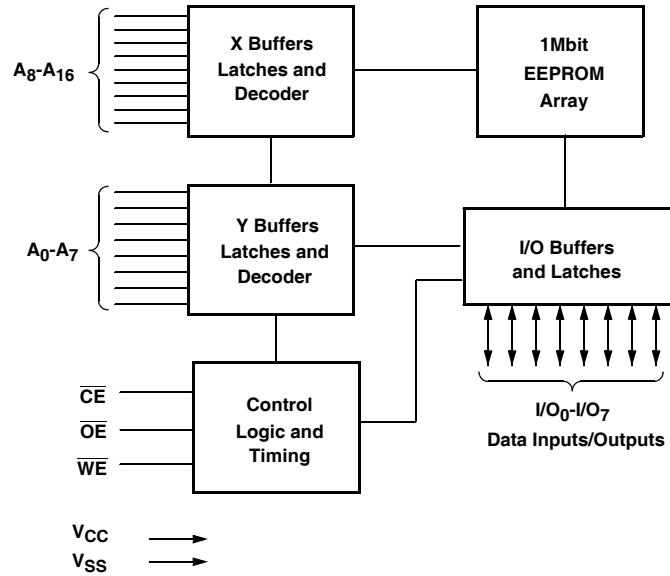


## X28C010, X28HT010

### Ordering Information

PART NUMBER	PART MARKING	ACCESS TIME	TEMP RANGE (°C)	PACKAGE	PKG. DWG #
X28C010D-12	X28C010D-12	120ns	0 to +70	32-Ld Cerdip	F32.6
X28C010D-15	X28C010D-15	150ns	0 to +70	32-Ld Cerdip	F32.6
X28C010DI	X28C010DI	-	-40 to +85	32-Ld Cerdip	F32.6
X28C010DI-12	X28C010DI-12	120ns	-40 to +85	32-Ld Cerdip	F32.6
X28C010DI-15	X28C010DI-15	150ns	-40 to +85	32-Ld Cerdip	F32.6
X28C010DM	X28C010DM	-	-55 to +125	32-Ld Cerdip	F32.6
X28C010DM-12	X28C010DM-12	120ns	-55 to +125	32-Ld Cerdip	F32.6
X28C010DM-15	X28C010DM-15	150ns	-55 to +125	32-Ld Cerdip	F32.6
X28C010DMB-12	C X28C010DMB-12	120ns	MIL-STD-883	32-Ld Cerdip	F32.6
X28C010DMB-15	C X28C010DMB-15	150ns	MIL-STD-883	32-Ld Cerdip	F32.6
X28C010DMB-20	C X28C010DMB-20	200ns	MIL-STD-883	32-Ld Cerdip	
X28C010FI-12	X28C010FI-12	120ns	-40 to +85	32-Ld Flat Pack	
X28C010FI-15	X28C010FI-15	150ns	-40 to +85	32-Ld Flat Pack	
X28C010FI-20	X28C010FI-20	200ns	-40 to +85	32-Ld Flat Pack	
X28C010FM	X28C010FM	-	-55 to +125	32-Ld Flat Pack	
X28C010FM-12	X28C010FM-12	120ns	-55 to +125	32-Ld Flat Pack	
X28C010FMB-12	C X28C010FMB-12	120ns	MIL-STD-883	32-Ld Flat Pack	
X28C010FMB-15	C X28C010FMB-15	150ns	MIL-STD-883	32-Ld Flat Pack	
X28C010K-25	X28C010K-25	250ns	0 to +70	36-Ld Pin Grid Array	G36.760x760A
X28C010KM-12	X28C010KM-12	120ns	-55 to +125	36-Ld Pin Grid Array	G36.760x760A
X28C010KM-25	X28C010KM-25	250ns	-55 to +125	36-Ld Pin Grid Array	G36.760x760A
X28C010KMB-12	C X28C010KMB-12	120ns	MIL-STD-883	36-Ld Pin Grid Array	G36.760x760A
X28C010KMB-15	C X28C010KMB-15	150ns	MIL-STD-883	36-Ld Pin Grid Array	G36.760x760A
X28C010NM-12	X28C010NM-12	120ns	-55 to +125	32-Ld Extended LCC	
X28C010NM-15	X28C010NM-15	150ns	-55 to +125	32-Ld Extended LCC	
X28C010NMB-12	C X28C010NMB-12	120ns	MIL-STD-883	32-Ld Extended LCC	
X28C010NMB-15	C X28C010NMB-15	150ns	MIL-STD-883	32-Ld Extended LCC	
X28C010RI-12	X28C010RI-12	120ns	-40 to +85	32-Ld Ceramic SOIC (Gull Wing)	
X28C010RI-20	X28C010RI-20	200ns	-40 to +85	32-Ld Ceramic SOIC (Gull Wing)	
X28C010RI-20T1	X28C010RI-20	200ns	-40 to +85	32-Ld Ceramic SOIC (Gull Wing)	
X28C010RM-15	X28C010RM-15	150ns	-55 to +125	32-Ld Ceramic SOIC (Gull Wing)	
X28C010RMB-25	C X28C010RMB-25	250ns	MIL-STD-883	32-Ld Ceramic SOIC (Gull Wing)	
X28HT010W		200ns	-40 to +175	Wafer	

**Block Diagram**



**Pin Descriptions**

**Addresses (A<sub>0</sub>-A<sub>16</sub>)**

The Address inputs select an 8-bit memory location during a read or write operation.

**Chip Enable ( $\overline{CE}$ )**

The Chip Enable input must be LOW to enable all read/write operations. When  $\overline{CE}$  is HIGH, power consumption is reduced.

**Output Enable ( $\overline{OE}$ )**

The Output Enable input controls the data output buffers, and is used to initiate read operations.

**Data In/Data Out (I/O<sub>0</sub>-I/O<sub>7</sub>)**

Data is written to or read from the X28C010/X28HT010 through the I/O pins.

**Write Enable ( $\overline{WE}$ )**

The Write Enable input controls the writing of data to the X28C010/X28HT010.

**Back Bias Voltage (V<sub>BB</sub>) (X28HT010 only)**

It is required to provide -3V on pin 1. This negative voltage improves higher temperature functionality.

**Pin Names**

SYMBOL	DESCRIPTION
A <sub>0</sub> -A <sub>16</sub>	Address Inputs
I/O <sub>0</sub> -I/O <sub>7</sub>	Data Input/Output
$\overline{WE}$	Write Enable
$\overline{CE}$	Chip Enable
$\overline{OE}$	Output Enable
V <sub>CC</sub>	+5V
V <sub>SS</sub>	Ground
NC	No Connect
V <sub>BB</sub> *	-3V

\*V<sub>BB</sub> applies to X28HT010 only.

**Device Operation**

**Read**

Read operations are initiated by both  $\overline{OE}$  and  $\overline{CE}$  LOW. The read operation is terminated by either  $\overline{CE}$  or  $\overline{OE}$  returning HIGH. This two line control architecture eliminates bus contention in a system environment. The data bus will be in a high impedance state when either  $\overline{OE}$  or  $\overline{CE}$  is HIGH.

**Write**

Write operations are initiated when both  $\overline{CE}$  and  $\overline{WE}$  are LOW and  $\overline{OE}$  is HIGH. The X28C010/X28HT010 supports both a  $\overline{CE}$  and  $\overline{WE}$  controlled write cycle. That is, the address is latched by the falling edge of either  $\overline{CE}$  or  $\overline{WE}$ , whichever occurs last. Similarly, the data is latched internally by the rising edge of either  $\overline{CE}$  or  $\overline{WE}$ , whichever occurs first. A byte write operation, once initiated, will automatically continue to completion, typically within 5ms.

**Page Write Operation**

The page write feature of the X28C010/X28HT010 allows the entire memory to be written in 5 seconds. Page write allows two to two hundred fifty-six bytes of data to be consecutively written to the X28C010/X28HT010 prior to the commencement of the internal programming cycle. The host can fetch data from another device within the system during a page write operation (change the source address), but the page address ( $A_8$  through  $A_{16}$ ) for each subsequent valid write cycle to the part during this operation must be the same as the initial page address.

The page write mode can be initiated during any write operation. Following the initial byte write cycle, the host can write an additional one to two hundred fifty six bytes in the same manner as the first byte was written. Each successive byte load cycle, started by the  $\overline{WE}$  HIGH to LOW transition, must begin within 100 $\mu$ s of the falling edge of the preceding  $\overline{WE}$ . If a subsequent  $\overline{WE}$  HIGH to LOW transition is not detected within 100 $\mu$ s, the internal automatic programming cycle will commence. There is no page write window limitation. Effectively the page write window is infinitely wide, so long as the host continues to access the device within the byte load cycle time of 100 $\mu$ s.

