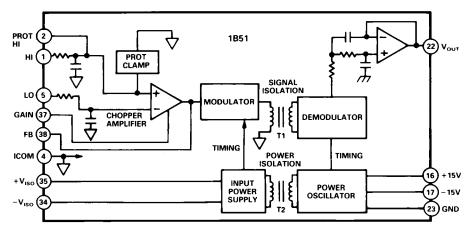
1B51 — SPECIFICATIONS (typical @ +25°C and $V_s = \pm 15V$ unless otherwise noted)

Model	1B51AN	1B51BN	
GAIN	_		
Gain Equation	$G = \left[1 + \frac{R_{FB}}{R_G}\right] \times 2$	*	OUTLINE DIMENSIONS
Gain Error Gain Temperature Coefficient ¹ Gain Nonlinearity	1% max 50ppm/°C ±0.035% (±0.05% max)	* * ±0.025% (±0.04% max)	Dimensions shown in inches and (mm).
OFFSET VOLTAGES Input Offset Voltage Initial, @ +25°C (Adjustable to Zero) vs. Temperature vs. Time, Noncumulative Output Offset Voltage Initial vs. Temperature	25μV (100μV max) ±0.1μV/°C (±0.5μV/°C max) ±1μV/month max -50mV -175μV/°C	* * -25mV -50μV/℃	0.15 0.15 (0.76) 0.15 0.15 0.15 0.76) 0.03 0.03 0.76) 0.75) 0
INPUT OFFSET CURRENT Initial vs. Temperature	0.6nA (2.5nA max) ±2.5pA/°C (12.5pA/°C max)	* *	
INPUT BIAS CURRENT Initial @ +25°C vs. Temperature	10nA 10pA/°C	*	(53.3) MAX
INPUT IMPEDANCE Power On Power Off	50MΩ 40kΩ min	* *	VIEW 1.60 (40.6)
INPUT VOLTAGE RANGE Linear Differential Input Max CMV, Input to Output ac, 60Hz, Continuous Continuous, dc CMR @ 60Hz, 1k\Omega Source Imbalance, G = 1000 NMR @ 60Hz Transient Protection	±10mV to ±5V 1500V rms ±2000V 160dB min 60dB min IEEE-STD 472 (SWC)	* * * *	$\begin{array}{c} 0.1 \\ (2.54) \\ TYP \\ 0.150 \\ (3.8) \\ TYP \\ TYP \\ 1 \\ 0.150 \\ (2.54) $
INPUT NOISE Voltage, 0.1Hz to 10Hz, 1kΩ Source Imbalance	lµV p-p	*	TYP
RATED OUTPUT Voltage, 2kΩ Load, min Current Output Noise, dc to 100kHz Impedance, dc	±10V ±5mA 1mV p-p 0.1Ω	* * *	PIN DESIGNATIONS
FREQUENCY RESPONSE Bandwidth, -3dB	dc to 3Hz	*	PIN DESIGNATION 1 HI
ISOLATED POWER Voltage, No Load Current Regulation, No Load to Full Load Ripple	±6.2V±5% 2mA 7.5% 250mV p-p	* * *	2 PROT HI 4 ICOM 5 LO 16 +15V 17 -15V 22 V _o
POWER SUPPLY Voltage, Rated Performance Voltage, Operating Current, Quiescent PSRR	±15V dc ±13.5V to ±18V +12mA @ +15V, -4mA @ -15V 0.1%/V	* * *	22 V ₀ 23 GND 34 -V _{ISO} 35 +V _{ISO} 37 GAIN 38 FB
ENVIRONMENTAL Temperature Range Rated Performance Operating Storage Relative Humidity	-25°C to +85°C -40°C to +85°C -40°C to +85°C 0 to 95% @ +60°C	* * * *	
CASE SIZE	1.00"×2.10"×0.35" (25.4×53.3×8.9)mm	*	

NOTES

*Specifications same as 1B51AN. See graph in text.

Specifications subject to change without notice.



Functional Block Diagram

INSIDE THE 1B51

Referring to the functional block diagram, the $\pm 15V$ power inputs provide power to both the output side circuitry and the power oscillator. The 25kHz power oscillator provides the timing information for the signal demodulator and drives power transformer T2 for the input side power supplies. The secondary winding of T2 is half wave rectified and filtered to create the input side bipolar unregulated supplies.

The signal input (HI) is single-pole filtered for noise rejection and antialiasing. The protection clamps limit the voltage at PROT HI to $\pm 8V$. Thus, a large voltage applied between HI and input common (I COM) appears mostly across the input resistor.

The chopper stabilized gain stage amplifies the differential input voltage with a gain set by external resistors. The voltage at the inverting input of the chopper stabilized amplifier (LO) should be equal to the input voltage at which the desired output voltage is zero. This is a true input referred zero suppression function.

The signal is amplitude modulated onto a 25kHz carrier and passed through the signal transformer T1. The synchronous demodulator restores the signal to the baseband. A two-pole active low pass stage filters out clock noise and completes a three-pole Butterworth filter formed with the input pole.

