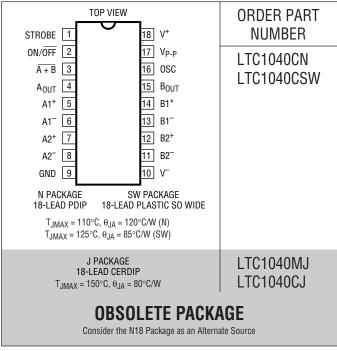
# **ABSOLUTE MAXIMUM RATINGS**

(Note 1)

Total Supply Voltage (V <sup>+</sup> to V <sup>-</sup> )
Input Voltage $(V^+ + 0.3V)$ to $(V^ 0.3V)$
Operating Temperature Range
LTC1040C $-40^{\circ}$ C $\leq$ T <sub>A</sub> $\leq$ 85 $^{\circ}$ C
LTC1040M ( <b>OBSOLETE</b> )55°C to 125°C
Storage Temperature Range55°C to 150°C
Lead Temperature (Soldering, 10 sec)300°C
Output Short-Circuit Duration Continuous

# PACKAGE/ORDER INFORMATION



Consult LTC Marketing for parts specified with wider operating temperature ranges.

# **ELECTRICAL CHARACTERISTICS** The • denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^{\circ}C$ . Test conditions: $V^+ = 5V$ , $V^- = -5V$ , unless otherwise noted.

			LTC1040M/LTC1040C				
SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
V <sub>0S</sub>	Offset Voltage (Note 2)	Split Supplies $\pm 2.8 \text{V}$ to $\pm 6 \text{V}$ Single Supply (V <sup>-</sup> = GND) 2.8V to 6V	•		±0.3	± 0.75	mV
		Split Supplies ±6V to ±8V Single Supply (V <sup>-</sup> = GND) 6V to 15V	•		±1	±4.5	mV
	Tracking Error Between Input Pairs (Notes 2 and 3)	Split Supplies ±2.8V to ±8V Single Supplies (V <sup>-</sup> = GND) 2.8 to 16V	•		0.05	0.1	%
I <sub>BIAS</sub>	Input Bias Current	OSC = GND			±0.3		nA
R <sub>IN</sub>	Average Input Resistance	f <sub>S</sub> = 1kHz (Note 4)	•	20	30		MΩ
CMR	Common Mode Range		•	V-		V+	V
PSR	Power Supply Range	Split Supplies	•	±2.8		±8	V
		Single Supplies (V <sup>-</sup> = GND)	•	2.8		16	V
I <sub>S(ON)</sub>	Power Supply ON Current (Note 5)	V <sup>+</sup> = 5V, V <sub>P-P</sub> On	•		1.2	3	mA
I <sub>S(OFF)</sub>	Power Supply OFF Current (Note 5)	V <sup>+</sup> = 5V, V <sub>P-P</sub> Off LTC1040C LTC1040M	•		0.001 0.001	0.5 5	μA μA
t <sub>D</sub>	Response Time (Note 6)			60	80	100	μS
V <sub>OH</sub> V <sub>OL</sub>	A, B, A + B and ON/OFF Outputs (Note 7) Logic "1" Output Voltage Logic "0" Output Voltage	V <sup>+</sup> = 4.75V, I <sub>OUT</sub> = −360μA V <sup>+</sup> = 4.75V, I <sub>OUT</sub> = 1.6mA	•	2.4	4.4 0.25	0.4	V

LINEAR

# **ELECTRICAL CHARACTERISTICS** The • denotes the specifications which apply over the full operating

temperature range otherwise specifications are at  $T_A = 25^{\circ}C$ . Test conditions:  $V^+ = 5V$ ,  $V^- = -5V$ , unless otherwise specified

			LTC1040M/LTC1040C				
SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
V <sub>IH</sub> V <sub>IL</sub>	STROBE Input (Note 7) Logic "1" Input Voltage Logic "0" Input Voltage	V+ = 5.25V V+ = 4.75V	•	2.0	1.6 1.0	0.8	V
R <sub>EXT</sub>	External Timing Resistor	Resistor Tied Between V <sup>+</sup> and OSC Pin	•	100		10,000	kΩ
f <sub>S</sub>	Sampling Frequency	$R_{EXT} = 1M$ , $C_{EXT} = 0.1 \mu F$			5		Hz

Note 1: Absolute Maximum Ratings are those values beyond which the life of a device may be impaired.

