#### **ABSOLUTE MAXIMUM RATINGS**

|   | -1                        |
|---|---------------------------|
| V <sub>DD</sub> to GND                    | 6V                        |
| REF, RFB to GND                           | ±12V                      |
| Digital Inputs (SCLK, DIN, LOAD, CLR)     | )                         |
| to GND                                    | 0.3V to 6V                |
| OUT to GND                                | 0.3V to $(V_{DD} + 0.3V)$ |
| AGND to DGND                              | ±0.3V                     |
| Continuous Power Dissipation ( $T_A = +7$ | 70°C)                     |
| Plastic DIP (derate 9.09mW/°C above       | e +70°C)727mW             |
| μMAX (derate 5.60mW/°C above +70          | )°C)444mW                 |
|   |                           |

| 0°C to +70°C   |
|----------------|
| 40°C to +85°C  |
| 65°C to +150°C |
| +300°C         |
|                |

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **ELECTRICAL CHARACTERISTICS—MAX551**

 $(V_{DD} = +4.5V \text{ to } +5.25V, V_{REF} = 5V, OUT = AGND = GND, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}C.)$  (Note 1)

| PARAMETER                    | SYMBOL | CONDITIONS  |                         | MIN  | TYP  | MAX               | UNITS  |  |  |
|------------------------------|--------|---|-------------------------|------|------|-------------------|--------|--|--|
| STATIC PERFORMANCE           |        |   |                         |      |      |                   |        |  |  |
| Resolution                   | N      |   |                         | 12   |      |                   | Bits   |  |  |
| Integral Nonlinearity        | INL    |   | MAX551A                 |      |      | ±1/2              | LSB    |  |  |
| integral Normheanty          | IINL   |   | MAX551B                 |      |      | ±1                | LSB    |  |  |
| Differential Nonlinearity    | DNL    | Guaranteed monotonic over   | MAX551A                 |      |      | ±1/2              | LSB    |  |  |
| Differential Northinearity   | DIVL   | temperature   | MAX551B                 |      |      | ±1                | LOD    |  |  |
| Gain Error                   |        | Using internal feedback   | MAX551A                 |      |      | ±1                | LSB    |  |  |
| Gain Endi                    |        | resistor (R <sub>FB</sub> )   | MAX551B                 |      |      | ±2                | LOD    |  |  |
| Gain Tempco<br>(ΔGain/ΔTemp) |        | Using internal feedback resis (Note 2)                                    | stor (R <sub>FB</sub> ) |      | ±0.2 | ±1                | ppm/°C |  |  |
| Power-Supply Rejection       | PSR    | $\Delta V_{DD} = +5\%, -10\%$   |                         |      |      | 2                 | ppm/%  |  |  |
| DYNAMIC PERFORMANCE (No      | ote 3) |   |                         |      |      |                   |        |  |  |
| Current Settling Time        | ts     | $T_A$ = +25°C, to 1/2LSB, OUT 100ΩII13pF, DAC register alt with 1s and 0s |                         | 0.08 | 1    | μs                |        |  |  |
| Digital-to-Analog Glitch     |        | V <sub>REF</sub> = 0V, OUT load is 1000 register alternately loaded wi    |                         |      | 0.65 | 20                | nV-s   |  |  |
| AC Feedthrough at OUT        |        | V <sub>REF</sub> = 5V <sub>P-P</sub> at 10kHz, DAC with all 0s            |                         | 0.3  | 1    | mV <sub>P-P</sub> |        |  |  |
| Total Harmonic Distortion    | THD    | VREF = 6VRMS at 1kHz, DAC with all 1s                                     |                         | -85  |      | dB                |        |  |  |
| Output Noise-Voltage Density |        | 10Hz to 100kHz, measured b  | petween RFB and         |      | 13   | 15                | nV/√Hz |  |  |

