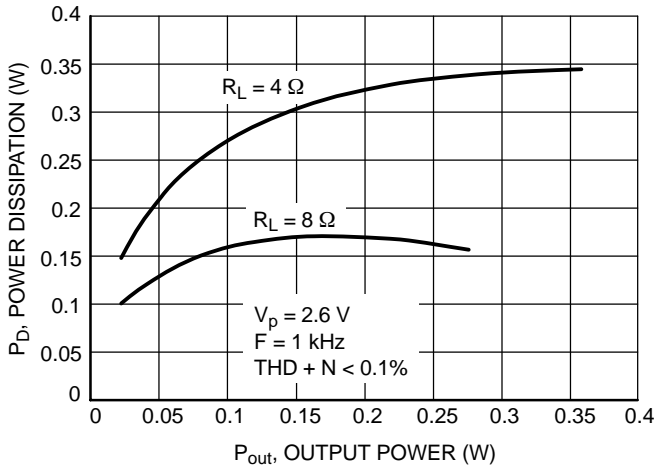


Figure 26. Power Dissipation versus Output Power

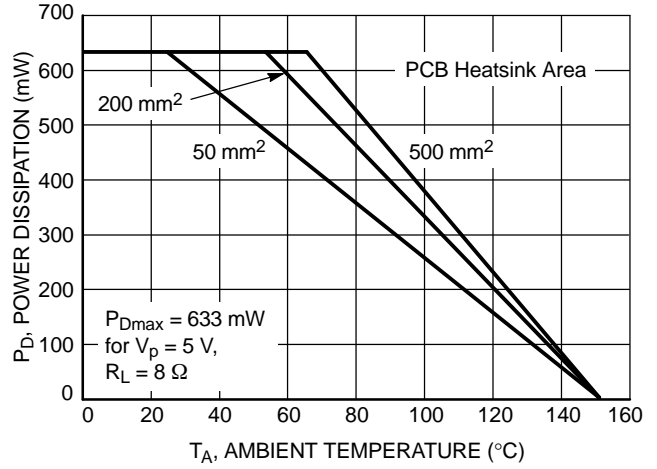


# NCP2892 Series

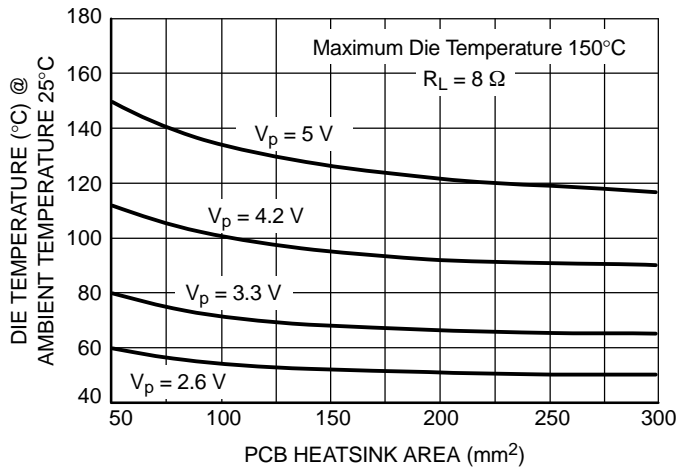
## TYPICAL PERFORMANCE CHARACTERISTICS



**Figure 27. Power Dissipation versus Output Power**



**Figure 28. Power Derating – 9-Pin Flip-Chip CSP**



**Figure 29. Maximum Die Temperature versus PCB Heatsink Area**

TYPICAL PERFORMANCE CHARACTERISTICS

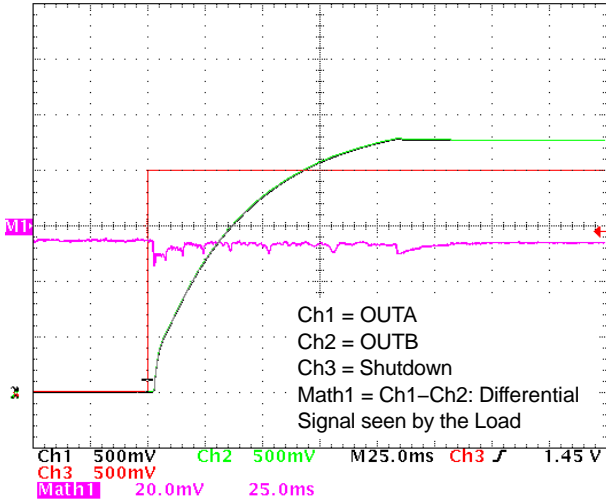


Figure 30. Zero Pop Noise Turn On Sequence with Differential Input to Ground;  $C_{in} = 100 \text{ nF}$ ,  $R_{in} = 24 \Omega$ ,  $R_f = 100 \text{ k}\Omega$ ,  $C_{byp} = 1 \mu\text{F}$ ,  $R_L = 8 \Omega$

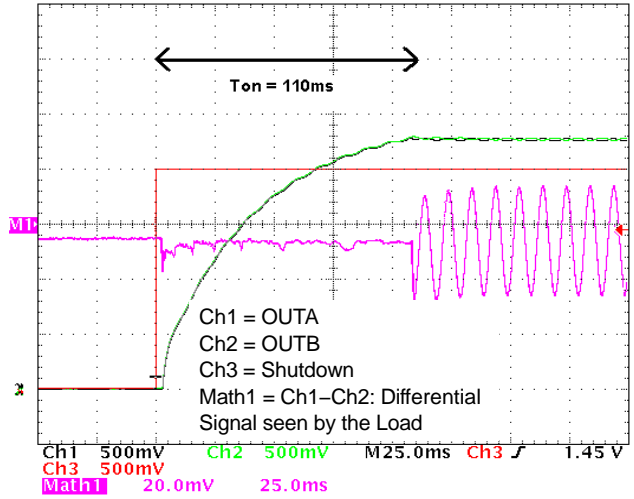


Figure 31. Zero Pop Noise Turn On Sequence with Differential Audio Source;  $C_{in} = 100 \text{ nF}$ ,  $R_{in} = 24 \Omega$ ,  $R_f = 100 \text{ k}\Omega$ ,  $C_{byp} = 1 \mu\text{F}$ ,  $R_L = 8 \Omega$

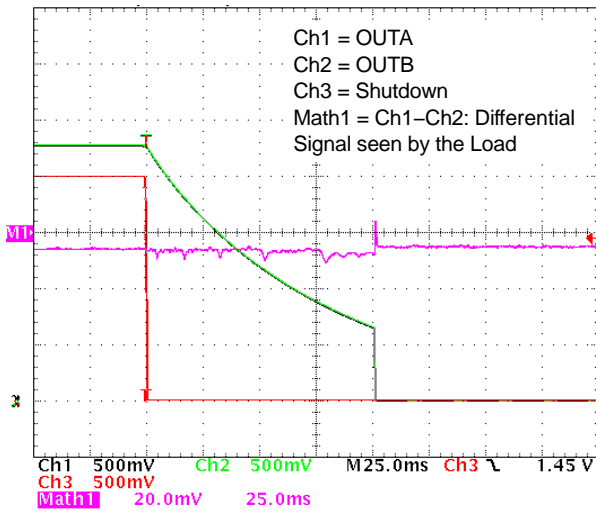


Figure 32. Zero Pop Noise Turn Off Sequence with Differential Input to Ground;  $C_{in} = 100 \text{ nF}$ ,  $R_{in} = 24 \Omega$ ,  $R_f = 100 \text{ k}\Omega$ ,  $C_{byp} = 1 \mu\text{F}$ ,  $R_L = 8 \Omega$

