

+5V, Fail-Safe, 20Mbps, Profibus RS-485/ RS-422 Transceivers

ABSOLUTE MAXIMUM RATINGS

| | | | |
|--|------------------------------|---|---|
| Supply Voltage (V_{CC}) to GND | -0.3V to +6V | Continuous Power Dissipation ($T_A = +70^\circ\text{C}$) | |
| Control Input Voltage (\overline{RE} , DE, DI, SHDN, TXP, RXP) to GND..... | -0.3V to ($V_{CC} + 0.3V$) | 8-Pin SO (derate 5.88mW/ $^\circ\text{C}$ above $+70^\circ\text{C}$)..... | 471mW |
| Driver Output Voltage (Y, Z) to GND..... | -8V to +13V | 8-Pin DIP (derate 9.09mW/ $^\circ\text{C}$ above $+70^\circ\text{C}$)..... | 727mW |
| Receiver Input Voltage (A, B) to GND..... | -8V to +13V | 14-Pin SO (derate 8.33mW/ $^\circ\text{C}$ above $+70^\circ\text{C}$)..... | 667mW |
| Differential Driver Output Voltage (Y - Z)..... | $\pm 8V$ | 14-Pin DIP (derate 10mW/ $^\circ\text{C}$ above $+70^\circ\text{C}$)..... | 800mW |
| Differential Receiver Input (A - B)..... | $\pm 8V$ | Operating Temperature Range | |
| Receiver Output Voltage (RO)..... | -0.3V to ($V_{CC} + 0.3V$) | MAX346_C_..... | 0°C to $+70^\circ\text{C}$ |
| Output Driver Current (Y, Z) | $\pm 250\text{mA}$ | MAX346_E_..... | -40°C to $+85^\circ\text{C}$ |
| | | Junction Temperature | $+150^\circ\text{C}$ |
| | | Storage Temperature Range | -65°C to $+150^\circ\text{C}$ |
| | | Lead Temperature (soldering, 10s) | $+300^\circ\text{C}$ |

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

($V_{CC} = +5V \pm 5\%$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $V_{CC} = +5V$ and $T_A = +25^\circ\text{C}$.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | |
|---|-----------------|--|-----------------------------------|------|----------|------------------|----|
| Power-Supply Range | V_{CC} | | 4.75 | | 5.25 | V | |
| DRIVER | | | | | | | |
| Differential Driver Output (no load) | V_{OD} | Figure 5, $R = \infty$ | | | V_{CC} | V | |
| Differential Driver Output | V_{OD} | Figure 5, $R = 27\Omega$ | 2.1 | | | V | |
| Change in Magnitude of Differential Output Voltage | ΔV_{OD} | Figure 5, $R = 50\Omega$ or 27Ω (Note 2) | | | 0.2 | V | |
| Driver Common-Mode Output Voltage | V_{OC} | Figure 5, $R = 50\Omega$ or 27Ω | | | 3 | V | |
| Change in Magnitude of Common-Mode Voltage | ΔV_{OC} | Figure 5, $R = 50\Omega$ or 27Ω (Note 2) | | | 0.2 | V | |
| Input High Voltage | V_{IH} | DE, DI, \overline{RE} , SHDN | 2.0 | | | V | |
| Input Low Voltage | V_{IL} | DE, DI, \overline{RE} , SHDN | | | 0.8 | V | |
| Input Hysteresis | V_{HYS} | DE, DI, \overline{RE} , SHDN | | 50 | | mV | |
| Output Leakage (Y and Z) Full Duplex | I_O | DE = GND, $V_{CC} =$ GND or +5.25V | $V_{IN} = +12V$ $V_{IN} = -7V$ | | +125 | μA | |
| Input Current | I_{IN} | DI, \overline{RE} , DE, SHDN | | | ± 1 | μA | |
| Pulldown Current | | RXP = TXP = V_{CC} | 5 | 15 | 30 | μA | |
| Driver Short-Circuit Output Current (Note 3) | I_{OSD} | $0 \leq V_{OUT} \leq 12V$, output low $-7V \leq V_{OUT} \leq V_{CC}$, output high | | | +250 | mA | |
| Driver Short-Circuit Foldback Output Current (Note 3) | I_{OSFD} | $(V_{CC} - 1V) \leq V_{OUT} \leq 12V$, output low $-7V \leq V_{OUT} \leq 1V$, output high | +25 | | -25 | mA | |
| Thermal Shutdown Threshold | | | | 140 | | $^\circ\text{C}$ | |
| RECEIVER | | | | | | | |
| Differential Input Capacitance | $C_{A, B}$ | | | 8 | | pF | |
| Input Current (A and B) Full Duplex | $I_{A, B}$ | DE = GND, $V_{CC} =$ GND or 5.25V | $V_{IN} = +12V$ $V_{IN} = -7V$ | | 250 | μA | |
| Receiver Differential Threshold Voltage | V_{TH} | $-7V \leq V_{CM} \leq 12V$ | | -200 | -125 | -50 | mV |

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MAX3460-MAX3464

ELECTRICAL CHARACTERISTICS (continued)

