

4. Ordering information

Table 1. Ordering information

| Type number | Package | | |
|--------------|---------|--|----------|
| | Name | Description | Version |
| 74HC4046AD | SO16 | plastic small outline package; 16 leads; body width 3.9 mm | SOT109-1 |
| 74HCT4046AD | | | |
| 74HC4046ADB | SSOP16 | plastic shrink small outline package; 16 leads; body width 5.3 mm | SOT338-1 |
| 74HCT4046ADB | | | |
| 74HC4046APW | TSSOP16 | plastic thin shrink small outline package; 16 leads; body width 4.4 mm | SOT403-1 |

5. Block diagram

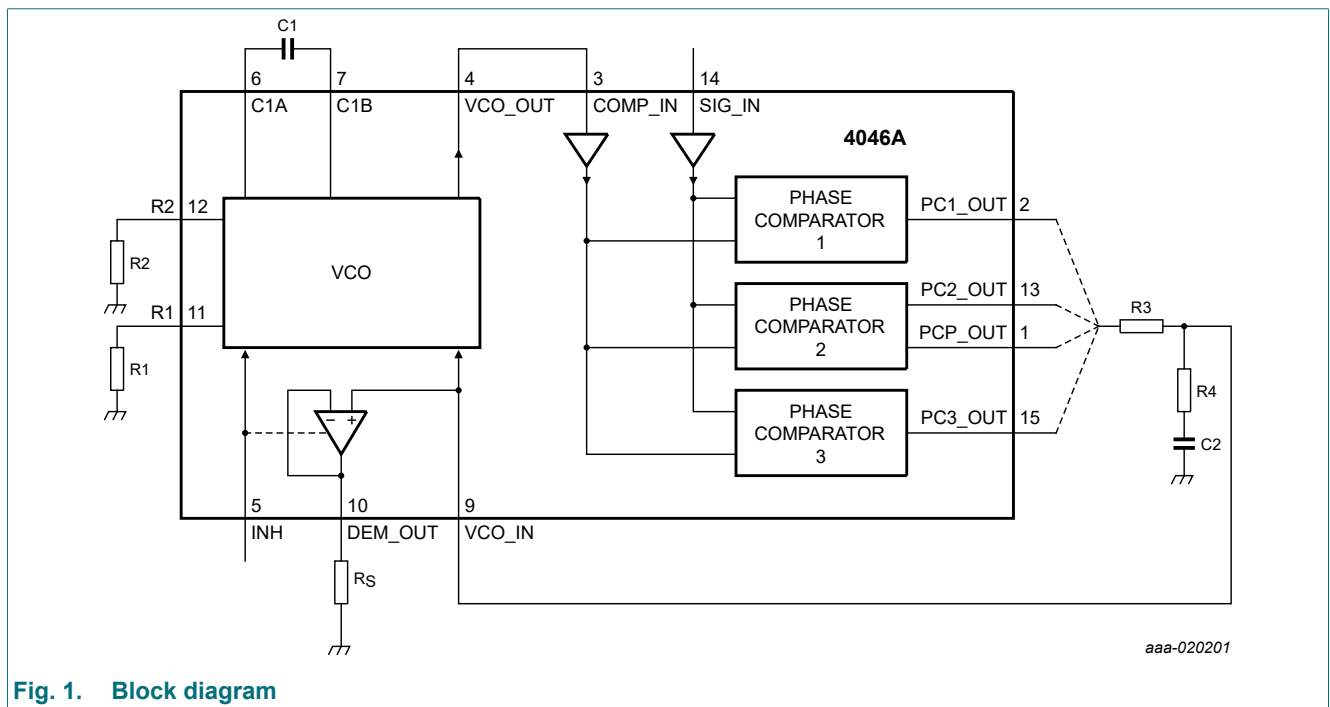


Fig. 1. Block diagram

6. Functional diagram

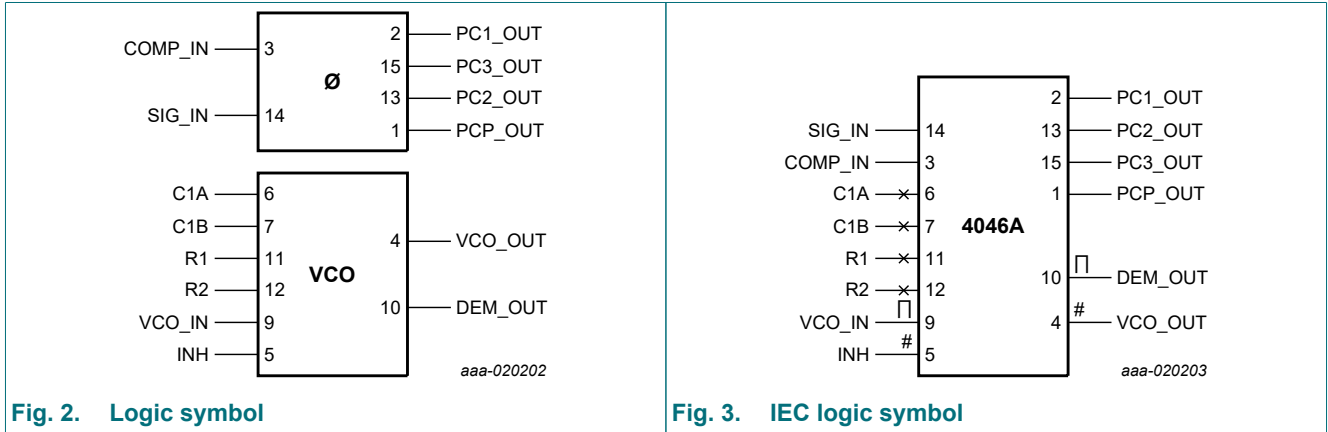


Fig. 2. Logic symbol

Fig. 3. IEC logic symbol

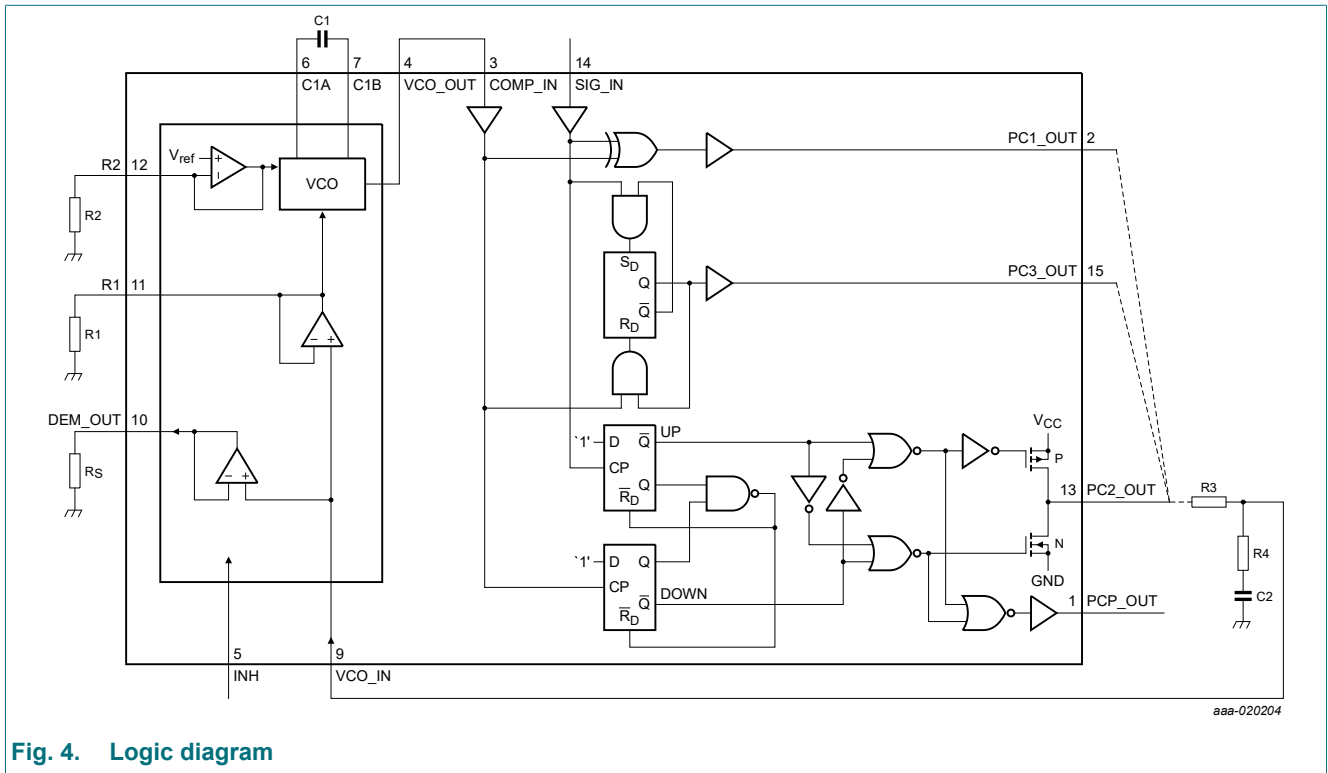
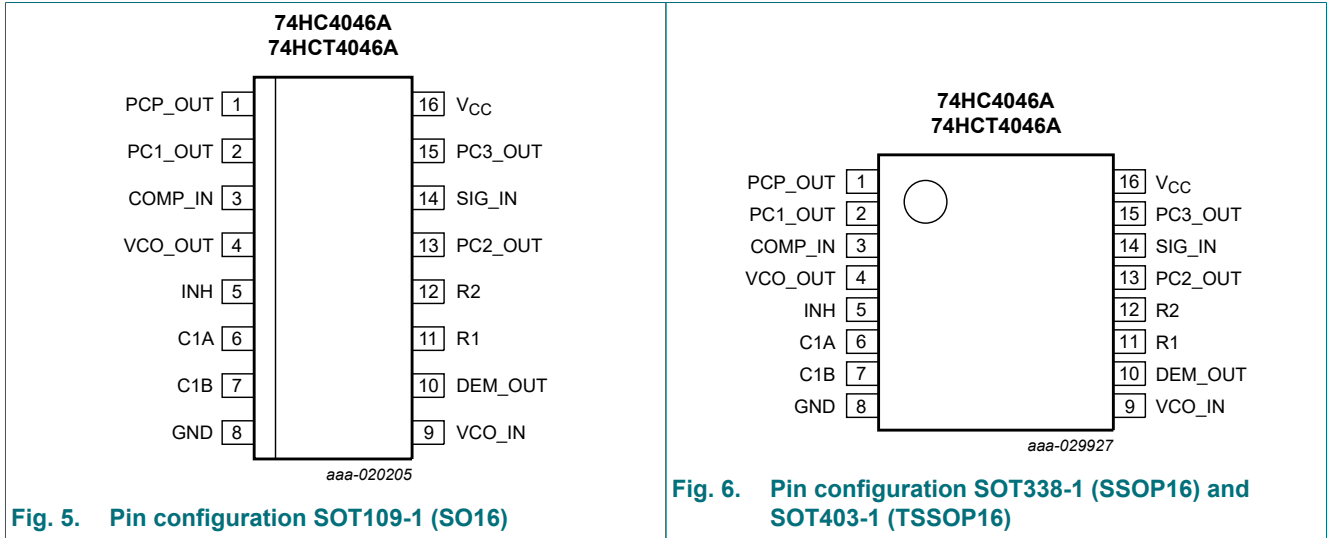


Fig. 4. Logic diagram

7. Pinning information

7.1. Pinning



7.2. Pin description

Table 2. Pin description

| Symbol | Pin | Description |
|-----------------|-----|-------------------------------|
| PCP_OUT | 1 | phase comparator pulse output |
| PC1_OUT | 2 | phase comparator 1 output |
| COMP_IN | 3 | comparator input |
| VCO_OUT | 4 | VCO output |
| INH | 5 | inhibit input |
| C1A | 6 | capacitor C1 connection A |
| C1B | 7 | capacitor C1 connection B |
| GND | 8 | ground (0 V) |
| VCO_IN | 9 | VCO input |
| DEM_OUT | 10 | demodulator output |
| R1 | 11 | resistor R1 connection |
| R2 | 12 | resistor R2 connection |
| PC2_OUT | 13 | phase comparator 2 output |
| SIG_IN | 14 | signal input |
| PC3_OUT | 15 | phase comparator 3 output |
| V _{CC} | 16 | supply voltage |

8. Functional description

The 74HC4046A; 74HCT4046A is a phase-locked-loop circuit that comprises a linear VCO and three different phase comparators (PC1, PC2 and PC3). It has a common signal input amplifier and a common comparator input (see Fig. 1). The signal input can be directly coupled to a large voltage signal, or indirectly coupled (with a series capacitor) to a small voltage signal. A self-bias input circuit keeps small voltage signals within the linear region of the input amplifiers. With a passive low-pass filter, the 74HC4046A; 74HCT4046A forms a second-order loop PLL. The excellent VCO linearity is achieved by the use of linear op amp techniques.

8.1. VCO

The VCO requires one external capacitor C1 (between pins C1A and C1B) and one external resistor R1 (between pins R1 and GND). Alternatively, it requires two external resistors R1 and R2 (between pins R1 and GND, and R2 and GND). Resistor R1 and capacitor C1 determine the frequency range of the VCO. Resistor R2 enables the VCO to have a frequency offset if necessary (see Fig. 4).

The high input impedance of the VCO simplifies the design of the low-pass filters by giving the designer a wide choice of resistor/capacitor ranges. In order not to load the low-pass filter, a demodulator output of the VCO input voltage is provided at pin DEM_OUT. In contrast to conventional techniques, where the DEM_OUT voltage is one threshold voltage lower than the VCO input voltage, the DEM_OUT voltage equals the VCO input. If DEM_OUT is used, a series resistor (R_s) should be connected from pin DEM_OUT to GND. If unused, DEM_OUT should be left open. The VCO output (pin VCO_OUT) can be connected directly to the comparator input (pin COMP_IN) or connected via a frequency divider. When the VCO input DC level is held constant, the VCO output signal has a duty cycle of 50 % (maximum expected deviation 1 %). A LOW-level at the inhibit input (pin INH) enables the VCO and demodulator, while a HIGH-level turns off both to minimize standby power consumption.

The only difference between the 74HC4046A and 74HCT4046A is the input level specification of the INH input. A HIGH on the INH input disables the VCO section. The input level specification for the SIG_IN and COMP_IN inputs are identical for both 74HC4046A and 74HCT4046A.

8.2. Phase comparators

The input signal can be coupled to the self-biasing amplifier at pin SIG_IN, when the signal swing is between the standard HC/T family input logic levels. Capacitive coupling is required for signals with smaller swings.