**Write Operation Status Bits**

The X28C010/X28HT010 provides the user two write operation status bits. These can be used to optimize a system write cycle time. The status bits are mapped onto the I/O bus as shown in Figure 1.

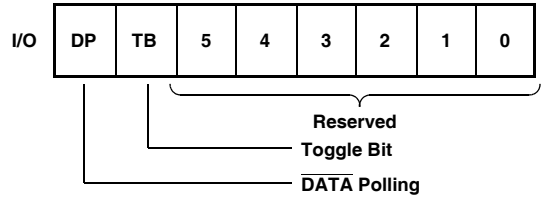


FIGURE 1. STATUS BIT ASSIGNMENT

**DATA Polling ( $I/O_7$ )**

The X28C010/X28HT010 features  $\overline{DATA}$  Polling as a method to indicate to the host system that the byte write or page write cycle has completed.  $\overline{DATA}$  Polling allows a simple bit test operation to determine the status of the X28C010/X28HT010, eliminating additional interrupt inputs or external hardware. During the internal programming cycle, any attempt to read the last byte written will produce the complement of that data on  $I/O_7$  (i.e., write data = 0xxx xxxx, read data = 1xxx xxxx). Once the programming cycle is complete,  $I/O_7$  will reflect true data. Note: If the X28C010/X28HT010 is in the protected state, and an illegal write operation is attempted,  $\overline{DATA}$  Polling will not operate.

**Toggle Bit ( $I/O_6$ )**

The X28C010/X28HT010 also provides another method for determining when the internal write cycle is complete. During the internal programming cycle,  $I/O_6$  will toggle from HIGH to LOW and LOW to HIGH on subsequent attempts to read the device. When the internal cycle is complete the toggling will cease and the device will be accessible for additional read or write operations.

**DATA Polling  $I/O_7$**

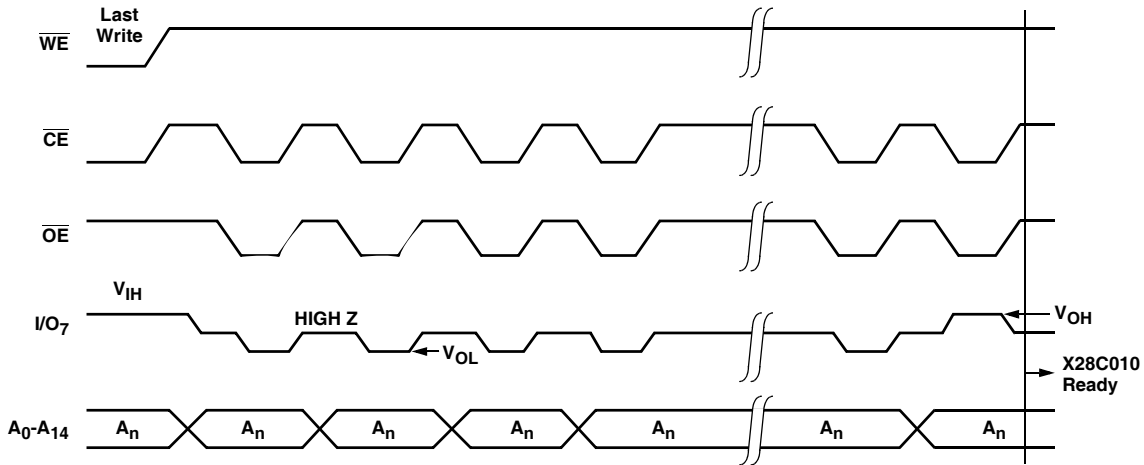


FIGURE 2. DATA POLLING BUS SEQUENCE

$\overline{\text{DATA}}$  Polling can effectively halve the time for writing to the X28C010/X28HT010. The timing diagram in Figure 2 illustrates the sequence of events on the bus. The software flow diagram in Figure 3 illustrates one method of implementing the routine.

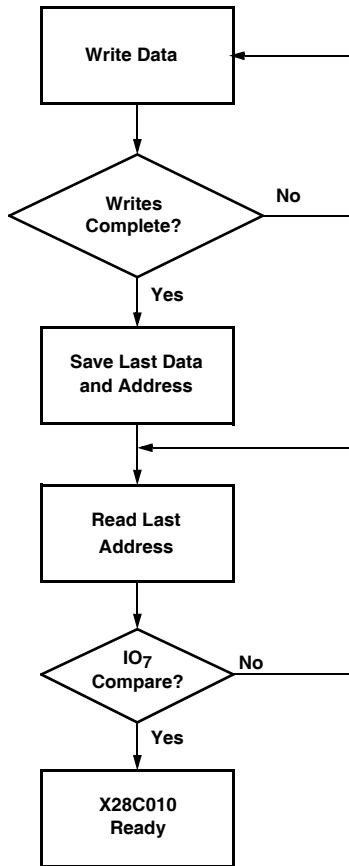


FIGURE 3.  $\overline{\text{DATA}}$  POLLING SOFTWARE FLOW

**The Toggle Bit I/O<sub>6</sub>**

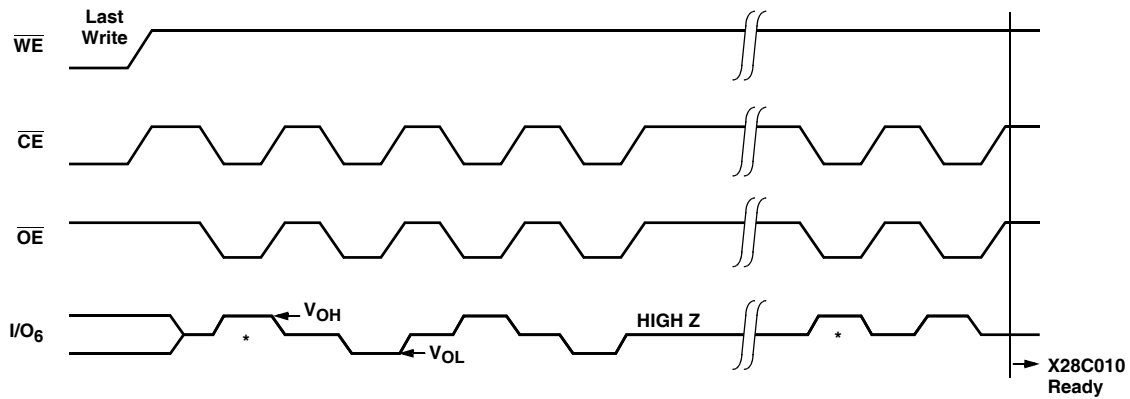


FIGURE 4. TOGGLE BIT BUS SEQUENCE

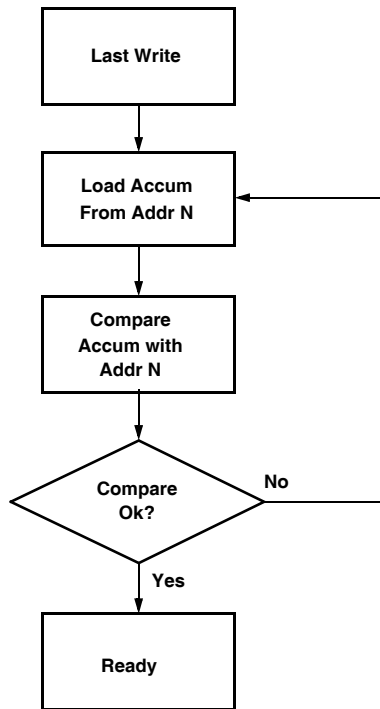


FIGURE 5. TOGGLE BIT SOFTWARE FLOW

The Toggle Bit can eliminate the software housekeeping chore of saving and fetching the last address and data written to a device in order to implement DATA Polling. This can be especially helpful in an array comprised of multiple X28C010/X28HT010 memories that is frequently updated. Toggle Bit Polling can also provide a method for status checking in multiprocessor applications. The timing diagram in Figure 4 illustrates the sequence of events on the bus. The software flow diagram in Figure 5 illustrates a method for polling the Toggle Bit.

### Hardware Data Protection

The X28C010/X28HT010 provides three hardware features that protect nonvolatile data from inadvertent writes.

- Noise Protection—A  $\overline{WE}$  pulse less than 10ns will not initiate a write cycle.
- Default  $V_{CC}$  Sense—All functions are inhibited when  $V_{CC}$  is  $\leq 3.5V$ .
- Write inhibit—Holding either  $\overline{OE}$  LOW,  $\overline{WE}$  HIGH, or  $\overline{CE}$  HIGH will prevent an inadvertent write cycle during power-up and power-down, maintaining data integrity.