### **ELECTRICAL CHARACTERISTICS—MAX551 (continued)**

 $(V_{DD} = +4.5V \text{ to } +5.25V, V_{REF} = 5V, OUT = AGND = GND, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$  Typical values are at  $T_A = +25^{\circ}C$ .) (Note 1)

| PARAMETER                | SYMBOL           | CONDITIONS                          |  | MIN  | TYP   | MAX  | UNITS  |
|--------------------------|------------------|-------------------------------------|--|------|-------|------|--------|
| REFERENCE INPUT          |                  | I.                                  | 1  |      |       |      |        |
| Input Resistance         | R <sub>REF</sub> | Measured between REF and OUT        |  | 7    | 11    | 15   | kΩ     |
| Input Resistance Tempco  |                  |                                     |  |      | 6.5   |      | ppm/°C |
| Reference -3dB Bandwidth | BW               | $V_{OUT} = 0.31V_{P-P}, R_L = 5$    | $50\Omega$ , code = full-scale           |      | 725   |      | kHz    |
| ANALOG OUTPUT            |                  |                                     |  |      |       |      |        |
| OUT Leakage Current      |                  | DAC register loaded                 | $T_A = +25^{\circ}C$                     |      | ±0.15 | ±5   | nA     |
| OUT Leakage Outrett      |                  | with all 0s                         | $T_A = T_{MIN}$ to $T_{MAX}$             |      |       | ±25  | 117 (  |
| OLIT Canacitanas         | 0                | Code = zero scale (Note             | e 2)                                     |      | 14    | 20   |        |
| OUT Capacitance          | Cout             | Code = full scale (Note             | 2)                                       |      | 20    | 30   | - pF   |
| DIGITAL INPUTS           | "                |                                     | 1  |      |       |      |        |
| Input High Voltage       | VIH              |                                     |  | 2.4  |       |      | V      |
| Input Low Voltage        | VIL              |                                     |  |      |       | 0.8  | V      |
| Input Hysteresis         | HYST             | LOAD, CLR, DIN, and S               | CLK, V <sub>DD</sub> = 5V                |      | 156   |      | mV     |
|                          |                  | CLR                                 | VCLR = VDD                               |      |       | ±1   |        |
| Input Leakage Current    | I <sub>IN</sub>  | CLR                                 | V <sub>CLR</sub> = 0V                    |      | 18    | 100  | μΑ     |
|                          |                  | SCLK, LOAD, DIN                     | Inputs at 0V or V <sub>DD</sub>          |      |       | ±1   |        |
| Input Capacitance        | CIN              | Inputs at 0V or V <sub>DD</sub> (No | te 2)                                    |      |       | 8    | рF     |
| SWITCHING CHARACTERIST   | ics              |                                     | <u> </u>                                 |      |       |      |        |
| SCLK Pulse Width High    | tCH              |                                     |  | 25   |       |      | ns     |
| SCLK Pulse Width Low     | t <sub>CL</sub>  |                                     |  | 25   |       |      | ns     |
| DIN Data to SCLK Setup   | t <sub>DS</sub>  |                                     |  | 15   |       |      | ns     |
| DIN Data to SCLK Hold    | tDH              |                                     |  | 15   |       |      | ns     |
| LOAD Pulse Width         | t <sub>LD</sub>  |                                     |  | 20   |       |      | ns     |
| LSB SCLK to LOAD         | tsL              |                                     |  | 0    |       |      | ns     |
| LOAD High to SCLK        | tLC              |                                     |  | 15   |       |      | ns     |
| CLR Pulse Width          | tCLR             |                                     |  | 20   |       |      | ns     |
| POWER SUPPLY             | '                |                                     | 1  |      |       |      | 1      |
| Supply Voltage           | V <sub>DD</sub>  |                                     |  | 4.50 |       | 5.25 | V      |
| Cuanty Current           | las              | All digital inputs at VIL o         | r V <sub>IH,</sub> CLR = V <sub>DD</sub> |      | 0.5   | 1.5  | mA     |
| Supply Current           | IDD              | All digital inputs at 0V or         | $r V_{DD,} \overline{CLR} = V_{DD}$      |      | 0.4   | 5    | μΑ     |

#### **ELECTRICAL CHARACTERISTICS—MAX552**

 $(V_{DD} = +2.7V \text{ to } +3.6V, V_{REF} = 2.5V, OUT = AGND = GND, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}C.)$  (Note 1)

