Low-Jitter, 800Mbps, 10-Port LVDS Repeaters with 100Ω Drive

ABSOLUTE MAXIMUM RATINGS

V_{CC} to GND .....-0.3V to +4.0V
RIN+, RIN- to GND .....-0.3V to +4.0V
$\overline{PWRDN}$ to GND.....-0.3V to (V_{CC} + 0.3V)
DO_+, DO_- to GND.....-0.3V to +4.0V
Short-Circuit Duration (DO_+, DO_-) .....Continuous
Continuous Power Dissipation (T_A = +70°C)
28-Pin TSSOP (derate 12.8mW/°C above +70°C) 1026mW
Storage Temperature.....-65°C to +150°C
Maximum Junction Temperature .....+150°C
Operating Temperature Range .....-40°C to +85°C
ESD Protection
Human Body Model (RIN+, RIN-, DO_+, DO_-) .....±8kV
Lead Temperature (soldering, 10s) .....+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

DC ELECTRICAL CHARACTERISTICS

(V_{CC} = +3.0V to +3.6V, R_L = 100Ω ±1%, differential input voltage $|V_{ID}|$ = 0.05V to 1.2V, MAX9153 LVDS input common-mode voltage V_{CM} = $|V_{ID}/2|$ to 2.4V - $|V_{ID}/2|$, MAX9154 LVPECL input voltage range = 0 to V_{CC}, $\overline{PWRDN}$ = high, T_A = -40°C to +85°C, unless otherwise noted. Typical values are at V_{CC} = +3.3V, $|V_{ID}|$ = 0.2V, V_{CM} = 1.2V, T_A = +25°C.) (Notes 1 and 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
CONTROL INPUT ($\overline{PWRDN}$)						
Input High Voltage	V_{IH}		2.0		V_{CC}	V
Input Low Voltage	V_{IL}		GND		0.8	V
Input Current	I_{IN}	$\overline{PWRDN}$ = high or low	-20		20	µA
DIFFERENTIAL INPUT (RIN+, RIN-)						
Differential Input High Threshold	V_{TH}			-3	50	mV
Differential Input Low Threshold	V_{TL}		-50	-3		mV
Input Current (MAX9153)	I_{RIN+}, I_{RIN-}	0.05V ≤ $\|V_{ID}\|$ ≤ 0.6V, $\overline{PWRDN}$ = high or low (Figure 1)	-15	-3	15	µA
		0.6V < $\|V_{ID}\|$ ≤ 1.2V, $\overline{PWRDN}$ = high or low (Figure 1)	-20	-4	20	
Power-Off Input Current (MAX9153)	$I_{RIN+ (OFF)}$, $I_{RIN- (OFF)}$	0.05V ≤ $\|V_{ID}\|$ ≤ 0.6V, V_{CC} = 0 or open, $\overline{PWRDN}$ = 0 or open (Figure 1)	-15	3	15	µA
		0.6V < $\|V_{ID}\|$ ≤ 1.2V, V_{CC} = 0 or open, $\overline{PWRDN}$ = 0 or open (Figure 1)	-20	4	20	
Input Resistor 1 (MAX9153)	R_{IN1}	$\overline{PWRDN}$ = high or low (Figure 1)	103			kΩ
		V_{CC} = 0 or open, $\overline{PWRDN}$ = 0 or open (Figure 1)	103			
Input Resistor 2 (MAX9153)	R_{IN2}	$\overline{PWRDN}$ = high or low (Figure 1)	154			kΩ
		V_{CC} = 0 or open, $\overline{PWRDN}$ = 0 or open(Figure 1)	154			
Input Current (MAX9154)	I_{RIN+}, I_{RIN-}	V_{RIN+} = 3.6V, V_{RIN-} = 3.6V or 0, $\overline{PWRDN}$ = high or low (Figure 2)	-10	3	10	µA
		V_{RIN+} = 0, V_{RIN-} = 3.6V or 0, $\overline{PWRDN}$ = high or low (Figure 2)	-10	±3	10	
Power-Off Input Current (MAX9154)	$I_{RIN+ (OFF)}$, $I_{RIN- (OFF)}$	V_{RIN+} = 3.6V, V_{RIN-} = 0, V_{CC} = 0 or open, $\overline{PWRDN}$ = 0 or open (Figure 2)	-10	3	10	µA
		V_{RIN+} = 0, V_{RIN-} = 3.6V, V_{CC} = 0 or open, $\overline{PWRDN}$ = 0 or open (Figure 2)	-10	3	10	

DC ELECTRICAL CHARACTERISTICS (continued)