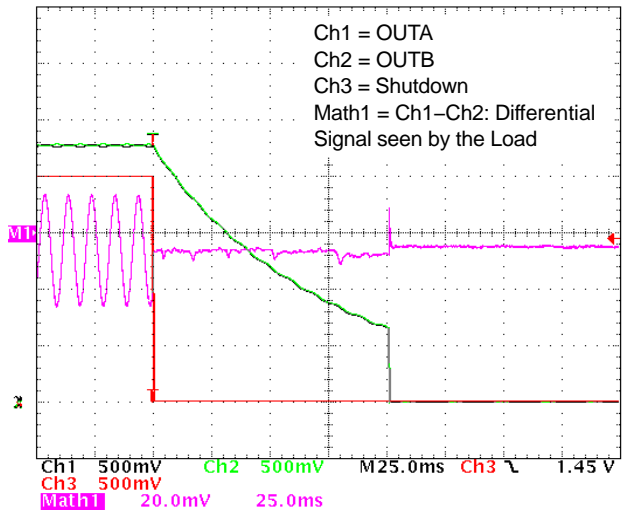


Figure 33. Zero Pop Noise Turn Off Sequence with Differential Audio Source;  $C_{in} = 100 \text{ nF}$ ,  $R_{in} = 24 \Omega$ ,  $R_f = 100 \text{ k}\Omega$ ,  $C_{byp} = 1 \mu\text{F}$ ,  $R_L = 8 \Omega$

## APPLICATION INFORMATION

**Detailed Description**

The NCP2892 audio amplifier can operate under 2.6 V until 5.5 V power supply. With less than 1% THD+N, B version can deliver up to 1.2 W rms output power to an 8.0  $\Omega$  load ( $V_p = 5.0$  V). If application allows to reach 10% THD+N, then 1.6 W can be provided using a 5.0 V power supply.

The structure of the NCP2892 is basically composed of two identical internal power amplifiers; the first one is externally configurable with gain-setting resistors  $R_{in}$  and  $R_f$  (the closed-loop gain is fixed by the ratios of these resistors) and the second is internally fixed in an inverting unity-gain configuration by two resistors of 20 k $\Omega$ . So the load is driven differentially through OUTA and OUTB outputs. This configuration eliminates the need for an output coupling capacitor. The NCP2892A has around 100  $\Omega$  and the NCP2892B has around 10 k $\Omega$  output impedance in the shutdown mode.

**Internal Power Amplifier**

The output PMOS and NMOS transistors of the amplifier were designed to deliver the output power of the specifications without clipping. The channel resistance ( $R_{on}$ ) of the NMOS and PMOS transistors does not exceed 0.6  $\Omega$  when they drive current.

The structure of the internal power amplifier is composed of three symmetrical gain stages, first and medium gain stages are transconductance gain stages to obtain maximum bandwidth and DC gain.

**Turn-On and Turn-Off Transitions**

A cycle with a turn-on and turn-off transition is illustrated with plots that show both single ended signals on the previous page.

In order to eliminate “pop and click” noises during transitions, output power in the load must be slowly established or cut. When logic high is applied to the shutdown pin, the bypass voltage begins to rise exponentially and once the output DC level is around the common mode voltage, the gain is established instantaneously. This way to turn-on the device is optimized in terms of rejection of “pop and click” noises.

The device has the same behavior when it is turned-off by a logic low on the shutdown pin. During the shutdown mode, amplifier outputs are connected to the ground.

When a shutdown low level is applied, with 1  $\mu$ F bypass capacitor, it takes 65 ms before the DC output level is tied to Ground on each output. However, no audio signal will be provided to the BTL load only 1  $\mu$ s after the falling edge on the shutdown pin.

With 1  $\mu$ F bypass capacitor, turn on time is set to 90 ms. This fast turn on time added to a very low shutdown current saves battery life and brings flexibility when designing the audio section of the final application.

NCP2892 is a zero pop noise device when using a differential audio input. In case of a single ended one, there

is no audible pop click noise, especially when the input cut off frequency is higher than 100 Hz.

**Shutdown Function**

The device enters shutdown mode when shutdown signal is low. During the shutdown mode, the DC quiescent current of the circuit does not exceed 100 nA. In this configuration, the output impedance is 10 k $\Omega$  on each output.

**Current Limit Circuit**

The maximum output power of the circuit ( $P_{orms} = 1.0$  W,  $V_p = 5.0$  V,  $R_L = 8.0$   $\Omega$ ) requires a peak current in the load of 500 mA.

In order to limit the excessive power dissipation in the load when a short-circuit occurs, the current limit in the load is fixed to 800 mA. The current in the four output MOS transistors are real-time controlled, and when one current exceeds 800 mA, the gate voltage of the MOS transistor is clipped and no more current can be delivered.