8.2.1. Phase Comparator 1 (PC1)

This circuit is an EXCLUSIVE-OR network. The signal and comparator input frequencies (f_i) must have a 50 % duty cycle to obtain the maximum locking range. The transfer characteristic of PC1, assuming ripple ($f_r = 2f_i$) is suppressed, is:

$$V_{\text{DEM_OUT}} = \frac{V_{\text{CC}}}{\pi} (\Phi_{\text{SIG_IN}} - \Phi_{\text{COMP_IN}})$$

where:

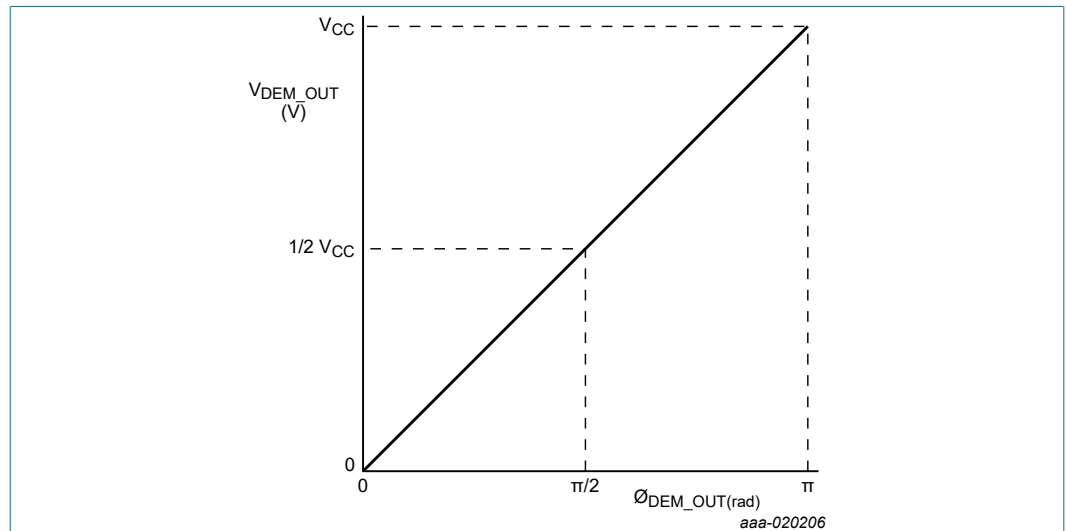
- $V_{\text{DEM_OUT}}$ is the demodulator output at pin DEM_OUT
- $V_{\text{DEM_OUT}} = V_{\text{PC1_OUT}}$ (via low-pass filter)

The phase comparator gain is: $K_p = \frac{V_{\text{CC}}}{\pi}$ (V/rad)

PC1 is fed to the VCO input via the low-pass filter and provided at the demodulator output at pin DEM_OUT (V_{DEM_OUT}). The average output voltage from PC1 is the result of the phase differences of signals (SIG_IN) and the comparator input (COMP_IN). These phase differences are shown in Fig. 7. The average of V_{DEM_OUT} is equal to $0.5V_{CC}$ when no signal or noise is present at SIG_IN. Using this input, the VCO oscillates at the center frequency (f_0). Typical waveforms for the PC1 loop locked at f_0 are shown in Fig. 8.

The frequency capture range ($2f_c$) is defined as the frequency range of input signals on which the PLL locks when it was initially out-of-lock. The frequency lock range ($2f_L$) is the frequency range of the input signals on which the loop stays locked when it was initially in lock. The capture range is smaller or equal to the lock range.

With PC1, the capture range depends on the low-pass filter characteristics and can be made as large as the lock range. This configuration remains locked even with very noisy input signals. Typical behavior of this type of phase comparator is that it can lock to input frequencies close to the harmonics of the VCO center frequency.



$$V_{DEM_OUT} = V_{PC1_OUT} = \frac{V_{CC}}{\pi} (\Phi_{SIG_IN} - \Phi_{COMP_IN})$$

$$\Phi_{DEM_OUT} = (\Phi_{SIG_IN} - \Phi_{COMP_IN})$$

Fig. 7. Phase comparator 1; average output voltage as a function of input phase difference

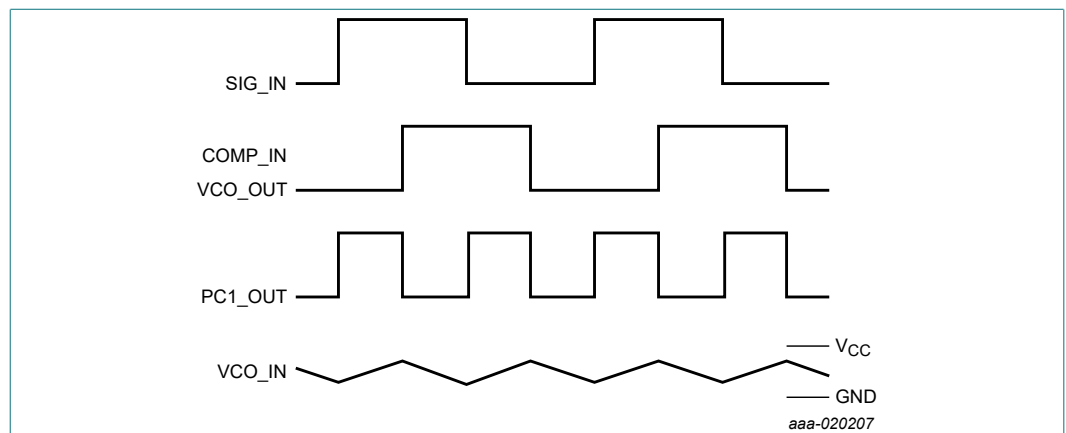


Fig. 8. Typical waveforms for PLL using phase comparator 1; loop-locked at f_0

8.2.2. Phase Comparator 2 (PC2)

PC2 is a positive edge-triggered phase and frequency detector. When the PLL uses this comparator, positive signal transitions control the loop and the duty cycles of SIG_IN and COMP_IN are not important. PC2 comprises two D-type flip-flops, control gating and a 3-state output stage. The circuit functions as an up-down counter (see Fig. 4) where SIG_IN causes an up-count and COMP_IN a down count. The transfer function of PC2, assuming ripple ($f_r = f_i$) is suppressed, is:

$$V_{\text{DEM_OUT}} = \frac{V_{\text{CC}}}{4\pi} (\Phi_{\text{SIG_IN}} - \Phi_{\text{COMP_IN}})$$

where:

- $V_{\text{DEM_OUT}}$ is the demodulator output at pin DEM_OUT
- $V_{\text{DEM_OUT}} = V_{\text{PC2_OUT}}$ (via low-pass filter)

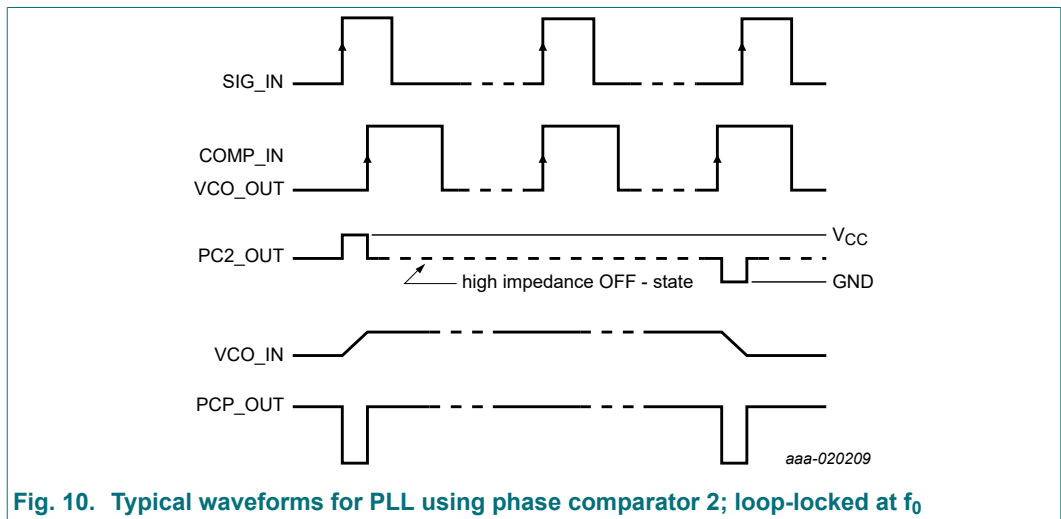
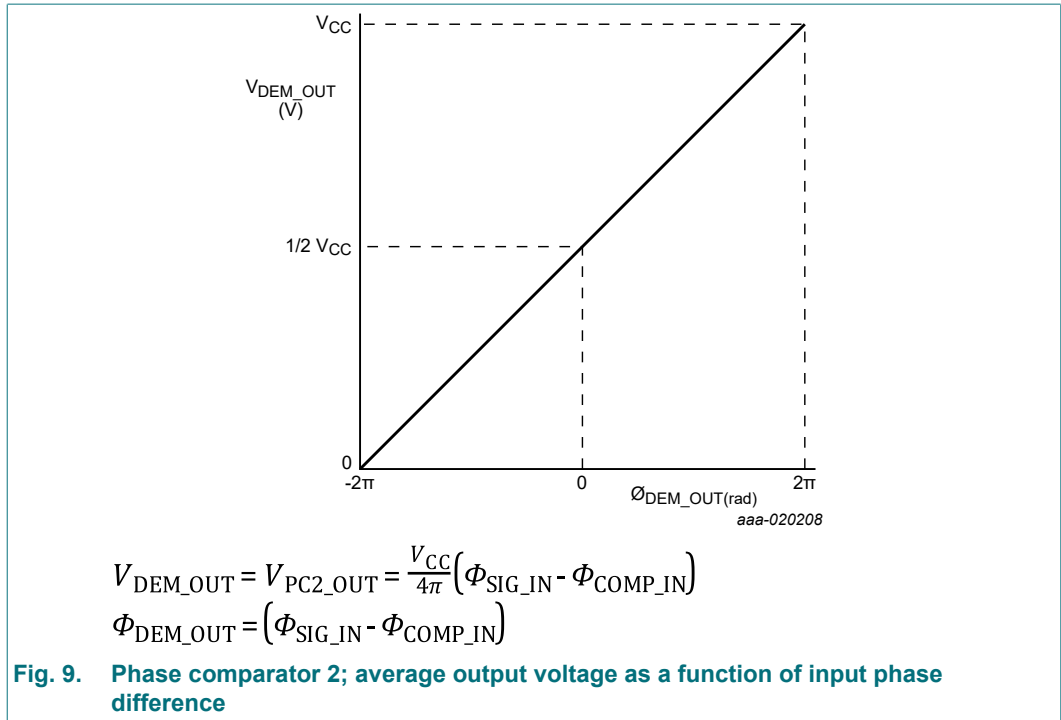
The phase comparator gain is: $K_p = \frac{V_{\text{CC}}}{4\pi} (\text{V/rad})$

$V_{\text{DEM_OUT}}$ is the resultant of the initial phase differences of SIG_IN and COMP_IN as shown in Fig. 9. Typical waveforms for the PC2 loop locked at f_o are shown in Fig. 10.

When the SIG_IN and COMP_IN frequencies are equal but the phase of SIG_IN leads that of COMP_IN, the p-type output driver at PC2_OUT is held 'ON'. The time that it is held 'ON' corresponds with the phase difference ($\Phi_{\text{DEM_OUT}}$). When the phase of SIG_IN lags that of COMP_IN, the n-type driver is held 'ON'.

When the SIG_IN frequency is higher than the COMP_IN frequency, the p-type output driver is held 'ON' for most of the input signal cycle time. For the remainder of the cycle time, both n- and p-type drivers are 'OFF' (3-state). If the SIG_IN frequency is lower than the COMP_IN frequency, the n-type driver is held 'ON' for most of the cycle. The voltage at capacitor (C2) of the low-pass filter, connected to PC2_OUT, varies until the phase and frequency of the signal and comparator inputs are equal. At this stable point, the voltage on C2 remains constant as the PC2 output is in 3-state and the VCO_IN input is in a high-impedance state. In this condition, the signal at the phase comparator pulse output (PCP_OUT) is a HIGH level and can be used for indicating a locked condition.

Thus for PC2 no phase difference exists between SIG_IN and COMP_IN over the full frequency range of the VCO. The power dissipation due to the low-pass filter is reduced because both n- and p-type output drivers are 'OFF' for most of the signal input cycle. The PLL lock range for this type of phase comparator is equal to the capture range and is independent of the low-pass filter. With no signal present at SIG_IN the VCO adjust, via PC2, to its lowest frequency.



8.2.3. Phase Comparator 3 (PC3)

PC3 is a positive edge-triggered sequential phase detector using an RS-type flip-flop. When the PLL is using this comparator, positive signal transitions control the loop and the duty factors of SIG_IN and COMP_IN are not important. The transfer characteristic of PC3, assuming ripple ($f_r = f_i$) is suppressed, is:

$$V_{\text{DEM_OUT}} = \frac{V_{\text{CC}}}{2\pi} (\Phi_{\text{SIG_IN}} - \Phi_{\text{COMP_IN}})$$

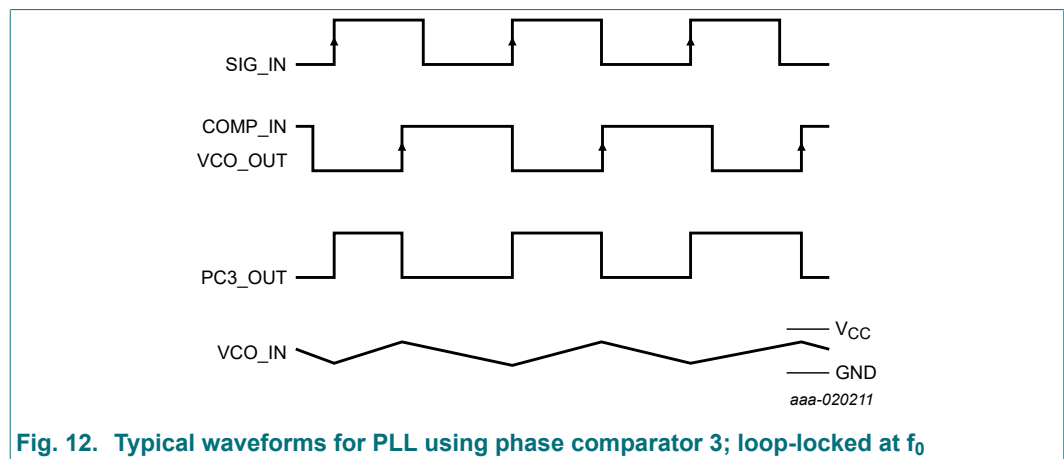
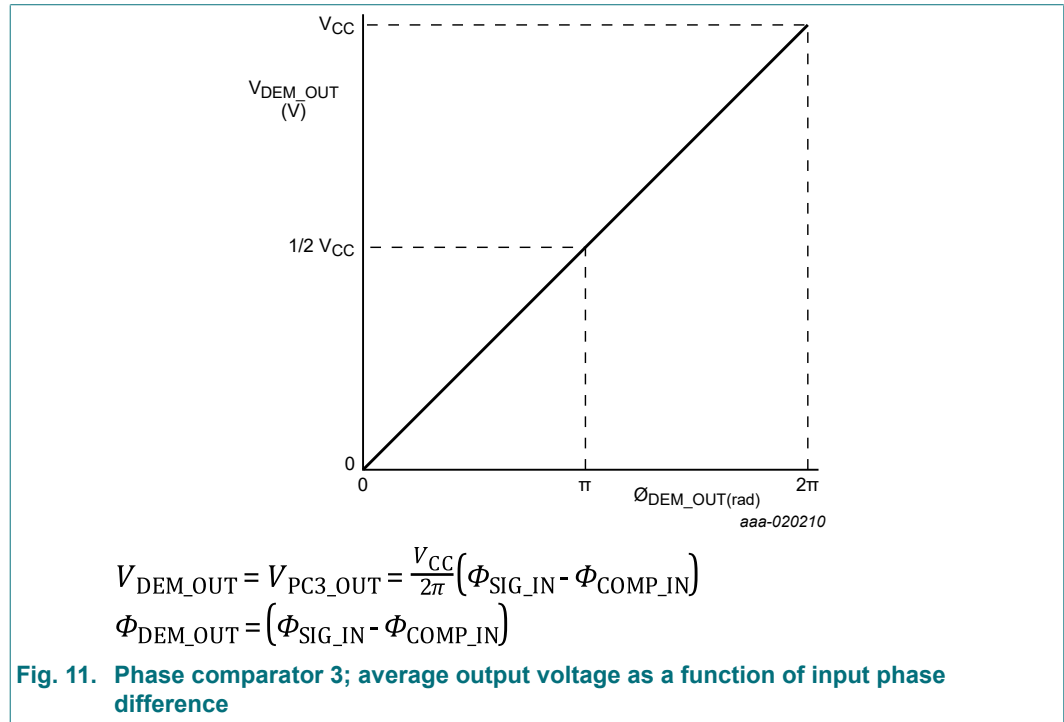
where:

- $V_{\text{DEM_OUT}}$ is the demodulator output at pin DEM_OUT
- $V_{\text{DEM_OUT}} = V_{\text{PC3_OUT}}$ (via low-pass filter)

The phase comparator gain is: $K_p = \frac{V_{\text{CC}}}{2\pi} (\text{V/rad})$

PC3 is fed to the VCO via the low-pass filter and present at the demodulator output at pin DEM_OUT. The average output from PC3 is the resultant of the phase differences of SIG_IN and COMP_IN, see Fig. 11. Typical waveforms for the PC3 loop locked at f_0 are shown in Fig. 12.