($V_{CC} = +5V \pm 5\%$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $V_{CC} = +5V$ and $T_A = +25^\circ C$.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|-----------------|--|----------------|-----|----------|-----------|
| Receiver Input Hysteresis | ΔV_{TH} | $V_A + V_B = 0$ | | 20 | | mV |
| Receiver Output High Voltage | V_{OH} | $I_O = -4mA$, $V_A - V_B = V_{TH}$ | $V_{CC} - 1.5$ | | | V |
| Receiver Output Low Voltage | V_{OL} | $I_O = 4mA$, $V_B - V_A = V_{TH}$ | | | 0.4 | V |
| Three-State Output Current at Receiver | I_{OZR} | $0 \leq V_O \leq V_{CC}$ | | | ± 1 | μA |
| Receiver Input Resistance | R_{IN} | $-7V \leq V_{CM} \leq 12V$ | 48 | | | $k\Omega$ |
| Receiver Output Short-Circuit Current | I_{OSR} | $0 \leq V_{RO} \leq V_{CC}$ | ± 7 | | ± 95 | mA |
| SUPPLY CURRENT | | | | | | |
| Normal Operation (static condition) | I_Q | No load, $DI = V_{CC}$ or $DI = GND$ | | 2.5 | 4 | mA |
| Supply Current in SHDN | I_{SHDN} | $DE = GND$ and $\overline{RE} = V_{CC}$, or $SHDN = V_{CC}$ | | 1 | 10 | μA |
| SWITCHING CHARACTERISTICS | | | | | | |
| Driver Propagation Delay | t_{PLH} | Figures 6 and 7, $R_{DIFF} = 54\Omega$, $C_L = 50pF$ | | | 20 | ns |
| | t_{PHL} | | | | | |
| Driver Differential Output Rise or Fall Time | t_R | Figures 6 and 7, $R_{DIFF} = 54\Omega$, $C_L = 50pF$ | | | 20 | ns |
| | t_F | | | | | |
| Driver Output Skew $ t_{PLH} - t_{PHL} $ | t_{SKEW} | Figures 6 and 7, $R_{DIFF} = 54\Omega$, $C_L = 50pF$, $TXP = GND$ or floating | | | 2 | ns |
| Maximum Data Rate | | | 20 | | | Mbps |
| Driver Enable to Output High | t_{ZH} | Figures 8 and 9, S2 closed, $R_L = 500\Omega$, $C_L = 50pF$ | | | 100 | ns |
| Driver Enable to Output Low | t_{ZL} | Figures 8 and 9, S1 closed, $R_L = 500\Omega$, $C_L = 50pF$ | | | 100 | ns |
| Driver Disable Time from Low | t_{LZ} | Figures 8 and 9, S1 closed, $R_L = 500\Omega$, $C_L = 50pF$ | | | 100 | ns |
| Driver Disable Time from High | t_{HZ} | Figures 8 and 9, S2 closed, $R_L = 500\Omega$, $C_L = 50pF$ | | | 100 | ns |
| Receiver Propagation Delay | t_{PLH} | Figure 10, $C_L = 15pF$ (Note 4) | | | 20 | ns |
| | t_{PHL} | | | | | |
| Receiver Output Skew $ t_{PLH} - t_{PHL} $ | t_{SKEW} | Figure 10, $C_L = 15pF$, $RXP = GND$ or floating (Note 4) | | | 2 | ns |
| Receiver Enable to Output Low | t_{ZL} | Figures 8 and 11, $R_L = 1k\Omega$, $C_L = 15pF$, S1 closed (Note 4) | | | 100 | ns |
| Receiver Enable to Output High | t_{ZH} | Figures 8 and 11, $R_L = 1k\Omega$, $C_L = 15pF$, S2 closed (Note 4) | | | 100 | ns |
| Receiver Disable Time from Low | t_{LZ} | Figures 8 and 11, $R_L = 1k\Omega$, $C_L = 15pF$, S1 closed (Note 4) | | | 100 | ns |
| Receiver Disable Time from High | t_{HZ} | Figures 8 and 11, $R_L = 1k\Omega$, $C_L = 15pF$, S2 closed (Note 4) | | | 100 | ns |

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ELECTRICAL CHARACTERISTICS (continued)

($V_{CC} = +5V \pm 5\%$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $V_{CC} = +5V$ and $T_A = +25^\circ C$.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|-----------------|--|-----|-----|-----|---------|
| Time to Shutdown | t_{SHDN} | (Note 5) | 50 | | 800 | ns |
| Driver Enable from Shutdown to Output High | $t_{ZH} (SHDN)$ | Figures 8 and 9, $R_L = 500\Omega$, $C_L = 50pF$, S2 closed (Note 5) | | | 4 | μs |
| Driver Enable from Shutdown to Output Low | $t_{ZL} (SHDN)$ | Figures 8 and 9, $R_L = 500\Omega$, $C_L = 50pF$, S1 closed (Note 5) | | | 4 | μs |
| Receiver Enable from Shutdown to Output High | $t_{ZH} (SHDN)$ | Figures 8 and 11, $R_L = 1k\Omega$, $C_L = 15pF$, S2 closed (Notes 4, 5) | | | 4 | μs |
| Receiver Enable from Shutdown to Output Low | $t_{ZL} (SHDN)$ | Figures 8 and 11, $R_L = 1k\Omega$, $C_L = 15pF$, S1 closed (Notes 4, 5) | | | 4 | μs |

Note 1: All currents into the device are positive; all currents out of the device are negative. All voltages are referenced to device ground, unless otherwise noted.

Note 2: ΔV_{OD} and ΔV_{OC} are the changes in V_{OD} and V_{OC} , respectively, when the DI input changes state.

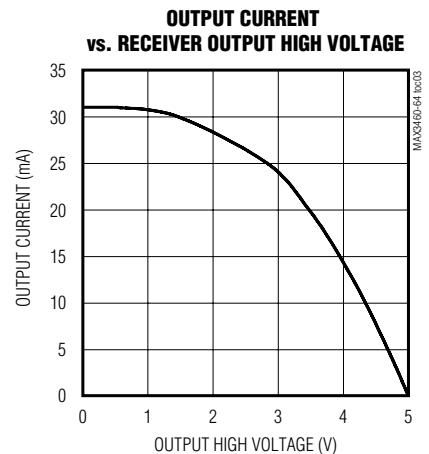
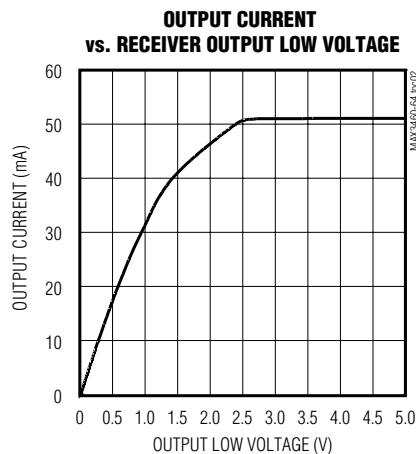
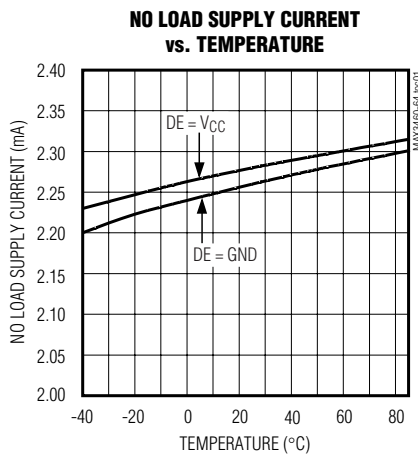
Note 3: The short-circuit output current applies to peak current just prior to foldback-current limiting; the short-circuit foldback output current applies during current limiting to allow a recovery from bus contention.

