ABSOLUTE MAXIMUM RATINGS

\/ O\/ to OND	0.01/+0.01/
V _{DD} , OV _{DD} to GND	
OGND to GND	0.3V to +0.3V
INA+, INA-, INB+, INB- to GND	0.3V to V _{DD}
REFIN, REFOUT, REFP, REFN,	
COM, CLK to GND	0.3V to $(V_{DD} + 0.3V)$
OE, PD, SLEEP, T/B, D7A-D0A,	
D7B-D0B to OGND	0.3V to $(OV_{DD} + 0.3V)$

Continuous Power Dissipation ($T_A = +70^{\circ}C$)	
48-Pin TQFP (derate 12.5mW/°C above +7	0°C)1000mW
Operating Temperature Range	40°C to +85°C
Junction Temperature	+150°C
Storage Temperature Range	60°C to +150°C
Lead Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(V_{DD} = OV_{DD} = 3V, 0.1 \mu F$ and $2.2 \mu F$ capacitors from REFP, REFN, and COM to GND; REFOUT connected to REFIN through a $10 k\Omega$ resistor, $V_{IN} = 2V_{P-P}$ (differential with respect to COM), $C_L = 10 pF$ at digital outputs, $f_{CLK} = 60 MHz$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. $\geq +25^{\circ}C$ guaranteed by production test, $< +25^{\circ}C$ guaranteed by design and characterization. Typical values are at $T_A = +25^{\circ}C$.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DC ACCURACY						
Resolution			8			Bits
Integral Nonlinearity	INL	f _{IN} = 7.5MHz (Note 1)		±0.3	±1	LSB
Differential Nonlinearity	DNL	f _{IN} = 7.5MHz, no missing codes guaranteed (Note 1)		±0.2	±1	LSB
Offset Error					±4	%FS
Gain Error					±4	%FS
Gain Temperature Coefficient				±100		ppm/°C
ANALOG INPUT						
Differential Input Voltage Range	V _{DIFF}	Differential or single-ended inputs		±1.0		V
Common-Mode Input Voltage Range	V _{CM}			V _{DD} / 2 ±0.2		٧
Input Resistance	RIN	Switched capacitor load		95		kΩ
Input Capacitance	CIN			5		рF
CONVERSION RATE						
Maximum Clock Frequency	fCLK		60			MHz
Data Latency				5		Clock Cycles
DYNAMIC CHARACTERISTICS (CLK = 60MHz	z, 4096-point FFT)				
		f _{INA or B} = 7.5MHz at -1dB FS		48.7		
Signal to Naisa Batia	SNR	f _{INA or B} = 20MHz at -1dB FS	47	48.7		dB
Signal-to-Noise Ratio	SINU	f _{INA or B} = 30MHz at -1dB FS		48.6		u D
		f _{INA or B} = 115.1MHz at -1dB FS		48.3		

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD} = OV_{DD} = 3V, 0.1 \mu F$ and 2.2 μF capacitors from REFP, REFN, and COM to GND; REFOUT connected to REFIN through a $10k\Omega$ resistor, $V_{IN} = 2V_{P-P}$ (differential with respect to COM), $C_L = 10pF$ at digital outputs, $f_{CLK} = 60MHz$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. $\geq +25^{\circ}C$ guaranteed by production test, $< +25^{\circ}C$ guaranteed by design and characterization. Typical values are at $T_A = +25^{\circ}C$.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
		f _{INA or B} = 7.5MHz at -1dB FS		48.6		
Signal-to-Noise	CINIAD	f _{INA or B} = 20MHz at -1dB FS	46.5	48.6	18.6	
and Distortion	SINAD	f _{INA or B} = 30MHz at -1dB FS		48.5		dB
		f _{INA or B} = 115.1MHz at -1dB FS	48.2			
		f _{INA or B} = 7.5MHz at -1dB FS		71		
Spurious-Free	0500	f _{INA or B} = 20MHz at -1dB FS	60	69		ID.
Dynamic Range	SFDR	f _{INA or B} = 30MHz at -1dB FS		69		dBc
		f _{INA or B} = 115.1MHz at -1dB FS		68		
		f _{INA or B} = 7.5MHz at -1dB FS		-75		
Third-Harmonic	LIDO	f _{INA or B} = 20MHz at -1dB FS		-72		ID.
Distortion	HD3	f _{INA or B} = 30MHz at -1dB FS		-72		dBc
		f _{INA or B} = 115.1MHz at -1dB FS		-68		
Intermodulation Distortion (First Five Odd-Order IMDs)	IMD	f _{IN1} (A or B) = 1.985MHz at -7dB FS f _{IN2} (A or B) = 2.029MHz at -7dB FS (Note 2)		-70		dBc
Third-Order Intermodulation Distortion	IM3	f _{IN1(A or B)} = 1.985MHz at -7dB FS f _{IN2(A or B)} = 2.029MHz at -7dB FS (Note 2)		-71.8		dBc
Total Harmonic Distortion (First Four Harmonics)		f _{INA or B} = 7.5MHz at -1dB FS	or B = 7.5MHz at -1dB FS -69			
	TUD	f _{INA or B} = 20MHz at -1dB FS		-67 -57 -67 -65		dBc
	THD	f _{INA or B} = 30MHz at -1dB FS				
		f _{INA or B} = 115.1MHz at -1dB FS				
Small-Signal Bandwidth		Input at -20dB FS, differential inputs		500		MHz
Full-Power Bandwidth	FPBW	Input at -1dB FS, differential inputs	400			MHz
Gain Flatness (12MHz Spacing)		f _{IN1(A or B)} = 106 MHz at -1dB FS f _{IN2(A or B)} = 118 MHz at -1dB FS (Note 3)			dB	
Aperture Delay	t _{AD}			1		ns
Aperture Jitter	taj	1dB SNR degradation at Nyquist		2		psRMS
Overdrive Recovery Time	İ	For 1.5 × full-scale input		2		ns
INTERNAL REFERENCE (REFIN	= REFOUT throu	ıgh 10k Ω resistor; REFP, REFN, and COM levels	are generat	ed interna	ly.)	
Reference Output Voltage	V _{REFOUT}	(Note 4)		2.048 ±3%		V
Positive Reference Output Voltage	V _{REFP}	(Note 5) 2.012			V	
Negative Reference Output Voltage	VREFN	(Note 5) 0.988			V	
Common-Mode Level	Vcoм	(Note 5)		V _{DD} / 2 ±0.1		V

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD}=OV_{DD}=3V,\,0.1\mu F$ and $2.2\mu F$ capacitors from REFP, REFN, and COM to GND; REFOUT connected to REFIN through a $10k\Omega$ resistor, $V_{IN}=2V_{P-P}$ (differential with respect to COM), $C_L=10pF$ at digital outputs, $f_{CLK}=60MHz$, $T_A=T_{MIN}$ to T_{MAX} , unless otherwise noted. $\geq +25^{\circ}C$ guaranteed by production test, $< +25^{\circ}C$ guaranteed by design and characterization. Typical values are at $T_A=+25^{\circ}C$.)