Note 2: Applies over input voltage range limit and includes gain uncertainty.

Note 3: Tracking error =  $(V_{IN1} - V_{IN2})/V_{IN1}$ .

Note 4: R<sub>IN</sub> is guaranteed by design and is not tested.

 $R_{IN} = 1/(f_S \cdot 33pF).$ 

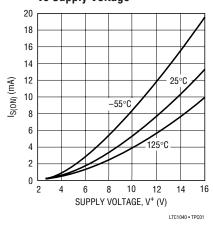
**Note 5:** Average supply current =  $t_D \cdot I_{S(ON)} \cdot f_S + (1 - t_D \times f_S) \cdot I_{S(OFF)}$ .

Note 6: Response time is set by an internal oscillator and is independent of overdrive voltage.

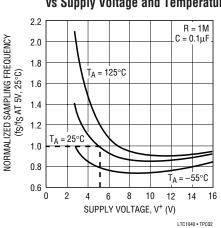
Note 7: Inputs and outputs also capable of meeting EIA/JEDEC B series CMOS specifications.

# TYPICAL PERFORMANCE CHARACTERISTICS

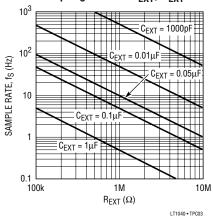
#### **Peak Supply Current** vs Supply Voltage



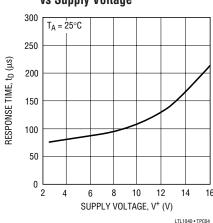
**Normalized Sampling Frequency** vs Supply Voltage and Temperature



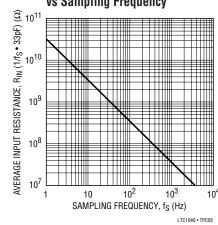
Sampling Rate vs R<sub>EXT</sub>, C<sub>EXT</sub>



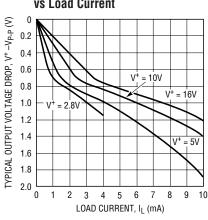
Response Time vs Supply Voltage



Input Resistance vs Sampling Frequency

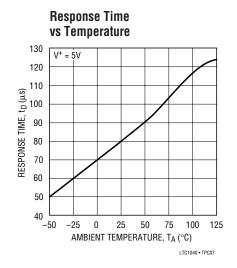


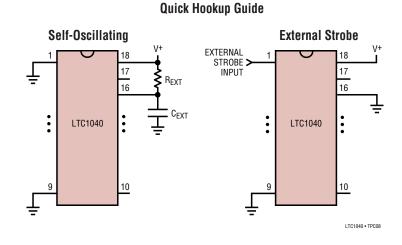
**V<sub>P-P</sub>** Output Voltage vs Load Current



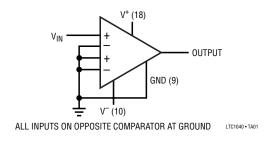


# TYPICAL PERFORMANCE CHARACTERISTICS

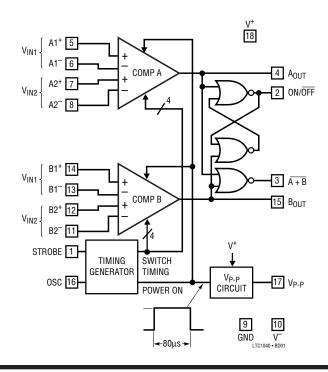




# **TEST CIRCUIT**



# **BLOCK DIAGRAM**



LINEAR

The LTC1040 uses sampled data techniques to achieve its unique characteristics. Some of the experience acquired using classic linear comparators does not apply to this circuit, so a brief description of internal operation is essential to proper application.

The most obvious difference between the LTC1040 and other comparators is the dual differential input structure. Functionally, when the sum of inputs is positive, the comparator output is high and when the sum of the inputs is negative, the output is low. This unique input structure is achieved with CMOS switches and a precision capacitor array. Because of the switching nature of the inputs, the concept of input current and input impedance needs to be examined.