Note 4: Capacitive load includes test probe and fixture capacitance.

Note 5: Shutdown is enabled by bringing \overline{RE} high and DE low or by bringing SHDN high. If the enable inputs are in this state for less than 50ns, the device is guaranteed not to enter shutdown. If the enable inputs are in this state for at least 800ns, the device is guaranteed to have entered shutdown.

Typical Operating Characteristics

($V_{CC} = +5V$, $T_A = +25^\circ C$, unless otherwise noted.)

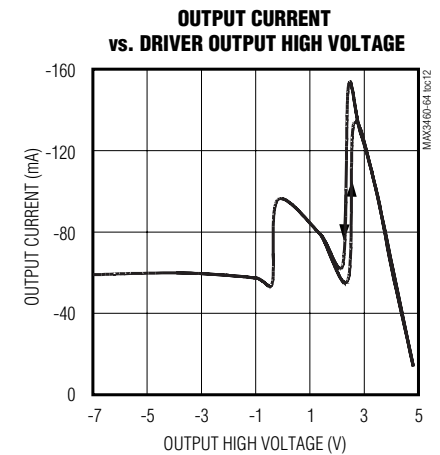
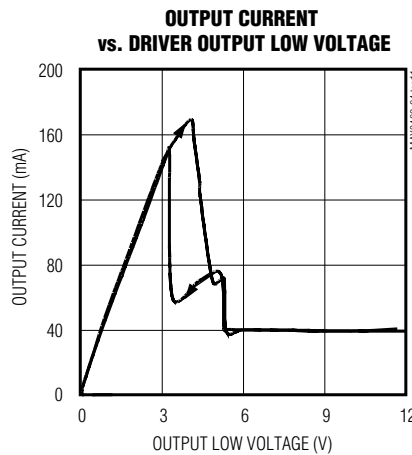
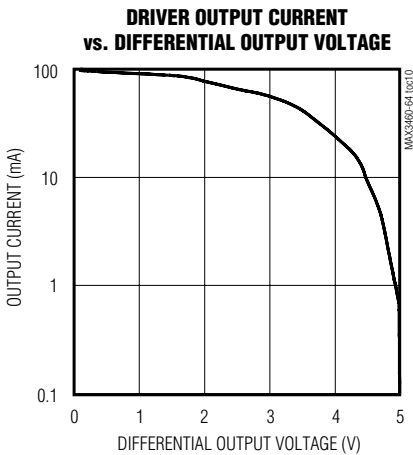
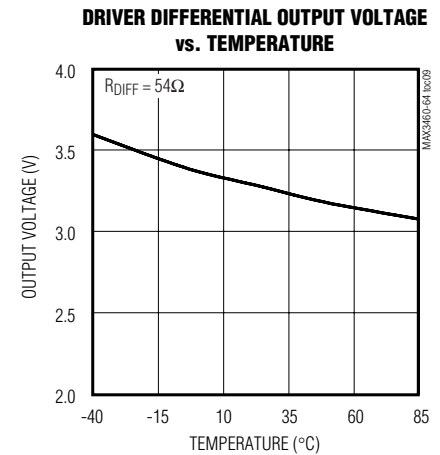
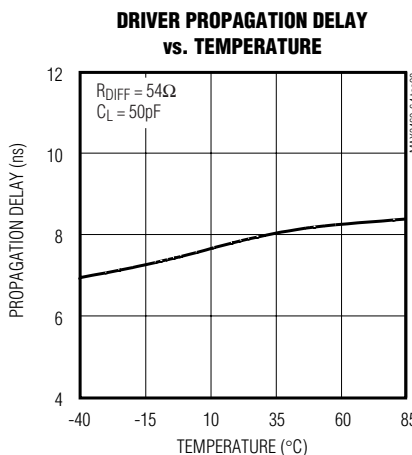
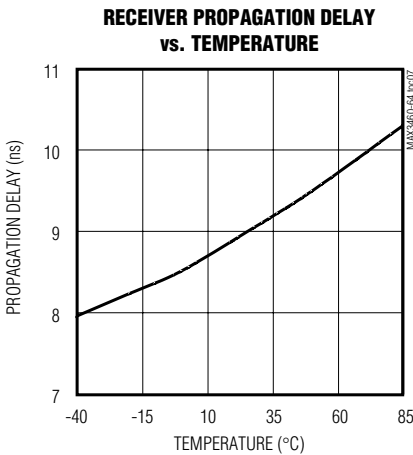
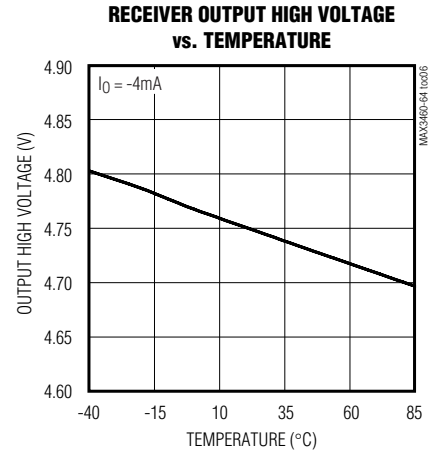
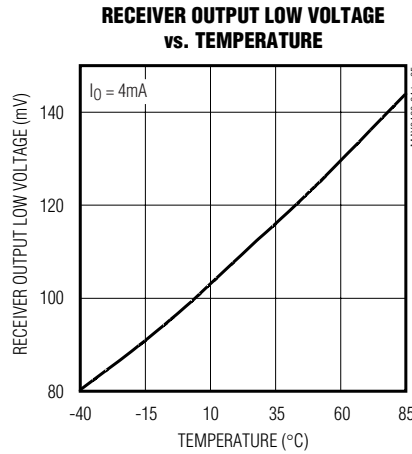
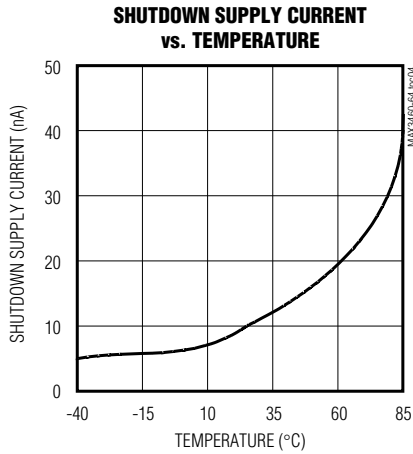