The phase-to-output response characteristic of PC3 (Fig. 11) differs from PC2 in that the phase angle between SIG_IN and COMP_IN varies between 0° and 360° . It is 180° at the center frequency. Also PC3 gives a greater voltage swing than PC2 for input phase differences. As a result, the ripple content of the VCO input signal is higher. The PLL lock range for this type of phase comparator and the capture range are dependent on the low-pass filter. With no signal present at SIG_IN, the VCO adjusts to its lowest frequency via PC3.



9. Limiting values

Table 3. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|-----------|-------------------------|--|------|----------|------|
| V_{CC} | supply voltage | | -0.5 | +7 | V |
| I_{IK} | input clamping current | $V_I < -0.5\text{ V}$ or $V_I > V_{CC} + 0.5\text{ V}$ | - | ± 20 | mA |
| I_{OK} | output clamping current | $V_O < -0.5\text{ V}$ or $V_O > V_{CC} + 0.5\text{ V}$ | - | ± 20 | mA |
| I_O | output current | $-0.5\text{ V} < V_O < V_{CC} + 0.5\text{ V}$ | - | ± 25 | mA |
| I_{CC} | supply current | | - | +50 | mA |
| I_{GND} | ground current | | -50 | - | mA |
| T_{stg} | storage temperature | | -65 | +150 | °C |
| P_{tot} | total power dissipation | $T_{amb} = -40\text{ °C}$ to $+125\text{ °C}$ [1] | - | 500 | mW |

- [1] For SO16 package: P_{tot} derates linearly with 8 mW/K above 70 °C.
For SSOP16 and TSSOP16 packages: P_{tot} derates linearly with 5.5 mW/K above 60 °C.

10. Recommended operating conditions

Table 4. Recommended operating conditions

| Symbol | Parameter | Conditions | 74HC4046A | | | 74HCT4046A | | | Unit |
|---------------------|-------------------------------------|-------------------------|-----------|------|----------|------------|------|----------|------|
| | | | Min | Typ | Max | Min | Typ | Max | |
| V_{CC} | supply voltage | | 3.0 | 5.0 | 6.0 | 4.5 | 5.0 | 5.5 | V |
| | | when VCO is not used | 2.0 | 5.0 | 6.0 | 4.5 | 5.0 | 5.5 | V |
| V_I | input voltage | | 0 | - | V_{CC} | 0 | - | V_{CC} | V |
| V_O | output voltage | | 0 | - | V_{CC} | 0 | - | V_{CC} | V |
| $\Delta t/\Delta V$ | input transition rise and fall rate | pin INH | | | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | - | 625 | - | - | - | ns/V |
| | | $V_{CC} = 4.5\text{ V}$ | - | 1.67 | 139 | - | 1.67 | 139 | ns/V |
| | | $V_{CC} = 6.0\text{ V}$ | - | - | 83 | - | - | - | ns/V |
| T_{amb} | ambient temperature | | -40 | +25 | +125 | -40 | +25 | +125 | °C |

11. Static characteristics

11.1. Static characteristics 74HC4046A

Table 5. Static characteristics 74HC4046A

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | 25 °C | | | -40 °C to +85 °C | | -40 °C to +125 °C | | Unit |
|---------------------------------|---------------------------|--|-------|------|------|------------------|------|-------------------|------|------|
| | | | Min | Typ | Max | Min | Max | Min | Max | |
| Phase comparator section | | | | | | | | | | |
| V _{IH} | HIGH-level input voltage | SIG_IN, COMP_IN; DC coupled | | | | | | | | |
| | | V _{CC} = 2.0 V | 1.5 | 1.2 | - | 1.5 | - | 1.5 | - | V |
| | | V _{CC} = 4.5 V | 3.15 | 2.4 | - | 3.15 | - | 3.15 | - | V |
| | | V _{CC} = 6.0 V | 4.2 | 3.2 | - | 4.2 | - | 4.2 | - | V |
| V _{IL} | LOW-level input voltage | SIG_IN, COMP_IN; DC coupled | | | | | | | | |
| | | V _{CC} = 2.0 V | - | 0.8 | 0.5 | - | 0.5 | - | 0.5 | V |
| | | V _{CC} = 4.5 V | - | 2.1 | 1.35 | - | 1.35 | - | 1.35 | V |
| | | V _{CC} = 6.0 V | - | 2.8 | 1.8 | - | 1.8 | - | 1.8 | V |
| V _{OH} | HIGH-level output voltage | PCP_OUT, PCn_OUT; V _I = V _{IH} or V _{IL} | | | | | | | | |
| | | I _O = -20 µA; V _{CC} = 2.0 V | 1.9 | 2.0 | - | 1.9 | - | 1.9 | - | V |
| | | I _O = -20 µA; V _{CC} = 4.5 V | 4.4 | 4.5 | - | 4.4 | - | 4.4 | - | V |
| | | I _O = -20 µA; V _{CC} = 6.0 V | 5.9 | 6.0 | - | 5.9 | - | 5.9 | - | V |
| | | I _O = -4 mA; V _{CC} = 4.5 V | 3.98 | 4.32 | - | 3.84 | - | 3.7 | - | V |
| | | I _O = -5.2 mA; V _{CC} = 6.0 V | 5.48 | 5.81 | - | 5.34 | - | 5.2 | - | V |
| V _{OL} | LOW-level output voltage | PCP_OUT, PCn_OUT; V _I = V _{IH} or V _{IL} | | | | | | | | |
| | | I _O = 20 µA; V _{CC} = 2.0 V | - | 0 | 0.1 | - | 0.1 | - | 0.1 | V |
| | | I _O = 20 µA; V _{CC} = 4.5 V | - | 0 | 0.1 | - | 0.1 | - | 0.1 | V |
| | | I _O = 20 µA; V _{CC} = 6.0 V | - | 0 | 0.1 | - | 0.1 | - | 0.1 | V |
| | | I _O = 4 mA; V _{CC} = 4.5 V | - | 0.15 | 0.26 | - | 0.33 | - | 0.4 | V |
| | | I _O = 5.2 mA; V _{CC} = 6.0 V | - | 0.16 | 0.26 | - | 0.33 | - | 0.4 | V |
| I _I | input leakage current | SIG_IN, COMP_IN; V _I = V _{CC} or GND | | | | | | | | |
| | | V _{CC} = 2.0 V | - | - | ±3 | - | ±4 | - | ±5 | µA |
| | | V _{CC} = 3.0 V | - | - | ±7 | - | ±9 | - | ±11 | µA |
| | | V _{CC} = 4.5 V | - | - | ±18 | - | ±23 | - | ±27 | µA |
| | | V _{CC} = 6.0 V | - | - | ±30 | - | ±38 | - | ±45 | µA |
| I _{OZ} | OFF-state output current | PC2_OUT; V _I = V _{IH} or V _{IL} ; V _O = V _{CC} or GND | | | | | | | | |
| | | V _{CC} = 6.0 V | - | - | ±0.5 | - | ±5 | - | ±10 | µA |
| R _I | input resistance | SIG_IN, COMP_IN; V _I at self-bias operating point; ΔV _I = 0.5 V; see Fig. 13 , Fig. 14 and Fig. 15 | | | | | | | | |
| | | V _{CC} = 3.0 V | - | 800 | - | - | - | - | - | kΩ |
| | | V _{CC} = 4.5 V | - | 250 | - | - | - | - | - | kΩ |
| | | V _{CC} = 6.0 V | - | 150 | - | - | - | - | - | kΩ |

| Symbol | Parameter | Conditions | 25 °C | | | -40 °C to +85 °C | | -40 °C to +125 °C | | Unit |
|---------------------|-----------------------------|--|-------|------|------|------------------|------|-------------------|------|------|
| | | | Min | Typ | Max | Min | Max | Min | Max | |
| VCO section | | | | | | | | | | |
| V _{IH} | HIGH-level input voltage | INH | | | | | | | | |
| | | V _{CC} = 3.0 V | 2.1 | 1.7 | - | 2.1 | - | 2.1 | - | V |
| | | V _{CC} = 4.5 V | 3.15 | 2.4 | - | 3.15 | - | 3.15 | - | V |
| | | V _{CC} = 6.0 V | 4.2 | 3.2 | - | 4.2 | - | 4.2 | - | V |
| V _{IL} | LOW-level input voltage | INH | | | | | | | | |
| | | V _{CC} = 3.0 V | - | 1.3 | 0.9 | - | 0.9 | - | 0.9 | V |
| | | V _{CC} = 4.5 V | - | 2.1 | 1.35 | - | 1.35 | - | 1.35 | V |
| | | V _{CC} = 6.0 V | - | 2.8 | 1.8 | - | 1.8 | - | 1.8 | V |
| V _{OH} | HIGH-level output voltage | VCO_OUT; V _I = V _{IH} or V _{IL} | | | | | | | | |
| | | I _O = -20 μA; V _{CC} = 3.0 V | 2.9 | 3.0 | - | 2.9 | - | 2.9 | - | V |
| | | I _O = -20 μA; V _{CC} = 4.5 V | 4.4 | 4.5 | - | 4.4 | - | 4.4 | - | V |
| | | I _O = -20 μA; V _{CC} = 6.0 V | 5.9 | 6.0 | - | 5.9 | - | 5.9 | - | V |
| | | I _O = -4 mA; V _{CC} = 4.5 V | 3.98 | 4.32 | - | 3.84 | - | 3.7 | - | V |
| V _{OL} | LOW-level output voltage | VCO_OUT; V _I = V _{IH} or V _{IL} | | | | | | | | |
| | | I _O = 20 μA; V _{CC} = 3.0 V | - | 0 | 0.1 | - | 0.1 | - | 0.1 | V |
| | | I _O = 20 μA; V _{CC} = 4.5 V | - | 0 | 0.1 | - | 0.1 | - | 0.1 | V |
| | | I _O = 20 μA; V _{CC} = 6.0 V | - | 0 | 0.1 | - | 0.1 | - | 0.1 | V |
| | | I _O = 4 mA; V _{CC} = 4.5 V | - | 0.15 | 0.26 | - | 0.33 | - | 0.4 | V |
| | | I _O = 5.2 mA; V _{CC} = 6.0 V | - | 0.16 | 0.26 | - | 0.33 | - | 0.4 | V |
| | | C1A, C1B; V _I = V _{IH} or V _{IL} | | | | | | | | |
| | | I _O = 4 mA; V _{CC} = 4.5 V | - | - | 0.40 | - | 0.47 | - | 0.54 | V |
| I _I | input leakage current | INH, VCO_IN; V _I = V _{CC} or GND | | | | | | | | |
| | | V _{CC} = 6.0 V | - | - | ±0.1 | - | ±1 | - | ±1 | μA |
| R1 | resistor 1 | V _{CC} = 3.0 V to 6.0 V | [1] | 3 | - | 300 | - | - | - | kΩ |
| R2 | resistor 2 | V _{CC} = 3.0 V to 6.0 V | [1] | 3 | - | 300 | - | - | - | kΩ |
| C1 | capacitor 1 | V _{CC} = 3.0 V to 6.0 V | | 40 | - | no limit | - | - | - | pF |
| V _{VCO_IN} | input voltage on pin VCO_IN | VCO_IN; over the range specified for R1; for linearity see Fig. 23 and Fig. 24 | | | | | | | | |
| | | V _{CC} = 3.0 V | 1.1 | - | 1.9 | - | - | - | - | V |
| | | V _{CC} = 4.5 V | 1.1 | - | 3.4 | - | - | - | - | V |
| | | V _{CC} = 6.0 V | 1.1 | - | 4.9 | - | - | - | - | V |

| Symbol | Parameter | Conditions | 25 °C | | | -40 °C to +85 °C | | -40 °C to +125 °C | | Unit |
|----------------------------|--------------------|--|-------|-----|-----|------------------|-----|-------------------|-----|------|
| | | | Min | Typ | Max | Min | Max | Min | Max | |
| Demodulator section | | | | | | | | | | |
| R _s | series resistance | at R _s > 300 kΩ, the leakage current can influence V _{DEM_OUT} | | | | | | | | |
| | | V _{CC} = 3.0 V to 6.0 V | 50 | - | 300 | - | - | - | - | kΩ |
| V _{offset} | offset voltage | VCO_IN to DEM_OUT; V _I = V _{VCO_IN} = 0.5V _{CC} ; values taken over R _s range; see Fig. 16 | | | | | | | | |
| | | V _{CC} = 3.0 V | - | ±30 | - | - | - | - | - | mV |
| | | V _{CC} = 4.5 V | - | ±20 | - | - | - | - | - | mV |
| | | V _{CC} = 6.0 V | - | ±10 | - | - | - | - | - | mV |
| R _{dyn} | dynamic resistance | DEM_OUT; V _{DEM_OUT} = 0.5V _{CC} | | | | | | | | |
| | | V _{CC} = 3.0 V to 6.0 V | - | 25 | - | - | - | - | - | Ω |
| General | | | | | | | | | | |
| I _{CC} | supply current | VCO disabled; COMP_IN, INH and SIG_IN at V _{CC} ; VCO_IN at GND; I _I at pins COMP_IN and SIGN_IN to be excluded | | | | | | | | |
| | | V _{CC} = 6.0 V | - | - | 8 | - | 80 | - | 160 | μA |
| C _I | input capacitance | INH | - | 3.5 | - | - | - | - | - | pF |

[1] The parallel value of R1 and R2 should be more than 2.7 kΩ. Optimum performance is achieved when R1 and/or R2 are/is > 10 kΩ.