### Software Data Protection

The X28C010/X28HT010 offers a software controlled data protection feature. The X28C010/X28HT010 is shipped from Intersil with the software data protection NOT ENABLED: that is the device will be in the standard operating mode. In this mode data should be protected during power-up/-down operations through the use of external circuits. The host would then have open read and write access of the device once  $V_{CC}$  was stable.

The X28C010/X28HT010 can be automatically protected during power-up and power-down without the need for external circuits by employing the software data protection feature. The internal software data protection circuit is enabled after the first write operation utilizing the software algorithm. This circuit is nonvolatile and will remain set for the life of the device unless the reset command is issued.

Once the software protection is enabled, the X28C010/X28HT010 is also protected from inadvertent and accidental writes in the powered-up state. That is, the software algorithm must be issued prior to writing additional data to the device.

### Software Algorithm

Selecting the software data protection mode requires the host system to precede data write operations by a series of three write operations to three specific addresses. Refer to Figures 6 and 7 for the sequence. The three byte sequence opens the page write window enabling the host to write from one to two hundred fifty-six bytes of data. Once the page load cycle has been completed, the device will automatically be returned to the data protected state.

Software Data Protection

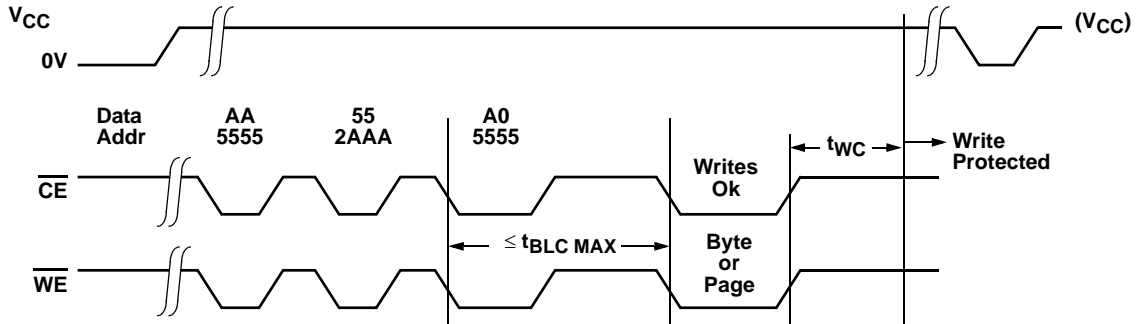


FIGURE 6. TIMING SEQUENCE—BYTE OR PAGE WRITE

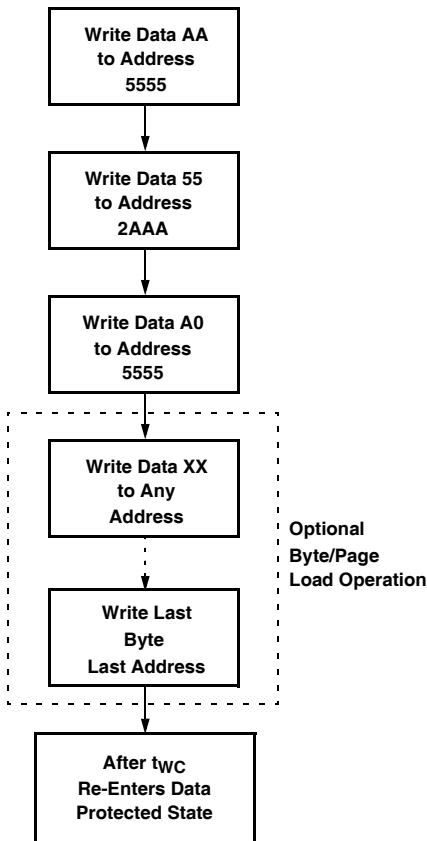


FIGURE 7. WRITE SEQUENCE FOR SOFTWARE DATA PROTECTION

Regardless of whether the device has previously been protected or not, once the software data protection algorithm is used and data has been written, the X28C010/X28HT010 will automatically disable further writes unless another command is issued to cancel it. If no further commands are issued the X28C010/X28HT010 will be write protected during power-down and after any subsequent power-up. The state of A<sub>15</sub> and A<sub>16</sub> while executing the algorithm is don't care.

**Note:** Once initiated, the sequence of write operations should not be interrupted.

**Resetting Software Data Protection**

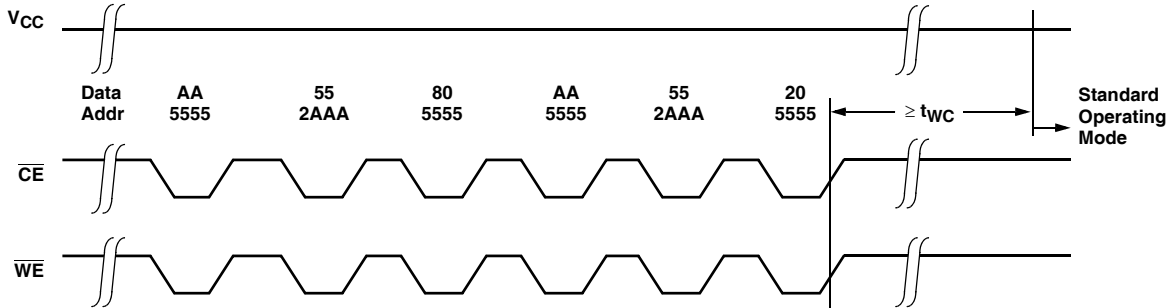


FIGURE 8. RESET SOFTWARE DATA PROTECTION TIMING SEQUENCE

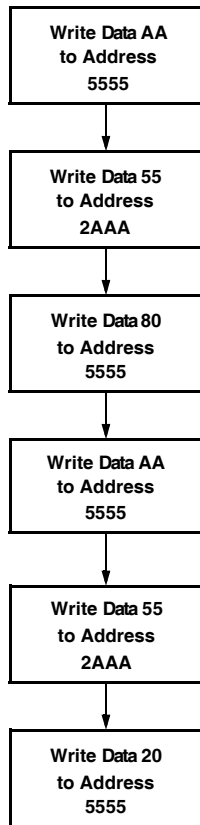


FIGURE 9. SOFTWARE SEQUENCE TO DEACTIVATE SOFTWARE DATA PROTECTION

In the event the user wants to deactivate the software data protection feature for testing or reprogramming in an EEPROM programmer, the following six step algorithm will reset the internal protection circuit. After  $t_{WC}$ , the X28C010/X28HT010 will be in standard operating mode.

**Note:** Once initiated, the sequence of write operations should not be interrupted.

**System Considerations**

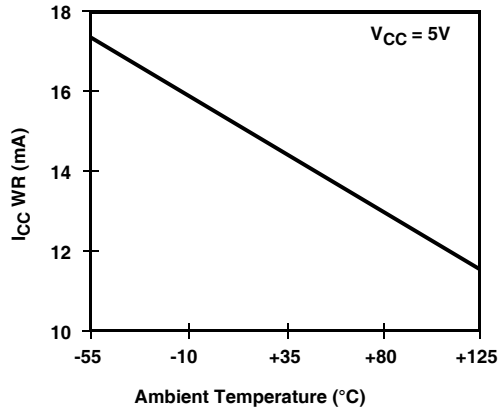
Because the X28C010/X28HT010 is frequently used in large memory arrays, it is provided with a two line control architecture for both read and write operations. Proper usage can provide the lowest possible power dissipation and eliminate the possibility of contention where multiple I/O pins share the same bus.

To gain the most benefit, it is recommended that  $\overline{CE}$  be decoded from the address bus and be used as the primary device selection input. Both  $\overline{OE}$  and  $\overline{WE}$  would then be common among all devices in the array. For a read operation this assures that all deselected devices are in their standby mode and that only the selected device(s) is outputting data on the bus.

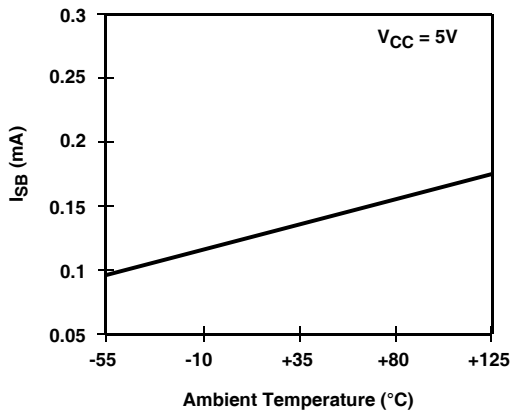
Because the X28C010/X28HT010 has two power modes, standby and active, proper decoupling of the memory array is of prime concern. Enabling  $\overline{CE}$  will cause transient current spikes. The magnitude of these spikes is dependent on the output capacitive loading of the I/Os. Therefore, the larger the array sharing a common bus, the larger the transient spikes. The voltage peaks associated with the current transients can be suppressed by the proper selection and placement of decoupling capacitors. As a minimum, it is recommended that a 0.1 $\mu$ F high frequency ceramic capacitor be used between  $V_{CC}$  and  $V_{SS}$  at each device. Depending on the size of the array, the value of the capacitor may have to be larger.