(V_{CC} = +3.0V to +3.6V, R_L = 100Ω ±1%, differential input voltage $|V_{ID}|$ = 0.05V to 1.2V, MAX9153 LVDS input common-mode voltage V_{CM} = $|V_{ID}/2|$ to 2.4V - $|V_{ID}/2|$, MAX9154 LVPECL input voltage range = 0 to V_{CC}, $\overline{PWRDN}$ = high, T_A = -40°C to +85°C, unless otherwise noted. Typical values are at V_{CC} = +3.3V, $|V_{ID}|$ = 0.2V, V_{CM} = 1.2V, T_A = +25°C.) (Notes 1 and 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input Resistor 3 (MAX9154)	R_{IN3}	$\overline{PWRDN}$ = high or low (Figure 2)	360			kΩ
		V_{CC} = 0 or open, $\overline{PWRDN}$ = 0 or open (Figure 2)	360			
LVDS OUTPUT (DO_+, DO_-)						
Differential Output Voltage	V_{OD}	Figure 3	250	380	450	mV
Charge in V_{OD} Between Complementary Output States	ΔV_{OD}	Figure 3		1	25	mV
Offset (Common-Mode) Voltage	V_{OS}	Figure 3	1.125	1.26	1.375	V
Change in V_{OS} Between Complementary Output States	ΔV_{OS}	Figure 3		3	25	mV
Output High Voltage	V_{OH}	Figure 3			1.6	V
Output Low Voltage	V_{OL}	Figure 3	0.9			V
Differential Output Resistance	RO_{DIFF}	$\overline{PWDRN}$ = high or low	150	238	330	Ω
		V_{CC} = 0 $\overline{PWDRN}$ = 0 or open				
Differential High Output Voltage in Fail-Safe	V_{OD+}	RIN+, RIN- undriven with short, open, or 100Ω termination (MAX9153)	250		450	mV
		RIN+, RIN- open (MAX9154)	250		450	
Single-Ended Output Short-Circuit Current	I_{OZ}	$\overline{PWDRN}$ = low; V_{DO_+} = 3.6V or 0, DO_- + open; or V_{DO_-} = 3.6V or 0, DO_+ = open	-1		1	µA
		V_{CC} = 0, $\overline{PWRDN}$ = 0 or open; V_{DO_+} = 3.6V or 0, DO_- = 3.6V or V_{DO_-} = 3.6V or 0, DO_+ = open	-1		1	
Single-Ended Output Short-Circuit Current	I_{OS}	V_{ID} = +50mV, V_{DO_+} = 0 or V_{CC}, V_{DO_-} = 0 or V_{CC}	-15		15	mA
		V_{ID} = -50mV, V_{DO_+} = 0 or V_{CC}, V_{DO_-} = 0 or V_{CC}				
Differential Output Short-Circuit Current (Note 3)	I_{OSD}	V_{ID} = +50mV, V_{OD} = 0	-15		15	mA
		V_{ID} = -50mV, V_{OD} = 0				
SUPPLY						
Supply Current	I_{CC}	DC, R_L = 100Ω (Figure 4)		70	95	mA
		200MHz (400Mbps), R_L = 100Ω (Figure 4 (Note 3))		90	115	
		400MHz (800Mbps), R_L = 100Ω (Figure 4 (Note 3))		118	145	
Power-Down Supply Current	I_{CCZ}	$\overline{PWDRN}$ = low		2	20	µA

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AC ELECTRICAL CHARACTERISTICS

(V_{CC} = +3.0V to +3.6V, R_L = 100Ω ±1%, C_L = 5pF, differential input voltage $|V_{ID}|$ = 0.15V to 1.2V, MAX9153 LVDS input common-mode voltage V_{CM} = $|V_{ID}/2|$ to 2.4V - $|V_{ID}/2|$, MAX9154 LVPECL input voltage range = 0 to V_{CC}, $\overline{PWRDN}$ = high, T_A = -40°C to +85°C, unless otherwise noted. Typical values are at V_{CC} = +3.3V, $|V_{ID}|$ = 0.2V, V_{CM} = 1.2V, T_A = +25°C.) (Notes 3, 4, 5)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Rise Time	t_{LHT}	Figures 4, 5		150	220	450	ps
Fall Time	t_{HLT}			150	220	450	ps
Added Deterministic Jitter (Note 6)	t_{DJ}	V_{ID} = 200mV, 2^{23} - 1 PRBS data, V_{CM} = 1.2V	400Mbps (NRZ)		13	50	ps (p-p)
			800Mbps (NRZ)		24	90	
Added Random Jitter (Note 6)	t_{RJ}	V_{ID} = 200mV, 50% duty cycle input, V_{CM} = 1.2V	200MHz			1	ps (RMS)
			400MHz			1	
Differential Propagation Delay Low to High	t_{PLHD}	Figures 4, 5		1.6	2.3	3.3	ns
Differential Propagation Delay High to Low	t_{PHLD}			1.6	2.3	3.3	
Pulse Skew $\|t_{PLHD} - t_{PHLD}\|$	t_{SKEW}	Figures 4, 5			27	80	ps
Channel-to-Channel Skew (Note 7)	t_{CCS}	Figures 4, 5			35	60	ps
Differential Part-to-Part Skew 1 (Note 8)	t_{PPS1}	Figures 4, 5				1.2	ns
Differential Part-to-Part Skew 2 (Note 9)	t_{PPS2}					1.7	ns
Maximum Input Frequency (Note 10)	f_{MAX}	Figures 4, 5		800			Mbps
Power-Down Time	t_{PD}	Figures 6, 7			10	20	ns
Power-Up Time	t_{PU}				20	40	µs

Note 1: Current into a pin is defined as positive. Current out of a pin is defined as negative. All voltages are referenced to ground except V_{TH}, V_{TL}, V_{ID}, V_{OD}, and ΔV_{OD}.

Note 2: Maximum and minimum limits over temperature are guaranteed by design and characterization. Devices are production tested at T_A = +25°C.

Note 3: Guaranteed by design and characterization.

Note 4: C_L includes scope probe and test jig capacitance.

Note 5: Signal generator conditions unless otherwise noted: frequency = 400MHz, 50% duty cycle, R_O = 50Ω, t_R = 0.6ns, and t_F = 0.6ns (0% to 100%).

Note 6: Device jitter added to the input signal.

Note 7: t_{CCS} is the magnitude difference in differential propagation delay between outputs for a same-edge transition.

Note 8: t_{PPS1} is the magnitude difference of any differential propagation delays between devices operating over rated conditions at the same supply voltage, input conditions, and ambient temperature.