11.2. Static characteristics 74HCT4046A

Table 6. Static characteristics 74HCT4046A

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | 25 °C | | | -40 °C to +85 °C | | -40 °C to +125 °C | | Unit |
|---------------------------------|---------------------------|---|-------|------|------|------------------|------|-------------------|------|------|
| | | | Min | Typ | Max | Min | Max | Min | Max | |
| Phase comparator section | | | | | | | | | | |
| V _{IH} | HIGH-level input voltage | SIG_IN, COMP_IN; DC coupled | | | | | | | | |
| | | V _{CC} = 4.5 V | 3.15 | 2.4 | - | 3.15 | - | 3.15 | - | V |
| V _{IL} | LOW-level input voltage | SIG_IN, COMP_IN; DC coupled | | | | | | | | |
| | | V _{CC} = 4.5 V | - | 2.1 | 1.35 | - | 1.35 | - | 1.35 | V |
| V _{OH} | HIGH-level output voltage | PCP_OUT, PCn_OUT; V _I = V _{IH} or V _{IL} | | | | | | | | |
| | | I _O = -20 μA; V _{CC} = 4.5 V | 4.4 | 4.5 | - | 4.4 | - | 4.4 | - | V |
| | | I _O = -4 μA; V _{CC} = 4.5 V | 3.98 | 4.32 | - | 3.84 | - | 3.7 | - | V |
| V _{OL} | LOW-level output voltage | PCP_OUT, PCn_OUT; V _I = V _{IH} or V _{IL} | | | | | | | | |
| | | I _O = 20 μA; V _{CC} = 4.5 V | - | 0 | 0.1 | - | 0.1 | - | 0.1 | V |
| | | I _O = 4 mA; V _{CC} = 4.5 V | - | 0.15 | 0.26 | - | 0.33 | - | 0.4 | V |
| I _I | input leakage current | SIG_IN, COMP_IN; V _I = V _{CC} or GND | | | | | | | | |
| | | V _{CC} = 5.5 V | - | - | ±30 | - | ±38 | - | ±45 | μA |
| I _{OZ} | OFF-state output current | PC2_OUT; V _I = V _{IH} or V _{IL} ; V _O = V _{CC} or GND | | | | | | | | |
| | | V _{CC} = 5.5 V | - | - | ±0.5 | - | ±5 | - | ±10 | μA |

| Symbol | Parameter | Conditions | 25 °C | | | -40 °C to +85 °C | | -40 °C to +125 °C | | Unit |
|----------------------------|-----------------------------|---|-------|------|----------|------------------|------|-------------------|------|------|
| | | | Min | Typ | Max | Min | Max | Min | Max | |
| R _I | input resistance | SIG_IN, COMP_IN; V _I at self-bias operating point; $\Delta V_I = 0.5$ V; see Fig. 13 , Fig. 14 and Fig. 15 | | | | | | | | |
| | | V _{CC} = 4.5 V | - | 250 | - | - | - | - | - | kΩ |
| VCO section | | | | | | | | | | |
| V _{IH} | HIGH-level input voltage | INH | | | | | | | | |
| | | V _{CC} = 4.5 V to 5.5 V | 2.0 | 1.6 | - | 2.0 | - | 2.0 | - | V |
| V _{IL} | LOW-level input voltage | INH | | | | | | | | |
| | | V _{CC} = 4.5 V to 5.5 V | - | 1.2 | 0.8 | - | 0.8 | - | 0.8 | V |
| V _{OH} | HIGH-level output voltage | VCO_OUT; V _I = V _{IH} or V _{IL} | | | | | | | | |
| | | I _O = -20 μA; V _{CC} = 4.5 V | 4.4 | 4.5 | - | 4.4 | - | 4.4 | - | V |
| | | I _O = -4 mA; V _{CC} = 4.5 V | 3.98 | 4.32 | - | 3.84 | - | 3.7 | - | V |
| V _{OL} | LOW-level output voltage | VCO_OUT; V _I = V _{IH} or V _{IL} | | | | | | | | |
| | | I _O = 20 μA; V _{CC} = 4.5 V | - | 0 | 0.1 | - | 0.1 | - | 0.1 | V |
| | | I _O = 4 mA; V _{CC} = 4.5 V | - | 0.15 | 0.26 | - | 0.33 | - | 0.4 | V |
| | | C1A, C1B; V _I = V _{IH} or V _{IL} | | | | | | | | |
| | | I _O = 4 mA; V _{CC} = 4.5 V | - | - | 0.40 | - | 0.47 | - | 0.54 | V |
| I _I | input leakage current | INH, VCO_IN; V _{CC} = 5.5 V; V _I = V _{CC} or GND | - | - | ±0.1 | - | ±1 | - | ±1 | μA |
| R1 | resistor 1 | V _{CC} = 4.5 V [1] | 3 | - | 300 | - | - | - | - | kΩ |
| R2 | resistor 2 | V _{CC} = 4.5 V [1] | 3 | - | 300 | - | - | - | - | kΩ |
| C1 | capacitor 1 | V _{CC} = 4.5 V | 40 | - | no limit | - | - | - | - | pF |
| V _{VCO_IN} | input voltage on pin VCO_IN | VCO_IN; over the range specified for R1; for linearity see Fig. 23 and Fig. 24 | | | | | | | | |
| | | V _{CC} = 4.5 V | 1.1 | - | 3.4 | - | - | - | - | V |
| Demodulator section | | | | | | | | | | |
| R _s | series resistance | at R _s > 300 kΩ, the leakage current can influence V _{DEM_OUT} | | | | | | | | |
| | | V _{CC} = 4.5 V | 50 | - | 300 | - | - | - | - | kΩ |
| V _{offset} | offset voltage | VCO_IN to DEM_OUT; V _I = V _{VCO_IN} = 0.5V _{CC} ; values taken over R _s range; see Fig. 16 | | | | | | | | |
| | | V _{CC} = 4.5 V | - | ±20 | - | - | - | - | - | mV |
| R _{dyn} | dynamic resistance | DEM_OUT; V _{DEM_OUT} = 0.5V _{CC} | | | | | | | | |
| | | V _{CC} = 4.5 V | - | 25 | - | - | - | - | - | Ω |
| General | | | | | | | | | | |
| I _{CC} | supply current | VCO disabled; COMP_IN, INH and SIG_IN at V _{CC} ; VCO_IN at GND; I _I at pins COMP_IN and SIGN_IN to be excluded | | | | | | | | |
| | | V _{CC} = 6 V | - | - | 8 | - | 80 | - | 160 | μA |

| Symbol | Parameter | Conditions | 25 °C | | | -40 °C to +85 °C | | -40 °C to +125 °C | | Unit |
|-----------------|---------------------------|--|-------|-----|-----|------------------|-----|-------------------|-----|---------|
| | | | Min | Typ | Max | Min | Max | Min | Max | |
| ΔI_{CC} | additional supply current | INH; $V_I = V_{CC} - 2.1$ V; COMP_IN and SIG_IN at V_{CC} ; VCO_IN at GND; I_I at pins COMP_IN and SIGN_IN to be excluded $V_{CC} = 4.5$ V to 5.5 V | - | 100 | 360 | - | 450 | - | 490 | μ A |
| C_I | input capacitance | INH | - | 3.5 | - | - | - | - | - | pF |

[1] The parallel value of R1 and R2 should be more than 2.7 k Ω . Optimum performance is achieved when R1 and/or R2 are/is > 10 k Ω .

11.3. Graphs

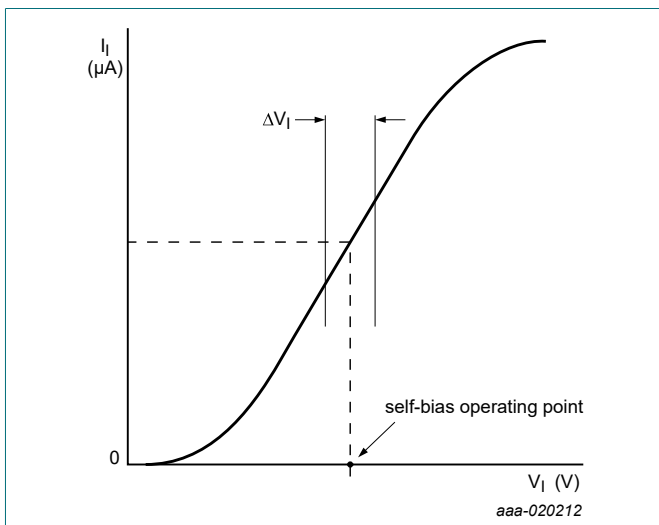


Fig. 13. Typical input resistance curve at SIG_IN and COMP_IN

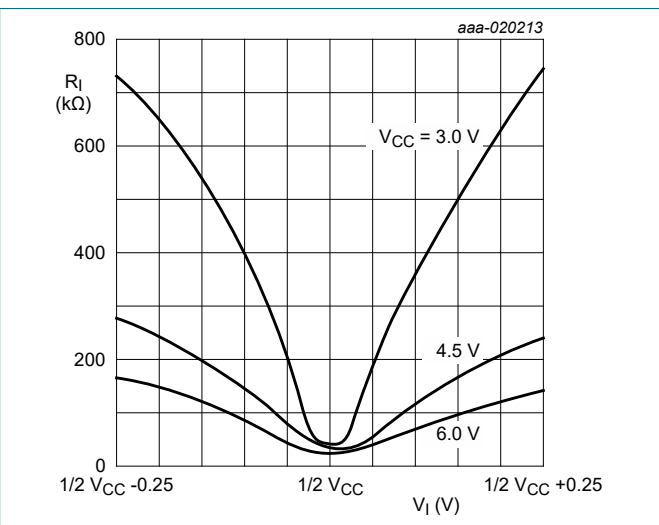


Fig. 14. Input resistance at SIG_IN, COMP_IN with $\Delta V_I = 0.5$ V at self-bias point

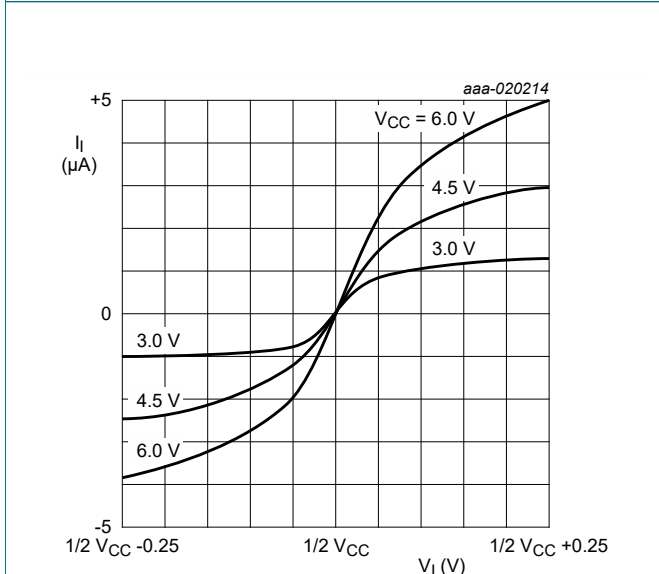


Fig. 15. Input current at SIG_IN, COMP_IN with $\Delta V_I = 0.5$ V at self-bias point

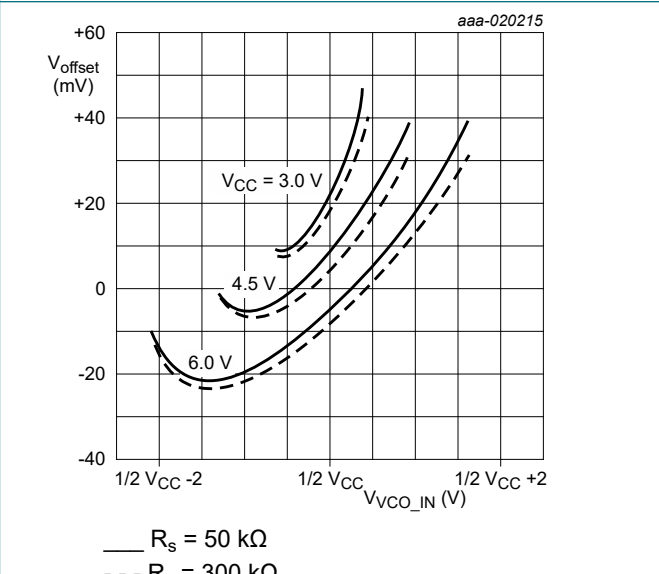


Fig. 16. Offset voltage at demodulator output as a function of V_{VCO_IN} and R_S

12. Dynamic characteristics

12.1. Dynamic characteristics 74HC4046A

Table 7. Dynamic characteristics 74HC4046A

$GND = 0\text{ V}$; $t_r = t_f = 6\text{ ns}$; $C_L = 50\text{ pF}$.

| Symbol | Parameter | Conditions | 25 °C | | | -40 °C to +85 °C | | | -40 °C to +125 °C | | Unit |
|---------------------------------|----------------------------|--|-------|-----|-----|------------------|-----|-----|-------------------|-----|------|
| | | | Min | Typ | Max | Min | Typ | Max | Min | Max | |
| Phase comparator section | | | | | | | | | | | |
| t_{pd} | propagation delay | SIG_IN, COMP_IN to PC1_OUT; see Fig. 17 [1] | | | | | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | 63 | 200 | - | - | 250 | - | 300 | ns |
| | | $V_{CC} = 4.5\text{ V}$ | - | 23 | 40 | - | - | 50 | - | 60 | ns |
| | | $V_{CC} = 6.0\text{ V}$ | - | 18 | 34 | - | - | 43 | - | 51 | ns |
| | | SIG_IN, COMP_IN to PCP_OUT; see Fig. 17 [1] | | | | | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | 96 | 340 | - | - | 425 | - | 510 | ns |
| | | $V_{CC} = 4.5\text{ V}$ | - | 35 | 68 | - | - | 85 | - | 102 | ns |
| | | $V_{CC} = 6.0\text{ V}$ | - | 28 | 58 | - | - | 72 | - | 87 | ns |
| | | SIG_IN, COMP_IN to PC3_OUT; see Fig. 17 [1] | | | | | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | 77 | 270 | - | - | 340 | - | 405 | ns |
| | | $V_{CC} = 4.5\text{ V}$ | - | 28 | 54 | - | - | 68 | - | 81 | ns |
| | | $V_{CC} = 6.0\text{ V}$ | - | 22 | 46 | - | - | 58 | - | 69 | ns |
| t_{en} | enable time | SIG_IN, COMP_IN to PC2_OUT; see Fig. 18 [1] | | | | | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | 83 | 280 | - | - | 350 | - | 420 | ns |
| | | $V_{CC} = 4.5\text{ V}$ | - | 30 | 56 | - | - | 70 | - | 84 | ns |
| | | $V_{CC} = 6.0\text{ V}$ | - | 24 | 48 | - | - | 60 | - | 71 | ns |
| t_{dis} | disable time | SIG_IN, COMP_IN to PC2_OUT; see Fig. 18 [1] | | | | | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | 99 | 325 | - | - | 405 | - | 490 | ns |
| | | $V_{CC} = 4.5\text{ V}$ | - | 36 | 65 | - | - | 81 | - | 98 | ns |
| | | $V_{CC} = 6.0\text{ V}$ | - | 29 | 55 | - | - | 69 | - | 83 | ns |
| t_t | transition time | PC1_OUT, PC3_OUT, PCP_OUT; see Fig. 17 [1] | | | | | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | 19 | 75 | - | - | 95 | - | 110 | ns |
| | | $V_{CC} = 4.5\text{ V}$ | - | 7 | 15 | - | - | 19 | - | 22 | ns |
| | | $V_{CC} = 6.0\text{ V}$ | - | 6 | 13 | - | - | 16 | - | 19 | ns |
| $V_{i(p-p)}$ | peak-to-peak input voltage | SIGN_IN, COMP_IN; AC coupled; $f_i = 1\text{ MHz}$ | | | | | | | | | |
| | | $V_{CC} = 2.0\text{ V}$ | - | 9 | - | - | - | - | - | - | mV |
| | | $V_{CC} = 3.0\text{ V}$ | - | 11 | - | - | - | - | - | - | mV |
| | | $V_{CC} = 4.5\text{ V}$ | - | 15 | - | - | - | - | - | - | mV |
| | | $V_{CC} = 6.0\text{ V}$ | - | 33 | - | - | - | - | - | - | mV |