PARAMETER	SYMBOL	CONDITIONS	MIN TYP MAX	UNITS
Differential Reference Output Voltage Range	ΔV _{REF}	ΔVREF = VREFP - VREFN	1.024 ±3%	V
Reference Temperature Coefficient	TC _{REF}		±100	ppm/°C
BUFFERED EXTERNAL REFERE	NCE (V _{REFIN}	= 2.048V)		
Positive Reference Output Voltage	VREFP	(Note 5)	2.012	V
Negative Reference Output Voltage	VREFN	(Note 5)	0.988	V
Common-Mode Level	V _{COM}	(Note 5)	V _{DD} / 2 ±0.1	V
Differential Reference Output Voltage Range	ΔV _{REF}	ΔVREF = VREFP - VREFN	1.024 ±2%	V
REFIN Resistance	RREFIN		750	МΩ
Maximum REFP, COM Source Current	ISOURCE		5	mA
Maximum REFP, COM Sink Current	Isink		-250	μΑ
Maximum REFN Source Current	ISOURCE		250	μΑ
Maximum REFN Sink Current	ISINK		-5	mA
UNBUFFERED EXTERNAL REFER	ENCE (V _{REFI}	$_{N}$ = AGND, reference voltage applied to REFP, R	EFN, and COM)	
REFP, REFN Input Resistance	R _{REFP} , R _{REFN}	Measured between REFP, COM, REFN, and COM	4	kΩ
REFP, REFN, COM Input Capacitance	CIN		15	pF
Differential Reference Input Voltage Range	ΔV_{REF}	ΔV _{REF} = V _{REFP} - V _{REFN}	1.024 ±10%	V
COM Input Voltage Range	V _{COM}		V _{DD} / 2 ±5%	V
REFP Input Voltage	VREFP		V _{COM} + Δ V _{REF} / 2	V
REFN Input Voltage	VREFN		VCOM - ΔV _{REF} / 2	V
DIGITAL INPUTS (CLK, PD, $\overline{\text{OE}}$,	SLEEP, T/B)			
Input High Throphold	V	CLK	0.8 × V _{DD}	
Input High Threshold	VIH	PD, $\overline{\text{OE}}$, SLEEP, T/B	0.8 × OV _{DD}	V

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD}=OV_{DD}=3V,\,0.1\mu F$ and $2.2\mu F$ capacitors from REFP, REFN, and COM to GND; REFOUT connected to REFIN through a $10k\Omega$ resistor, $V_{IN}=2V_{P-P}$ (differential with respect to COM), $C_L=10pF$ at digital outputs, $f_{CLK}=60MHz$, $T_A=T_{MIN}$ to T_{MAX} , unless otherwise noted. $\geq +25^{\circ}C$ guaranteed by production test, $< +25^{\circ}C$ guaranteed by design and characterization. Typical values are at $T_A=+25^{\circ}C$.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input Low Threshold	VIL	CLK			0.2 × V _{DD}	V
Input Low Threshold	VIL	PD, $\overline{\text{OE}}$, SLEEP, T/B			0.2 × OV _{DD}	V
Input Hysteresis	V _{HYST}			0.15		V
Input Leakage	IIH	$V_{IH} = V_{DD} = OV_{DD}$			±20	μΑ
input Leakage	I _I L	$V_{IL} = 0$			±20	μΛ
Input Capacitance	CIN			5		рF
DIGITAL OUTPUTS (D7A-D0A, D	7B-D0B)					
Output Voltage Low	V _{OL}	$I_{SINK} = -200\mu A$			0.2	V
Output Voltage High	Voн	ISOURCE = 200µA	OV _{DD} - 0.2			V
Three-State Leakage Current	I _{LEAK}	OE = OV _{DD}			±10	μΑ
Three-State Output Capacitance	Cout	OE = OV _{DD}		5		рF
POWER REQUIREMENTS	•		•			•
Analog Supply Voltage Range	V_{DD}		2.7	3	3.6	V
Output Supply Voltage Range	OV _{DD}	$C_L = 15pF$	1.7	3	3.6	V
,		Operating, f _{INA & B} = 20MHz at -1dB FS applied to both channels		40	50	mA
Analog Supply Current	I _{VDD}	Sleep mode		3		1
		Shutdown, clock idle, $PD = \overline{OE} = OV_{DD}$		0.1	20	μΑ
		Operating, f _{INA & B} = 20MHz at -1dB FS applied to both channels (Note 6)		9		mA
Output Supply Current	IOVDD	Sleep mode		3		
		Shutdown, clock idle, $PD = \overline{OE} = OV_{DD}$		3	10	μΑ
Analan Dawan Disainatian	PDICC	Operating, f _{INA & B} = 20MHz at -1dB FS applied to both channels		120	150	mW
Analog Power Dissipation	PDISS	Sleep mode		9		
		Shutdown, clock idle, $PD = \overline{OE} = OV_{DD}$		0.3	60	μW
Power-Supply	DODD	Offset, V _{DD} ±5%		±3		>//\/
Rejection	PSRR	Gain, V _{DD} ±5%		±3		mV/V
TIMING CHARACTERISTICS						
CLK Rise to Output Data Valid Time	t _{DO}	C _L = 20pF (Notes 1, 7)		6	9	ns
OE Fall to Output Enable Time	t _{ENABLE}			5		ns
OE Rise to Output Disable Time	tDISABLE			5		ns
CLK Pulse Width High	tch	Clock period: 16.67ns (Note 7)		8.33 ±1.5		ns



ELECTRICAL CHARACTERISTICS (continued)

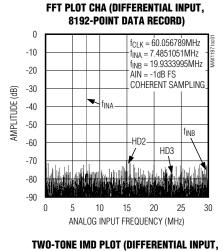
 $(V_{DD} = OV_{DD} = 3V, 0.1\mu F$ and $2.2\mu F$ capacitors from REFP, REFN, and COM to GND; REFOUT connected to REFIN through a $10k\Omega$ resistor, $V_{IN} = 2V_{P-P}$ (differential with respect to COM), $C_L = 10pF$ at digital outputs, $f_{CLK} = 60MHz$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. $\geq +25^{\circ}C$ guaranteed by production test, $< +25^{\circ}C$ guaranteed by design and characterization. Typical values are at $T_A = +25^{\circ}C$.)