| PARAMETER                    | SYMBOL           | CONDIT  | TONS   | MIN | TYP   | MAX               | UNITS  |
|------------------------------|------------------|---|--|-----|-------|-------------------|--------|
| STATIC PERFORMANCE           |                  |   |  |     |       |                   |        |
| Resolution                   | N                |   |  | 12  |       |                   | Bits   |
| Integral Nanlinggrity        | INL              |   | MAX552A  |     |       | ±1/2              | - LSB  |
| Integral Nonlinearity        | IINL             |   | MAX552B  |     |       | ±1                | LOD    |
| Differential Nonlinearity    | DNL              | Guaranteed monotonic  | over MAX552A   |     |       | ±1/2              | LSB    |
| Differential Northhearity    | DINL             | temperature   | MAX552B  |     |       | ±1                | LOD    |
| Gain Error                   |                  | Using internal feedback   | MAX552A  |     |       | ±1                | - LSB  |
| Gaill Elloi                  |                  | resistor (R <sub>FB</sub> )   | MAX552B  |     |       | ±2                | LOD    |
| Gain Tempco<br>(ΔGain/ΔTemp) |                  | Using internal feedback (Note 2)  | resistor (R <sub>FB</sub> )  |     | ±0.3  | ±1                | ppm/°C |
| Power-Supply Rejection       | PSR              | $\Delta V_{DD} = +20\%, -10\%$  |  |     |       | 1                 | ppm/%  |
| DYNAMIC PERFORMANCE (No      | ote 3)           |   |  |     |       |                   |        |
| Current Settling Time        | ts               |   | $T_A = +25$ °C, to 1/2LSB, OUT load is 100 $\Omega$ II13pF, DAC register alternately loaded with 1s and 0s |     | 0.12  | 1                 | μs     |
| Digital-to-Analog Glitch     |                  | V <sub>REF</sub> = 0V, OUT load is register alternately loade                 |  |     | 0.6   | 20                | nV-s   |
| AC Feedthrough at OUT        |                  | $V_{REF} = 3V_{P-P}$ at 10kHz, with all 0s                                    |  | 0.2 | 0.6   | mV <sub>P-P</sub> |        |
| Total Harmonic Distortion    | THD              | V <sub>REF</sub> = 6V <sub>RMS</sub> at 1kHz, DAC register loaded with all 1s |  |     | -85   |                   | dB     |
| Output Noise-Voltage Density |                  | 10Hz to 100kHz, measur<br>OUT   | red between RFB and  |     | 13    | 15                | nV/√Hz |
| REFERENCE INPUT              |                  |   |  |     |       |                   |        |
| Input Resistance             | R <sub>REF</sub> | Measured between REF  | and OUT  | 7   | 11    | 15                | kΩ     |
| Input Resistance Tempco      |                  |   |  |     | 7.5   |                   | ppm/°C |
| Reference -3dB Bandwidth     | BW               | $V_{OUT} = 0.31V_{P-P}$ , $R_L = 50\Omega$ , code = full-scale                |  |     | 725   |                   | kHz    |
| ANALOG OUTPUT                |                  |   |  |     |       |                   |        |
| OUT Leakage Current          |                  | DAC register loaded   | T <sub>A</sub> = +25°C   |     | ±0.13 | ±5                | nA     |
| 23. Isanago carron           |                  | with all 0s   | $T_A = T_{MIN}$ to $T_{MAX}$   |     |       | ±25               |        |
| OLIT Canagitanas             | Court            | Code = zero code (Note  | 2)   |     | 14    | 20                | pF     |
| OUT Capacitance              | Cout             | Code = full scale (Note 2)  |  |     | 20    | 30                | - μΓ   |

### **ELECTRICAL CHARACTERISTICS—MAX552 (continued)**

 $(V_{DD} = +2.7V \text{ to } +3.6V, V_{REF} = 2.5V, VOUT = AGND = GND, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$  Typical values are at  $T_A = +25^{\circ}C$ .) (Note 1)