| Symbol | Parameter | Conditions | 25 °C | | | -40 °C to +85 °C | | | -40 °C to +125 °C | | Unit |
|--------------------|--------------------------------------|--|-------|------|-----|------------------|------|-----|-------------------|-----|------|
| | | | Min | Typ | Max | Min | Typ | Max | Min | Max | |
| VCO section | | | | | | | | | | | |
| f ₀ | center frequency | V _{VCO_IN} = 0.5V _{CC} ; duty cycle = 50 %; R1 = 3 kΩ; R2 = ∞ Ω; C1 = 40 pF; see Fig. 21 and Fig. 22 | | | | | | | | | |
| | | V _{CC} = 3.0 V | 7.0 | 10.0 | - | - | - | - | - | - | MHz |
| | | V _{CC} = 4.5 V | 11.0 | 17.0 | - | - | - | - | - | - | MHz |
| | | V _{CC} = 5.0 V | - | 19.0 | - | - | - | - | - | - | MHz |
| | | V _{CC} = 6.0 V | 13.0 | 21.0 | - | - | - | - | - | - | MHz |
| Δf/f | relative frequency variation | R1 = 100 kΩ; R2 = ∞ Ω; C1 = 100 pF; see Fig. 23 and Fig. 24 | | | | | | | | | |
| | | V _{CC} = 3.0 V | - | 1.0 | - | - | - | - | - | - | % |
| | | V _{CC} = 4.5 V | - | 0.4 | - | - | - | - | - | - | % |
| | | V _{CC} = 6.0 V | - | 0.3 | - | - | - | - | - | - | % |
| Δf/ΔT | frequency variation with temperature | V _{VCO_IN} = 0.5V _{CC} ; R1 = 100 kΩ; R2 = ∞ Ω; C1 = 100 pF; see Fig. 19 and Fig. 20 | | | | | | | | | |
| | | V _{CC} = 3.0 V | - | - | - | - | 0.20 | - | - | - | %/K |
| | | V _{CC} = 4.5 V | - | - | - | - | 0.15 | - | - | - | %/K |
| | | V _{CC} = 6.0 V | - | - | - | - | 0.14 | - | - | - | %/K |
| δ | duty cycle | VCO_OUT; V _{CC} = 3.0 V to 6.0 V | - | 50 | - | - | - | - | - | - | % |
| General | | | | | | | | | | | |
| C _{PD} | power dissipation capacitance | [2][3] | - | 24 | - | - | - | - | - | - | pF |

- [1] t_{pd} is the same as t_{PLH} and t_{PHL}. t_{dis} is the same as t_{PLZ} and t_{PHZ}. t_{en} is the same as t_{PZL} and t_{PZH}. t_t is the same as t_{TLH} and t_{THL}.
- [2] Applies to the phase comparator section only (VCO disabled). For power dissipation of the VCO and demodulator sections, see Fig. 25, Fig. 26 and Fig. 27
- [3] C_{PD} is used to determine the dynamic power dissipation (P_D in μW).
 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma(C_L \times V_{CC}^2 \times f_o)$ where:
 f_i = input frequency in MHz;
 f_o = output frequency in MHz;
 C_L = output load capacitance in pF;
 V_{CC} = supply voltage in V;
 N = total load switching outputs;
 Σ(C_L × V_{CC}² × f_o) = sum of outputs.

12.2. Dynamic characteristics 74HCT4046A

Table 8. Dynamic characteristics 74HCT4046A

GND = 0 V; $t_r = t_f = 6$ ns; $C_L = 50$ pF.

| Symbol | Parameter | Conditions | 25 °C | | | -40 °C to +85 °C | | -40 °C to +125 °C | | Unit |
|---------------------------------|--------------------------------------|---|-------|------|-----|------------------|-----|-------------------|-----|------|
| | | | Min | Typ | Max | Min | Max | Min | Max | |
| Phase comparator section | | | | | | | | | | |
| t_{pd} | propagation delay | $V_{CC} = 4.5$ V; see Fig. 17 [1] | | | | | | | | |
| | | SIG_IN, COMP_IN to PC1_OUT | - | 23 | 40 | - | 50 | - | 60 | ns |
| | | SIG_IN, COMP_IN to PCP_OUT | - | 35 | 68 | - | 85 | - | 102 | ns |
| | | SIG_IN, COMP_IN to PC3_OUT | - | 28 | 54 | - | 68 | - | 81 | ns |
| t_{en} | enable time | SIG_IN, COMP_IN to PC2_OUT; $V_{CC} = 4.5$ V; see Fig. 18 [1] | - | 30 | 56 | - | 70 | - | 84 | ns |
| t_{dis} | disable time | SIG_IN, COMP_IN to PC2_OUT; $V_{CC} = 4.5$ V; see Fig. 18 [1] | - | 36 | 65 | - | 81 | - | 98 | ns |
| t_t | transition time | PC1_OUT, PC3_OUT, PCP_OUT; $V_{CC} = 4.5$ V; see Fig. 17 [1] | - | 7 | 15 | - | 19 | - | 22 | ns |
| $V_{i(p-p)}$ | peak-to-peak input voltage | SIGN_IN, COMP_IN; AC coupled; $V_{CC} = 4.5$ V; $f_i = 1$ MHz | - | 15 | - | - | - | - | - | mV |
| VCO section | | | | | | | | | | |
| f_0 | center frequency | $V_{VCO_IN} = 0.5V_{CC}$; duty cycle = 50 %; $R1 = 3$ k Ω ; $R2 = \infty$ Ω ; $C1 = 40$ pF; see Fig. 21 and Fig. 22 | | | | | | | | |
| | | $V_{CC} = 4.5$ V | 11.0 | 17.0 | - | - | - | - | - | MHz |
| | | $V_{CC} = 5.0$ V | - | 19.0 | - | - | - | - | - | MHz |
| $\Delta f/f$ | relative frequency variation | $R1 = 100$ k Ω ; $R2 = \infty$ Ω ; $C1 = 100$ pF; $V_{CC} = 4.5$ V; see Fig. 23 and Fig. 24 | - | 0.4 | - | - | - | - | - | % |
| $\Delta f/\Delta T$ | frequency variation with temperature | $V_{VCO_IN} = 0.5V_{CC}$; $R1 = 100$ k Ω ; $R2 = \infty$ Ω ; $C1 = 100$ pF; $V_{CC} = 4.5$ V; see Fig. 19 and Fig. 20 | - | - | - | 0.15 | - | - | - | %/K |
| δ | duty cycle | VCO_OUT; $V_{CC} = 4.5$ V | - | 50 | - | - | - | - | - | % |
| General | | | | | | | | | | |
| C_{PD} | power dissipation capacitance | [2][3] | - | 24 | - | - | - | - | - | pF |

[1] t_{pd} is the same as t_{PLH} and t_{PHL} . t_{dis} is the same as t_{PLZ} and t_{PHZ} . t_{en} is the same as t_{PZL} and t_{PZH} . t_t is the same as t_{TLH} and t_{THL} .

[2] Applies to the phase comparator section only (VCO disabled).

For power dissipation of the VCO and demodulator sections, see Fig. 25, Fig. 26 and Fig. 27

[3] C_{PD} is used to determine the dynamic power dissipation (P_D in μ W).

$P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma(C_L \times V_{CC}^2 \times f_o)$ where:

f_i = input frequency in MHz;

f_o = output frequency in MHz;

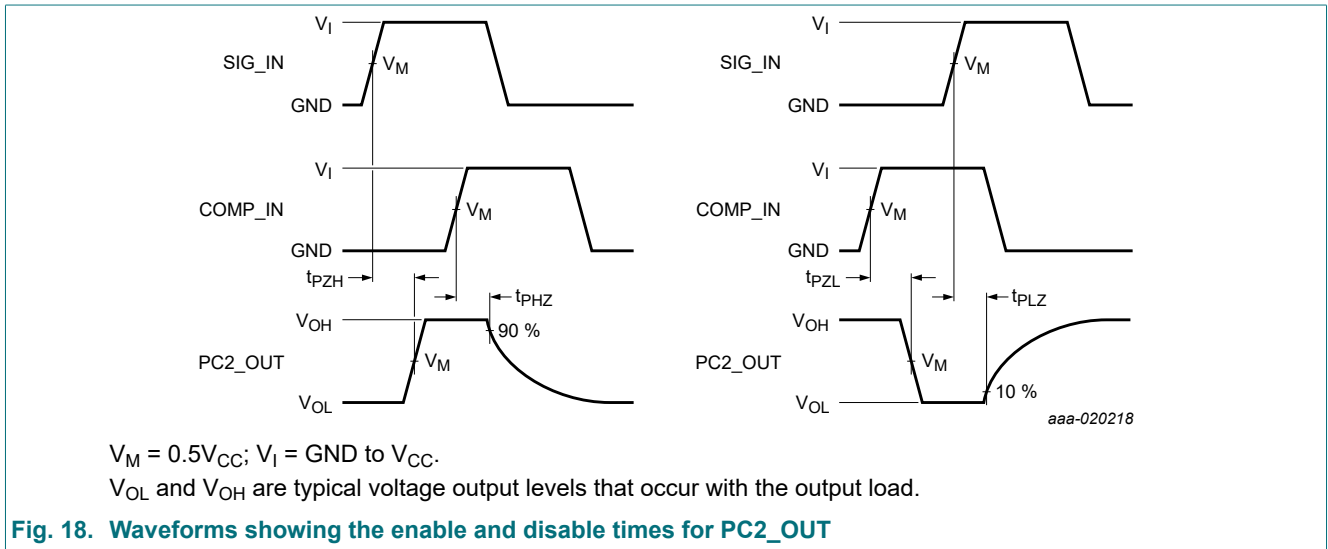
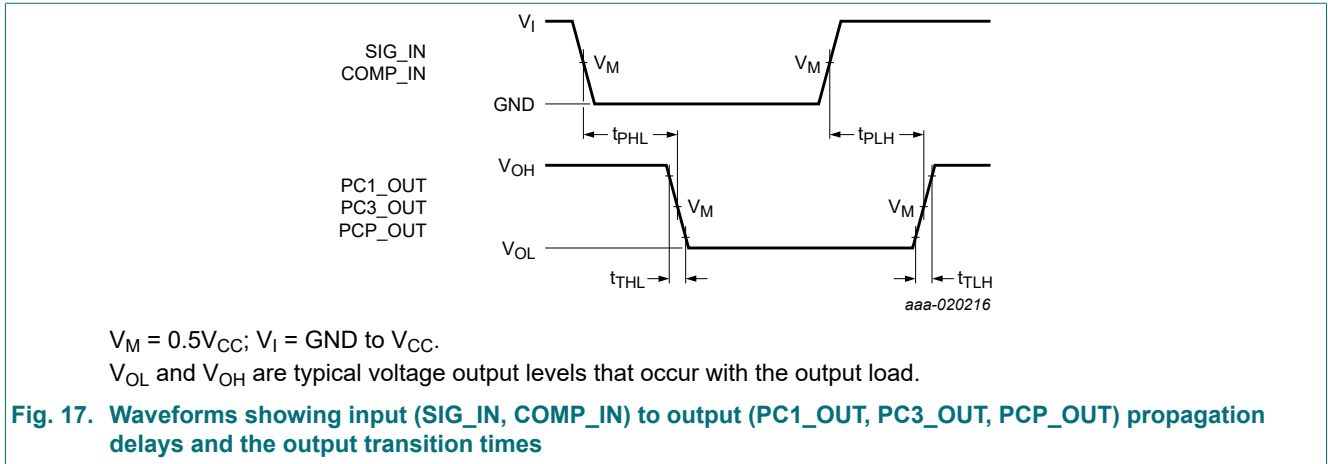
C_L = output load capacitance in pF;

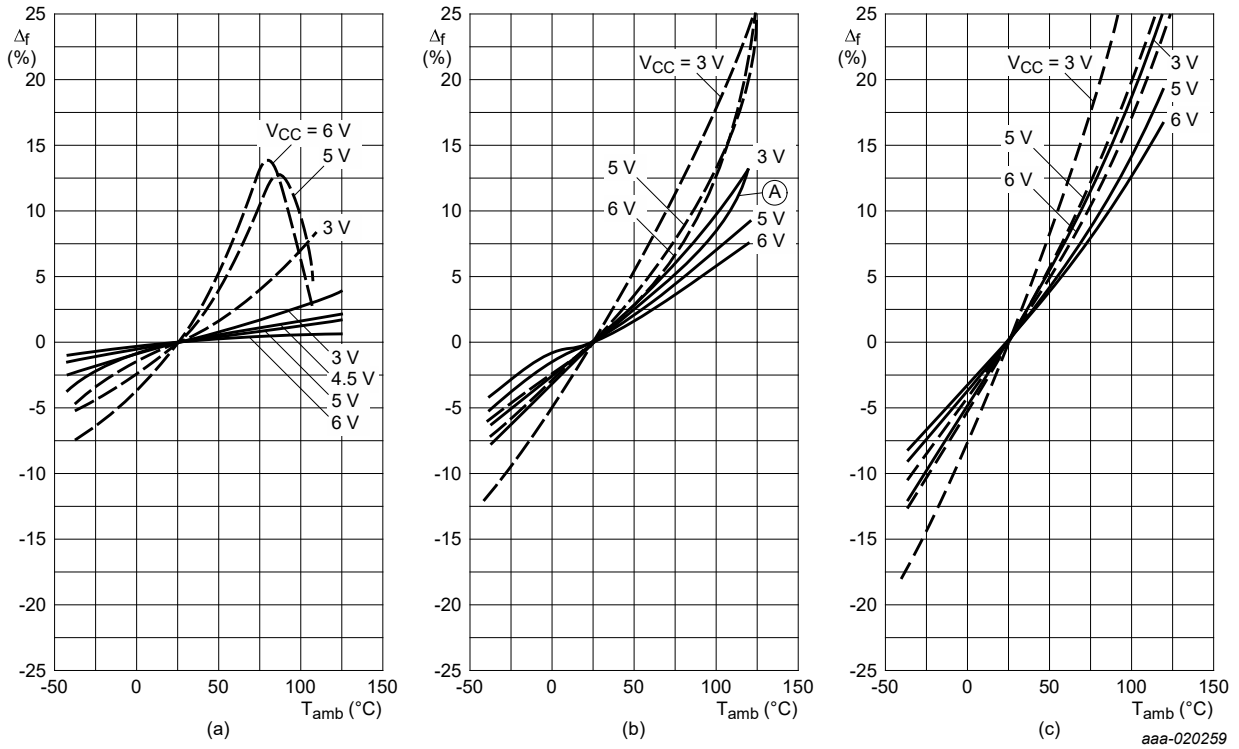
V_{CC} = supply voltage in V;

N = total load switching outputs;

$\Sigma(C_L \times V_{CC}^2 \times f_o)$ = sum of outputs.