The equivalent input circuit is shown in Figure 1. Here, the input is being driven by a resistive source,  $R_S$ , with a bypass capacitor,  $C_S$ . The bypass capacitor may or may not be needed, depending on the size of the source resistance and the magnitude of the input voltage,  $V_{IN}$ .

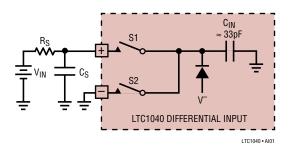


Figure 1. Equivalent Input Circuit

#### For $R_S < 10k$

Assuming  $C_S$  is zero, the input capacitor,  $C_{IN}$ , charges to  $V_{IN}$  with a time constant of  $R_S$   $C_{IN}$ . When  $R_S$  is too large,  $C_{IN}$  does not have a chance to fully charge during the sampling interval ( $\approx 80 \mu s$ ) and errors will result. If  $R_S$  exceeds  $10 k\Omega$ , a bypass capacitor is necessary to minimize errors.

#### For $R_S > 10k\Omega$

For  $R_S$  greater than  $10k\Omega$ ,  $C_{IN}$  cannot fully charge and a bypass capacitor,  $C_S$ , is needed. When switch S1 closes, charge is shared between  $C_S$  and  $C_{IN}$ . The change in voltage on  $C_S$  because of this charge sharing is:

$$\Delta V = V_{IN} \bullet \frac{C_{IN}}{C_{IN} + C_S}$$

This represents an error and can be made arbitrarily small by increasing  $C_S$ .

With the addition of  $C_S$ , a second error term caused by the finite input resistance of the LTC1040 must be considered. Switches S1 and S2 alternately open and close, charging and discharging  $C_{IN}$  between  $V_{IN}$  and ground. The alternate charge and discharge of  $C_{IN}$  causes a current to flow into the positive input and out of the negative input. The magnitude of this current is:

$$I_{IN} = q \bullet f_S = V_{IN} C_{IN} f_S$$

where  $f_S$  is the sampling frequency. Because the input current is directly proportional to input voltage, the LTC1040 can be said to have an average input resistance of:

$$R_{IN} = \frac{V_{IN}}{I_{IN}} = \frac{1}{f_S C_{IN}} = \frac{1}{f_S \cdot 33pF}$$

(see typical curve of Input Resistance vs Sampling Frequency). A voltage divider is set up between  $R_S$  and  $R_{IN}$  causing error.

The input voltage error caused by these two effects is:

$$V_{ERROR} = V_{IN} \left( \frac{C_{IN}}{C_{IN} + C_S} + \frac{R_S}{R_S + R_{IN}} \right)$$

Example: 
$$f_S = 10$$
Hz,  $R_S = 1$ M $\Omega$ ,  $C_S = 1$  $\mu$ F,  $V_{IN} = 1$ V

$$V_{ERROR} = 1V \left( \frac{33 \cdot 10^{-12}}{1 \cdot 10^{-6}} + \frac{10^{6}}{10^{6} + 3 \cdot 10^{9}} \right)$$

$$= 33\mu V + 330\mu V = 363\mu V.$$

Notice that most of the error is caused by  $R_{IN}$ . If the sampling frequency is reduced to 1Hz, the voltage error is reduced to  $66\mu$ V.



#### **Minimizing Comparison Errors**

The two differential input voltages, V1 and V2, are converted to charge by the input capacitors  $C_{IN1}$  and  $C_{IN2}$  (see Figure 2). The charge is summed at the virtual ground point; if the net charge is positive, the comparator output is high and if negative, it is low. There is an optimum way to connect these inputs, in a specific application, to minimize error.

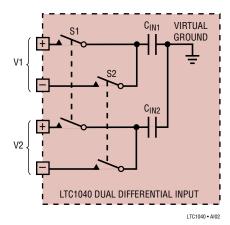


Figure 2. Dual Differential Equivalent Input Circuit

Ignoring internal offset, the LTC1040 will be at its switching point when:

$$V1 \cdot C_{IN1} + V2 \cdot C_{IN2} = 0.$$

Optimum error will be achieved when the differential voltages, V1 and V2, are individually minimized. Figure 3 shows two ways to connect the LTC1040 to compare an input voltage,  $V_{IN}$ , to a reference voltage,  $V_{REF}$ . Using the above equation, each method will be at null when:

(a) 
$$(V_{REF} - 0V) C_{IN1} - (0V - V_{IN}) C_{IN2} = 0$$
  
or  $V_{IN} = V_{REF} (C_{IN1}/C_{IN2})$ 

(b) 
$$(V_{REF} - V_{IN}) C_{IN1} - (0V - 0V) C_{IN2} = 0$$
  
or  $V_{IN} = V_{REF}$ .