| PARAMETER              | SYMBOL          | CONDITIONS                          |  | MIN | TYP  | MAX | UNITS |
|------------------------|-----------------|-------------------------------------|--|-----|------|-----|-------|
| DIGITAL INPUTS         |                 |                                     |  |     |      |     |       |
| Input High Voltage     | VIH             |                                     |  | 2.1 |      |     | V     |
| Input Low Voltage      | V <sub>IL</sub> |                                     |  |     |      | 0.6 | V     |
| Input Hysteresis       | HYST            | LOAD, CLR, DIN, and S               | SCLK, V <sub>DD</sub> = 3V                                     |     | 135  |     | mV    |
|                        |                 | CLR                                 | $V_{\overline{CLR}} = V_{DD}$                                  |     |      | ±1  |       |
| Input Leakage Current  | I <sub>IN</sub> | CLR                                 | V <sub>CLR</sub> = 0V  |     | 12   | 75  | μΑ    |
|                        |                 | SCLK, TOAD, DIN                     | Inputs at 0V or V <sub>DD</sub>                                |     |      | ±1  | 1     |
| Input Capacitance      | CIN             | Inputs at 0V or V <sub>DD</sub> (No | ote 2)   |     |      | 8   | pF    |
| SWITCHING CHARACTERIS  | STICS           |                                     | 1  |     |      |     |       |
| SCLK Pulse Width High  | tсн             |                                     |  | 40  |      |     | ns    |
| SCLK Pulse Width Low   | t <sub>CL</sub> |                                     |  | 40  |      |     | ns    |
| DIN Data to SCLK Setup | t <sub>DS</sub> |                                     |  | 15  |      |     | ns    |
| DIN Data to SCLK Hold  | t <sub>DH</sub> |                                     |  | 15  |      |     | ns    |
| LOAD Pulse Width       | t <sub>LD</sub> |                                     |  | 30  |      |     | ns    |
| LSB SCLK to LOAD       | t <sub>SL</sub> |                                     |  | 0   |      |     | ns    |
| LOAD High to SCLK      | tLC             |                                     |  | 15  |      |     | ns    |
| CLR Pulse Width        | tCLR            |                                     |  | 30  |      |     | ns    |
| POWER SUPPLY           |                 |                                     |  |     |      |     |       |
| Supply Voltage         | V <sub>DD</sub> |                                     |  | 2.7 |      | 3.6 | V     |
| Cupply Current         | laa             | All digital inputs at VIL of        | or V <sub>IH</sub> , $\overline{\text{CLR}}$ = V <sub>DD</sub> |     | 0.1  | 0.5 | mA    |
| Supply Current         | IDD             | All digital inputs at 0V of         | or $V_{DD}$ , $\overline{CLR} = V_{DD}$                        |     | 0.07 | 5   | μΑ    |

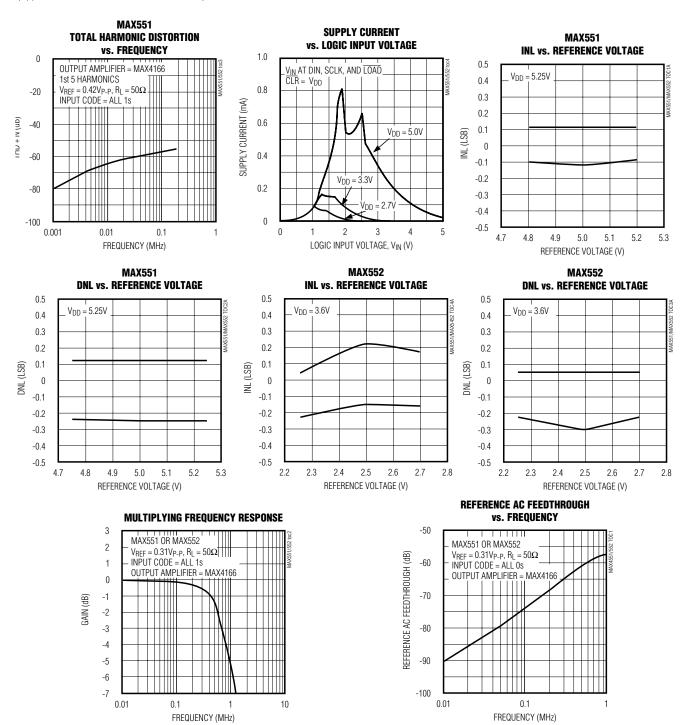
**Note 1:** AGND and  $\overline{CLR}$  are for  $\mu$ MAX only.

Note 2: Guaranteed by design. Not subject to production testing.

Note 3: Parametric limits are provided for design guidance, and are not production tested.

### **Typical Operating Characteristics**

 $(T_A = +25$ °C, unless otherwise noted.)