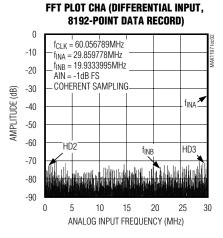
PARAMETER	SYMBOL	IBOL CONDITIONS MIN TYP		TYP	MAX	UNITS
Waka Lin Time		Wake up from sleep mode		1		
Wake-Up Time	tWAKE	Wake up from shutdown mode (Note 11) 20			μs	
CHANNEL-TO-CHANNEL MATCHING						
Crosstalk	$f_{INA \text{ or B}} = 20MHz \text{ at -1dB FS (Note 8)}$ -72			dB		
Gain Matching		f _{INA or B} = 20MHz at -1dB FS (Note 9) 0.05			dB	
Phase Matching		$f_{INA \text{ or } B} = 20MHz \text{ at -1dB FS (Note 10)}$ ±0.05			Degrees	

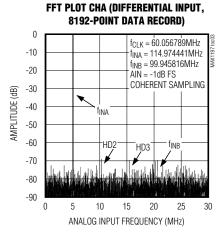
- Note 1: Guaranteed by design. Not subject to production testing.
- Note 2: Intermodulation distortion is the total power of the intermodulation products relative to the total input power.
- **Note 3:** Analog attenuation is defined as the amount of attenuation of the fundamental bin from a converted FFT between two applied input signals with the same magnitude (peak-to-peak) at f_{IN1} and f_{IN2}.
- Note 4: REFIN and REFOUT should be bypassed to GND with a 0.1µF (min) and 2.2µF (typ) capacitor.
- Note 5: REFP, REFN, and COM should be bypassed to GND with a 0.1µF (min) and 2.2µF (typ) capacitor.
- **Note 6:** Typical analog output current at f_{INA&B} = 20MHz. For digital output currents vs. analog input frequency, see *Typical Operating Characteristics*.
- **Note 7:** See Figure 3 for detailed system timing diagrams. Clock to data valid timing is measured from 50% of the clock level to 50% of the data output level.
- **Note 8:** Crosstalk rejection is tested by applying a test tone to one channel and holding the other channel at DC level. Crosstalk is measured by calculating the power ratio of the fundamental of each channel's FFT.
- **Note 9:** Amplitude matching is measured by applying the same signal to each channel and comparing the magnitude of the fundamental of the calculated FFT.
- **Note 10:** Phase matching is measured by applying the same signal to each channel and comparing the phase of the fundamental of the calculated FFT. The data from both ADC channels must be captured simultaneously during this test.
- Note 11: SINAD settles to within 0.5dB of its typical value in unbuffered external reference mode.

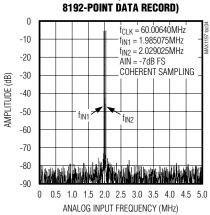
Typical Operating Characteristics

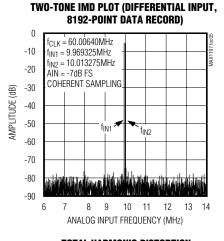
 $(V_{DD} = 3V, \ V_{REFIN} = 2.048V, \ differential input at -1dB FS, \ f_{CLK} = 40MHz, \ C_L \approx 10pF \ T_A = +25^{\circ}C, \ unless \ otherwise noted.)$