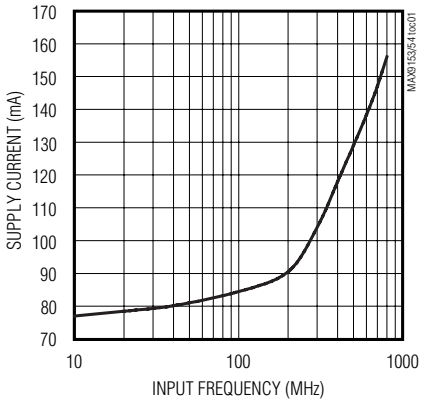
Note 9: T_{PPS2} is the magnitude difference of any differential propagation delays between devices operating over rated conditions.

Note 10: Device meets V_{OD} DC specification, and AC specifications while operating at f_{MAX}.

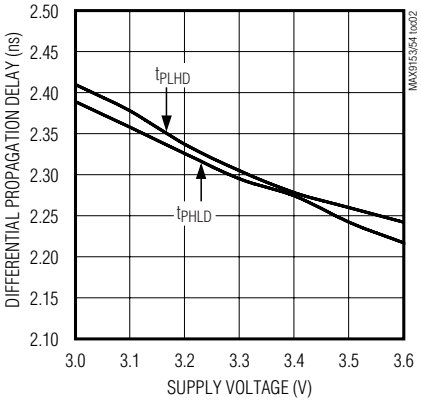
Typical Operating Characteristics

(V_{CC} = +3.3V, R_L = 100Ω, C_L = 5pF, $|V_{ID}|$ = 200mV, V_{CM} = 1.2V, f_{IN} = 200MHz, T_A = +25°C, unless otherwise noted.)

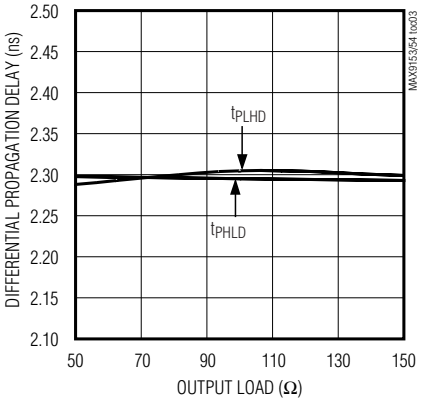
SUPPLY CURRENT vs. FREQUENCY



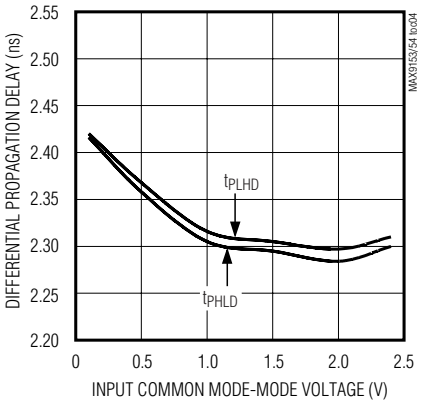
DIFFERENTIAL PROPAGATION DELAY vs. SUPPLY VOLTAGE



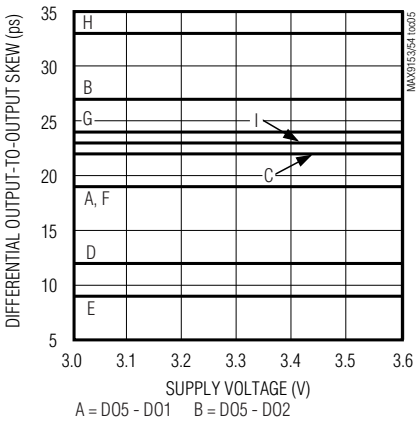
DIFFERENTIAL PROPAGATION DELAY vs. OUTPUT LOAD



DIFFERENTIAL PROPAGATION DELAY vs. INPUT COMMON-MODE VOLTAGE

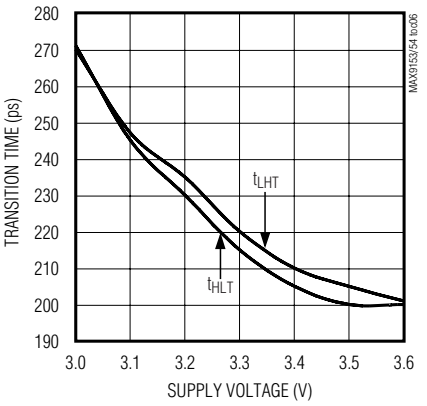


DIFFERENTIAL OUTPUT-TO-OUTPUT SKEW vs. SUPPLY VOLTAGE

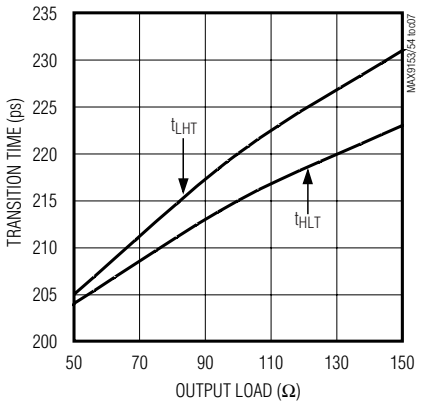


A = D05 - D01 B = D05 - D02
C = D05 - D03 D = D05 - D04
E = D05 - D06 F = D05 - D07
G = D05 - D08 H = D05 - D09
I = D05 - D010