### **Pin Description**

| F   | PIN  | NAME     | FUNCTION   |
|-----|------|----------|--|
| DIP | μМΑХ | NAME     | FUNCTION   |
| 1   | 1    | OUT      | DAC Current Output   |
| _   | 2    | AGND     | Analog Ground  |
| 2   | 3    | GND      | Digital Ground. Also Analog Ground for DIP package.  |
| 3   | 4    | $V_{DD}$ | Supply Voltage   |
| 4   | 5    | LOAD     | Active-Low Load DAC Input. Driving this asynchronous input low transfers the contents of the input register to the DAC register. |
| 5   | 6    | DIN      | Serial-Data Input  |
| 6   | 7    | SCLK     | Serial-Clock Input. The serial input data is clocked in on SCLK's rising edge.   |
| _   | 8    | CLR      | Clear DAC Input. Clears the DAC register. Tie to V <sub>DD</sub> or float if not used.   |
| 7   | 9    | REF      | Reference Input  |
| 8   | 10   | RFB      | Feedback Resistor  |

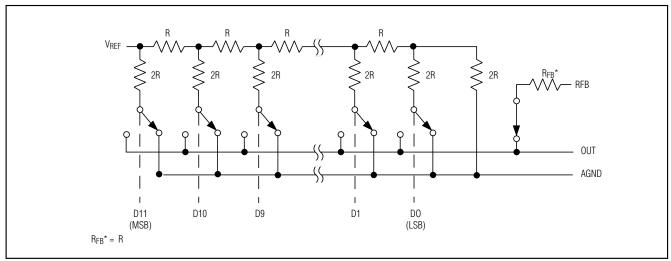


Figure 1. MAX551/MAX552 Simplified Circuit

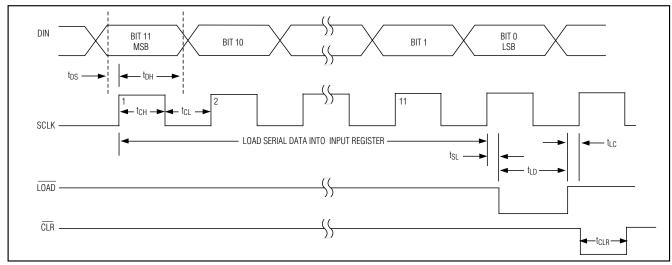


Figure 2. Write-Cycle Timing Diagram

### **Detailed Description**

The MAX551/MAX552 digital-to-analog converter (DAC) circuits consist of a laser-trimmed, thin-film R-2R resistor array with NMOS current switches (Figure 1). Binary-weighted currents are switched to either OUT or AGND, depending on the status of each input data bit. Although the currents at OUT and AGND depend on the digital input code, the sum of the two output currents is always equal to the input current at REF.

The output current (IOUT) can be converted into a voltage by adding an external output amplifier (Figure 3). The REF input accepts a wide range of signals, including fixed and time-varying voltage or current inputs. If a current source is used at the reference input, use a low-tempco, external feedback resistor in place of the

Table 1. Unipolar Binary-Code Table for Circuit of Figure 3

| DI<br>MSB | GITAL INF | PUT<br>LSB | ANALOG OUTPUT  |
|-----------|-----------|------------|--|
| 1111      | 1111      | 1111       | $-V_{REF}\left(\frac{4095}{4096}\right)$                         |
| 1000      | 0000      | 0000       | $-V_{REF} \left( \frac{2048}{4096} \right) = -\frac{V_{REF}}{2}$ |
| 0000      | 0000      | 0001       | $-V_{REF}\left(\frac{1}{4096}\right)$                            |
| 0000      | 0000      | 0000       | 0  |

internal feedback resistor (RFB) to minimize gain variation with temperature.

The internal feedback resistor (RFB) is compensated with an NMOS switch that matches the NMOS switches used in the R-2R array, resulting in excellent supply rejection and gain-temperature coefficient.

The OUT pin output capacitance ( $C_{OUT}$ ) is code dependent.  $C_{OUT}$  is typically 14pF at 000hex and 20pF at FFFhex.