Notice that in method (a) the null point depends on the ratio of  $C_{\text{IN1}}/C_{\text{IN2}}$ , but method (b) is independent of this ratio. Also, because method (b) has zero differential input voltage, the errors due to finite input resistance are negligible. The LTC1040 has a high accuracy capacitor array and even the non-optimum connection will only result in  $\pm\,0.1\%$  more error, worst-case compared to the optimum connection.

#### **Tracking Error**

Tracking error is caused by the ratio error between  $C_{IN1}$  and  $C_{IN2}$  and is expressed as a percentage. For example, consider Figure 3a with  $V_{REF} = 1V$ . Then at null,

$$V_{IN} = V_{REF} \frac{C_{IN1}}{C_{IN2}} = 1V \pm 1mV$$

because  $C_{IN1}$  is guaranteed to equal  $C_{IN2}$  to within 0.1%.

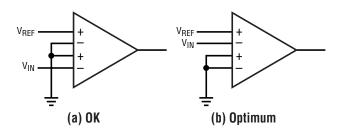


Figure 3. Two Ways to Do It

LTC1040 • TA0

#### **Common Mode Range**

The input switches of the LTC1040 are capable of switching to either the V+ or V^-supply. This means that the input common mode range includes both supply rails. Many applications, not feasible with conventional comparators, are possible with the LTC1040. In the load current detector shown in Figure 4, a  $0.1\Omega$  resistor is used to sense the current in the V+ supply. This application requires the dual differential input and common mode capabilities of the LTC1040.

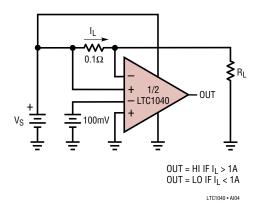


Figure 4. Load Current Detector



#### Offset Voltage Error

The errors due to offset, common mode, power supply variation, gain and temperature are all included in the offset voltage specification. This makes it easy to compute the error when using the LTC1040.

Example: error computation for Figure 4.

Assume:  $2.8V \le V_S \le 6V$ .

Then total worst-case error is:

$$I_{L \text{ (ERROR)}} = \pm (100\text{mV} \bullet 0.001 + 0.5\text{mV}) \bullet \frac{1\text{A}}{100\text{mV}} = \pm 6\text{mA}$$

$$\uparrow \qquad \uparrow \qquad \uparrow$$
Tracking Error  $V_{OS}$ 

$$I_{L \text{ (ERROR)}}\% = \frac{6\text{mA}}{1\text{A}} \bullet 100 = \pm 0.6\%.$$

Note: If source resistance exceeds 10k, bypass capacitors should be used and the associated errors must be included.

#### Pulsed Power (V<sub>P-P</sub>) Output

It is often desirable to use comparators with resistive networks such as bridges. Because of the extremely low power consumption of the LTC1040, the power consumed by these resistive networks can far exceed that of the device itself.

At low sample rates the LTC1040 spends most of its time off. To take advantage of this, a pulsed power ( $V_{P-P}$ ) output is provided.  $V_{P-P}$  is switched to  $V^+$  when the comparator is on and to a high impedance (open circuit) when the comparator is off. The ON time is nominally  $80\mu s$ . Figure 5 shows the  $V_{P-P}$  output circuit.

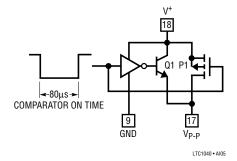


Figure 5. V<sub>P-P</sub> Output Switch

The  $V_{P-P}$  output voltage is not precise (see  $V_{P-P}$  Output Voltage versus Load Current curve). There are two ways  $V_{P-P}$  can be used to power external networks without excessive errors: (1) ratiometric networks and (2) fast settling references.

In a ratiometric network, the inputs are all proportional to  $V_{P-P}$  (see Figure 6). Consequently, for small changes, the absolute value of  $V_{P-P}$  does not affect accuracy.