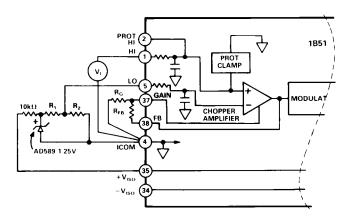


Figure 1. Input Gain Setting and Zero Supression

USING THE 1B51

Gain Setting:

The gain of the 1B51 is controlled on the input side by a pair of user provided resistors (see Figure 1). A feedback resistor of between $10k\Omega$ and $20k\Omega$ is required between the feedback pin (FB) and the gain pin. The gain setting resistor is connected between the gain pin and input side common (ICOM). The gain equation is

$$\mathbf{G} = \left[1 + \frac{\mathbf{R}_{\mathrm{FB}}}{\mathbf{R}_{\mathrm{G}}}\right] \times 2$$

Gains of 2-1000 can be achieved by adjusting this ratio.

The accuracy of the resistor values must be taken into account when calculating the initial gain accuracy of an application. The initial accuracy of the 1B51 must then be added to the resistor errors to predict the total accuracy. Likewise, the ratiometric temperature coefficient of the gain and feedback resistors must be added to the temperature coefficient of the 1B51 to predict the total resulting thermal drift.

It is possible to use a trimming potentiometer to correct for initial gain and system gain errors. The feedback resistor can be comprised of a resistor in series with a trimming potentiometer, as long as the total resistance remains between $10k\Omega$ and $20k\Omega$. Alternatively, the gain resistor can also be an adjustable resistor. In general, the greater the trim range, the coarser the resolution.

Zero Suppression:

Since the 1B51 is a differential input device, true input referred zero suppression can be accomplished (see Figure 1). A voltage reference powered by the input side power supplies is applied to the LO terminal. Since the transfer function is

$$V_0 = (V(HI) - V(LO)) \times GAIN$$

the input voltage for which the desired output is zero should be applied to the LO pin. The equation is

$$V_Z = 1.25(R_2/(R_1 + R_2))$$

Any drift of this input zero suppression voltage appears as offset drift, so a temperature stable reference should be used. The source impedance at the LO terminal should be kept below $1k\Omega$.

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Open Input Detection:

The 1B51 can sense an open thermocouple or broken input line with the addition of an external resistor. By connecting a 220M Ω resistor between the HI pin and the positive or negative isolated supply, an open input will cause a positive or negative full scale output, respectively.

To preserve the normal mode input protection capability of the 1B51, the resistor must be able to withstand 220Vac. A high voltage rating can be obtained by connecting lower value resistors in series.

Cold Junction Compensation:

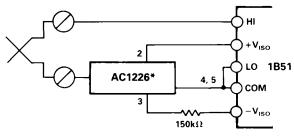
When using a thermocouple as an input to the 1B51, a second thermocouple junction is formed at the terminations of the thermocouple wires, commonly referred to as the cold junction. The measured output voltage of the sensor is the voltage generated by the thermocouple minus the voltage generated by the cold junction.

Since thermocouples are specified with 0V representing 0°C, it would be ideal to maintain the cold junction at 0°C. A more practical approach involves adding a temperature dependent voltage to the thermocouple signal so as to oppose the cold junction effects. This type of correction is known as cold junction compensation.

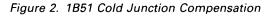
Many different methods are commonly used to implement cold junction compensation. Usually a thermistor or a semiconductor sensor is used to generate the cold junction voltage. The slope of the cold junction voltage must be the same as that of the thermocouple. Therefore, the cold junction compensation depends on the thermocouple type.

Sometimes, one cold junction compensation sensor is used by a number of thermocouple channels. This is accomplished by measuring the temperature of the connection block directly, and adding the appropriate voltage to each uncompensated thermo-couple channel after the gain has been taken. In all cases, the cold junction sensor must be in the thermal proximity with the connection block.

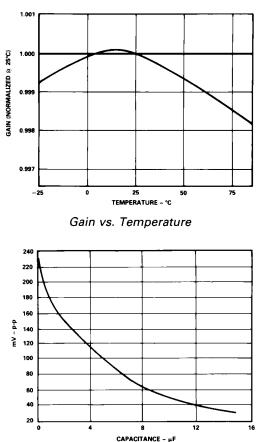
Figure 2 shows a monolithic cold junction compensation device used with the 1B51. The Analog Devices AC1226 measures the ambient temperature and generates the appropriate cold junction voltage for several different thermocouple types.



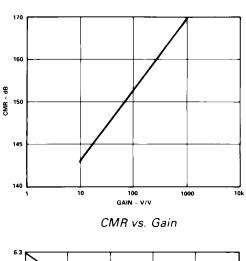
*PIN NUMBER DEPENDS ON THERMOCOUPLE TYPE SEE AC1226 DATA SHEET FOR DETAILS.

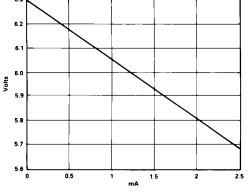


TYPICAL PERFORMANCE CURVES (@T_A = +25°C, $V_S = \pm 15V$)



+V_{ISO} Ripple vs. Capacitance





+V_{ISO} vs. Load

Mouser Electronics

Authorized Distributor

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