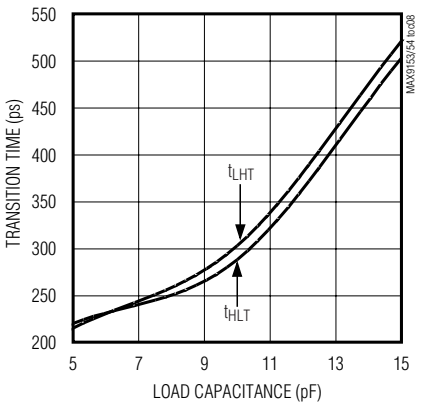
TRANSITION TIME vs. SUPPLY VOLTAGE



TRANSITION TIME vs. OUTPUT LOAD



TRANSITION TIME vs. LOAD CAPACITANCE

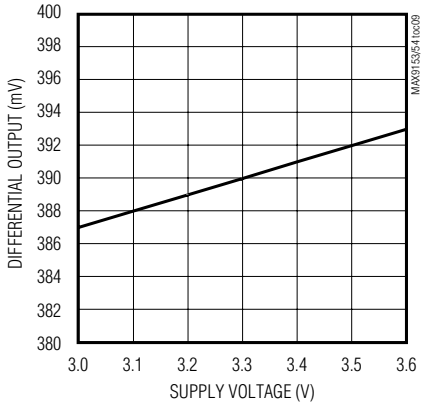


Low-Jitter, 800Mbps, 10-Port LVDS Repeaters with 100Ω Drive

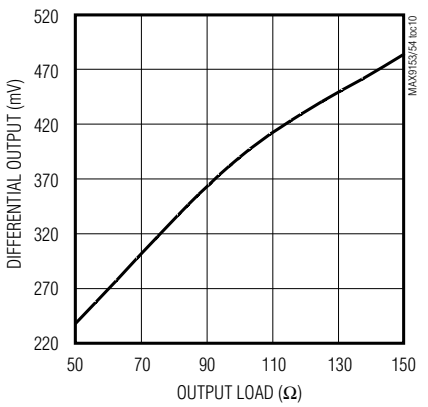
Typical Operating Characteristics (continued)

(V_{CC} = +3.3V, R_L = 100Ω, C_L = 5pF, $|V_{ID}|$ = 200mV, V_{CM} = 1.2V, f_{IN} = 200MHz, T_A = +25°C, unless otherwise noted.)

DIFFERENTIAL OUTPUT vs. SUPPLY VOLTAGE



DIFFERENTIAL OUTPUT vs. OUTPUT LOAD



Pin Description

PIN	NAME	FUNCTION
1, 3, 11, 13, 16, 18, 20, 24, 26, 28	DO2+, DO1+, DO10+, DO9+, DO8+, DO7+, DO6+, DO5+, DO4+, DO3+	Differential LVDS Outputs
2, 4, 12, 14, 15, 17, 19, 23, 25, 27	DO2-, DO1-, DO10-, DO9-, DO8-, DO7-, DO6-, DO5-, DO4-, DO3-	
5	$\overline{PWRDN}$	Power Down. Drive $\overline{PWRDN}$ low to disable all outputs and reduce supply current to 2µA. Drive $\overline{PWRDN}$ high for normal operation.
6, 9, 21	GND	Ground
10, 22	V_{CC}	Power. Bypass each V_{CC} pin to GND with 0.1µF and 1nF ceramic capacitors.
7	RIN+	LVDS (MAX9153) or LVPECL (MAX9154) Differential Inputs. RIN+ and RIN- are high-impedance inputs. Connect a resistor from RIN+ to RIN- to terminate the input signal.
8	RIN-	

Detailed Description

LVDS is a signaling method for point-to-point data communication over a controlled-impedance medium as defined by the ANSI/TIA/EIA-644 and IEEE 1596.3 standards. LVDS uses a lower voltage swing than other common communication standards, achieving higher data rates with reduced power consumption, while reducing EMI emissions and system susceptibility to noise.

The MAX9153/MAX9154 are 800Mbps, 10-port repeaters for high-speed, point-to-point, low-power applications. The MAX9153 accepts an LVDS input and has a fail-safe input circuit. The MAX9154 accepts an LVPECL input. Both devices repeat the input at 10 LVDS outputs. The devices detect differential signals as low as 50mV and as high as 1.2V within the 0 to 2.4V input voltage range as specified in the LVDS standards.

The MAX9153/MAX9154 outputs use a current-steering configuration to generate a 2.5mA to 4.5mA output current. This current-steering approach induces less ground bounce and no shoot-through current, enhancing noise margin and system speed performance. The outputs are short-circuit current limited and are high

impedance (to ground) when $\overline{PWRDN}$ = low or the device is not powered. The outputs have a typical differential resistance of 238Ω. The internal differential output resistance terminates induced noise and reflections from the primary termination located at the LVDS receiver.

The MAX9153/MAX9154 current-steering output requires a resistive load to terminate the signal and complete the transmission loop. Because the devices switch the direction of current flow and not voltage levels, the output voltage swing is determined by the value of the termination resistor multiplied by the output current. With a typical 3.8mA output current, the MAX9153/MAX9154 produce a 380mV output voltage when driving a transmission line terminated with a 100Ω resistor (3.8mA x 100Ω = 380mV). Logic states are determined by the direction of current flow through the termination resistor.

Table 1. Input/Output Function Table

INPUT, V_{ID}		OUTPUTS, V_{OD}
+50mV	MAX9153 MAX9154	High
-50mV		Low
Open		High
Undriven short	MAX9153	High
Undriven terminated	MAX9153	High

Note: *V_{ID} = RIN+ - RIN-, V_{OD} = DO_+ - DO_-*
High = 450mV > V_{OD} > 250mV
Low = -250mV > V_{OD} > -450mV

Fail-Safe

The fail-safe feature of the MAX9153 sets the outputs high when the differential input is:

- Open
- Undriven and shorted
- Undriven and terminated

Without a fail-safe circuit, when the input is undriven, noise at the input may switch the outputs and it may appear to the system that data is being sent. Open or undriven terminated input conditions can occur when a cable is disconnected or cut, or when an LVDS driver output is in high impedance. A shorted input can occur because of a cable failure.