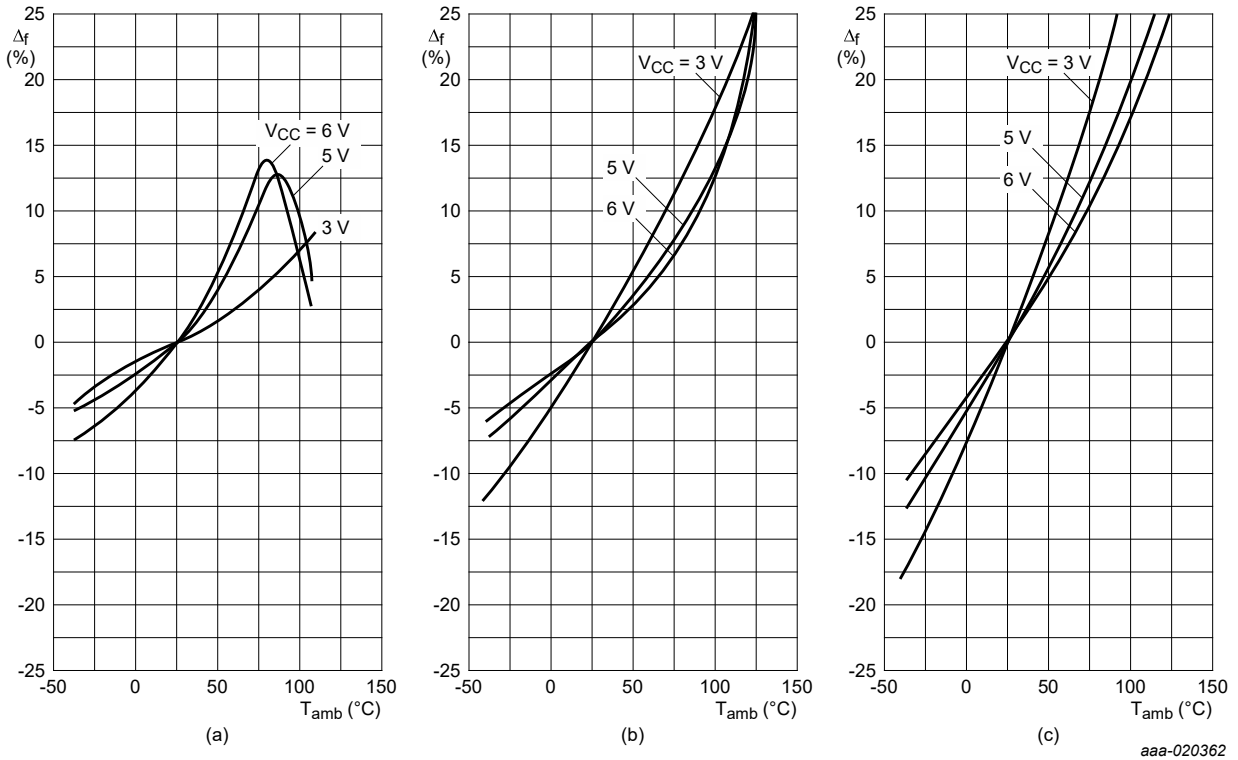
12.3. Waveforms and graphs





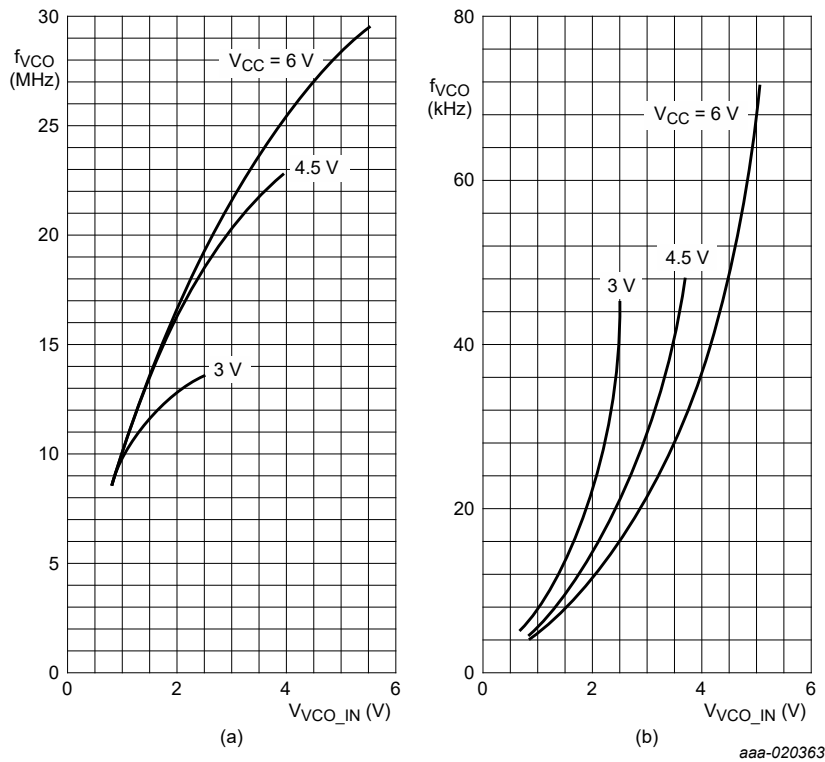
To obtain optimum temperature stability, C1 must be as small as possible but larger than 100 pF.
 In (b), the frequency stability for R1 = R2 = 10 kΩ at 5 V is also given (curve A). The total VCO bias current sets this curve, and is not simply the addition of the two 10 kΩ stability curves. C1 = 100 pF; V_{VCO_IN} = 0.5V_{CC}; This curve is set as follows:
 ___ Without offset R2 = ∞ Ω: (a) R1 = 3 kΩ; (b) R1 = 10 kΩ; (c) R1 = 300 kΩ.
 - - - With offset R1 = ∞ Ω: (a) R2 = 3 kΩ; (b) R2 = 10 kΩ; (c) R2 = 300 kΩ.

Fig. 19. Frequency stability of the VCO as a function of ambient temperature



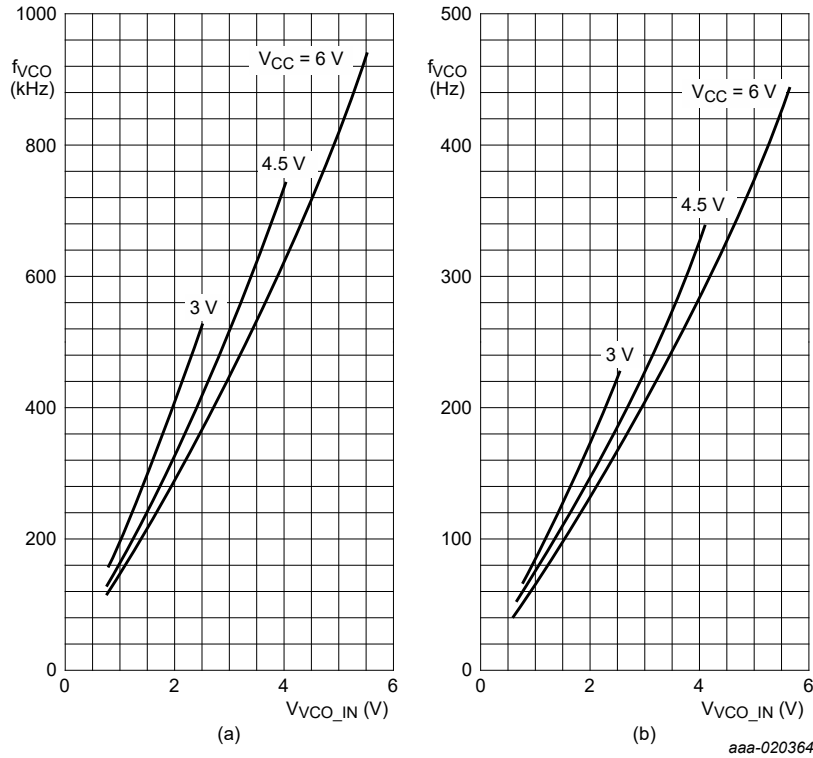
To obtain optimum temperature stability, C1 must be as small as possible but larger than 100 pF.
 ___ With offset; $R1 = \infty \Omega$: (a) $R2 = 3k\Omega$; (b) $R2 = 10k\Omega$; (c) $R2 = 300k\Omega$.

Fig. 20. Frequency stability of the VCO as a function of ambient temperature



To obtain optimum temperature stability, C1 must be as small as possible but larger than 100 pF.
 (a) $R1 = 3k\Omega$; $C1 = 40pF$ (b) $R1 = 3k\Omega$; $C1 = 100nF$

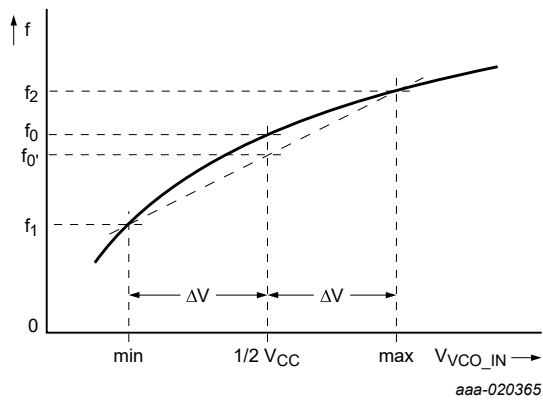
Fig. 21. Graphs showing VCO frequency as a function of the VCO input voltage



To obtain optimum temperature stability, C1 must be as small as possible but larger than 100 pF.

(a) R1 = 300 kΩ; C1 = 40 pF (b) R1 = 300 kΩ; C1 = 100 nF

Fig. 22. Graphs showing VCO frequency as a function of the VCO input voltage

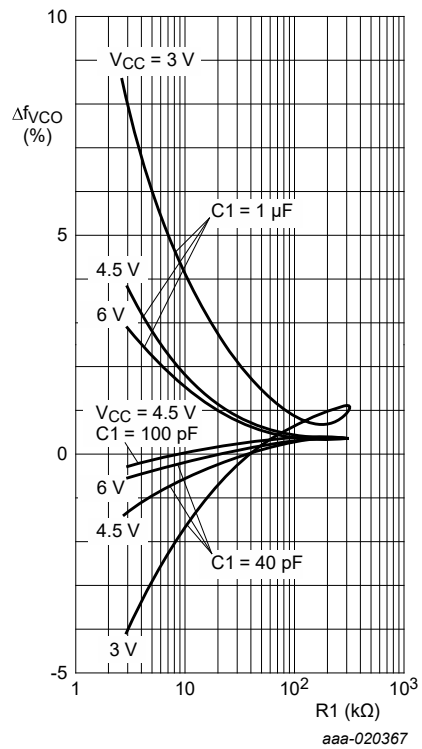


$\Delta V = 0.5 \text{ V}$ over the V_{CC} range.

$$f'_0 = \frac{f_1 + f_2}{2}$$

$$\text{linearity} = \frac{f'_0 - f_0}{f'_0} \times 100 \%$$

Fig. 23. Definition of VCO frequency linearity



$R_2 = \infty \Omega$; $\Delta V = 0.5 \text{ V}$

Fig. 24. Frequency linearity as a function of R1, C1

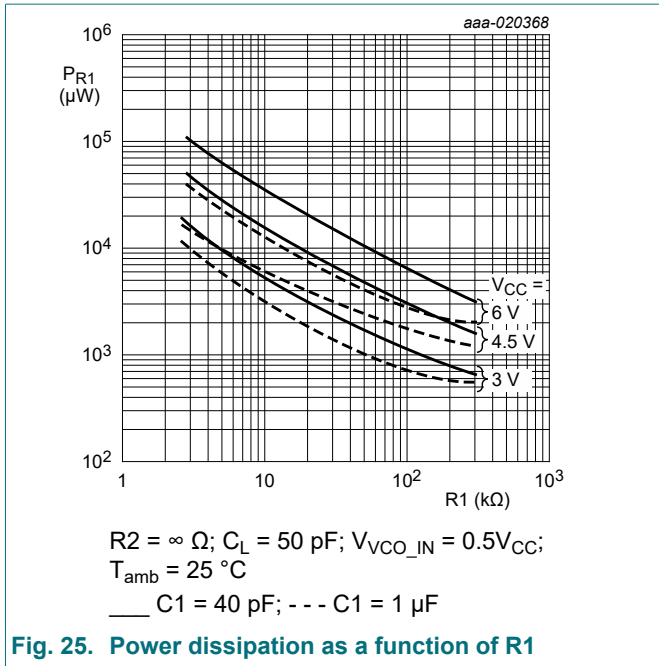


Fig. 25. Power dissipation as a function of R1

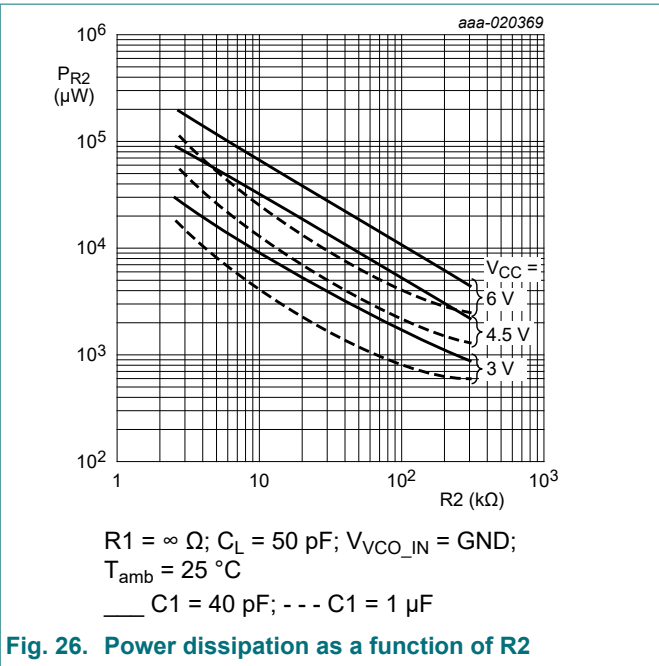


Fig. 26. Power dissipation as a function of R2

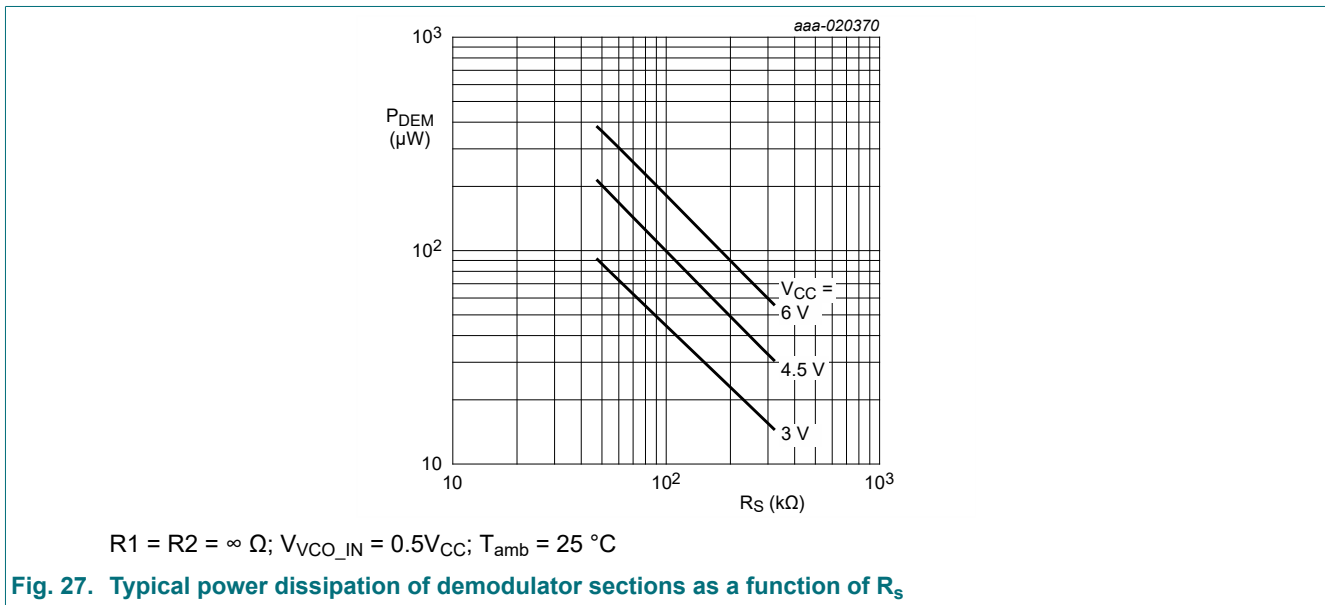


Fig. 27. Typical power dissipation of demodulator sections as a function of R_S

13. Application information

This information is a guide for the approximation of values of external components to be used with the 74HC4046A; 74HCT4046A in a phase-locked-loop system.