#### Serial Interface

The MAX551/MAX552 serial interface is compatible with the SPI/QSPI and MICROWIRE serial-interface standards. These devices accept serial clocks up to 12.5MHz (50% duty cycle). If the SCLK input is not

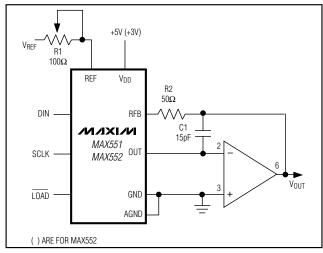


Figure 3. Unipolar Operation

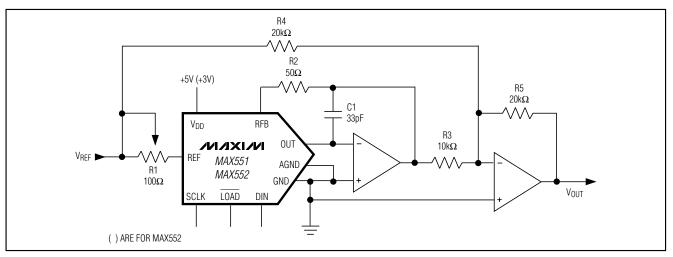


Figure 4. Bipolar Operation

## Table 2. Offset Binary-Code Table for Circuit of Figure 4

| DI<br>MSB | GITAL INF | PUT<br>LSB | ANALOG OUTPUT                             |
|-----------|-----------|------------|---|
| 1111      | 1111      | 1111       | $+V_{REF} \left(\frac{2047}{2048}\right)$ |
| 1000      | 0000      | 0001       | $+V_{REF}\left(\frac{1}{2048}\right)$     |
| 1000      | 0000      | 0000       | 0   |
| 0111      | 1111      | 1111       | $-V_{REF}\left(\frac{1}{2048}\right)$     |
| 0000      | 0000      | 0000       | $-V_{REF}\left(\frac{2048}{2048}\right)$  |

symmetrical, then the clock signal used must meet the  $t_{CH}$  and  $t_{CL}$  requirements given in the *Electrical Characteristics*.

Figure 2 shows the MAX551/MAX552 timing diagram. The most significant bit (MSB) is always loaded first on SCLK's rising edge. When all data is shifted into the input register, the DAC register is loaded by driving the  $\overline{\text{LOAD}}$  signal low. The DAC register is transparent when  $\overline{\text{LOAD}}$  is low and latched when  $\overline{\text{LOAD}}$  is high. The MAX551/MAX552 digital inputs are compatible with CMOS logic levels. The MAX551's inputs are also compatible with TTL logic.

#### **Unipolar Operation**

Figure 3 shows the MAX551/MAX552's basic application. This circuit is used for unipolar operation or 2-quadrant multiplication. The code table for this mode is given in Table 1. Note that the output's polarity is the opposite of the reference voltage polarity.

In many applications the gain accuracy is sufficient and gain adjustment is not necessary. In these cases, resistors R1 and R2 in Figure 3 can be omitted. If the gain is trimmed and the DAC is operated over a wide temperature range, use low-tempco (<300ppm/°C) resistors for R1 and R2. Capacitor C1 provides phase compensation and reduces overshoot and ringing when fast amplifiers are used at the DAC's output.

#### **Bipolar Operation**

Figure 4 shows the MAX551/MAX552 operating in bipolar (or 4-quadrant multiplying) mode. Matched resistors R3, R4, and R5 must be of the same material (preferably metal film or wire-wound) for good temperature-tracking characteristics (<15ppm/°C) and should match to 0.01% for 12-bit performance. The output code is offset binary, as listed in Table 2.

To adjust the circuit, load the DAC with a code of 1000 0000 0000 and trim R1 for a 0V output. With R1 and R2 omitted, an alternative zero trim is needed to adjust the ratio of R3 and R4 for 0V out. Trim full scale by loading the DAC with all 0s or 1s and adjusting the VREF amplitude or varying R5 until the desired positive or negative output is obtained. In applications where gain trim is not required, omit resistors R1 and R2. If gain trim is desired and the DAC is operated over a wide temperature range, then low-tempco ( $<300\text{ppm}/^{\circ}\text{C}$ ) resistors should be used.

### **Applications Information**

#### **Output Amplifier**

For best linearity, terminate OUT and GND at exactly OV. In most applications, OUT is connected to an inverting op amp's summing junction. The amplifier's input offset voltage can degrade the DAC's linearity by causing OUT to be terminated to a nonzero voltage. The resulting error is:

Error Voltage =  $Vos (1 + R_{FB} / R_O)$ 

where  $V_{OS}$  = is the op amp's offset and  $R_O$  is the DAC's output resistance, which is code dependent. The maximum error voltage ( $R_O = R_{FB}$ ) is 2V<sub>OS</sub>; the minimum error voltage ( $R_O = \infty$ ) is V<sub>OS</sub>. To minimize this error, use a low-offset amplifier such as the MAX4166 (unipolar output) or the MAX427 (bipolar output). Otherwise, the amplifier offset must be trimmed to zero. A good guide rule is that V<sub>OS</sub> should be no more than 1/10LSB.