In addition, it is recommended that a 4.7 $\mu$ F electrolytic bulk capacitor be placed between  $V_{CC}$  and  $V_{SS}$  for each eight devices employed in the array. This bulk capacitor is employed to overcome the voltage droop caused by the inductive effects of the PC board traces.

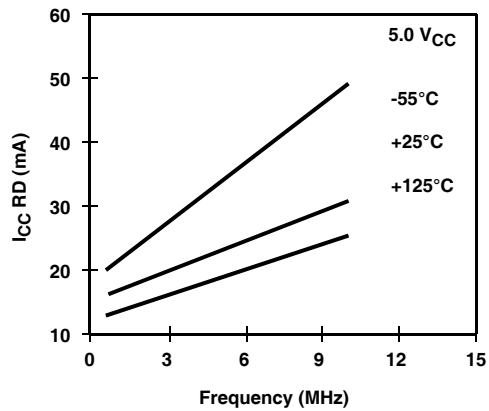
**Active Supply Current vs. Ambient Temperature**



**Standby Supply Current vs. Ambient Temperature**



**$I_{CC\ RD}$  by Temperature Over Frequency**





# X28C010, X28HT010

## Absolute Maximum Ratings

Temperature under bias	
X28C010	-10°C to +85°C
X28C010I	-65°C to +135°C
X28C010M	-65°C to +135°C
X28HT010	-55°C to +175°C
Storage temperature	-65°C to +150°C
Voltage on any pin with respect to V <sub>SS</sub>	-1V to +7V
D.C. output current	5mA
Lead temperature (soldering, 10 seconds)	+300°C

## Recommended Operating Conditions

Commercial	0°C to +70°C
Industrial	-40°C to +85°C
Military	-55°C to +125°C
Supply Voltage	.5V ±10%
High Temperature	-40°C to +175°C

*CAUTION: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions (above those indicated in the operational sections of this specification) is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.*

## DC Electrical Specifications Over the recommended operating conditions, unless otherwise specified.

SYMBOL	PARAMETER	TEST CONDITIONS	MIN	MAX	UNIT
I <sub>CC</sub>	V <sub>CC</sub> Current (Active) (TTL Inputs)	$\overline{CE} = \overline{OE} = V_{IL}$ , $\overline{WE} = V_{IH}$ , All I/O's = Open, Address Inputs = 0.4V/2.4V Levels @ f = 5MHz		50	mA
I <sub>SB1</sub>	V <sub>CC</sub> Current (Standby) (TTL Inputs)	$\overline{CE} = V_{IH}$ , $\overline{OE} = V_{IL}$ , All I/O's = Open, Other Inputs = V <sub>IH</sub>		3	mA
I <sub>SB2</sub>	V <sub>CC</sub> Current (Standby) (CMOS Inputs)	$\overline{CE} = V_{CC} - 0.3V$ , $\overline{OE} = V_{IL}$ , All I/O's = Open, Other Inputs = V <sub>CC</sub>		500	μA
I <sub>LI</sub>	Input Leakage Current	V <sub>IN</sub> = V <sub>SS</sub> to V <sub>CC</sub>		10	μA
		V <sub>IN</sub> = V <sub>SS</sub> to V <sub>CC</sub> (Note 2)		20	μA
I <sub>LO</sub>	Output Leakage Current	V <sub>OUT</sub> = V <sub>SS</sub> to V <sub>CC</sub> , $\overline{CE} = V_{IH}$		10	μA
		V <sub>OUT</sub> = V <sub>SS</sub> to V <sub>CC</sub> , $\overline{CE} = V_{IH}$ (Note 2)		20	μA
V <sub>IL</sub> (Note 1)	Input LOW Voltage		-1	0.8	V
		(Note 2)	-1	0.6	V
V <sub>IH</sub> (Note 1)	Input HIGH Voltage		2	V <sub>CC</sub> + 1	V
		(Note 2)	2.2	V <sub>CC</sub> + 1	V
V <sub>OL</sub>	Output LOW Voltage	I <sub>OL</sub> = 2.1mA		0.4	V
		I <sub>OL</sub> = 1mA (Note 2)		0.5	V
V <sub>OH</sub>	Output HIGH Voltage	I <sub>OH</sub> = -400μA	2.4		V
		I <sub>OH</sub> = -400μA	2.6		V
I <sub>BB</sub>	Back Bias Current	V <sub>BB</sub> = -3V ±10% (Note 2)		200	μA

NOTE:

- V<sub>IL</sub> min. and V<sub>IH</sub> max. are for reference only and are not tested.
- X28HT010W

## Power-Up Timing

SYMBOL	PARAMETER	MAX	UNIT
t <sub>PUR</sub> (Note 3)	Power-up to Read operation	100	μs
t <sub>PUW</sub> (Note 3)	Power-up to Write operation	5	ms

## Capacitance T<sub>A</sub> = +25°C, f = 1MHz, V<sub>CC</sub> = 5V

SYMBOL	PARAMETER	TEST CONDITIONS	MAX	UNIT
C <sub>I/O</sub> (Note 3)	Input/Output capacitance	V <sub>I/O</sub> = 0V	10	pF
C <sub>IN</sub> (Note 3)	Input capacitance	V <sub>IN</sub> = 0V	10	pF

NOTE:

- This parameter is periodically sampled and not 100% tested.

**Endurance and Data Retention**

PARAMETER	MIN	MAX	UNIT
Endurance	10,000		Cycles per byte
Endurance	100,000		Cycles per page
Data Retention	100		Years

**A.C. Conditions of Test**

Input pulse levels	0V to 3V
Input rise and fall times	10ns
Input and output timing levels	1.5V

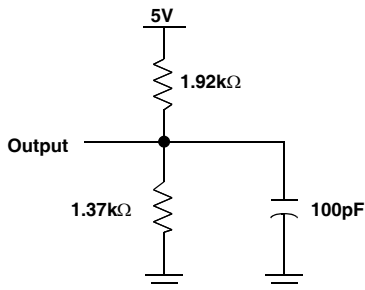
**Symbol Table**

WAVEFORM	INPUTS	OUTPUTS
	Must be steady	Will be steady
	May change from LOW to HIGH	Will change from LOW to HIGH
	May change from HIGH to LOW	Will change from HIGH to LOW
	Don't Care: Changes Allowed	Changing: State Not Known
	N/A	Center Line is High Impedance

**Mode Selection**

$\overline{CE}$	$\overline{OE}$	$\overline{WE}$	MODE	I/O	POWER
L	L	H	Read	D <sub>OUT</sub>	Active
L	H	L	Write	D <sub>IN</sub>	Active
H	X	X	Standby and Write Inhibit	High Z	Standby
X	L	X	Write Inhibit	—	—
X	X	H	Write Inhibit	—	—