References should be made to [Fig. 31](#), [Fig. 32](#) and [Fig. 33](#) as indicated in [Table 10](#).

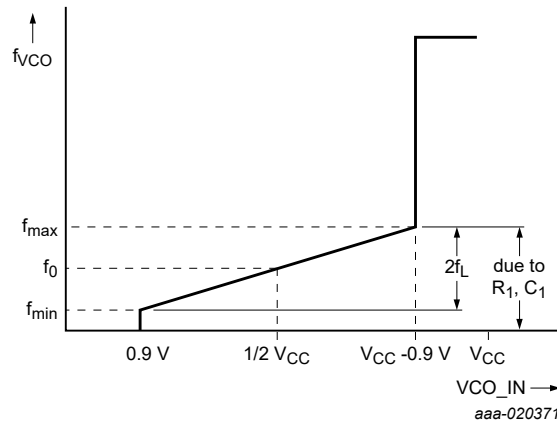
Values of the selected components should be within the ranges shown in [Table 9](#).

Table 9. Survey of components

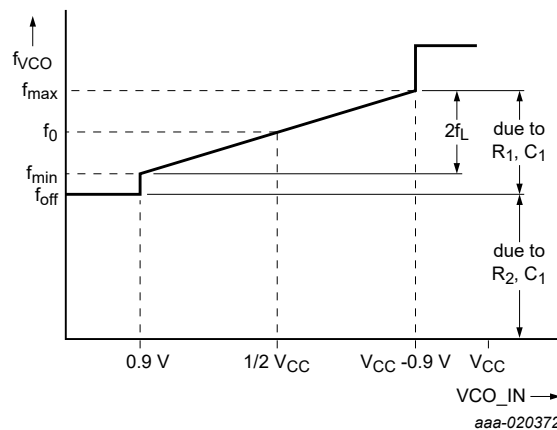
| Component | Value |
|-----------|---|
| R1 | between 3 k Ω and 300 k Ω |
| R2 | between 3 k Ω and 300 k Ω |
| R1 + R2 | parallel value > 2.7 k Ω |
| C1 | > 40 pF |

Table 10. Design considerations for VCO section

| Subject | Phase comparator | Design consideration |
|--|------------------|---|
| VCO frequency without extra offset | PC1, PC2 or PC3 | VCO frequency characteristic. With $R2 = \infty \Omega$ and $R1$ within the range $3 \text{ k}\Omega < R1 < 300 \text{ k}\Omega$, the characteristics of the VCO operation is as shown in Fig. 28a. (Due to $R1$, $C1$ time constant a small offset remains when $R2 = \infty \Omega$). |
| | PC1 | Selection of $R1$ and $C1$. Given f_0 , determine the values of $R1$ and $C1$ using Fig. 31. |
| | PC2 or PC3 | Given f_{max} and f_0 , determine the values of $R1$ and $C1$ using Fig. 31; use Fig. 33 to obtain $2f_L$ and then use it to calculate f_{min} . |
| VCO frequency with extra offset | PC1, PC2 or PC3 | VCO frequency characteristic. With $R1$ and $R2$ within the ranges $3 \text{ k}\Omega < R1 < 300 \text{ k}\Omega$ and $3 \text{ k}\Omega < R2 < 300 \text{ k}\Omega$. The characteristics of the VCO operation are as shown in Fig. 28b. |
| | PC1, PC2 or PC3 | Selection of $R1$, $R2$ and $C1$. Given f_0 and f_L determine the value of product $R1C1$ by using Fig. 33. Calculate f_{off} from the equation $f_{\text{off}} = f_0 - 1.6f_L$. Obtain the values of $C1$ and $R2$ by using Fig. 32. Calculate the value of $R1$ from the value of $C1$ and the product $R1C1$. |
| PLL conditions no signal at pin SIG_IN | PC1 | VCO adjusts to f_0 with $\Phi_{\text{DEM_OUT}} = 90^\circ$ and $V_{\text{VCO_IN}} = 0.5V_{\text{CC}}$, see Fig. 7 |
| | PC2 | VCO adjusts to f_0 with $\Phi_{\text{DEM_OUT}} = -360^\circ$ and $V_{\text{VCO_IN}} = \text{minimum}$, see Fig. 9 |
| | PC3 | VCO adjusts to f_0 with $\Phi_{\text{DEM_OUT}} = -360^\circ$ and $V_{\text{VCO_IN}} = \text{minimum}$, see Fig. 11 |



a. Operating without offset; f_0 = center frequency; $2f_L$ = frequency lock range.



b. Operating with offset; f_0 = center frequency; $2f_L$ = frequency lock range.

Fig. 28. Frequency characteristic of VCO

Table 11. General design considerations

| Subject | Phase comparator | Design consideration |
|--|------------------|--|
| PLL frequency capture range | PC1, PC2 or PC3 | Loop filter component selection, see Fig. 29 and Fig. 30 |
| PLL locks on harmonics at center frequency | PC1 or PC3 | yes |
| | PC2 | no |
| Noise rejection at signal input | PC1 | high |
| | PC2 or PC3 | low |
| AC ripple content when PLL is locked | PC1 | $f_r = 2f_i$; large ripple content at $\Phi_{\text{DEM_OUT}} = 90^\circ$ |
| | PC2 | $f_r = f_i$; small ripple content at $\Phi_{\text{DEM_OUT}} = 0^\circ$ |
| | PC3 | $f_r = f_i$; large ripple content at $\Phi_{\text{DEM_OUT}} = 180^\circ$ |

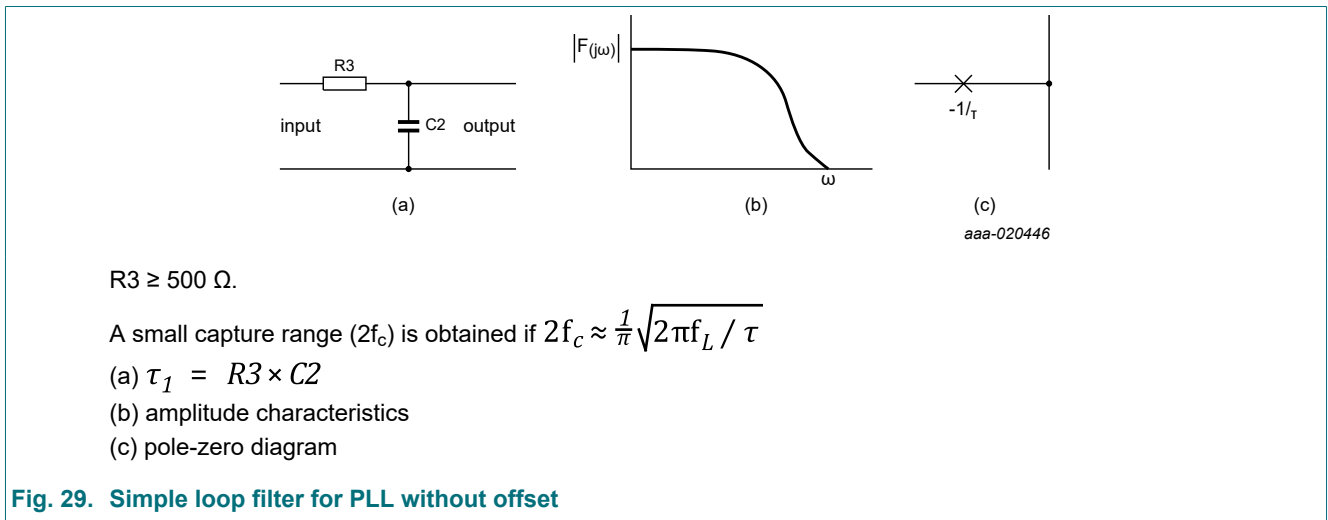


Fig. 29. Simple loop filter for PLL without offset

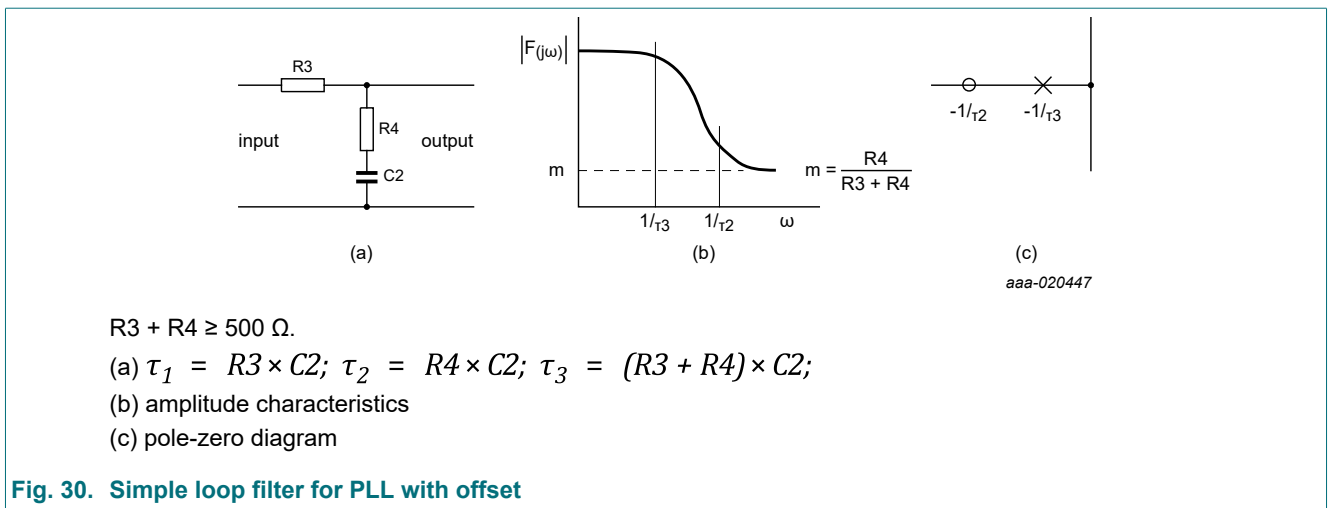
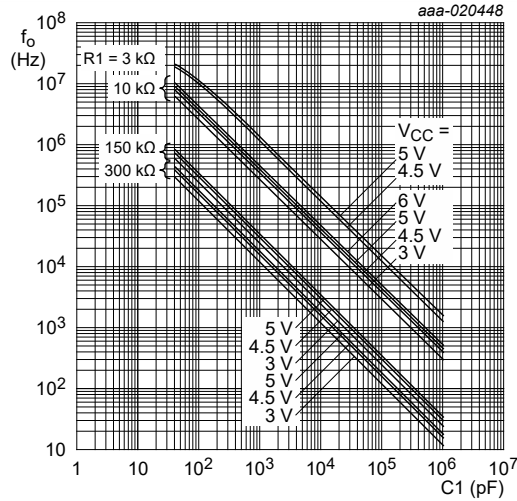
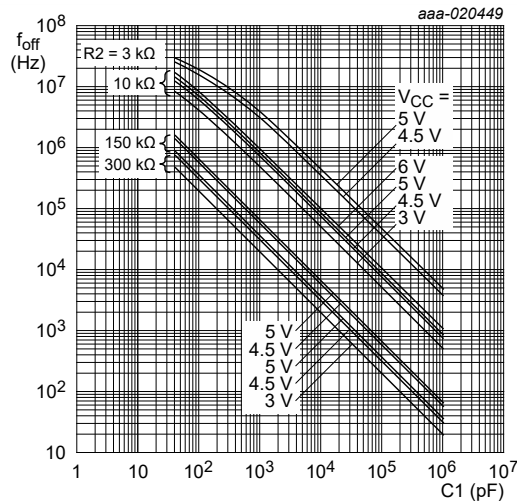


Fig. 30. Simple loop filter for PLL with offset



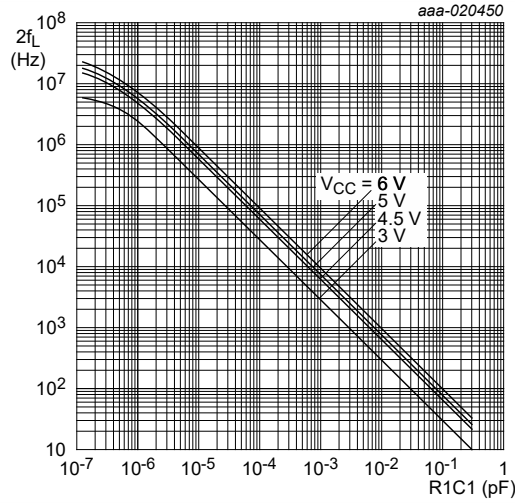
To obtain optimum VCO performance, C_1 must be as small as possible but larger than 100 pF. Interpolation for various values of R_1 can be easily calculated because a constant $R_1 C_1$ product produces almost the same VCO output frequency.
 $R_2 = \infty \Omega$; $V_{VCO_IN} = 0.5V_{CC}$; $INH = GND$; $T_{amb} = 25^\circ C$.

Fig. 31. Typical value of VCO center frequency (f_0) as a function of C_1



To obtain optimum VCO performance, C_1 must be as small as possible but larger than 100 pF. Interpolation for various values of R_2 can be easily calculated because a constant $R_2 C_1$ product produces almost the same VCO output frequency.
 $R_1 = \infty \Omega$; $V_{VCO_IN} = 0.5V_{CC}$; $INH = GND$; $T_{amb} = 25^\circ C$.