The output amplifier's input bias current (I<sub>B</sub>) can also limit performance, since I<sub>B</sub> x R<sub>FB</sub> generates an offset error. Choose an op amp with an I<sub>B</sub> much less than (e.g., one-tenth) the DAC's 1LSB output current (typically 111nA when V<sub>REF</sub> = 5V, and 55.5nA when V<sub>REF</sub> = 2.5V). Offset and linearity can also be impaired if the output amplifier's noninverting input is grounded through a bias-current compensation resistor. This resistor adds to the offset at this pin and thus should not be used. For best performance, connect the noninverting input directly to ground.

In static or DC applications, the output amplifier's characteristics are not critical. In higher speed applications in which either the reference input is an AC signal or the DAC output must quickly settle to a new programmed value, the output op amp's AC parameters must be considered.

A compensation capacitor, C1, may be required when the DAC is used with a high-speed output amplifier. The purpose of the capacitor is to cancel the pole formed by the DAC output capacitance, COUT, and the internal feedback resistor, RFB. Its value depends on the type of op amp used but typically ranges from 14pF to 30pF. Too small a value causes output ringing, while excess capacitance overdamps the output. C1's size can be minimized and the output voltage settling time improved by keeping the circuit-board trace short and stray capacitance at OUT as low as possible.

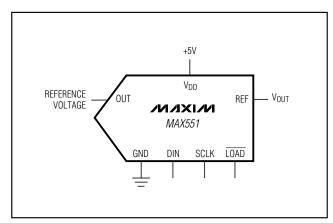


Figure 5. Single-Supply, Voltage Mode Operation

## **Single-Supply Operation**Reference Voltage

The MAX551/MAX552 are true 4-quadrant DACs, making them ideal for multiplying applications. The reference input accepts both AC and DC signals within a voltage range of ±6V. The R-2R ladder is implemented with thin-film resistors, enabling the use of unipolar or bipolar reference voltages with only a single power supply for the DAC. The voltage at the VREF input sets the DAC's full-scale output voltage.

If the reference is too noisy, it should be bypassed to GND (AGND on the 10-pin  $\mu$ MAX package) with a 0.1 $\mu$ F ceramic capacitor located as close to the REF pin as possible.

#### Voltage Mode (MAX551)

The MAX551 can be conveniently used in voltage mode, single-supply operation with OUT biased at any voltage between GND and VDD. OUT must not be allowed to go 0.3V lower than GND or 0.3V higher than VDD. Otherwise, internal diodes turn on, causing a high current flow that could damage the device.

Figure 5 shows the MAX551 connected as a voltage output DAC. In this mode of operation, the OUT pin is connected to the reference-voltage source, and the GND pin is connected to the PCB ground plane. The DAC output now appears at the REF pin, which has a constant resistance equal to the reference input resistance (11k $\Omega$  typ). This output should be buffered with an op amp when a lower output impedance is required. The RFB pin is not used in this mode. The reference input (OUT) impedance is code dependent, and the circuit's response time depends on the reference source's behavior with changing load conditions.

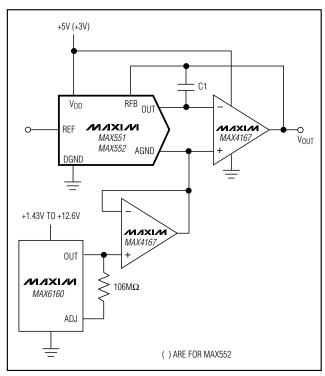


Figure 6. Single-Supply, Current Mode Operation

An advantage of voltage mode operation is that a negative reference is not required for a positive output. Note that the reference input (OUT) must always be positive and is limited to no more than 2V when VDD is 5V. The unipolar and bipolar circuits in Figures 3 and 4 can be converted to voltage mode.

#### **Current Mode**

Figure 6 shows the MAX551/MAX552 in a current output configuration in which the output amplifier is powered from a single supply, and AGND is biased to 1.23V. With 0V applied to the REF input, the output can be programmed from 1.23V (zero code) to 2.46V (full scale). With 2.45V applied to REF, the output can be programmed from 1.23V (zero code) to 0.01V (full scale).