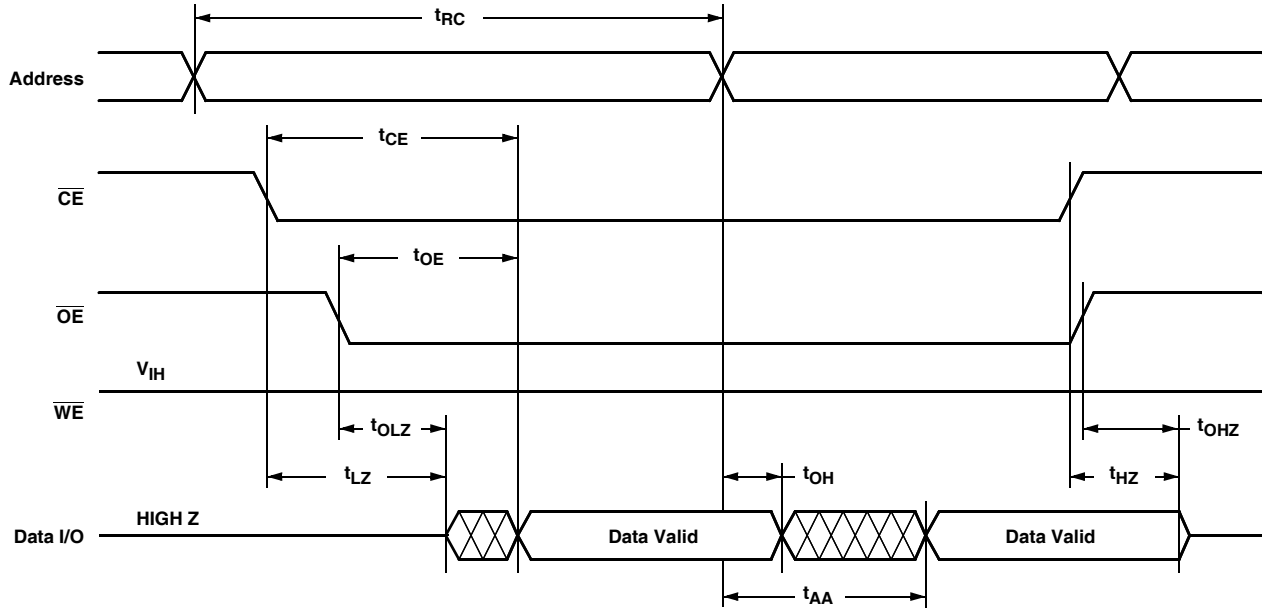
**Equivalent A.C. Load Circuit**



**AC Electrical Specifications** Over the recommended operating conditions, unless otherwise specified.

SYMBOL	PARAMETER	X28C010-12		X28C010-15		X28C010-20, X28HT010W		X28C010-25		UNIT
		MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	
<b>READ CYCLE LIMITS</b>										
t <sub>RC</sub>	Read cycle time	120		150		200		250		ns
t <sub>CE</sub>	Chip enable access time		120		150		200		250	ns
t <sub>AA</sub>	Address access time		120		150		200		250	ns
t <sub>OE</sub>	Output enable access time		50		50		50		50	ns
t <sub>LZ</sub> (Note 4)	$\overline{CE}$ LOW to active output	0		0		0		0		ns
t <sub>OLZ</sub> (Note 4)	$\overline{OE}$ LOW to active output	0		0		0		0		ns
t <sub>HZ</sub> (Note 4)	$\overline{CE}$ HIGH to high Z output		50		50		50		50	ns
t <sub>OHZ</sub> (Note 4)	$\overline{OE}$ HIGH to high Z output		50		50		50		50	ns
t <sub>OH</sub>	Output hold from address change	0		0		0		0		ns

Read Cycle



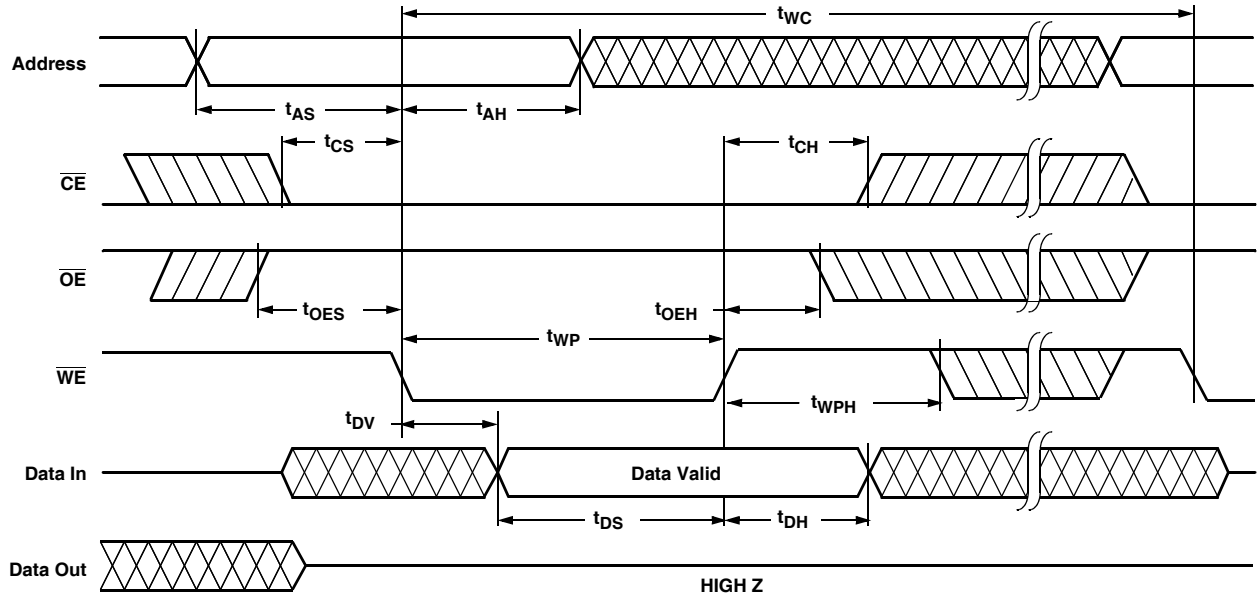
NOTE:

4.  $t_{LZ}$  min.,  $t_{HZ}$ ,  $t_{OLZ}$  min., and  $t_{OHZ}$  are periodically sampled and not 100% tested.  $t_{HZ}$  max. and  $t_{OHZ}$  max. are measured, with  $C_L = 5\text{pF}$ , from the point when  $\overline{CE}$  or  $\overline{OE}$  return HIGH (whichever occurs first) to the time when the outputs are no longer driven.

Write Cycle Limits

SYMBOL	PARAMETER	MIN	MAX	UNIT
$t_{WC}$ (Note 5)	Write cycle time		10	ms
$t_{AS}$	Address setup time	0		ns
$t_{AH}$	Address hold time	50		ns
$t_{CS}$	Write setup time	0		ns
$t_{CH}$	Write hold time	0		ns
$t_{CW}$	$\overline{CE}$ pulse width	100		ns
$t_{OES}$	$\overline{OE}$ HIGH setup time	10		ns
$t_{OEH}$	$\overline{OE}$ HIGH hold time	10		ns
$t_{WP}$	$\overline{WE}$ pulse width	100		ns
$t_{WPH}$	$\overline{WE}$ HIGH recovery	100		ns
$t_{DV}$	Data valid		1	$\mu\text{s}$
$t_{DS}$	Data setup	50		ns
$t_{DH}$	Data hold	0		ns
$t_{DW}$	Delay to next write	10		$\mu\text{s}$
$t_{BLC}$	Byte load cycle	0.2	100	$\mu\text{s}$

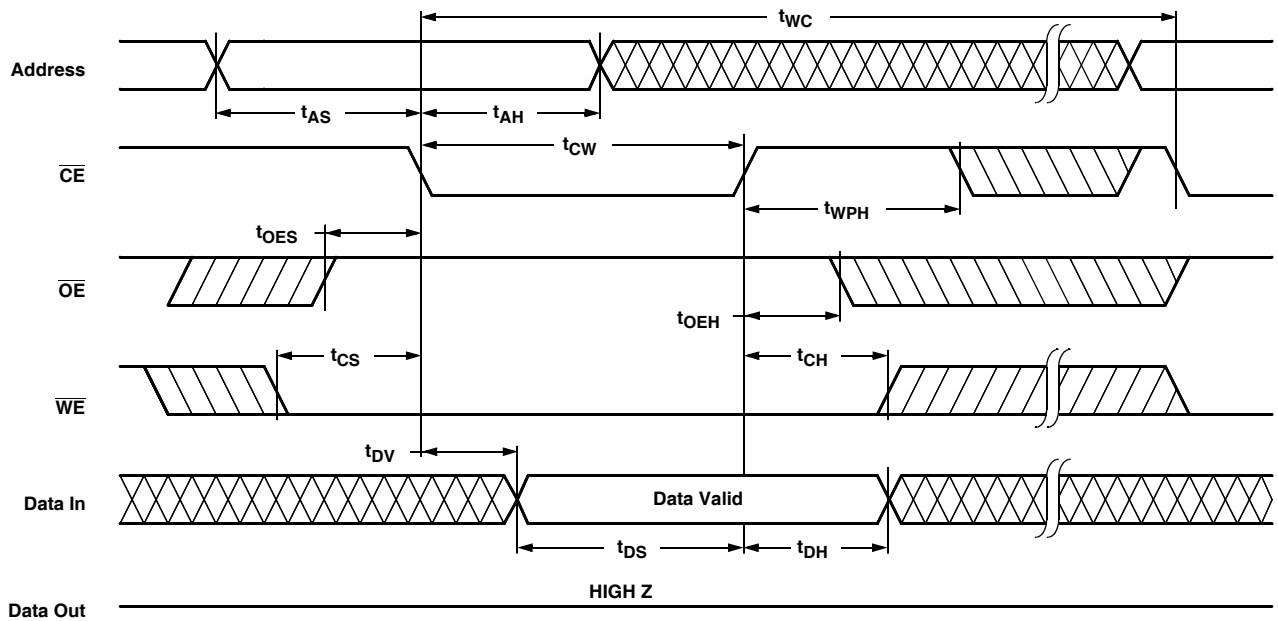
**$\overline{WE}$  Controlled Write Cycle**