When the input is driven with signals meeting the LVDS standard, the input common-mode voltage is less than V_{CC} - 0.3V and the fail-safe circuit is not activated. If the input is open, undriven and shorted, or undriven and parallel terminated, an internal resistor in the fail-safe circuit pulls both inputs above V_{CC} - 0.3V, activating the fail-safe circuit and forcing the outputs high (Figure 1).

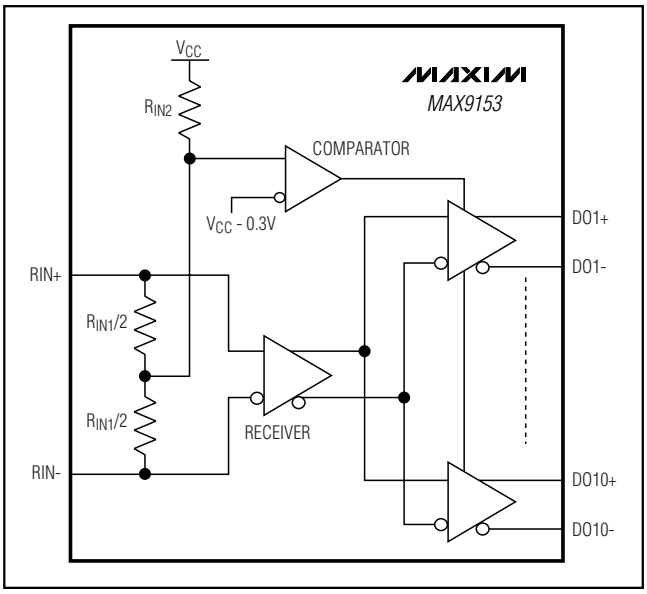


Figure 1. MAX9153 Input Fail-Safe Circuit

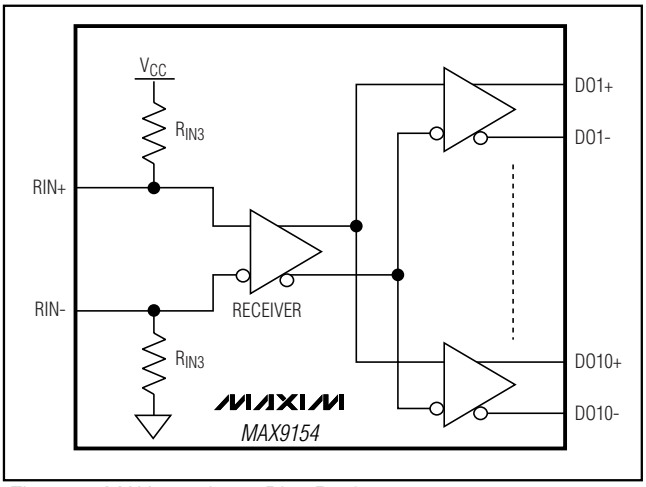


Figure 2. MAX9154 Input Bias Resistors

The MAX9154 is essentially the MAX9153 without the fail-safe circuit. The MAX9154 accepts input voltages from 0 to V_{CC} (vs. 0 to 2.4V for the MAX9153), which allows interfacing to LVPECL input signals while retaining a good common-mode tolerance.

Low-Jitter, 800Mbps, 10-Port LVDS Repeaters with 100Ω Drive

Applications Information

Supply Bypassing

Bypass each V_{CC} with high-frequency surface-mount ceramic 0.1µF and 1nF capacitors in parallel as close to the device as possible, with the smaller value capacitor closest to the V_{CC} pin.

Traces, Cables, and Connectors

The characteristics of input and output connections affect the performance of the MAX9153/MAX9154. Use controlled-impedance traces, cables, and connectors with matched characteristic impedance.

Ensure that noise couples as common mode by running the traces of a differential pair close together. Reduce within-pair skew by matching the electrical length of the traces of a differential pair. Excessive skew can result in a degradation of magnetic field cancellation. Maintain the distance between traces of a differential pair to avoid discontinuities in differential impedance. Minimize the number of vias to further prevent impedance discontinuities.

Avoid the use of unbalanced cables, such as ribbon cable. Balanced cables, such as twisted pair, offer superior signal quality and tend to generate less EMI due to canceling effects. Balanced cables tend to pick up noise as common mode, which is rejected by the LVDS receiver.

Termination

The MAX9153/MAX9154 are specified for 100Ω differential characteristic impedance but can operate with 90Ω to 132Ω to accommodate various types of interconnect. The termination resistor should match the differential characteristic impedance of the interconnect and be located close to the LVDS receiver input. Use a ±1% surface-mount termination resistor.

The output voltage swing is determined by the value of the termination resistor multiplied by the output current. With a typical 3.8mA output current, the MAX9153/MAX9154 produce a 380mV output voltage when driving a transmission line terminated with a 100Ω resistor (3.8mA x 100Ω = 380mV).