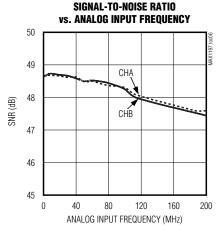


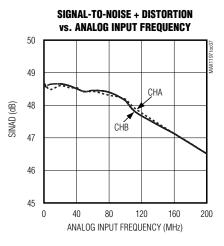


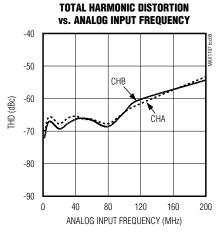


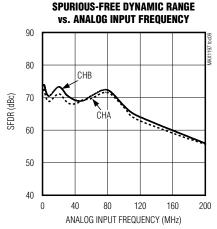






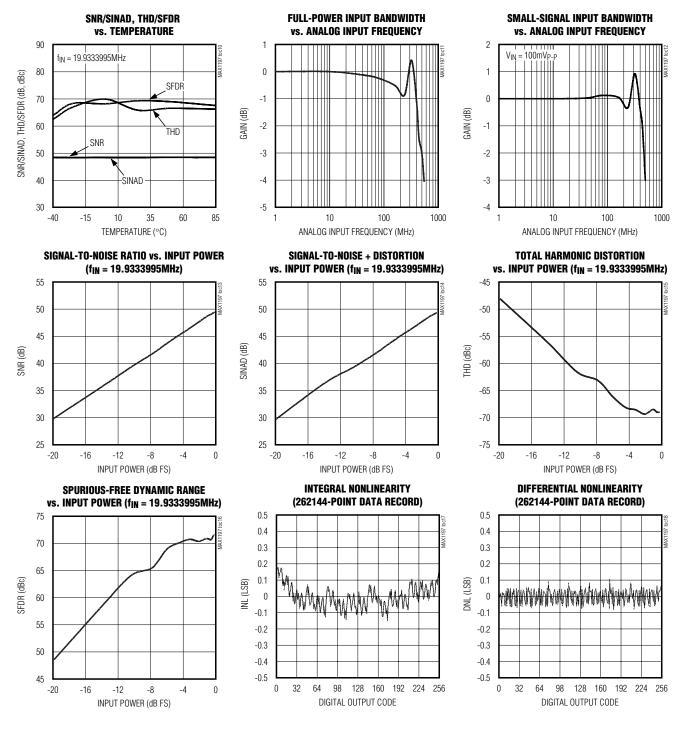






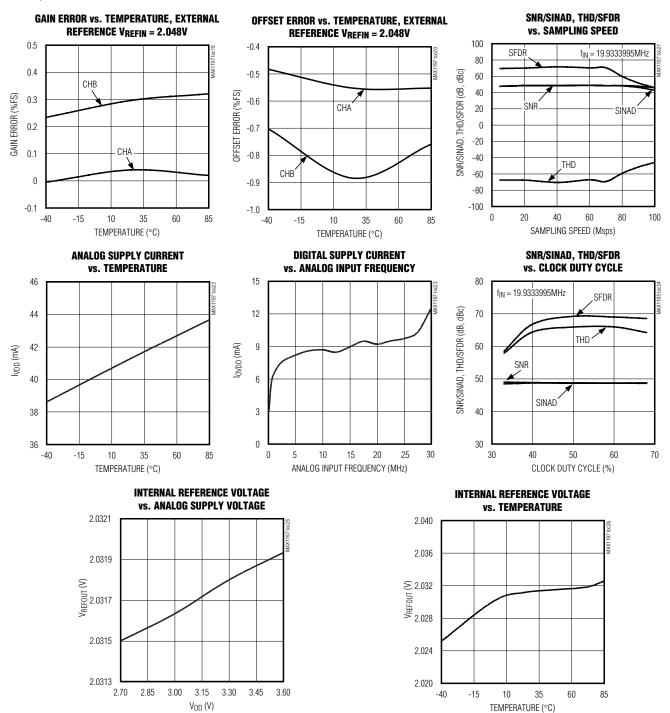
Typical Operating Characteristics (continued)

 $(V_{DD} = 3V, \ V_{REFIN} = 2.048V, \ differential input at -1dB FS, \ f_{CLK} = 40MHz, \ C_L \approx 10pF \ T_A = +25^{\circ}C, \ unless \ otherwise noted.)$



Typical Operating Characteristics (continued)

 $(V_{DD} = 3V, \ V_{REFIN} = 2.048V, \ differential input at -1dB FS, \ f_{CLK} = 40MHz, \ C_L \approx 10pF \ T_A = +25^{\circ}C, \ unless \ otherwise noted.)$



Pin Description

PIN	NAME	FUNCTION			
1	COM	Common-Mode Voltage I/O. Bypass to GND with a ≥ 0.1µF capacitor.			
2, 6, 11, 14, 15	V_{DD}	Analog Supply Voltage. Bypass to GND with a capacitor combination of 2.2µF in parallel with 0.1µF.			
3, 7, 10, 13, 16	GND	Analog Ground			
4	INA+	Channel A Positive Analog Input. For single-ended operation connect signal source to INA+.			
5	INA-	Channel A Negative Analog Input. For single-ended operation connect INA- to COM.			
8	INB-	Channel B Negative Analog Input. For single-ended operation connect INB- to COM.			
9	INB+	Channel B Positive Analog Input. For single-ended operation connect signal source to INB+.			
12	CLK	Converter Clock Input			
17	T/B	T/B Selects the ADC Digital Output Format High: Two's complement Low: Straight offset binary			
18	SLEEP	Sleep Mode Input High: Disables both quantizers, but leaves the reference bias circuit active Low: Normal operation			
19	PD	High-Active Power Down Input High: Power-down mode Low: Normal operation			
20	ŌĒ	Low-Active Output Enable Input High: Digital outputs disabled Low: Digital outputs enabled			
21	D7B	Three-State Digital Output, Bit 7 (MSB), Channel B			
22	D6B	Three-State Digital Output, Bit 6, Channel B			
23	D5B	Three-State Digital Output, Bit 5, Channel B			
24	D4B	Three-State Digital Output, Bit 4, Channel B			
25	D3B	Three-State Digital Output, Bit 3, Channel B			
26	D2B	Three-State Digital Output, Bit 2, Channel B			
27	D1B	Three-State Digital Output, Bit 1, Channel B			
28	D0B	Three-State Digital Output, Bit 0, Channel B			
29, 30, 35, 36	N.C.	No Connect			
31, 34	OGND	Output Driver Ground			
32, 33	OV _{DD}	Output Driver Supply Voltage. Bypass to OGND with a capacitor combination of 2.2µF in parallel with 0.1µF.			
37	D0A	Three-State Digital Output, Bit 0, Channel A			
38	D1A	Three-State Digital Output, Bit 1, Channel A			
39	D2A	Three-State Digital Output, Bit 2, Channel A			
40	D3A	Three-State Digital Output, Bit 3, Channel A			
41	D4A	Three-State Digital Output, Bit 4, Channel A			

Pin Description (continued)

PIN	NAME	FUNCTION
42	D5A	Three-State Digital Output, Bit 5, Channel A
43	D6A	Three-State Digital Output, Bit 6, Channel A
44	D7A	Three-State Digital Output, Bit 7 (MSB), Channel A
45	REFOUT	Internal Reference Voltage Output. May be connected to REFIN through a resistor or a resistor divider.
46	REFIN	Reference Input. V _{REFIN} = 2 x (V _{REFP} – V _{REFN}). Bypass to GND with a > 0.1µF capacitor.
47	REFP	Positive Reference I/O. Conversion range is ±(V _{REFP} – V _{REFN}). Bypass to GND with a > 0.1µF capacitor.
48	REFN	Negative Reference I/O. Conversion range is \pm (V _{REFP} – V _{REFN}). Bypass to GND with a > 0.1 μ F capacitor.

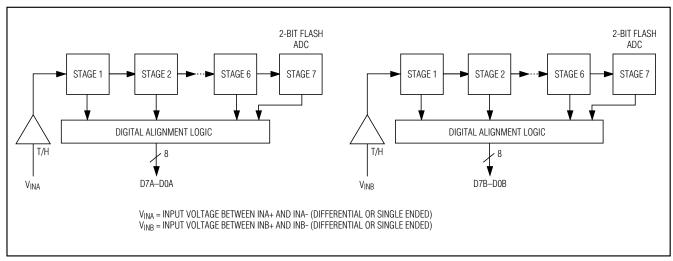


Figure 1. Pipelined Architecture—Stage Blocks

Detailed Description

The MAX1197 uses a seven-stage, fully differential, pipelined architecture (Figure 1) that allows for high-speed conversion while minimizing power consumption. Samples taken at the inputs move progressively through the pipeline stages every half-clock cycle. Including the delay through the output latch, the total clock-cycle latency is five clock cycles.

Flash ADCs convert the held input voltages into a digital code. Internal MDACs convert the digitized results

back into analog voltages, which are then subtracted from the original held input signals. The resulting error signals are then multiplied by two, and the residues are passed along to the next pipeline stages where the process is repeated until the signals have been processed by all seven stages.