The MAX4166 op amp that drives AGND maintains the 1.23V bias as AGND's impedance changes with the DAC's digital code, from high impedance (zero code) to  $7k\Omega$  minimum (full scale).

#### Using an AC Reference

In applications where reference voltage has AC signal components, the MAX551/MAX552 have multiplying capability within the reference input range of ±6V. If the DAC and the output amplifier are operated with a single

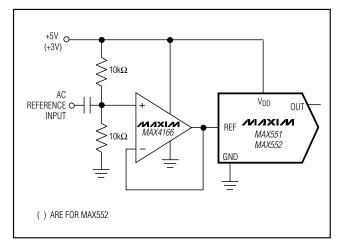


Figure 7. Single-Supply AC Reference Input Circuit

supply voltage, then an AC reference input can be offset with the circuit shown in Figure 7 to prevent the DAC output voltage from exceeding the output amplifier's negative output rail. The reference input's typical -3dB bandwidth is greater than 700kHz, as shown in the *Typical Operating Characteristics* graphs.

#### **Offsetting AGND**

The MAX551/MAX552 provide separate  $A\bar{G}ND$  and GND inputs in the  $\mu MAX$  package. With this package, AGND can be biased above GND to provide an arbitrary nonzero output voltage for a "0" input code (Figure 8).

#### Layout, Grounding, and Bypassing

Bypass V<sub>DD</sub> with a  $0.1\mu F$  capacitor, located as close to V<sub>DD</sub> and GND as possible. The ground pins (AGND and GND) should be connected in a star configuration to the highest quality ground available, which should be located as close to the MAX551/MAX552 as possible.

Since OUT and the output amplifier's noninverting input are sensitive to offset voltage, nodes that are to be grounded should be connected directly to a single-point ground through a separate, low-resistance (less than  $0.2\Omega$ ) connection. The current at OUT and AGND varies with input code, creating a code-dependent error if these terminals are connected to ground (or virtual ground) through a resistive path.

Parasitic coupling of the signal from REF to OUT is an error source in dynamic applications. This coupling is normally a function of board layout and pin-to-pin package capacitance. Minimize digital feedthrough with guard traces between digital inputs, REF, and OUT pins.

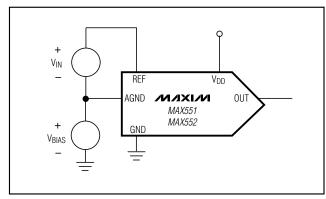


Figure 8. AGND Bias Current

The MAX551/MAX552 have high-impedance digital inputs. To minimize noise pickup, tie them to either  $V_{DD}$  or GND when they are not in use. As a good practice, connect active inputs to  $V_{DD}$  or GND through high-value resistors (1M $\Omega$ ) to prevent static charge accumulation if the pins are left floating, such as when a circuit card is left unconnected.

The  $\overline{\text{CLR}}$  input on the  $\mu\text{MAX}$  device has an internal pullup resistor with a typical value of  $125\text{k}\Omega$ . If the  $\overline{\text{CLR}}$  input is not used, tie it to  $\overline{\text{Vpp}}$  to minimize supply current.

### \_Ordering Information (continued)

| PART       | TEMP RANGE     | PIN-<br>PACKAGE | LINEARITY<br>(LSB) |
|------------|----------------|-----------------|--------------------|
| MAX552ACPA | 0°C to +70°C   | 8 Plastic DIP   | ±1/2               |
| MAX552BCPA | 0°C to +70°C   | 8 Plastic DIP   | ±1                 |
| MAX552ACUB | 0°C to +70°C   | 10 μMAX         | ±1/2               |
| MAX552BCUB | 0°C to +70°C   | 10 μMAX         | ±1                 |
| MAX552AEPA | -40°C to +85°C | 8 Plastic DIP   | ±1/2               |
| MAX552BEPA | -40°C to +85°C | 8 Plastic DIP   | ±1                 |
| MAX552AEUB | -40°C to +85°C | 10 μMAX         | ±1/2               |
| MAX552BEUB | -40°C to +85°C | 10 μMAX         | ±1                 |

### **Chip Information**

TRANSISTOR COUNT: 887
SUBSTRATE CONNECTED TO VDD

### **Package Information**

For the latest package outline information, go to **www.maxim-ic.com/packages**.

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