It is critical that the inputs to the LTC1040 completely settle within  $4\mu s$  of the start of the comparison cycle and that they do not change during the  $80\mu s$  ON time. When driving resistive networks with  $V_{P-P}$ , capacitive loading on

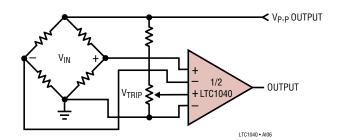


Figure 6. Ratiometric Network Driven by VP-P

the network should be minimized to meet the  $4\mu s$  settling time requirement. It is not recommended that  $V_{P-P}$  be used to drive networks with source impedances, as seen by the inputs, of greater than  $10k\Omega$ .

In applications where an absolute reference is required, the  $V_{P\text{-}P}$  output can be used to drive a fast settling reference. The LT1009 2.5V reference, ideal in this application, settles in approximately  $2\mu s$  (see Figure 7). The current through R1 must be large enough to supply the LT1009 minimum bias current ( $\approx 1 \text{mA}$ ) and the load current,  $I_{I}$ .

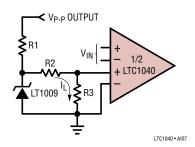


Figure 7. Driving Reference with V<sub>P-P</sub> Output



#### **Output Logic**

In addition to the normal outputs  $(A_{OUT})$  and  $B_{OUT}$ , two additional outputs,  $\overline{A} + \overline{B}$  and ON/OFF, are provided (see Figure 8 and Table 1). All logic is powered from V<sup>+</sup> and ground, thus input and output logic levels are independent of the V<sup>-</sup> supply. The LTC1040 is directly compatible with CMOS logic and is TTL compatible for  $4.75V \le V^+ \le 5.25V$ . No external pull-up resistors are required.

Table 1. Output Logic Truth Table

ΣA INPUTS	$\Sigma$ B INPUTS	A <sub>OUT</sub>	B <sub>OUT</sub>	A + B	ON/OFF
+	+	Н	Н	L	L
+	_	Н	L	L	L
_	+	L	Н	L	Н
-	-	L	L	Н	l*

<sup>\*</sup>I = indeterminate. When both A and B outputs are low, the  $ON/\overline{OFF}$  output remains in the state it was in prior to entering  $A_{OUT} = B_{OUT} = L$ .

#### **Using External Strobe**

A positive pulse on the strobe input, with the OSC input tied to ground, will initiate a comparison cycle. The STROBE input is edge-sensitive and pulse widths of 50ns will typically trigger the device.

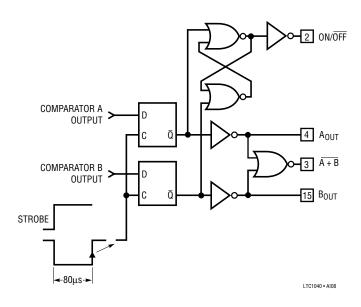


Figure 8. LTC1040 Logic Diagram

Because of the sampling nature of the LTC1040, some sensitivity exists between the offset voltage and the falling edge of the input strobe. When the falling edge of the strobe signal falls within the comparator's active time ( $80\mu s$  after rising edge), offset changes of as much as 2mV can occur. To eliminate this problem, make sure the strobe pulse width is greater than the response time,  $t_D$ .

#### **Using Internal Strobe**

An internal oscillator allows the LTC1040 to strobe itself. The frequency of oscillation, and hence sampling rate, is set by an external RC network (see typical curve of Sampling Rate vs  $R_{\text{EXT}}$ ,  $C_{\text{EXT}}$ ).

For self-oscillation, the STROBE pin must be tied to ground. The external RC network is connected as shown in Figure 9.

To assure oscillation,  $R_{\text{EXT}}$  must be between 100k and 10M. There is no limit to the size of  $C_{\text{EXT}}$ .

 $R_{EXT}$  is very important in determining the power consumption. The average voltage at the oscillator pin is approximately V+/2. The power consumed by  $R_{EXT}$  is then:  $P_{REXT} = (V+/2)^2/R_{EXT}$ .