Input Track-and-Hold Circuits

Figure 2 displays a simplified functional diagram of the input T/H circuits in both track and hold mode. In track mode, switches S1, S2a, S2b, S4a, S4b, S5a, and S5b

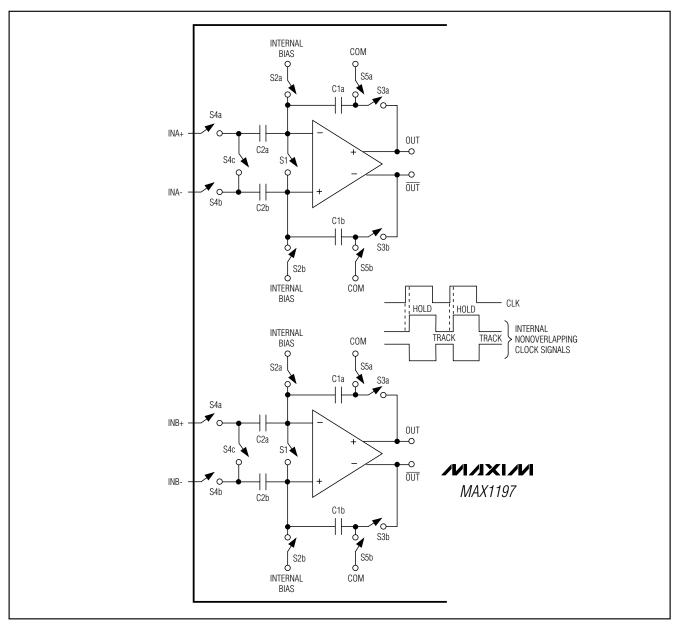


Figure 2. MAX1197 T/H Amplifiers

are closed. The fully differential circuits sample the input signals onto the two capacitors (C2a and C2b) through switches S4a and S4b. S2a and S2b set the common mode for the amplifier input, and open simultaneously with S1 sampling the input waveform. Switches S4a, S4b, S5a, and S5b are then opened before switches S3a and S3b connects capacitors C1a and C1b to the output of the amplifier and switch S4c is closed. The resulting differential voltages are held on

capacitors C2a and C2b. The amplifiers are used to charge capacitors C1a and C1b to the same values originally held on C2a and C2b. These values are then presented to the first-stage quantizers and isolate the pipelines from the fast-changing inputs. The wide input bandwidth T/H amplifiers allow the MAX1197 to track and sample/hold analog inputs of high frequencies (>Nyquist). Both ADC inputs (INA+, INB+ and INA-, INB-) can be driven either differentially or single-ended.

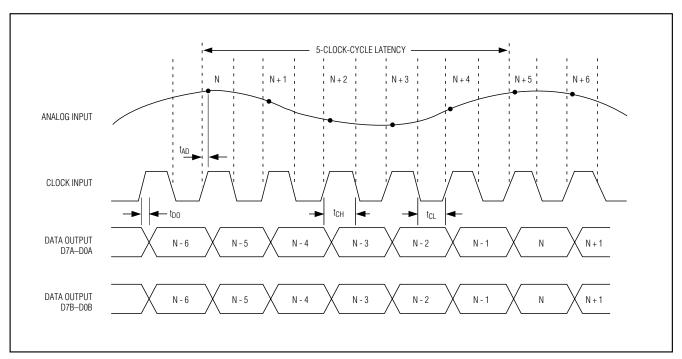


Figure 3. System Timing Diagram

Match the impedance of INA+ and INA-, as well as INB+ and INB-, and set the common-mode voltage to mid-supply (VDD/2) for optimum performance.

Analog Inputs and Reference Configurations

The full-scale range of the MAX1197 is determined by the internally generated voltage difference between REFP ($V_{DD}/2 + V_{REFIN}/4$) and REFN ($V_{DD}/2 - V_{REFIN}/4$). The full-scale range for both on-chip ADCs is adjustable through the REFIN pin, which is provided for this purpose.

The MAX1197 provides three modes of reference operation:

- Internal reference mode
- · Buffered external reference mode
- Unbuffered external reference mode

In internal reference mode, connect the internal reference output REFOUT to REFIN through a resistor (e.g., $10 k\Omega)$ or resistor divider, if an application requires a reduced full-scale range. For stability and noise-filtering purposes, bypass REFIN with a >10nF capacitor to GND. In internal reference mode, REFOUT, COM, REFP, and REFN become low-impedance outputs.

In buffered external reference mode, adjust the reference voltage levels externally by applying a stable and accurate voltage at REFIN. In this mode, COM, REFP, and REFN are outputs. REFOUT can be left open or connected to REFIN through a >10k Ω resistor.

In unbuffered external reference mode, connect REFIN to GND. This deactivates the on-chip reference buffers for REFP, COM, and REFN. With their buffers shut down, these nodes become high-impedance inputs and can be driven through separate, external reference sources.

For detailed circuit suggestions and how to drive this dual ADC in buffered/unbuffered external reference mode, see the *Applications Information* section.

Clock Input (CLK)

The MAX1197's CLK input accepts a CMOS-compatible clock signal. Since the interstage conversion of the device depends on the repeatability of the rising and falling edges of the external clock, use a clock with low jitter and fast rise and fall times (<2ns). In particular, sampling occurs on the rising edge of the clock signal, requiring this edge to provide lowest possible jitter. Any significant aperture jitter would limit the SNR performance of the on-chip ADCs as follows:

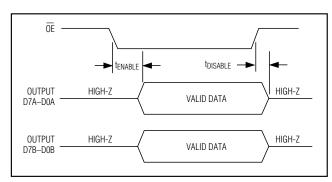


Figure 4. Output Timing Diagram $SNR = 20 \times log \frac{1}{2 \times \pi \times f_{|N|} \times t_{A,J}}$

where f_{IN} represents the analog input frequency and t_{AJ} is the time of the aperture jitter.

Clock jitter is especially critical for undersampling applications. The clock input should always be considered as an analog input and routed away from any analog input or other digital signal lines.

The MAX1197 clock input operates with a voltage threshold set to V_{DD}/2. Clock inputs with a duty cycle other than 50% must meet the specifications for high and low periods as stated in the *Electrical Characteristics* table.

System Timing Requirements

Figure 3 depicts the relationship between the clock input, analog input, and data output. The MAX1197 samples at the rising edge of the input clock. Output data for channels A and B is valid on the next rising edge of the input clock. The output data has an internal latency of five clock cycles. Figure 3 also determines the relationship between the input clock parameters and the valid output data on channels A and B.