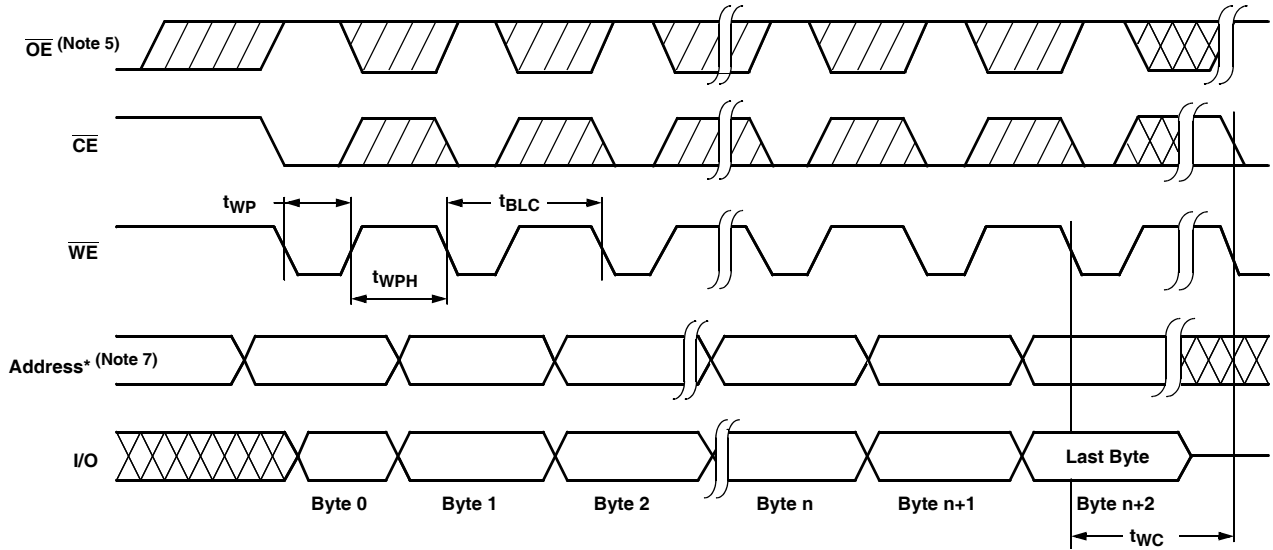
NOTE:

- $t_{WC}$  is the minimum cycle time to be allowed from the system perspective unless polling techniques are used. It is the maximum time the device requires to complete internal write operation.

**$\overline{CE}$  Controlled Write Cycle**



**Page Write Cycle**

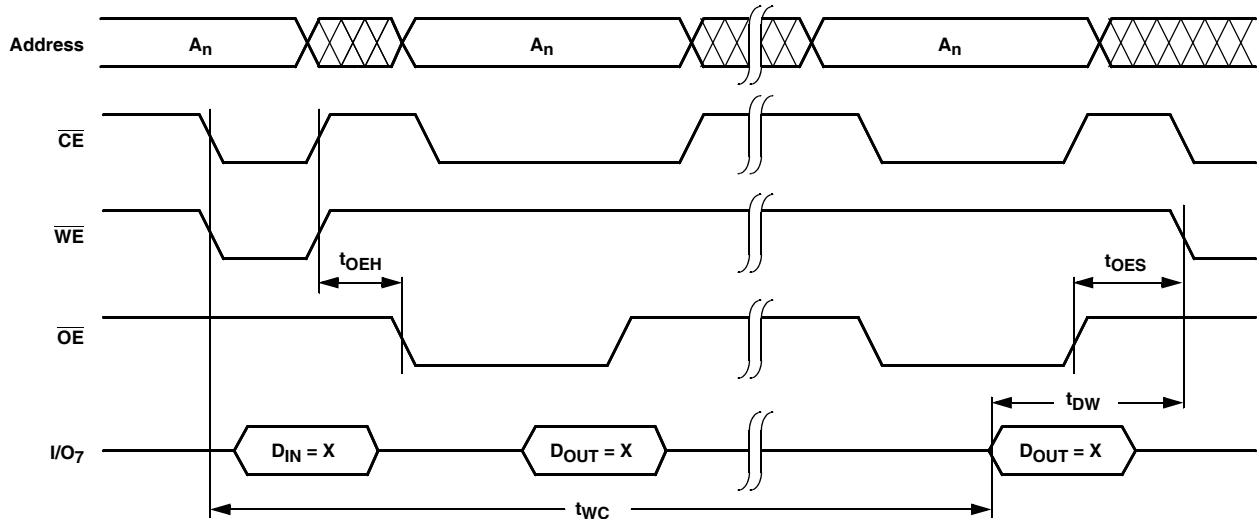


\*For each successive write within the page write operation,  $A_8-A_{16}$  should be the same or writes to an unknown address could occur.

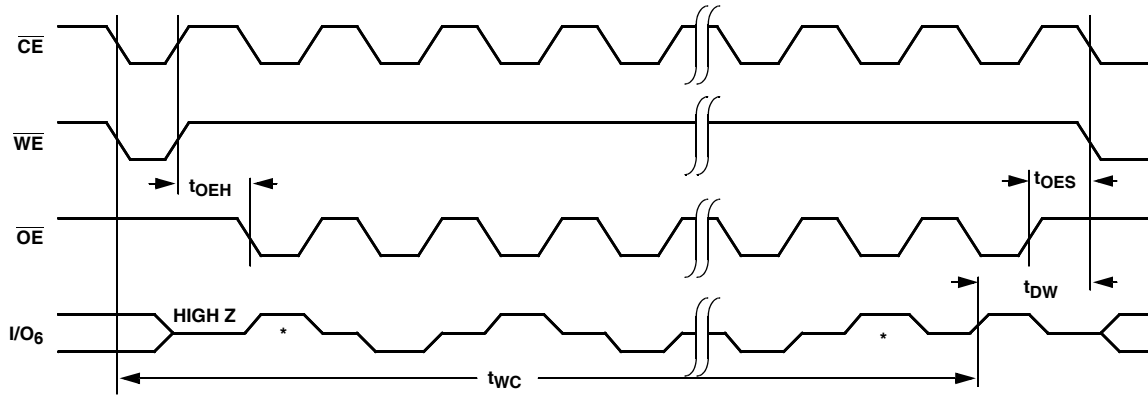
**NOTES:**

6. Between successive byte writes within a page write operation,  $\overline{OE}$  can be strobed LOW: e.g. this can be done with  $\overline{CE}$  and  $\overline{WE}$  HIGH to fetch data from another memory device within the system for the next write; or with  $\overline{WE}$  HIGH and  $\overline{CE}$  LOW effectively performing a polling operation.
7. The timings shown above are unique to page write operations. Individual byte load operations within the page write must conform to either the  $\overline{CE}$  or  $\overline{WE}$  controlled write cycle timing.

**DATA Polling Timing Diagram (Note 8)**



**Toggle Bit Timing Diagram**

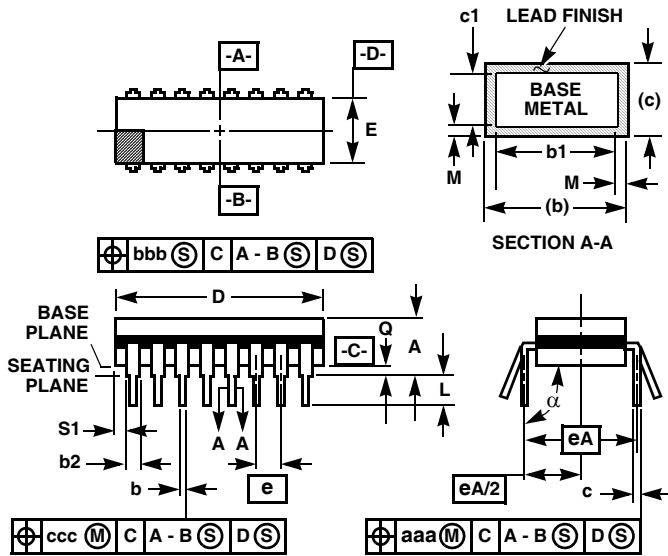


\*  $I/O_6$  beginning and ending state will vary.

**NOTE:**

- 8. Polling operations are by definition read cycles and are therefore subject to read cycle timings.