**Thermal Overload Protection**

Internal amplifiers are switched off when the temperature exceeds 160°C, and will be switched on again only when the temperature decreases fewer than 140°C.

The NCP2892 is unity-gain stable and requires no external components besides gain-setting resistors, an input coupling capacitor and a proper bypassing capacitor in the typical application.

The first amplifier is externally configurable ( $R_f$  and  $R_{in}$ ), while the second is fixed in an inverting unity gain configuration.

The differential-ended amplifier presents two major advantages:

- The possible output power is four times larger (the output swing is doubled) as compared to a single-ended amplifier under the same conditions.
- Output pins (OUTA and OUTB) are biased at the same potential  $V_p/2$ , this eliminates the need for an output coupling capacitor required with a single-ended amplifier configuration.

The differential closed loop-gain of the amplifier is given by  $A_{vd} = 2 * \frac{R_f}{R_{in}} = \frac{V_{orms}}{V_{inrms}}$ .

Output power delivered to the load is given by  $P_{orms} = \frac{(V_{opeak})^2}{2 * R_L}$  ( $V_{opeak}$  is the peak differential output voltage).

When choosing gain configuration to obtain the desired output power, check that the amplifier is not current limited or clipped.

The maximum current which can be delivered to the load is 500 mA  $I_{opeak} = \frac{V_{opeak}}{R_L}$ .