Digital Output Data (DOA/B-D7A/B), Output Data Format Selection (T/B), Output Enable (OE)

All digital outputs, D0A–D7A (channel A) and D0B–D7B (channel B), are TTL/CMOS-logic compatible. There is a five-clock-cycle latency between any particular sample and its corresponding output data. The output coding can either be straight offset binary or two's complement (Table 1) controlled by a single pin (T/B). Pull T/B low to select offset binary and high to activate two's complement output coding. The capacitive load on the digital outputs D0A–D7A and D0B–D7B should be kept as low as possible (<15pF), to avoid large digital currents that could feed back into the analog portion of the MAX1197, thereby degrading its dynamic performance. Using

Table 1. MAX1197 Output Codes For Differential Inputs

DIFFERENTIAL INPUT VOLTAGE*	DIFFERENTIAL INPUT	STRAIGHT OFFSET BINARY T/B = 0	TWO'S COMPLEMENT T/B = 1
V _{REF} x 255/256	+Full Scale -1LSB	1111 1111	0111 1111
V _{REF} x 1/256	+1LSB	1000 0001	0000 0001
0	Bipolar zero	1000 0000	0000 0000
-V _{REF} x 1/256	-1LSB	0111 1111	1111 1111
-V _{REF} x 255/256	-Full Scale +1LSB	0000 0001	1000 0001
-V _{REF} x 256/256	-Full Scale	0000 0000	1000 0000

^{*}VREF = VREFP - VREFN

buffers on the digital outputs of the ADCs can further isolate the digital outputs from heavy capacitive loads. To further improve the dynamic performance of the MAX1197, small series resistors (e.g., 100Ω) may be added to the digital output paths close to the MAX1197.

Figure 4 displays the timing relationship between output enable and data output valid, as well as power-down/wake-up and data output valid.

Power-Down and Sleep Modes

The MAX1197 offers two power-save modes—sleep mode (SLEEP) and full power-down (PD) mode. In sleep mode (SLEEP = 1), only the reference bias circuit is active (both ADCs are disabled), and current consumption is reduced to 3mA.

To enter full power-down mode, pull PD high. With \overline{OE} simultaneously low, all outputs are latched at the last value prior to the power down. Pulling \overline{OE} high forces the digital outputs into a high-impedance state.

Applications Information

Figure 5 depicts a typical application circuit containing two single-ended-to-differential converters. The internal reference provides a $V_{DD}/2$ output voltage for level-shifting purposes. The input is buffered and then split to a voltage follower and inverter. One lowpass filter per amplifier suppresses some of the wideband noise associated with high-speed operational amplifiers. The user can select the RISO and CIN values to optimize the filter performance, to suit a particular application. For the application in Figure 5, a RISO of 50Ω is placed before the capacitive load to prevent ringing and oscil-

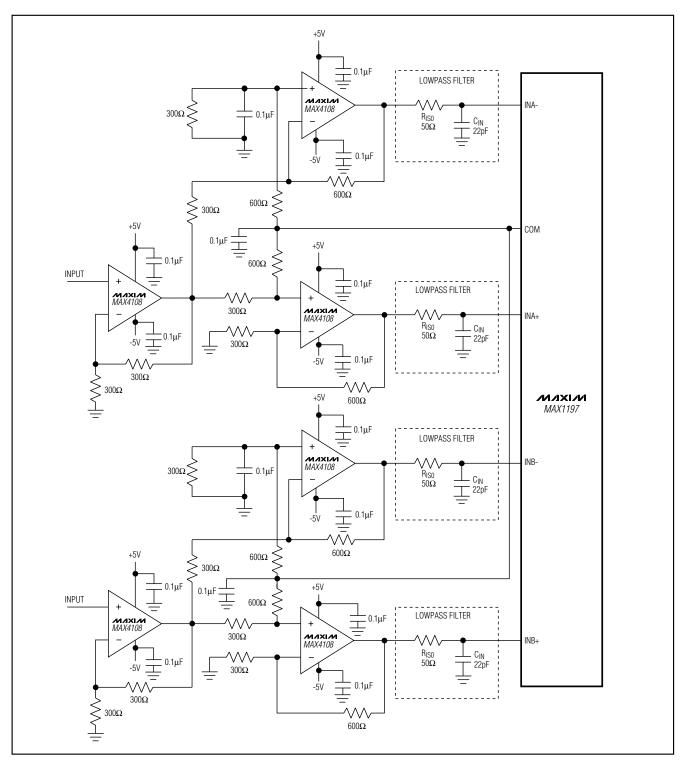


Figure 5. Typical Application for Single-Ended-to-Differential Conversion

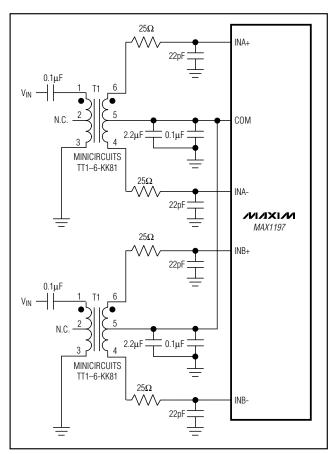


Figure 6. Transformer-Coupled Input Drive

lation. The 22pF $C_{\mbox{\scriptsize IN}}$ capacitor acts as a small filter capacitor.

Using Transformer Coupling

An RF transformer (Figure 6) provides an excellent solution to convert a single-ended source signal to a fully differential signal, required by the MAX1197 for optimum performance. Connecting the center tap of the transformer to COM provides a VDD/2 DC level shift to the input. Although a 1:1 transformer is shown, a stepup transformer can be selected to reduce the drive requirements. A reduced signal swing from the input driver, such as an op amp, can also improve the overall distortion.

In general, the MAX1197 provides better SFDR and THD with fully differential input signals than single-ended drive, especially for very high input frequencies. In differential input mode, even-order harmonics are lower as both inputs (INA+, INA- and/or INB+, INB-) are

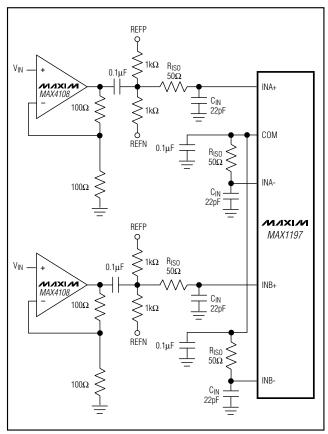


Figure 7. Using an Op Amp for Single-Ended, AC-Coupled Input Drive

balanced, and each of the ADC inputs only requires half the signal swing compared to single-ended mode.

Single-Ended AC-Coupled Input Signal

Figure 7 shows an AC-coupled, single-ended application. Amplifiers like the MAX4108 provide high speed, high bandwidth, low noise, and low distortion to maintain the integrity of the input signal.