Fig. 32. Typical value of frequency offset as a function of C_1



$V_{VCO_IN} = 0.9\text{ V to } (V_{CC} - 0.9)\text{ V}; R_2 = \infty\ \Omega.$

$$\text{VCO gain: } K_V = \frac{2f_L}{V_{VCO_IN\ range}} 2\pi \text{ (rad/s/V)}$$

Fig. 33. Typical frequency lock range ($2f_L$) as a function of the product $R1C1$

13.1. PLL design example

The frequency synthesizer used in the design example shown in [Fig. 34](#) has the following parameters:

- Output frequency: 2 MHz to 3 MHz
- Frequency steps: 100 kHz
- Settling time: 1 ms
- Overshoot: < 20 %

The open loop gain is:

$$H(s) \times G(s) = K_p(s) \times K_f(s) \times K_o(s) \times K_n$$

where:

- $K_p(s)$ = phase comparator gain
- $K_f(s)$ = low-pass filter transfer gain
- $K_o(s) = K_v/s$ VCO gain
- $K_n = 1/n$ divider ratio

The programmable counter ratio K_n can be found as follows:

$$N_{\min} = \frac{f_{\text{OUT}}}{f_{\text{step}}} = \frac{2 \text{ MHz}}{100 \text{ kHz}} = 20$$

$$N_{\max} = \frac{f_{\text{OUT}}}{f_{\text{step}}} = \frac{3 \text{ MHz}}{100 \text{ kHz}} = 30$$

The values of R1, R2 and C1; R2 = 10 kΩ (adjustable) set the VCO.

The values can be determined using the information in [Table 10](#) and [Table 11](#).

With $f_0 = 2.5 \text{ MHz}$ and $f_L = 500 \text{ kHz}$, the following values ($V_{CC} = 5.0 \text{ V}$) are given:

- R1 = 10 kΩ
- R2 = 10 kΩ
- C1 = 500 pF

The VCO gain is:

$$K_v = \frac{2f_L \times 2\pi}{0.9 - (V_{CC} - 0.9)} = \frac{1 \text{ MHz}}{3.2} \times 2\pi \approx 2 \times 10^6 \text{ rad/s/V}$$

The gain of the phase comparator is:

$$K_p = \frac{V_{CC}}{4\pi} = 0.4 \text{ V/rad}$$

The transfer gain of the filter is calculated as follows:

$$K_f(s) = \frac{1 + \tau_2(s)}{1 + (\tau_1 + \tau_2)(s)}$$

Where:

$$\tau_1 = R3 \times C2$$

$$\tau_2 = R4 \times C2$$

The characteristic equation is: $1 + H(s) \times G(s) = 0$

It results in:

$$S^2 + \frac{1 + K_p \times K_v \times K_n \times \tau_2}{(\tau_1 + \tau_2)} \times S + \frac{K_p \times K_v \times K_n}{(\tau_1 + \tau_2)} = 0$$

The natural frequency ω_n is defined as:

$$\omega_n = \sqrt{\frac{K_p \times K_v \times K_n}{(\tau_1 + \tau_2)}}$$

and the damping value (ζ) given as: $\zeta = \frac{1}{2\omega_n} \times \frac{1 + K_p \times K_v \times K_n \times \tau_2}{(\tau_1 + \tau_2)}$

In Fig. 35, the output frequency response to a step of input frequency is shown.

The overshoot and settling time percentages are now used to determine ω_n . Fig. 35 shows that the damping ratio $\zeta = 0.45$ produces an overshoot of less than 20 % and settle to within 5 % at $\omega_n t = 5$. The required settling time is 1 ms. It results in:

$$\omega_n = \frac{5}{t} = \frac{5}{0.001} = 5 \times 10^3 \text{ rad/s}$$

Rewriting the equation for natural frequency results in:

$$(\tau_1 + \tau_2) = \frac{K_p \times K_v \times K_n}{(\omega_n)^2}$$

The maximum overshoot occurs at N_{max} :

$$(\tau_1 + \tau_2) = \frac{0.4 \times 2 \times 10^6}{5000^2 \times 30} = 0.0011 \text{ s}$$

When $C2 = 470 \text{ nF}$, then:

$$R4 = \frac{(\tau_1 + \tau_2) \times 2 \times \omega_n \times \zeta - 1}{K_p \times K_v \times K_n \times C2} = 315 \Omega$$

$R3$ can be calculated: $R3 = \frac{\tau_1}{C2} - R4 = 2 \text{ k}\Omega$

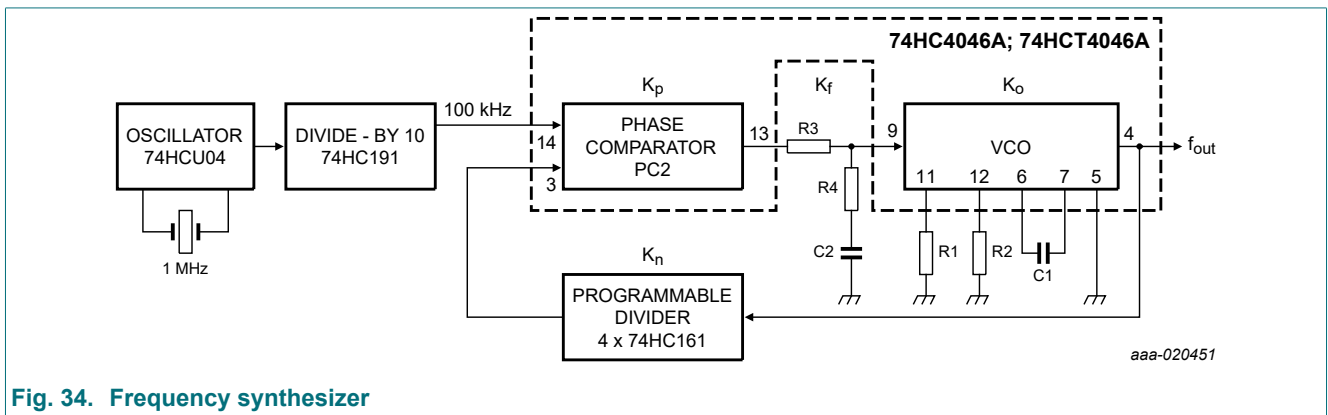


Fig. 34. Frequency synthesizer

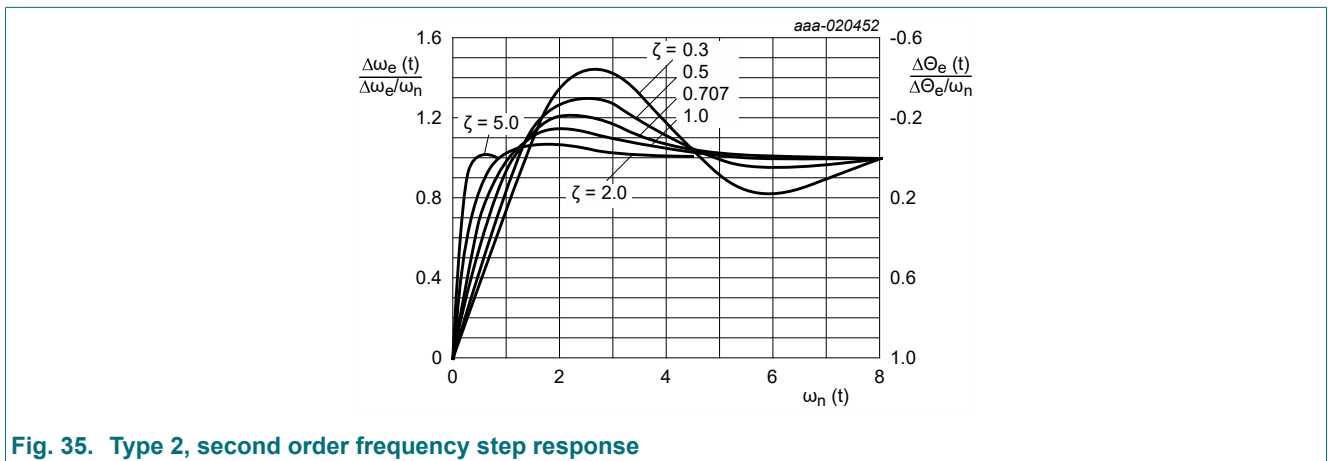
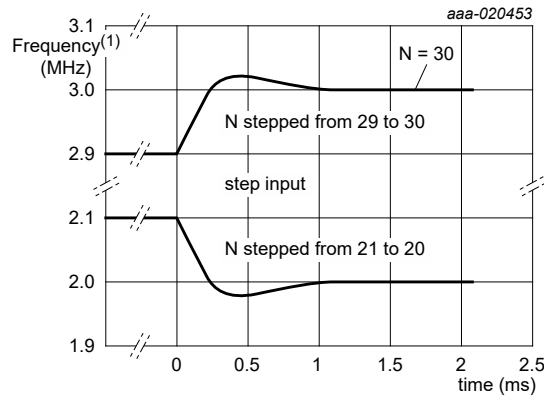


Fig. 35. Type 2, second order frequency step response



The output frequency is proportional to the VCO control voltage. As a result, the PLL frequency response can be observed with an oscilloscope by monitoring pin VCO_IN of the VCO. The average frequency response, as calculated by the Laplace method, is found experimentally by smoothing this voltage at pin VCO_IN using a simple RC filter. The filter has a long time constant when compared with the phase detector sampling rate, but short when compared with the PLL response time.

Fig. 36. Frequency compared to the time response

14. Package outline

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1



DIMENSIONS (inch dimensions are derived from the original mm dimensions)

| UNIT | A max. | A ₁ | A ₂ | A ₃ | b _p | c | D ⁽¹⁾ | E ⁽¹⁾ | e | H _E | L | L _p | Q | v | w | y | Z ⁽¹⁾ | θ |
|--------|--------|----------------|----------------|----------------|----------------|------------------|------------------|------------------|------|----------------|-------|----------------|----------------|------|------|-------|------------------|----------|
| mm | 1.75 | 0.25 0.10 | 1.45 1.25 | 0.25 | 0.49 0.36 | 0.25 0.19 | 10.0 9.8 | 4.0 3.8 | 1.27 | 6.2 5.8 | 1.05 | 1.0 0.4 | 0.7 0.6 | 0.25 | 0.25 | 0.1 | 0.7 0.3 | 8° 0° |
| inches | 0.069 | 0.010 0.004 | 0.057 0.049 | 0.01 | 0.019 0.014 | 0.0100 0.0075 | 0.39 0.38 | 0.16 0.15 | 0.05 | 0.244 0.228 | 0.041 | 0.039 0.016 | 0.028 0.020 | 0.01 | 0.01 | 0.004 | 0.028 0.012 | |

Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

| OUTLINE VERSION | REFERENCES | | | | EUROPEAN PROJECTION | ISSUE DATE |
|-----------------|------------|--------|-------|--|---------------------|----------------------|
| | IEC | JEDEC | JEITA | | | |
| SOT109-1 | 076E07 | MS-012 | | | | 99-12-27 03-02-19 |

Fig. 37. Package outline SOT109-1 (SO16)

SSOP16: plastic shrink small outline package; 16 leads; body width 5.3 mm

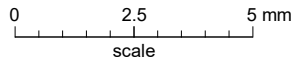
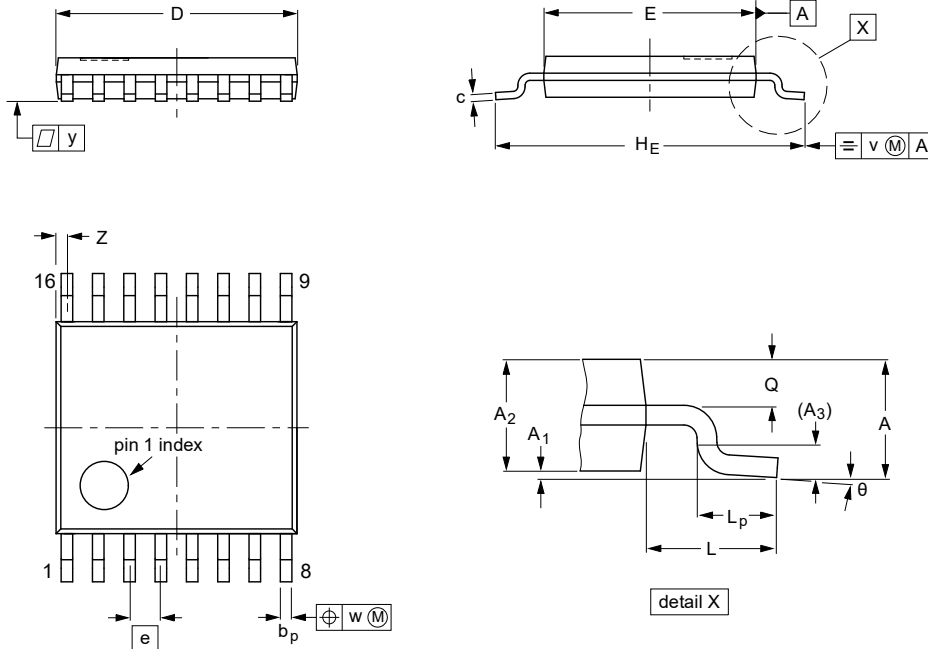
SOT338-1



Fig. 38. Package outline SOT338-1 (SSOP16)

TSSOP16: plastic thin shrink small outline package; 16 leads; body width 4.4 mm

SOT403-1



DIMENSIONS (mm are the original dimensions)

| UNIT | A max. | A ₁ | A ₂ | A ₃ | b _p | c | D ⁽¹⁾ | E ⁽²⁾ | e | H _E | L | L _p | Q | v | w | y | Z ⁽¹⁾ | θ |
|------|--------|----------------|----------------|----------------|----------------|------------|------------------|------------------|------|----------------|---|----------------|------------|-----|------|-----|------------------|----------|
| mm | 1.1 | 0.15 0.05 | 0.95 0.80 | 0.25 | 0.30 0.19 | 0.2 0.1 | 5.1 4.9 | 4.5 4.3 | 0.65 | 6.6 6.2 | 1 | 0.75 0.50 | 0.4 0.3 | 0.2 | 0.13 | 0.1 | 0.40 0.06 | 8° 0° |

Notes

1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

| OUTLINE VERSION | REFERENCES | | | | EUROPEAN PROJECTION | ISSUE DATE |
|-----------------|------------|--------|-------|--|---------------------|----------------------|
| | IEC | JEDEC | JEITA | | | |
| SOT403-1 | | MO-153 | | | | 99-12-27 03-02-18 |

Fig. 39. Package outline SOT403-1 (TSSOP16)

15. Abbreviations

Table 12. Abbreviations

| Acronym | Description |
|---------|--|
| CMOS | Complementary Metal Oxide Semiconductors |
| DUT | Device Under Test |
| ESD | ElectroStatic Discharge |
| HBM | Human Body Model |
| MM | Machine Model |
| PLL | Phase-Locked Loop |
| VCO | Voltage Controlled Oscillator |

16. Revision history

Table 13. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|-----------------------|---|-------------------------|---------------|-----------------------|
| 74HC_HCT4046A v.4 | 20190806 | Product data sheet | - | 74HC_HCT4046A v.3 |
| Modifications: | <ul style="list-style-type: none"> The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia. Legal texts have been adapted to the new company name where appropriate. Typo corrected in Fig. 21 and Fig. 22. | | | |
| 74HC_HCT4046A v.3 | 20160608 | Product data sheet | - | 74HC_HCT4046A_CNV v.2 |
| Modifications: | <ul style="list-style-type: none"> The format of this data sheet has been redesigned to comply with the new identity guidelines of NXP Semiconductors. Legal texts have been adapted to the new company name where appropriate. | | | |
| 74HC_HCT4046A_CNV v.2 | 19971125 | Product specification | - | 74HC_HCT4046A v.1 |
| 74HC_HCT4046A v.1 | 19930901 | Objective specification | - | - |

17. Legal information

Data sheet status

| Document status [1][2] | Product status [3] | Definition |
|--------------------------------|--------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions".
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