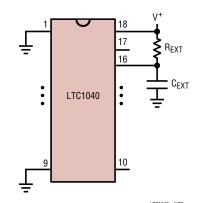


Figure 9. External RC Connection

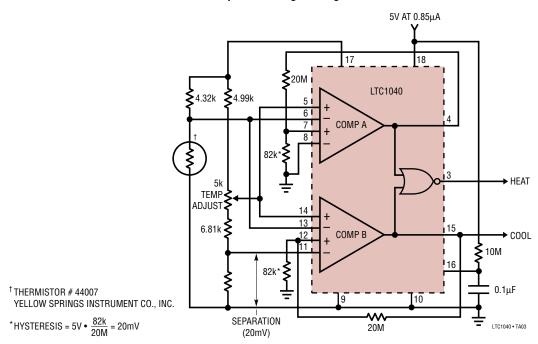
Example:  $R_{EXT} = 1M$ ,  $V^+ 5V$ ,  $P_{REXT} = (2.5)^2/10^6 = 6.25 \cdot 10^{-6}W$ .

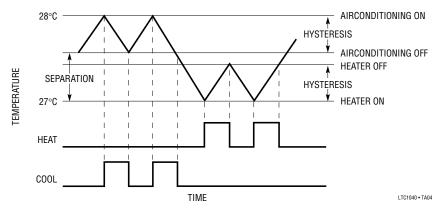
This is about four times the power consumed by the LTC1040 at  $V^+ = 5V$  and  $f_S = 1$  sample/second. Where power is a premium  $R_{EXT}$  should be made as large as possible. Note that the power consumed by  $R_{EXT}$  is *not* a function of  $f_S$  or  $C_{EXT}$ .



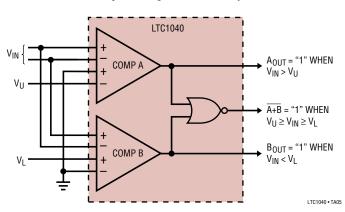
# TYPICAL APPLICATIONS

#### **Complete Heating/Cooling Automatic Thermostat**

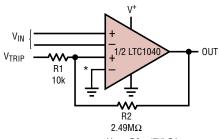




# Window Comparator with Independent Window Limits and Fully Floating Differential Input



#### Hysteresis Comparator with Fully Floating Differential Input



OUT = "0" WHEN  $V_{IN} > V_{U} = \frac{V_{TRIP} R2 + (5V) R1}{R1 + R2} = 0.996 V_{TRIP} + 20 mV$ 

 $\label{eq:out_norm} \text{OUT} = \text{``1''} \text{ WHEN V}_{IN} < \text{V1} = \frac{\text{V}_{TRIP} \text{ R2}}{\text{R1} + \text{R2}} = 0.996 \text{V}_{TRIP}$ 

\* TO CENTER HYSTERESIS ABOUT V<sub>TRIP</sub>, FORCE THIS INPUT TO HYSTERESIS/2 (10mV)  $$_{\rm LTC1}$$ 



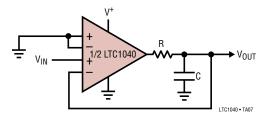
### TYPICAL APPLICATIONS

#### The LTC1040 as a Linear Amplifier

With a simple RC filter, the LTC1040 can be made to function as a linear amplifier. By filtering the logic output and feeding it back to the negative input, the loop forces the output duty cycle  $[t_{ON}/(t_{ON}+t_{OFF})]$  so that  $V_{OUT}$  equals  $V_{IN}$  (Figure 10).

The RC time constant is set to keep the ripple on the output small. The maximum output ripple is:  $\Delta V = V^+/f_SRC$  and

should be set to 0.5 mV to 1 mV for best results. Notice that the higher the sampling frequency,  $f_S$ , the lower RC can be. This is important because the RC filter also sets the loop response. A convenient way to keep  $f_S$  as high as possible under all conditions is to connect a 100 k resistor to pin 16 (OSC) with no capacitance to ground.