Chip Information

TRANSISTOR COUNT: 1394

PROCESS: CMOS

Test Circuits and Timing Diagrams

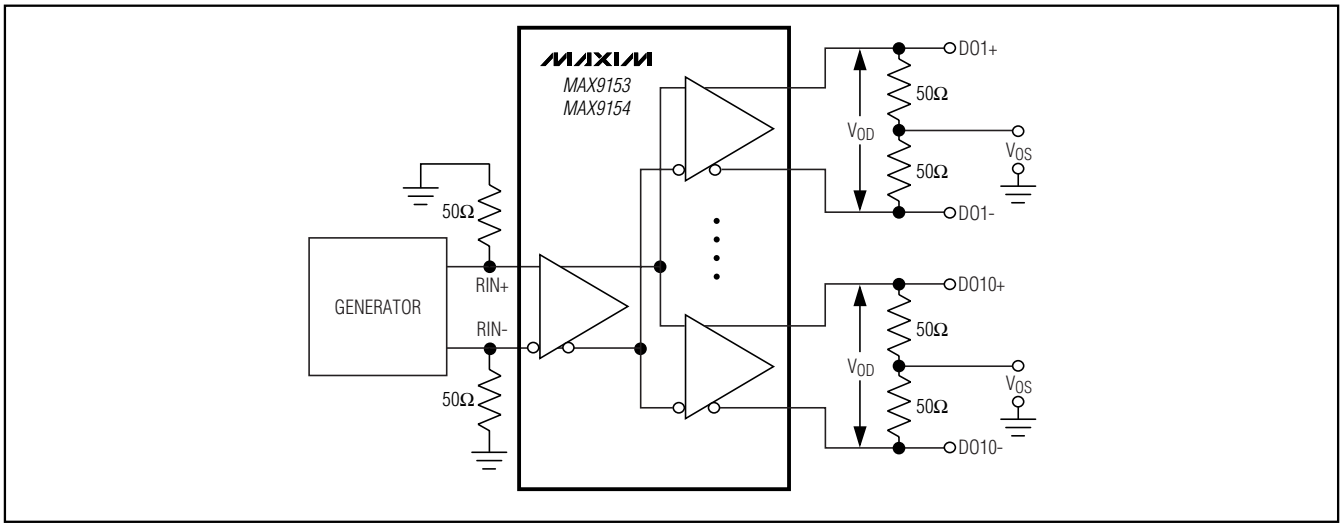


Figure 3. Driver-Load Test Circuit

Test Circuits and Timing Diagrams (continued)

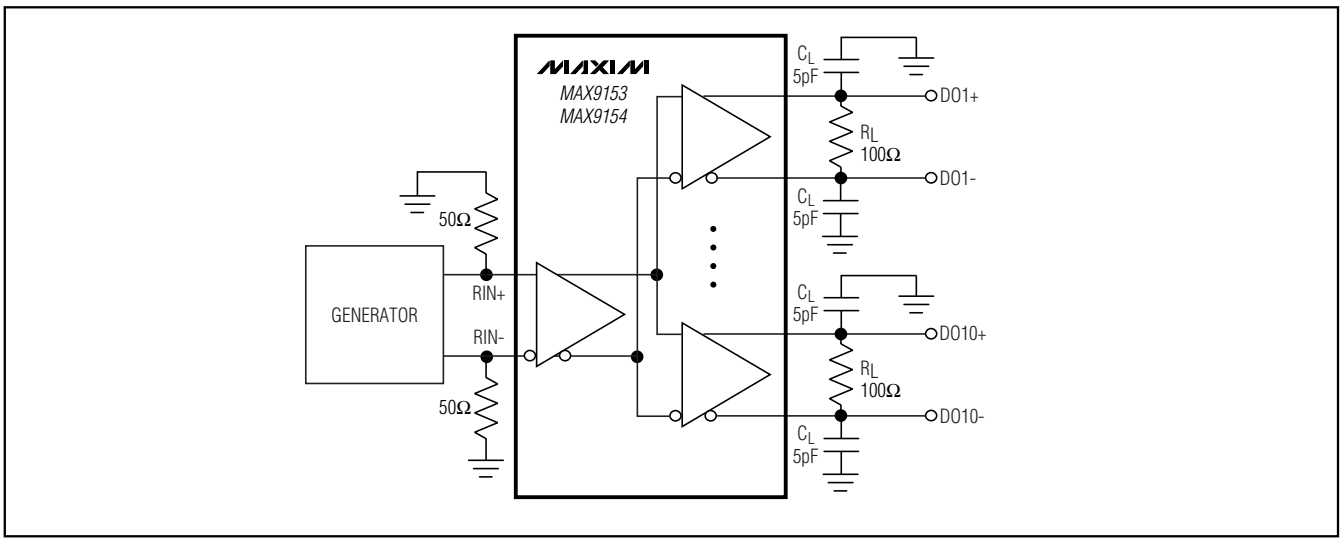


Figure 4. Propagation Delay and Transition Time Test Circuit

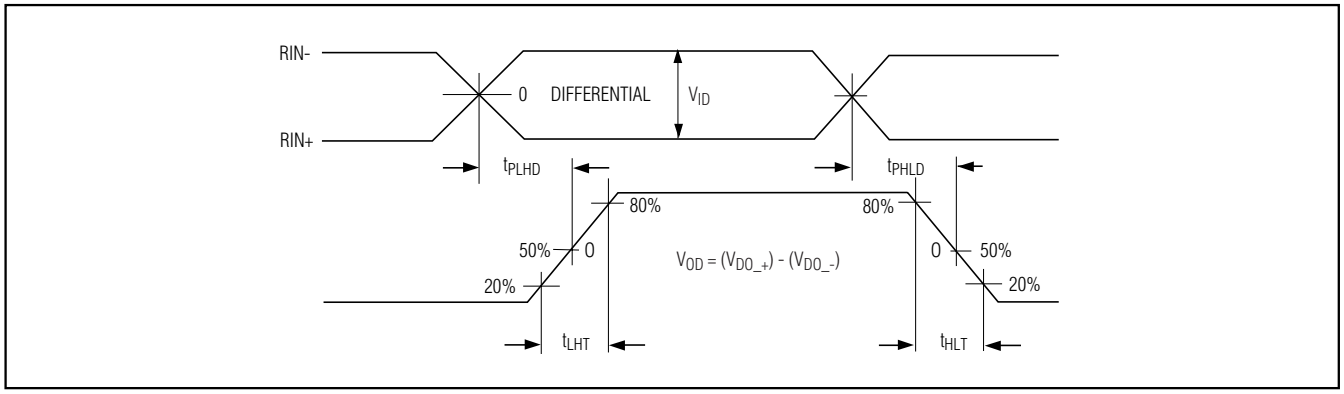


Figure 5. Propagation Delay and Transition Time Waveforms

Low-Jitter, 800Mbps, 10-Port LVDS Repeaters with 100Ω Drive

Test Circuits and Timing Diagrams (continued)