**Ceramic Dual-In-Line Frit Seal Packages (CERDIP)**



**F32.6 MIL-STD-1835 GDIP1-T32 (D-16, CONFIGURATION A)  
32 LEAD CERAMIC DUAL-IN-LINE FRIT SEAL PACKAGE**

SYMBOL	INCHES		MILLIMETERS		NOTES
	MIN	MAX	MIN	MAX	
A	-	0.232	-	5.92	-
b	0.014	0.026	0.36	0.66	2
b1	0.014	0.023	0.36	0.58	3
b2	0.045	0.065	1.14	1.65	-
b3	0.023	0.045	0.58	1.14	4
c	0.008	0.018	0.20	0.46	2
c1	0.008	0.015	0.20	0.38	3
D	-	1.690	-	42.95	5
E	0.500	0.610	12.70	15.49	5
e	0.100 BSC		2.54 BSC		-
eA	0.600 BSC		15.24 BSC		-
eA/2	0.300 BSC		7.62 BSC		-
L	0.125	0.200	3.18	5.08	-
Q	0.015	0.060	0.38	1.52	6
S1	0.005	-	0.13	-	7
$\alpha$	90°	105°	90°	105°	-
aaa	-	0.015	-	0.38	-
bbb	-	0.030	-	0.76	-
ccc	-	0.010	-	0.25	-
M	-	0.0015	-	0.038	2, 3
N	32		32		8

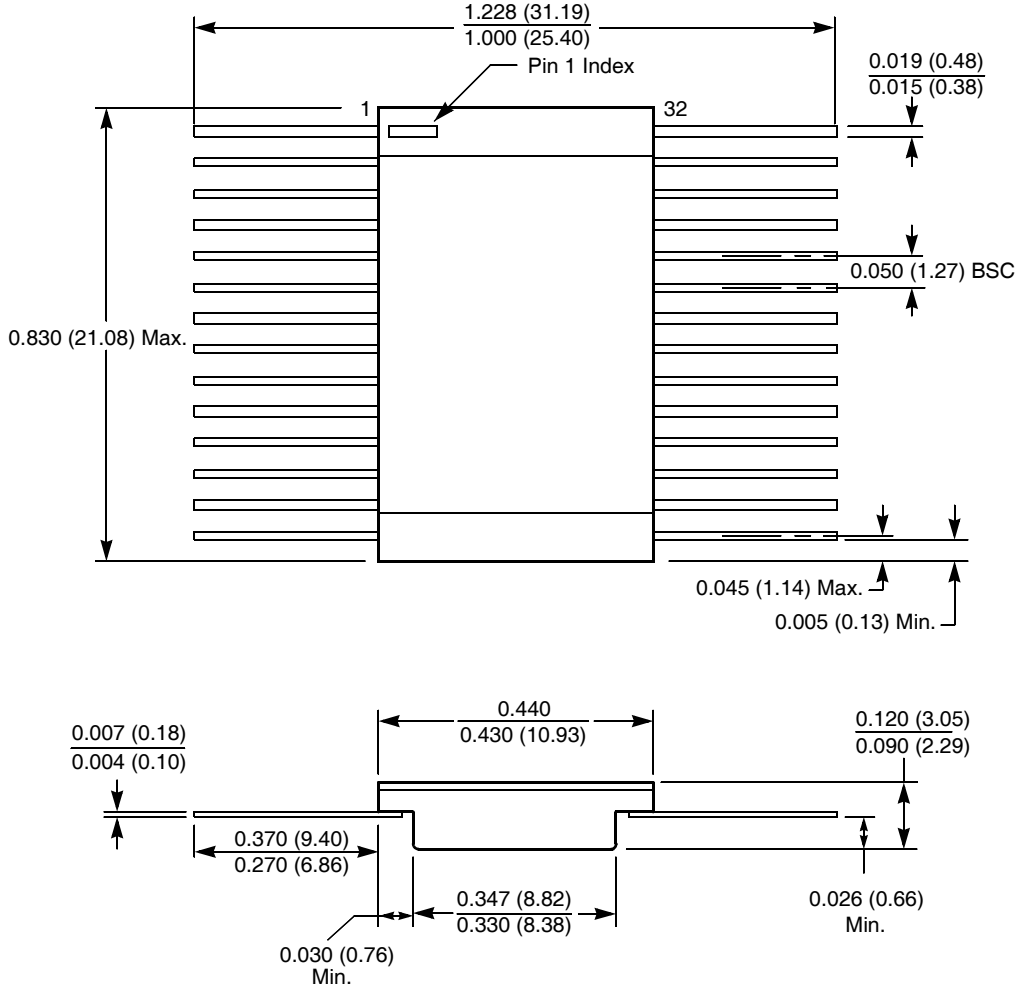
**NOTES:**

1. Index area: A notch or a pin one identification mark shall be located adjacent to pin one and shall be located within the shaded area shown. The manufacturer's identification shall not be used as a pin one identification mark.
2. The maximum limits of lead dimensions b and c or M shall be measured at the centroid of the finished lead surfaces, when solder dip or tin plate lead finish is applied.
3. Dimensions b1 and c1 apply to lead base metal only. Dimension M applies to lead plating and finish thickness.
4. Corner leads (1, N, N/2, and N/2+1) may be configured with a partial lead paddle. For this configuration dimension b3 replaces dimension b2.
5. This dimension allows for off-center lid, meniscus, and glass overrun.
6. Dimension Q shall be measured from the seating plane to the base plane.
7. Measure dimension S1 at all four corners.
8. N is the maximum number of terminal positions.
9. Dimensioning and tolerancing per ANSI Y14.5M - 1982.
10. Controlling dimension: INCH.

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Packaging Information

32-Lead Ceramic Flat Pack Type F

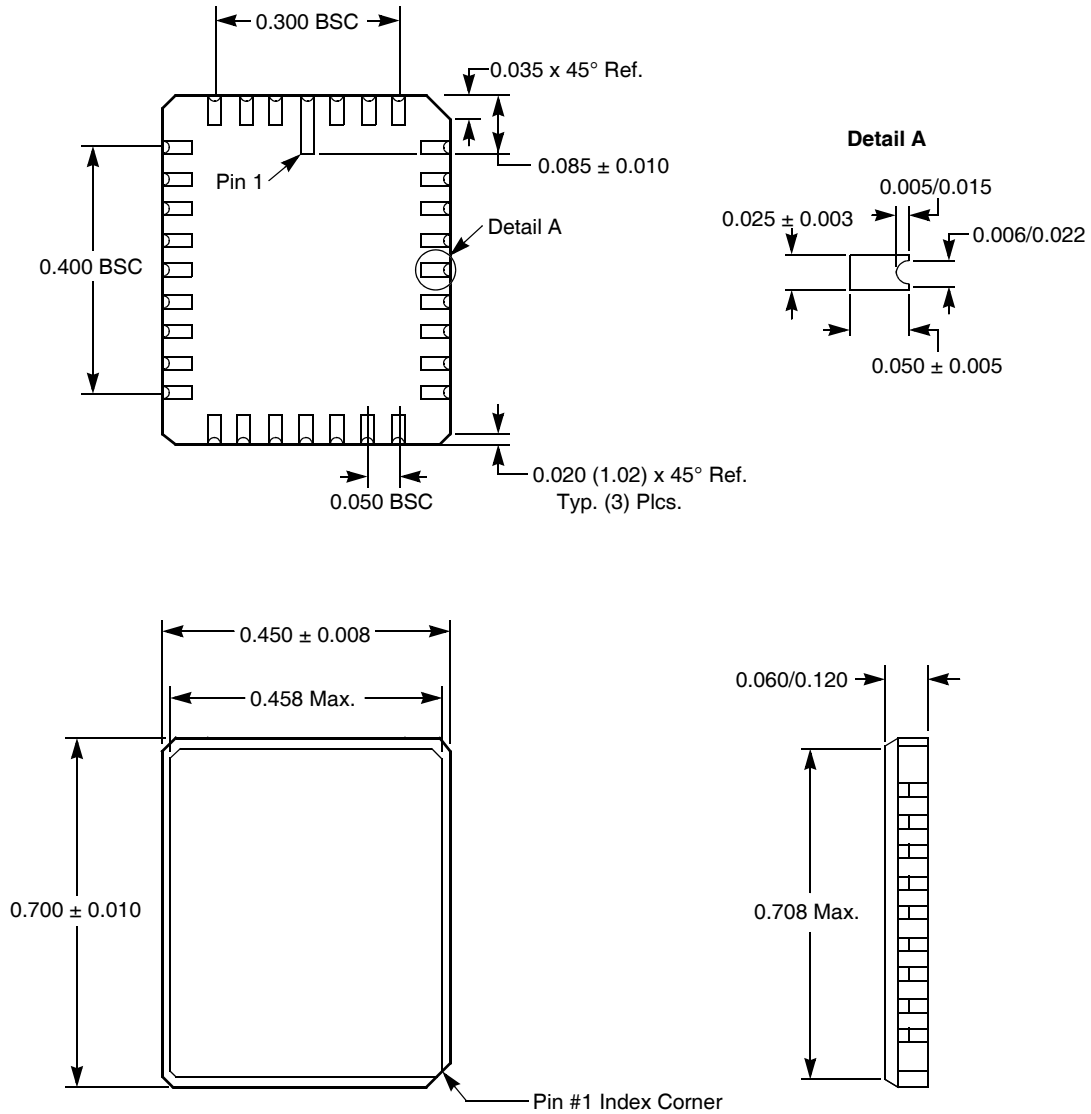


NOTE: ALL DIMENSIONS IN INCHES (IN PARENTHESES IN MILLIMETERS)