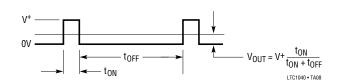
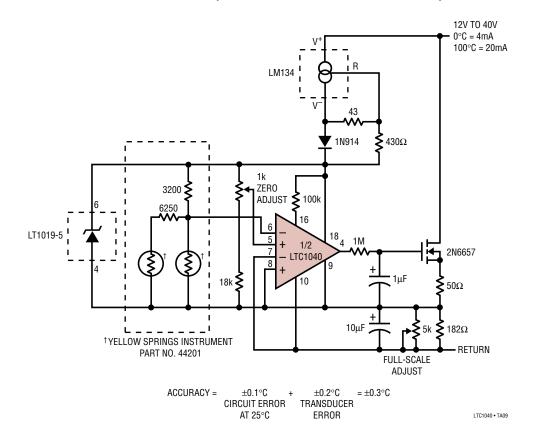


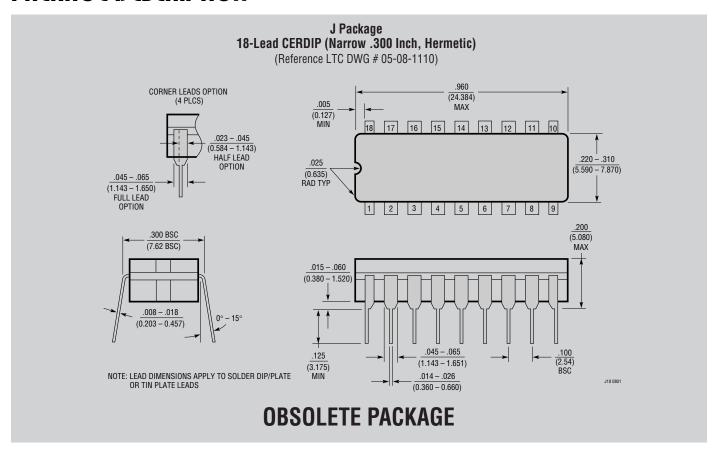
Figure 10. The LTC1040 as a Linear Amplifier

#### 2-Wire 0°C to 100°C Temperature Transducer with 4mA to 20mA Output



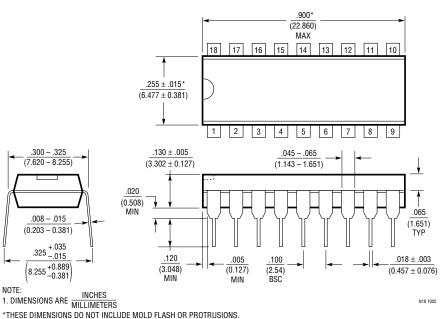
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### PACKAGE DESCRIPTION



#### N Package 18-Lead PDIP (Narrow .300 Inch)

(Reference LTC DWG # 05-08-1510)



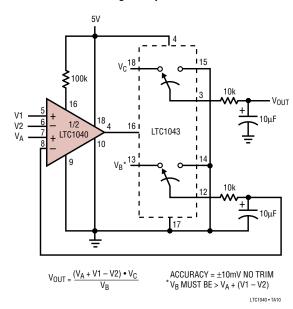
\*THESE DIMENSIONS DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS.

MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED .010 INCH (0.254mm)

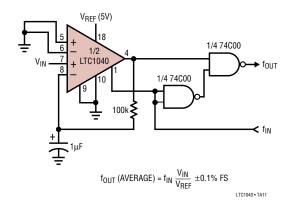


### TYPICAL APPLICATIONS

#### Analog Multiplier/Divider



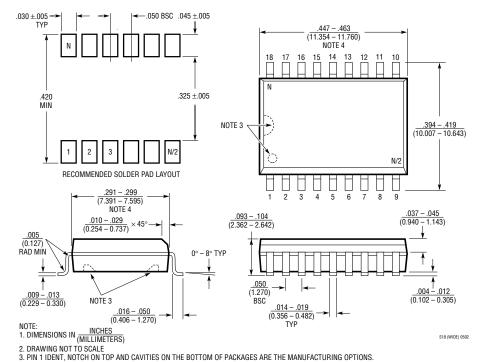
#### Single + 5V Voltage-to-Frequency Converter



# PACKAGE DESCRIPTION

#### **SW Package** 18-Lead Plastic Small Outline (Wide .300 Inch)

(Reference LTC DWG # 05-08-1620)



THE PART MAY BE SUPPLIED WITH OR WITHOUT ANY 0F THE OPTIONS

4. THESE DIMENSIONS DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS.

MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED .006" (0.15mm)

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