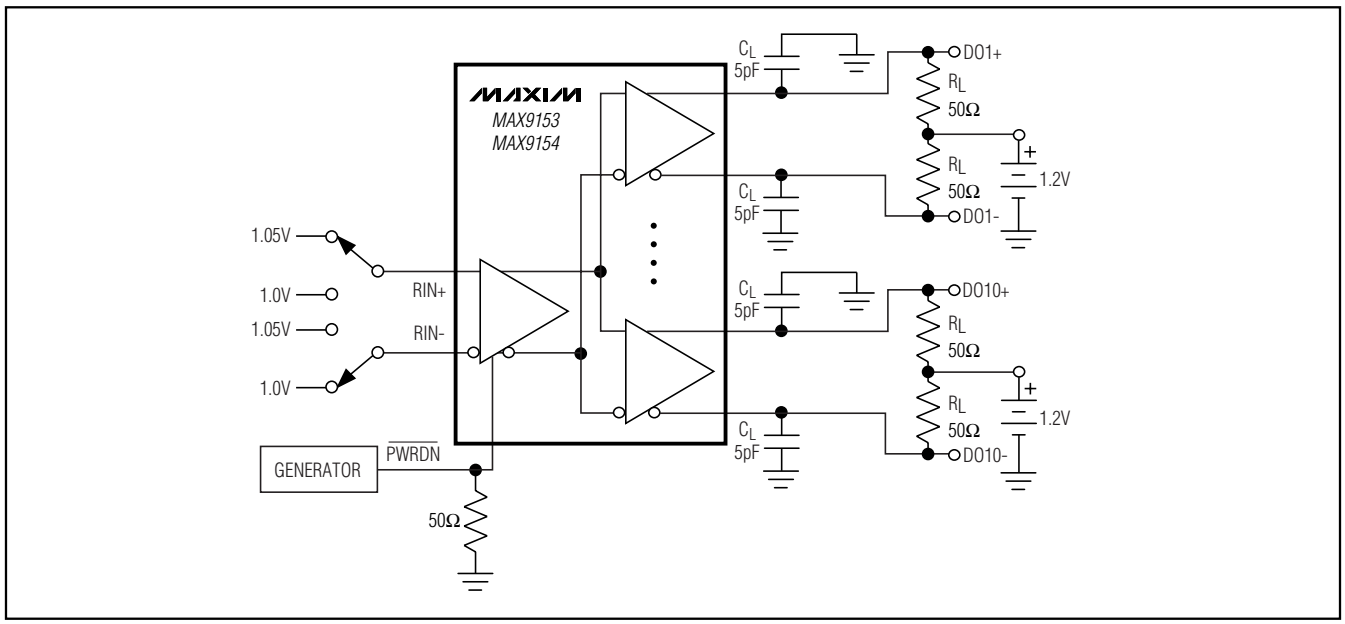


Figure 6. Power-Up/Down Delay Test Circuit

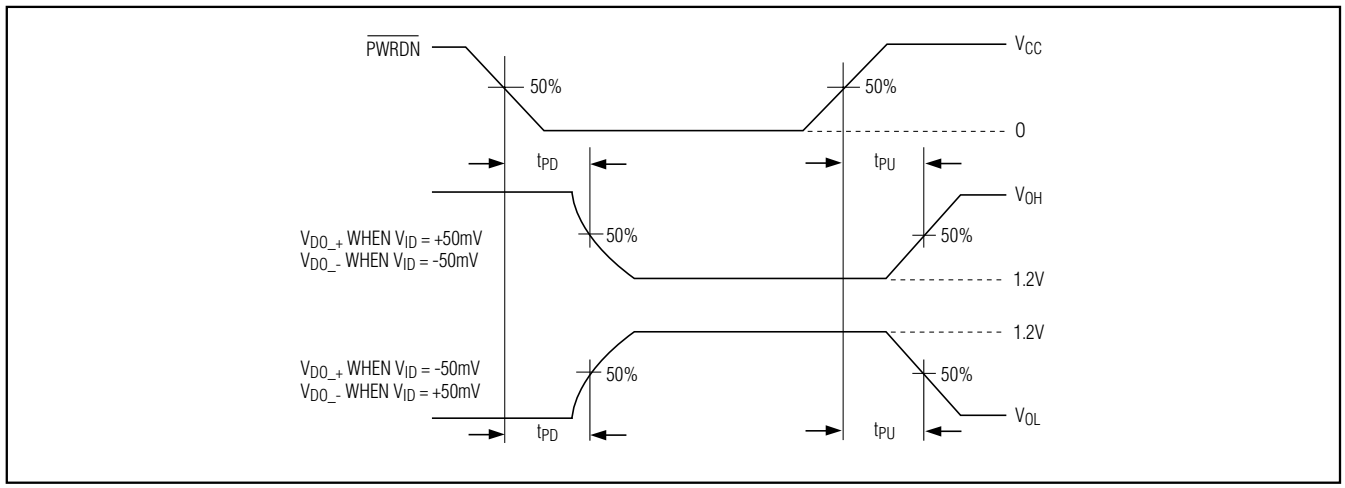
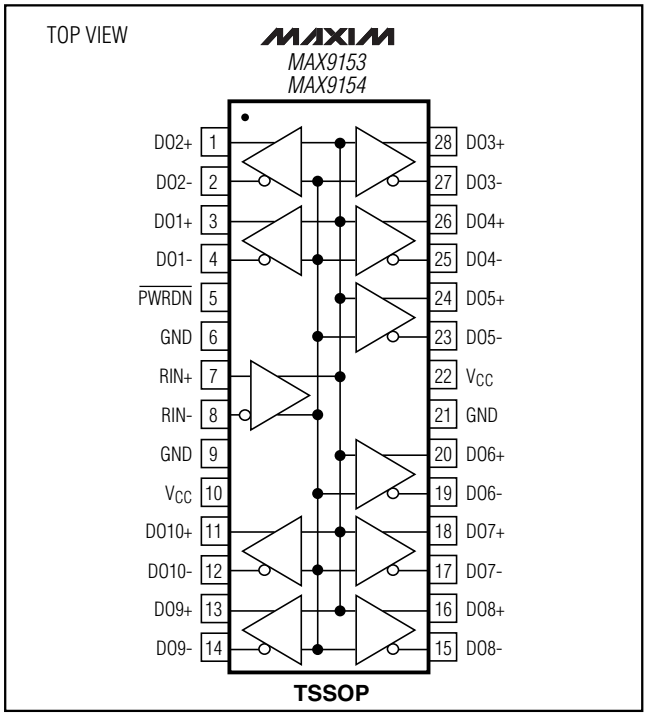