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Typical Operating Characteristics (continued)

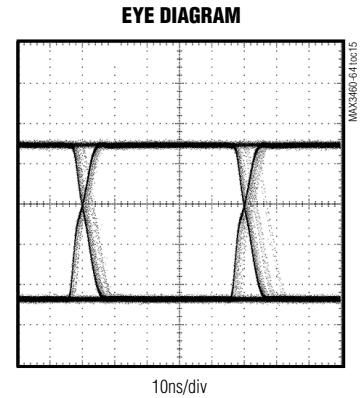
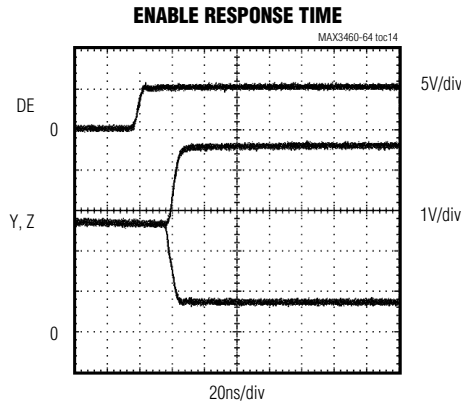
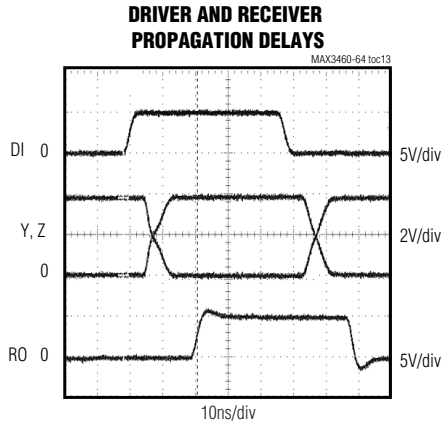
($V_{CC} = +5V$, $T_A = +25^\circ C$, unless otherwise noted.)



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Typical Operating Characteristics (continued)

(V_{CC} = +5V, T_A = +25°C, unless otherwise noted.)



Pin Description

| PIN | | | NAME | FUNCTION |
|---------------------|---------|---------------------|-----------------|--|
| MAX3460/ MAX3461 | MAX3462 | MAX3463/ MAX3464 | | |
| FULL DUPLEX | | HALF DUPLEX | | |
| 1 | — | — | SHDN | Shutdown. Drive SHDN high to enter low-power shutdown mode. |
| 2 | 2 | 1 | RO | Receiver Output. When \overline{RE} is low and $(A - B) \geq -50\text{mV}$, RO is high; if $(A - B) \leq -200\text{mV}$, RO is low. |
| 3 | — | 2 | \overline{RE} | Receiver Output Enable. Drive \overline{RE} low to enable RO; RO is high impedance when \overline{RE} is high. Drive \overline{RE} high and DE low to enter low-power shutdown mode. |
| 4 | — | 3 | DE | Driver Output Enable. Drive DE high to enable driver output. These outputs are high impedance when DE is low. Drive \overline{RE} high and DE low to enter low-power shutdown mode. |
| 5 | 3 | 4 | DI | Driver Input. With DE high, a low on DI forces the noninverting output low and the inverting output high. Similarly, a high on DI forces the noninverting output high and the inverting output low. |
| 6, 7 | 4 | 5 | GND | Ground |
| 8 | — | — | TXP | Transmitter Phase. Connect TXP to GND, or leave unconnected for normal transmitter phase/polarity. Connect TXP to V _{CC} to invert the transmitter phase/polarity. TXP has an internal 15 μA pulldown. |
| 9 | 5 | — | Y | Noninverting Driver Output |
| 10 | 6 | — | Z | Inverting Driver Output |
| 11 | 7 | — | B | Inverting Receiver Input |
| 12 | 8 | — | A | Noninverting Receiver Input |
| 13 | — | — | RXP | Receiver Phase. Connect RXP to GND, or leave unconnected for normal receiver phase/polarity. Connect RXP to V _{CC} to invert the receiver phase/polarity. RXP has an internal 15 μA pulldown. |
| 14 | 1 | 8 | V _{CC} | Positive Supply: +4.75V \leq V _{CC} \leq +5.25V. Bypass V _{CC} to GND with a 0.1 μF capacitor. |
| — | — | 7 | B | Inverting Receiver Input and Inverting Driver Output |
| — | — | 6 | A | Noninverting Receiver Input and Noninverting Driver Output |

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Function Tables

MAX3460-MAX3464

MAX3460/MAX3461

| TRANSMITTING | | | | | |
|-----------------|----|---------------|------|----------|--------|
| INPUTS | | | | OUTPUTS | |
| \overline{RE} | DE | DI | SHDN | Z | Y |
| X | 1 | 1 | 0 | 0 | 1 |
| X | 1 | 0 | 0 | 1 | 0 |
| 0 | 0 | X | 0 | High-Z | High-Z |
| 1 | 0 | X | X | Shutdown | |
| X | X | X | 1 | Shutdown | |
| RECEIVING | | | | | |
| INPUTS | | | | OUTPUT | |
| \overline{RE} | DE | A-B | SHDN | RO | |
| 0 | X | $\geq -0.05V$ | 0 | 1 | |
| 0 | X | $\leq -0.2V$ | 0 | 0 | |
| 0 | X | Open/Shorted | 0 | 1 | |
| 1 | 1 | X | 0 | High-Z | |
| 1 | 0 | X | X | Shutdown | |
| X | X | X | 1 | Shutdown | |

MAX3462

| TRANSMITTING | | |
|---------------|---------|---|
| INPUT | OUTPUTS | |
| DI | Z | Y |
| 1 | 0 | 1 |
| 0 | 1 | 0 |
| RECEIVING | | |
| INPUTS | OUTPUT | |
| A-B | RO | |
| $\geq -0.05V$ | 1 | |
| $\leq -0.2V$ | 0 | |
| Open/Shorted | 1 | |