# NCP2892 Series

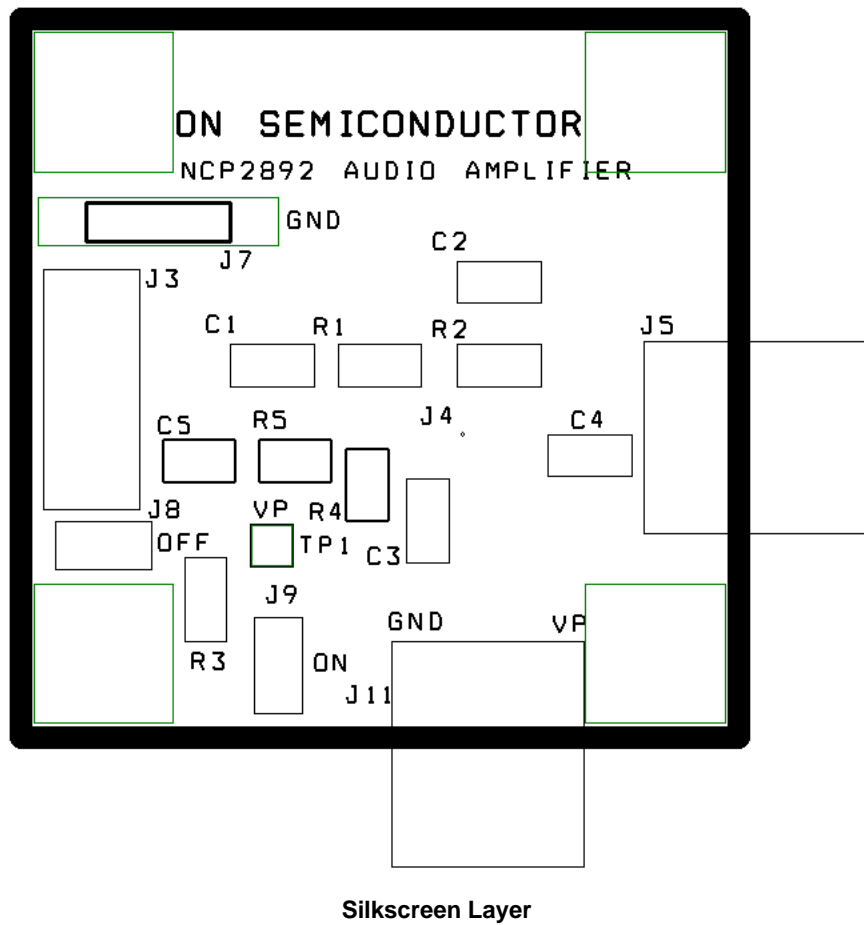


Figure 35. Demonstration Board for 9-Pin Flip-Chip CSP Device – PCB Layers

## NCP2892 Series

### BILL OF MATERIAL

Item	Part Description	Ref.	PCB Footprint	Manufacturer	Manufacturer Reference
1	NCP2892 Audio Amplifier	–	–	ON Semiconductor	NCP2892
2	SMD Resistor 20 K $\Omega$	R1, R5	0805	Panasonic	ERJ-6GEYJ203V
3	SMD Resistor 100 K $\Omega$	R2, R4	0805	Panasonic	ERJ-6GEYJ104V
4	SMD Resistor 150 K $\Omega$	R3	0805	Panasonic	ERJ-6GEYJ154V
5	Ceramic Capacitor 100 nF, 100 V X7R	C1, C5	0805	TDK	C2012X7R2A473K
6	Ceramic Capacitor 1.0 $\mu$ F, 10 V X7R	C3, C4	0805	TDK	C2012X7R1A105K
7	Jumper Header Vertical Mount, 2 positions, 100 mils	J8, J9, J12	100 mils	Tyco Electronics / AMP	5-826629-0
8	I/O Connector, 2 positions	J5, J11	200 mils	Phoenix Contact	1757242
9	Jumper Connector	J7	400 mils	Harwin	D3082-B01
10	Not Mounted	C2, TP1	–	–	–

### ORDERING INFORMATION

Device	Marking	Package	Shipping†
NCP2892AFCT2G	MAX	9-Pin Flip-Chip CSP (Pb-Free)	3000/Tape and Reel
NCP2892BFCT2G	MAZ	9-Pin Flip-Chip CSP (Pb-Free)	3000/Tape and Reel

†For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

NOTE: The NCP2892AFCT2G version requires a lead-free solder paste and should not be used with a SnPb solder paste.

# MECHANICAL CASE OUTLINE

## PACKAGE DIMENSIONS

ON Semiconductor®

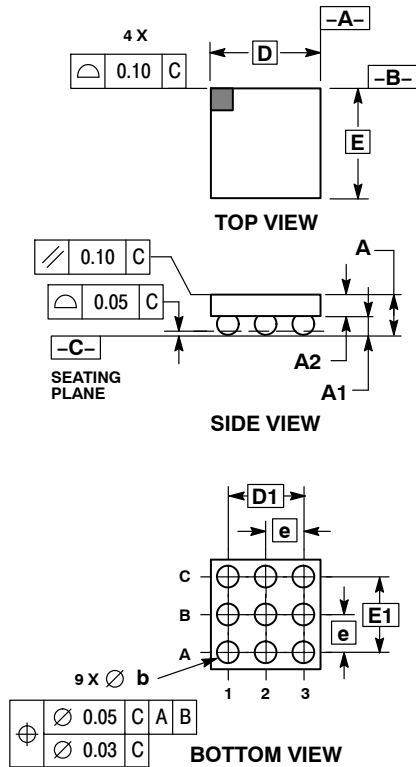


### 9 PIN FLIP-CHIP CASE 499E-01 ISSUE A

DATE 30 JUN 2004



SCALE 4:1

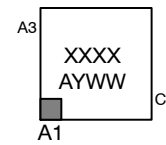


NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: MILLIMETERS.
3. COPLANARITY APPLIES TO SPHERICAL CROWNS OF SOLDER BALLS.

MILLIMETERS		
DIM	MIN	MAX
A	0.540	0.660
A1	0.210	0.270
A2	0.330	0.390
D	1.450 BSC	
E	1.450 BSC	
b	0.290	0.340
e	0.500 BSC	
D1	1.000 BSC	
E1	1.000 BSC	

### GENERIC MARKING DIAGRAM\*



- XXXX = Specific Device Code
- A = Assembly Location
- Y = Year
- WW = Work Week
- G or ■ = Pb-Free Package

\*This information is generic. Please refer to device data sheet for actual part marking. Pb-Free indicator, "G" or microdot "■", may or may not be present.

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<b>DESCRIPTION:</b>	<b>9 PIN FLIP-CHIP, 1.45 X 1.45 MM</b>	<b>PAGE 1 OF 1</b>

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