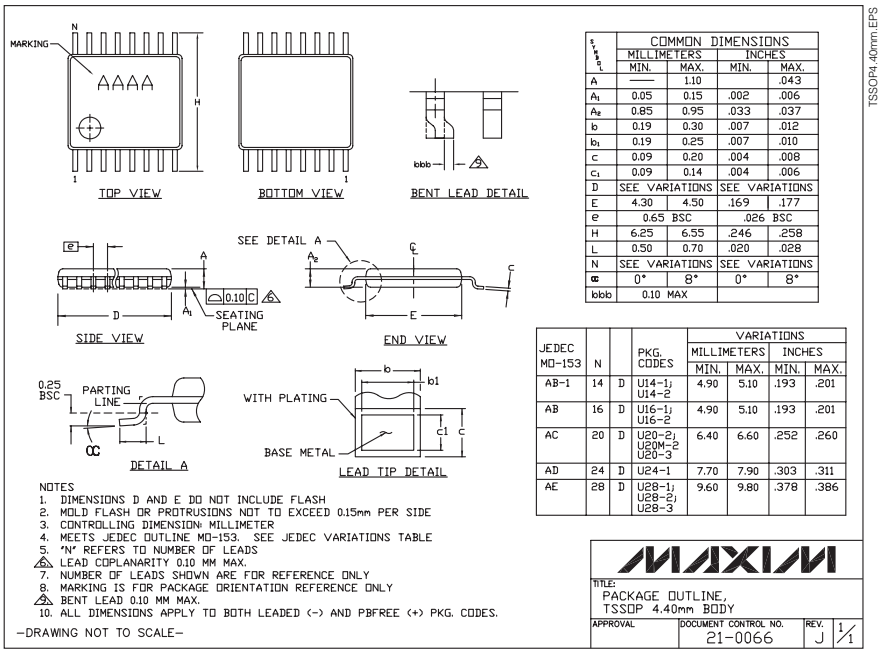
Figure 7. Power-Up/Down Delay Waveforms

Low-Jitter, 800Mbps, 10-Port LVDS Repeaters with 100Ω Drive

Pin Configuration



Package Information



SYMBOL	COMMON DIMENSIONS			
	MILLIMETERS		INCHES	
	MIN.	MAX.	MIN.	MAX.
A	——	1.10		.043
A_1	0.05	0.15	.002	.006
A_2	0.85	0.95	.033	.037
b	0.19	0.30	.007	.012
b_1	0.19	0.25	.007	.010
c	0.09	0.20	.004	.008
c_1	0.09	0.14	.004	.006
D	SEE VARIATIONS		SEE VARIATIONS	
E	4.30	4.50	.169	.177
e	0.65 BSC		.026 BSC	
H	6.25	6.55	.246	.258
L	0.50	0.70	.020	.028
N	SEE VARIATIONS		SEE VARIATIONS	
α	0°	8°	0°	8°
bbb	0.10 MAX			

JEDEC MO-153	N		PKG. CODES	VARIATIONS			
				MILLIMETERS		INCHES	
				MIN.	MAX.	MIN.	MAX.
AB-1	14	D	U14-1, U14-2	4.90	5.10	.193	.201
AB	16	D	U16-1, U16-2	4.90	5.10	.193	.201
AC	20	D	U20-2, U20M-2 U20-3	6.40	6.60	.252	.260
AD	24	D	U24-1	7.70	7.90	.303	.311
AE	28	D	U28-1, U28-2, U28-3	9.60	9.80	.378	.386

NOTES
1. DIMENSIONS D AND E DO NOT INCLUDE FLASH
2. MOLD FLASH OR PROTRUSIONS NOT TO EXCEED 0.15mm PER SIDE
3. CONTROLLING DIMENSION: MILLIMETER
4. MEETS JEDEC OUTLINE MO-153. SEE JEDEC VARIATIONS TABLE
5. "N" REFERS TO NUMBER OF LEADS
6. LEAD COPLANARITY 0.10 MM MAX.
7. NUMBER OF LEADS SHOWN ARE FOR REFERENCE ONLY
8. MARKING IS FOR PACKAGE ORIENTATION REFERENCE ONLY
9. BENT LEAD 0.10 MM MAX.
10. ALL DIMENSIONS APPLY TO BOTH LEADED (-) AND PBFREE (+) PKG. CODES.

—DRAWING NOT TO SCALE—

MAXIM

TITLE: PACKAGE OUTLINE, TSSOP 4.40mm BODY

APPROVAL	DOCUMENT CONTROL NO.	REV.	
	21-0066	J	1/1

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