MAX3463/MAX3464

| TRANSMITTING | | | | |
|-----------------|----|---------------|----------|--------|
| INPUTS | | | OUTPUTS | |
| \overline{RE} | DE | DI | B | A |
| X | 1 | 1 | 0 | 1 |
| X | 1 | 0 | 1 | 0 |
| 0 | 0 | X | High-Z | High-Z |
| 1 | 0 | X | Shutdown | |
| RECEIVING | | | | |
| INPUTS | | | OUTPUT | |
| \overline{RE} | DE | A-B | RO | |
| 0 | X | $\geq -0.05V$ | 1 | |
| 0 | X | $\leq -0.2V$ | 0 | |
| 0 | X | Open/Shorted | 1 | |
| 1 | 1 | X | High-Z | |
| 1 | 0 | X | Shutdown | |

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Pin Configurations and Typical Operating Circuit

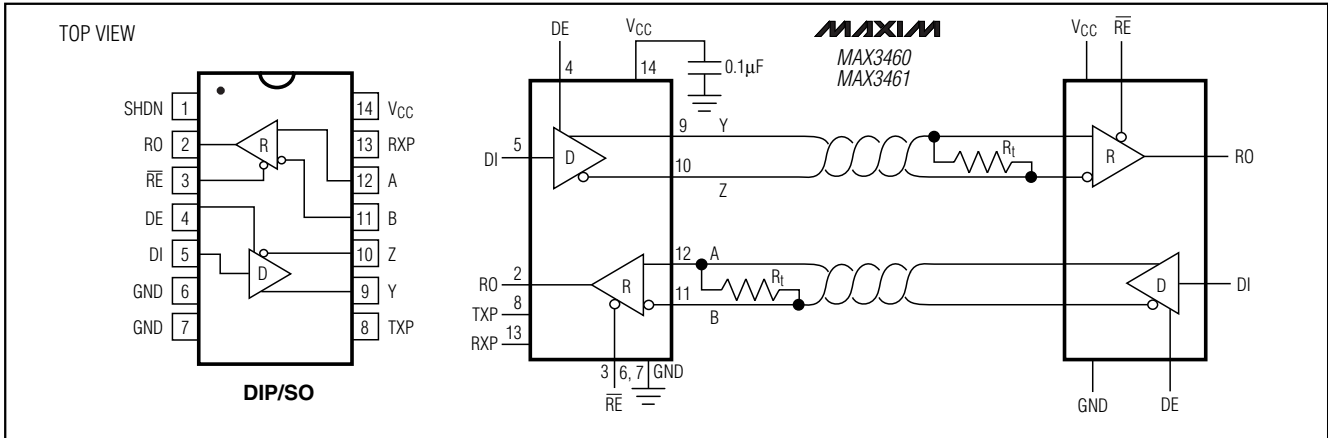


Figure 1. MAX3460/MAX3461 Pin Configuration and Typical Full-Duplex Operating Circuit

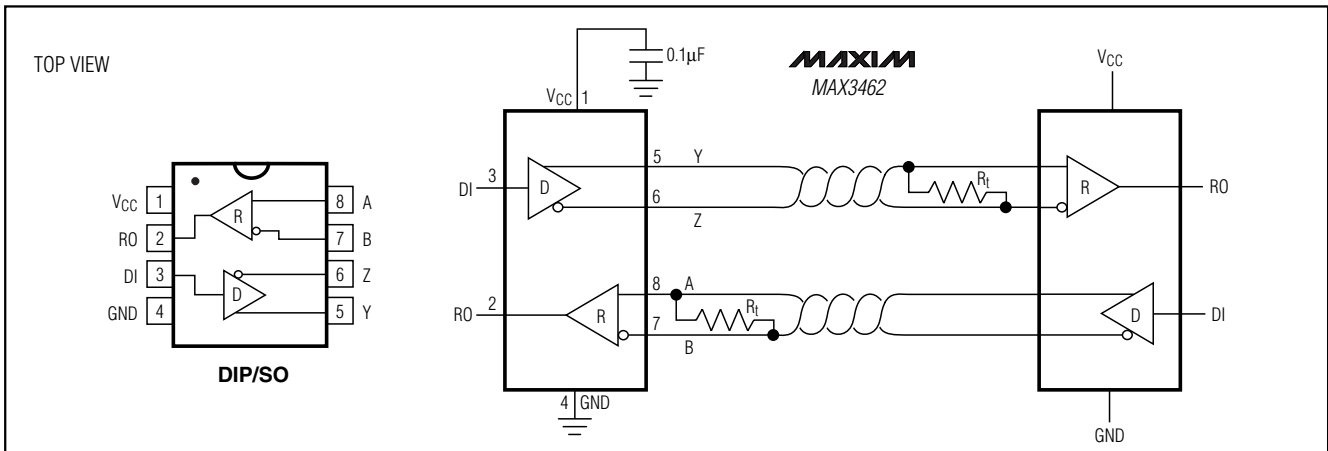


Figure 2. MAX3462 Pin Configuration and Typical Full-Duplex Operating Circuit

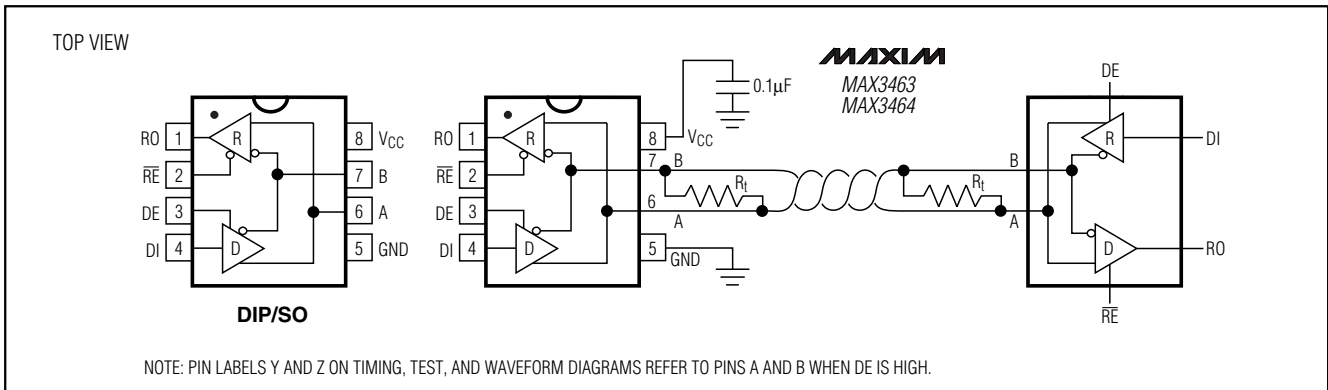


Figure 3. MAX3463/MAX3464 Pin Configuration and Typical Full-Duplex Operating Circuit