Buffered External Reference Drives Multiple ADCs

Multiple-converter systems based on the MAX1197 are well suited for use with a common reference voltage. The REFIN pin of those converters can be connected directly to an external reference source.

A precision bandgap reference like the MAX6062 generates an external DC level of 2.048V (Figure 8), and exhibits a noise voltage density of $150\text{nV}/\sqrt{\text{Hz}}$. Its output passes through a 1-pole lowpass filter (with 10Hz

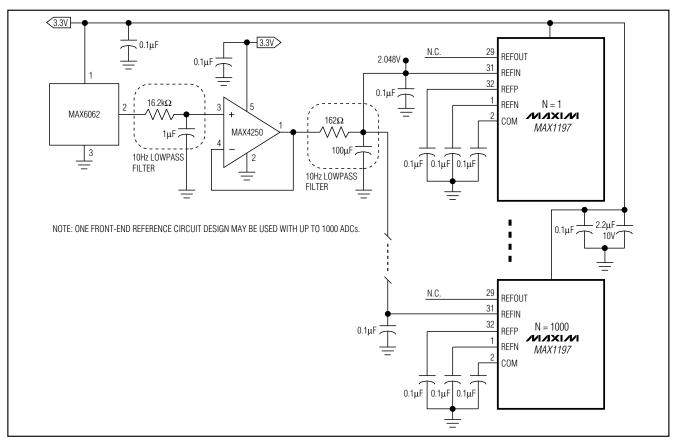


Figure 8. External Buffered (MAX4250) Reference Drive Using a MAX6062 Bandgap Reference

cutoff frequency) to the MAX4250, which buffers the reference before its output is applied to a second 10Hz lowpass filter. The MAX4250 provides a low offset voltage (for high gain accuracy) and a low noise level. The passive 10Hz filter following the buffer attenuates noise produced in the voltage reference and buffer stages. This filtered noise density, which decreases for higher frequencies, meets the noise levels specified for precision ADC operation.

Unbuffered External Reference Drives Multiple ADCs

Connecting each REFIN to analog ground disables the internal reference of each device, allowing the internal reference ladders to be driven directly by a set of external reference sources. Followed by a 10Hz low-pass filter and precision voltage divider, the MAX6066 generates a DC level of 2.500V. The buffered outputs of this divider are set to 2.0V, 1.5V, and 1.0V, with an accuracy that depends on the tolerance of the divider resistors. These three voltages are buffered by the

MAX4252, which provides low noise and low DC offset. The individual voltage followers are connected to 10Hz lowpass filters, which filter both the reference voltage and amplifier noise to a level of 3nV/\(\sqrt{Hz}\). The 2.0V and 1.0V reference voltages set the differential full-scale range of the associated ADCs at 2VP-P. The 2.0V and 1.0V buffers drive the ADC's internal ladder resistances between them.

Note that the common power supply for all active components removes any concern regarding power-supply sequencing when powering up or down. With the outputs of the MAX4252 matching better than 0.1%, the buffers and subsequent lowpass filters can be replicated to support as many as 32 ADCs. For applications that require more than 32 matched ADCs, a voltage reference and divider string common to all converters is highly recommended.

Typical QAM Demodulation Application

A frequently used modulation technique in digital communications applications is quadrature amplitude

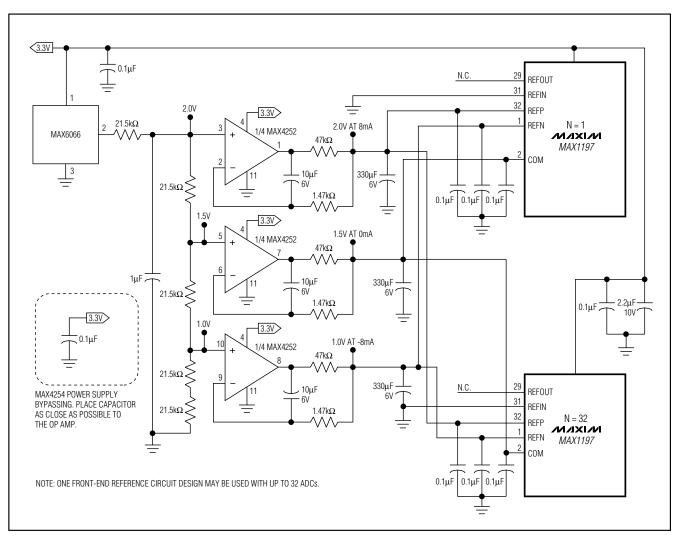


Figure 9. External Unbuffered Reference Drive with MAX4252 and MAX6066

modulation (QAM). Typically found in spread-spectrum-based systems, a QAM signal represents a carrier frequency modulated in both amplitude and phase. At the transmitter, modulating the baseband signal with quadrature outputs, a local oscillator followed by subsequent upconversion can generate the QAM signal. The result is an in-phase (I) and a quadrature (Q) carrier component, where the Q component is 90° phase shifted with respect to the in-phase component. At the receiver, the QAM signal is divided down into its I and Q components, essentially representing the modulation process reversed. Figure 10 displays the demodulation process performed in the analog domain, using the dual matched 3V, 8-bit ADC MAX1197 and the MAX2451 quadrature demodulator to recover and digi-

tize the I and Q baseband signals. Before being digitized by the MAX1197, the mixed-down signal components may be filtered by matched analog filters, such as Nyquist or pulse-shaping filters which remove unwanted images from the mixing process, thereby enhancing the overall signal-to-noise (SNR) performance and minimizing intersymbol interference.

Grounding, Bypassing, ___and Board Layout

The MAX1197 requires high-speed board layout design techniques. Locate all bypass capacitors as close to the device as possible, preferably on the same side as the ADC, using surface-mount devices for minimum

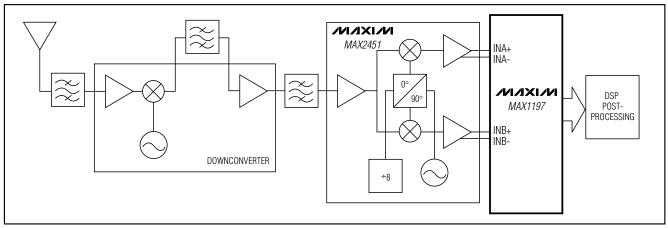


Figure 10. Typical QAM Application Using the MAX1197

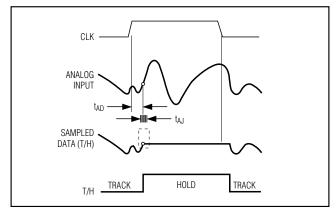


Figure 11. T/H Aperture Timing

inductance. Bypass VDD, REFP, REFN, and COM with two parallel 0.1µF ceramic capacitors and a 2.2µF bipolar capacitor to GND. Follow the same rules to bypass the digital supply (OVDD) to OGND. Multilayer boards with separated ground and power planes produce the highest level of signal integrity. Consider the use of a split ground plane arranged to match the physical location of the analog ground (GND) and the digital output driver ground (OGND) on the ADC's package. The two ground planes should be joined at a single point so the noisy digital ground currents do not interfere with the analog ground plane. The ideal location for this connection can be determined experimentally at a point along the gap between the two ground planes, which produces optimum results. Make this connection with a low-value, surface-mount resistor (1 Ω to 5Ω), a ferrite bead, or a direct short.