**Packaging Information**

**32-Pad Stretched Ceramic Leadless Chip Carrier Package Type N**

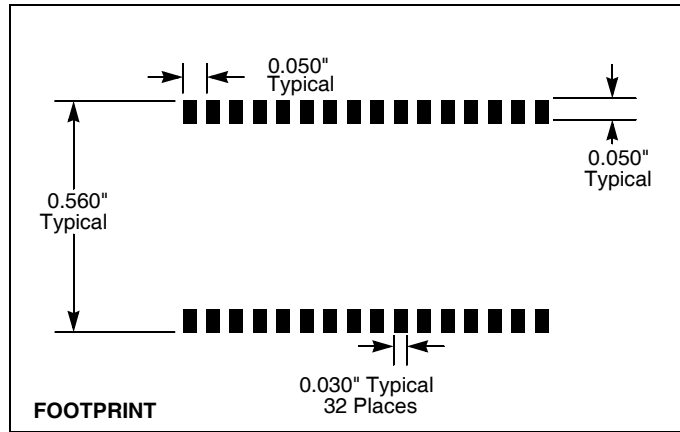
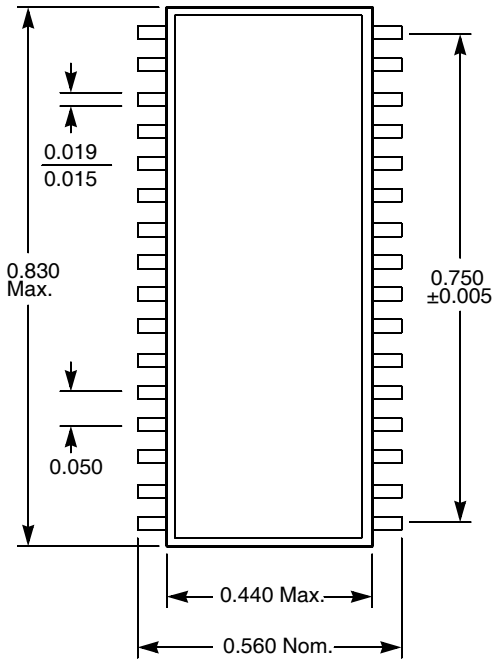
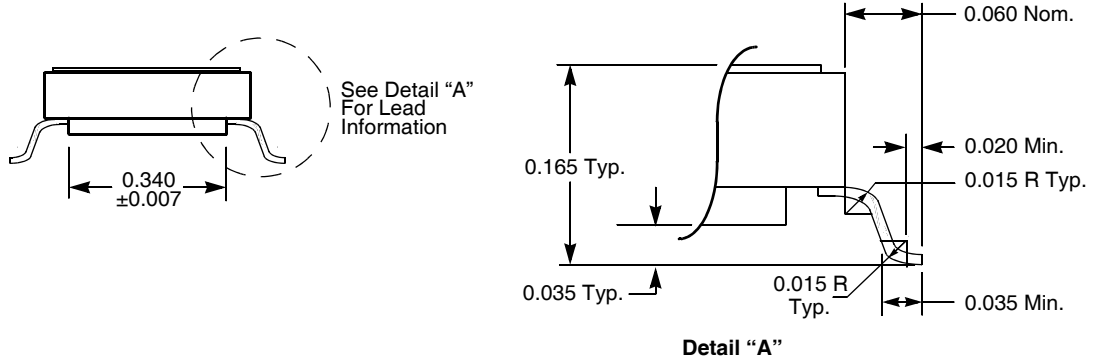


**NOTES:**

1. ALL DIMENSIONS IN INCHES (IN PARENTHESES IN MILLIMETERS)
2. TOLERANCE:  $\pm 1\%$  NLT  $\pm 0.005$  (0.127)

Packaging Information

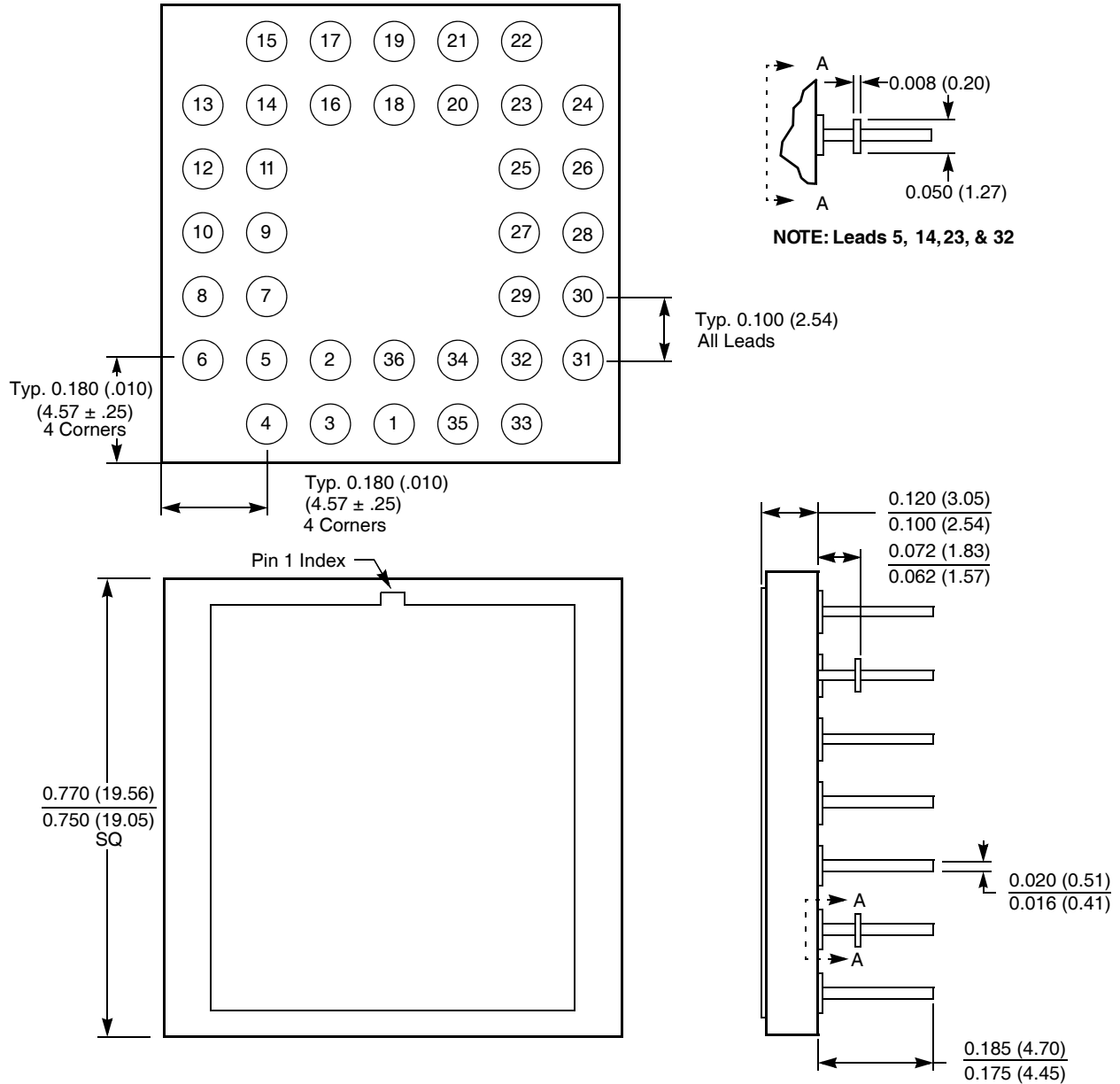
32-Lead Ceramic Small Outline Gull Wing Package Type R



- NOTES:**
1. ALL DIMENSIONS IN INCHES
  2. FORMED LEAD SHALL BE PLANAR WITH RESPECT TO ONE ANOTHER WITHIN 0.004 INCHES

Packaging Information

36 Lead Ceramic Pin Grid Array Package  
Package Code G36.760x760A



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