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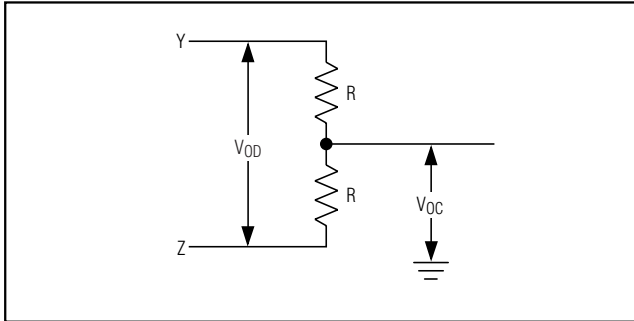


Figure 5. Driver DC Test Load

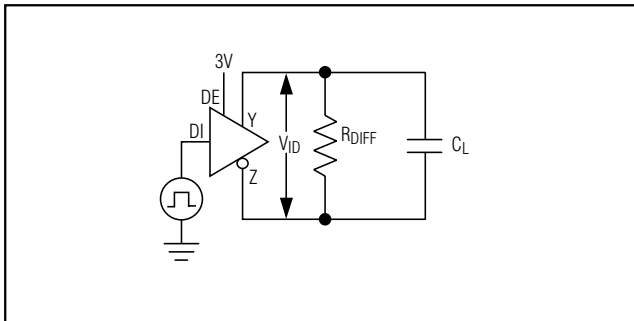


Figure 6. Driver Timing Test Circuit

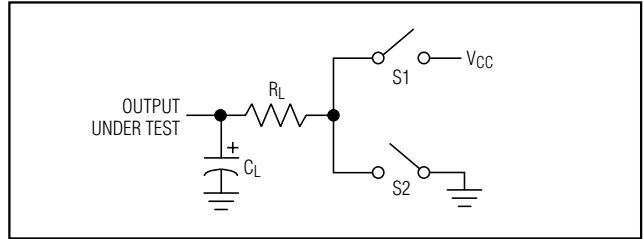


Figure 8. Enable/Disable Timing Test Load

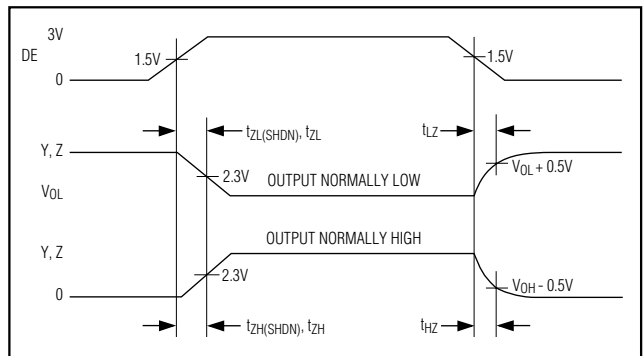


Figure 9. Driver Enable and Disable Times

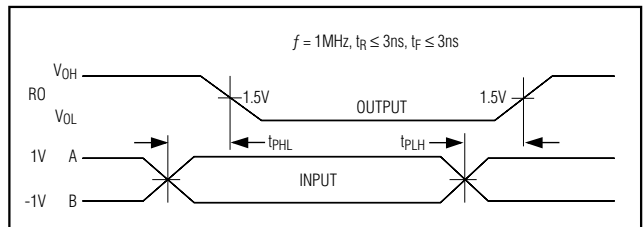


Figure 10. Receiver Propagation Delays

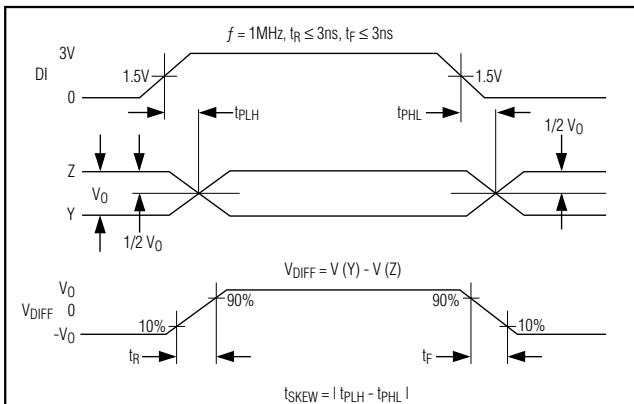


Figure 7. Driver Propagation Delays

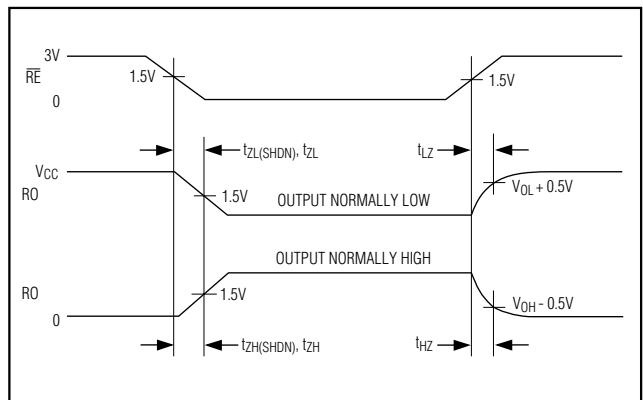


Figure 11. Receiver Enable and Disable Times

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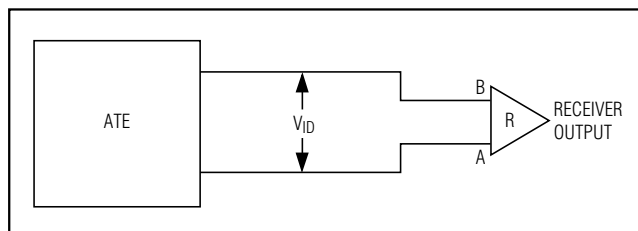


Figure 12. Receiver Propagation Delay Test Circuit

Applications Information

128 Transceivers on the Bus

The standard RS-485 receiver input impedance is $12k\Omega$ (one-unit load), and the standard driver can drive up to 32 unit loads. The MAX3460-MAX3464 family of transceivers has a 1/4-unit-load receiver input impedance ($48k\Omega$), allowing up to 128 transceivers to be connected in parallel on one communication line. Any combination of these devices and/or other RS-485 transceivers with a total of 32 unit loads or less can be connected to the line.