Alternatively, all ground pins could share the same ground plane, if the ground plane is sufficiently isolated

from any noisy, digital systems ground plane (e.g., downstream output buffer or DSP ground plane). Route high-speed digital signal traces away from the sensitive analog traces of either channel. Make sure to isolate the analog input lines to each respective converter to minimize channel-to-channel crosstalk. Keep all signal lines short and free of 90° turns.

Static Parameter Definitions

Integral Nonlinearity

Integral nonlinearity (INL) is the deviation of the values on an actual transfer function from a straight line. This straight line can be either a best-straight-line fit or a line drawn between the endpoints of the transfer function, once offset and gain errors have been nullified. The static linearity parameters for the MAX1197 are measured using the best-straight-line-fit method.

Differential Nonlinearity

Differential nonlinearity (DNL) is the difference between an actual step width and the ideal value of 1LSB. A DNL error specification of less than 1LSB guarantees no missing codes and a monotonic transfer function.

Dynamic Parameter Definitions

Aperture Jitter

Figure 11 depicts the aperture jitter (t̄AJ), which is the sample-to-sample variation in the aperture delay.

Aperture Delay

Aperture delay (t_{AD}) is the time defined between the rising edge of the sampling clock and the instant when an actual sample is taken (Figure 11).

Signal-to-Noise Ratio

For a waveform perfectly reconstructed from digital samples, the theoretical maximum SNR is the ratio of the full-scale analog input (RMS value) to the RMS quantization error (residual error). The ideal, theoretical minimum analog-to-digital noise is caused by quantization error only and results directly from the ADC's resolution (N-bits):

$$SNR_{dB[max]} = 6.02_{dB} \times N + 1.76_{dB}$$

In reality, there are other noise sources besides quantization noise: thermal noise, reference noise, clock jitter, etc. SNR is computed by taking the ratio of the RMS signal to the RMS noise, which includes all spectral components minus the fundamental, the first five harmonics, and the DC offset.

Signal-to-Noise Plus Distortion

SINAD is computed by taking the ratio of the RMS signal to all spectral components minus the fundamental and the DC offset.

Effective Number of Bits

Effective number of bits (ENOB) specifies the dynamic performance of an ADC at a specific input frequency and sampling rate. An ideal ADC's error consists of quantization noise only. ENOB for a full-scale sinusoidal input waveform is computed from:

$$ENOB = \frac{SINAD - 1.76}{6.02}$$

Total Harmonic Distortion

THD is typically the ratio of the RMS sum of the first four harmonics of the input signal to the fundamental itself. This is expressed as:

THD =
$$20 \times \log \frac{\sqrt{V_2^2 + V_3^2 + V_4^2 + V_5^2}}{V_1}$$

where V_1 is the fundamental amplitude, and V_2 through V_5 are the amplitudes of the 2nd- through 5th-order harmonics.

Spurious-Free Dynamic Range

Spurious-free dynamic range (SFDR) is the ratio expressed in decibels of the RMS amplitude of the fundamental (maximum signal component) to the RMS value of the next largest spurious component, excluding DC offset.

Intermodulation Distortion

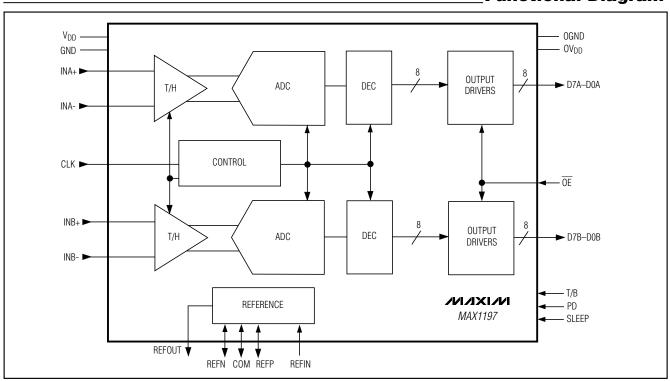
The two-tone intermodulation distortion (IMD) is the ratio expressed in decibels of either input tone to the worst third-order (or higher) intermodulation products. The individual input tone levels are at -7dB full scale and their envelope is at -1dB full scale.

Chip Information

TRANSISTOR COUNT: 11,601

PROCESS: CMOS

Functional Diagram



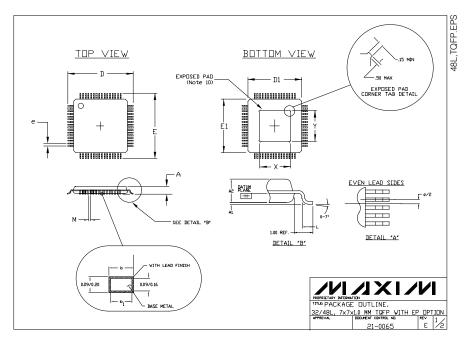
Pin-Compatible Upgrades (Sampling Speed and Resolution)

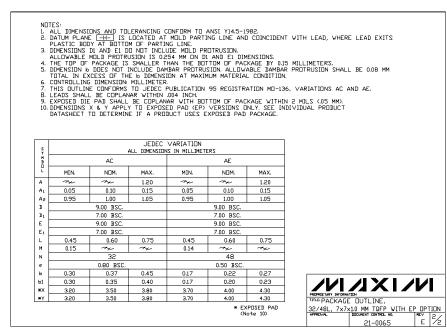
8-BIT PART	10-BIT PART	SAMPLING SPEED (Msps)
MAX1195	MAX1183	40
MAX1197	MAX1182	60
MAX1198	MAX1180	100
MAX1196*	MAX1186	40, multiplexed

^{*}Future product, please contact factory for availability.

Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)





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