Low-Power Shutdown Mode (except MAX3462)

Low-power shutdown mode is initiated by bringing SHDN high (MAX3460/MAX3461), or both \overline{RE} high and DE low. In shutdown, the devices typically draw only $1\mu A$ of supply current. \overline{RE} and DE can be driven simultaneously; the parts are guaranteed not to enter shutdown if \overline{RE} is high and DE is low for less than 50ns. If the inputs are in this state for at least 800ns, the parts are guaranteed to enter shutdown.

Driver Output Protection

Two mechanisms prevent excessive output current and power dissipation caused by faults or by bus contention. The first, a foldback current limit on the output stage, provides immediate protection against short circuits over the whole common-mode voltage range (see *Typical Operating Characteristics*). The second, a thermal shutdown circuit, forces the driver outputs into a

high-impedance state if the die temperature exceeds $+140^\circ C$.

Propagation Delay

Many digital encoding schemes depend on the difference between the driver and receiver propagation delay times. Typical propagation delays are shown in the *Typical Operating Characteristics*. The difference in receiver delay times, $t_{PLH} - t_{PHL}$, is a maximum of 2ns. The driver skew time $t_{PLH} - t_{PHL}$ is also a maximum of 2ns.

Typical Applications

The MAX3460-MAX3464 transceivers are designed for bidirectional data communications on multipoint bus transmission lines. Figures 13 and 14 show typical network applications circuits. To minimize reflections, the line should be terminated at both ends in its characteristic impedance, and stub lengths off the main line should be kept as short as possible.

Profibus Termination

The MAX3460-MAX3464 are designed for driving Profibus termination networks. With a worst-case loading of two termination networks with 220Ω termination impedance and 390Ω pullups and pulldowns, the drivers can drive $V_{A-B} > 2.1V$ output.

Chip Information

TRANSISTOR COUNT: 610

PROCESS: BiCMOS

Ordering Information (continued)

| PART | TEMP RANGE | PIN-PACKAGE |
|------------|--------------------------------|----------------|
| MAX3461CSD | $0^\circ C$ to $+70^\circ C$ | 14 SO |
| MAX3461CPD | $0^\circ C$ to $+70^\circ C$ | 14 Plastic DIP |
| MAX3461ESD | $-40^\circ C$ to $+85^\circ C$ | 14 SO |
| MAX3461EPD | $-40^\circ C$ to $+85^\circ C$ | 14 Plastic DIP |
| MAX3462CSA | $0^\circ C$ to $+70^\circ C$ | 8 SO |
| MAX3462CPA | $0^\circ C$ to $+70^\circ C$ | 8 Plastic DIP |
| MAX3462ESA | $-40^\circ C$ to $+85^\circ C$ | 8 SO |
| MAX3462EPA | $-40^\circ C$ to $+85^\circ C$ | 8 Plastic DIP |
| MAX3463CSA | $0^\circ C$ to $+70^\circ C$ | 8 SO |
| MAX3463CPA | $0^\circ C$ to $+70^\circ C$ | 8 Plastic DIP |
| MAX3463ESA | $-40^\circ C$ to $+85^\circ C$ | 8 SO |
| MAX3463EPA | $-40^\circ C$ to $+85^\circ C$ | 8 Plastic DIP |
| MAX3464CSA | $0^\circ C$ to $+70^\circ C$ | 8 SO |
| MAX3464CPA | $0^\circ C$ to $+70^\circ C$ | 8 Plastic DIP |
| MAX3464ESA | $-40^\circ C$ to $+85^\circ C$ | 8 SO |
| MAX3464EPA | $-40^\circ C$ to $+85^\circ C$ | 8 Plastic DIP |

+5V, Fail-Safe, 20Mbps, Profibus RS-485/ RS-422 Transceivers

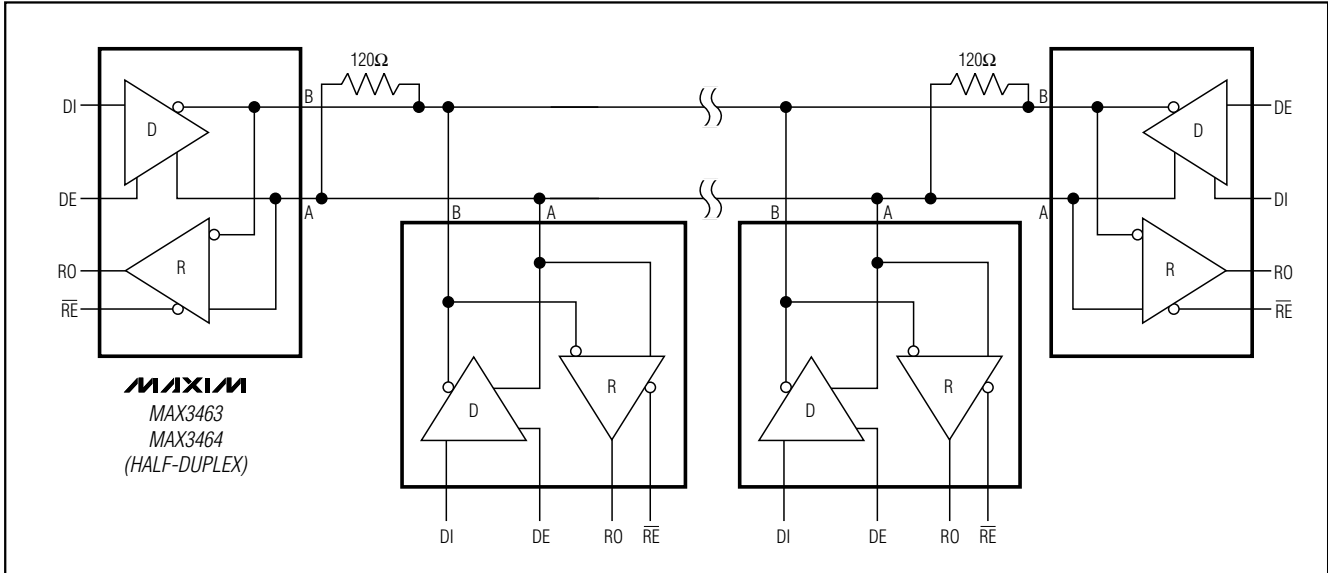


Figure 13. Typical Half-Duplex RS-485 Network

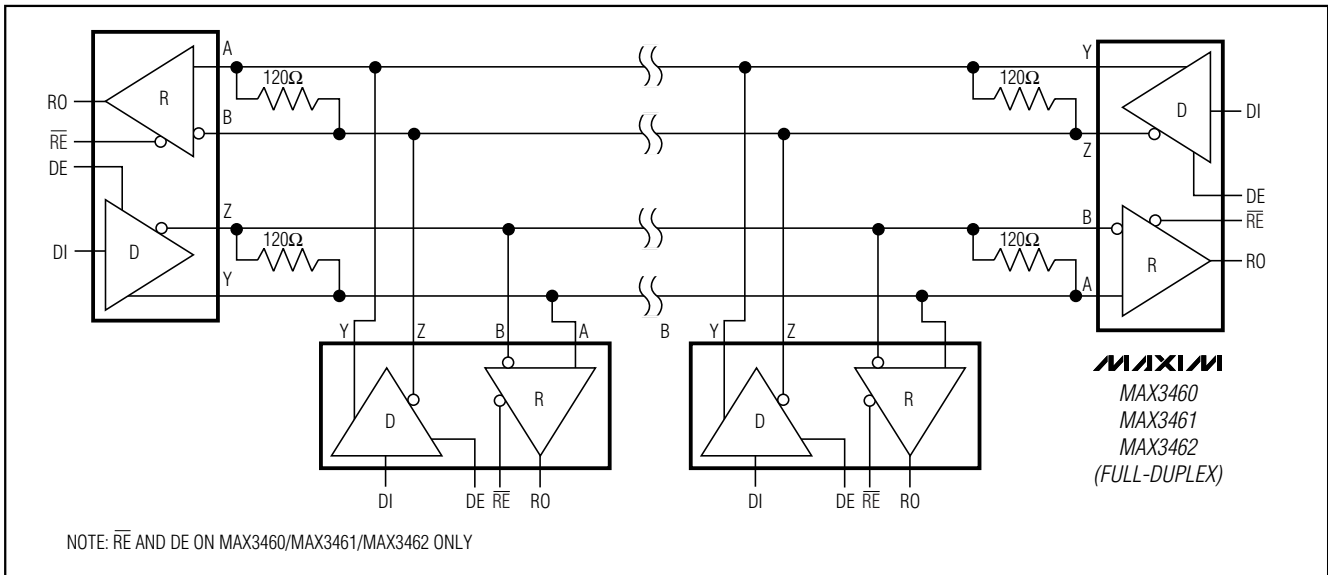


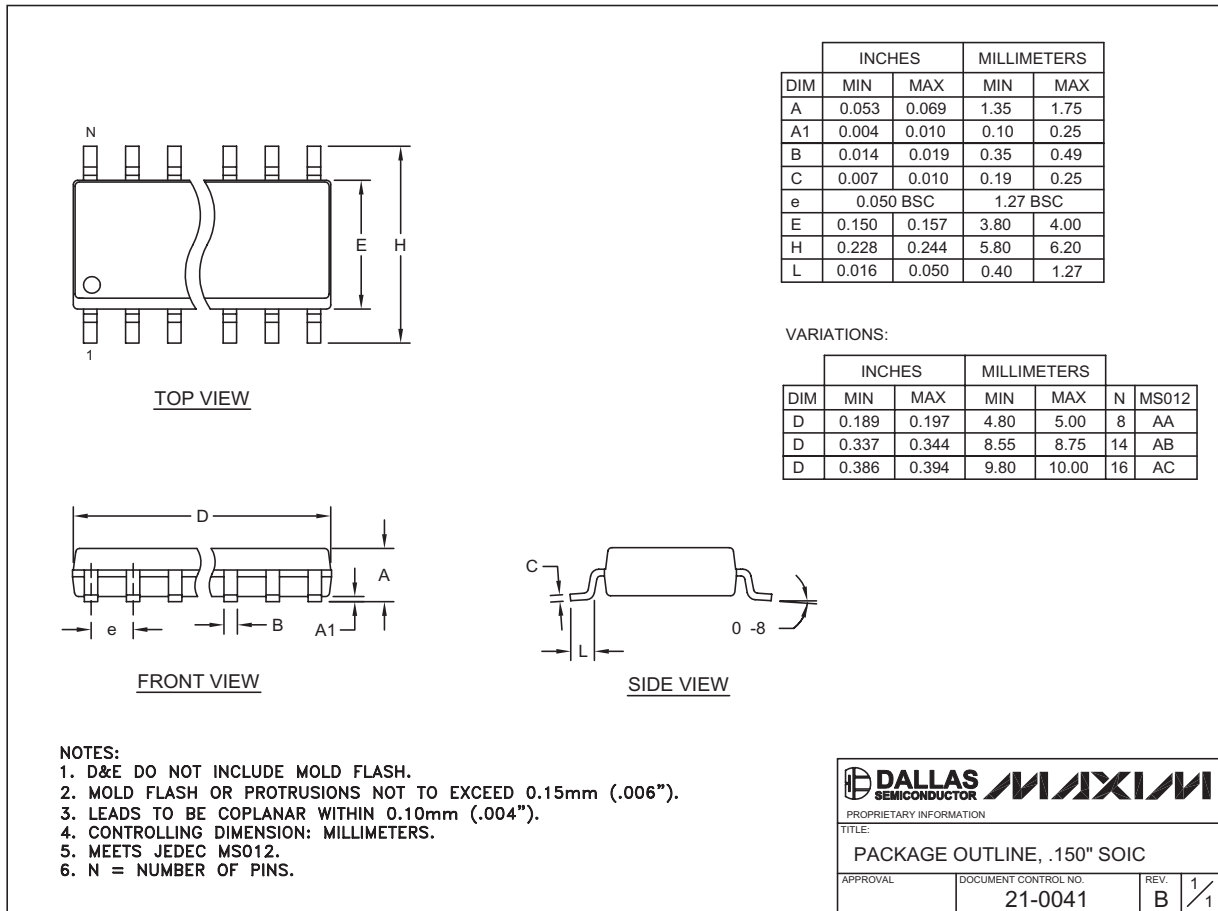
Figure 14. Typical Full-Duplex RS-485 Network

+5V, Fail-Safe, 20Mbps, Profibus RS-485/ RS-422 Transceivers

Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to www.maxim-ic.com/packages.)

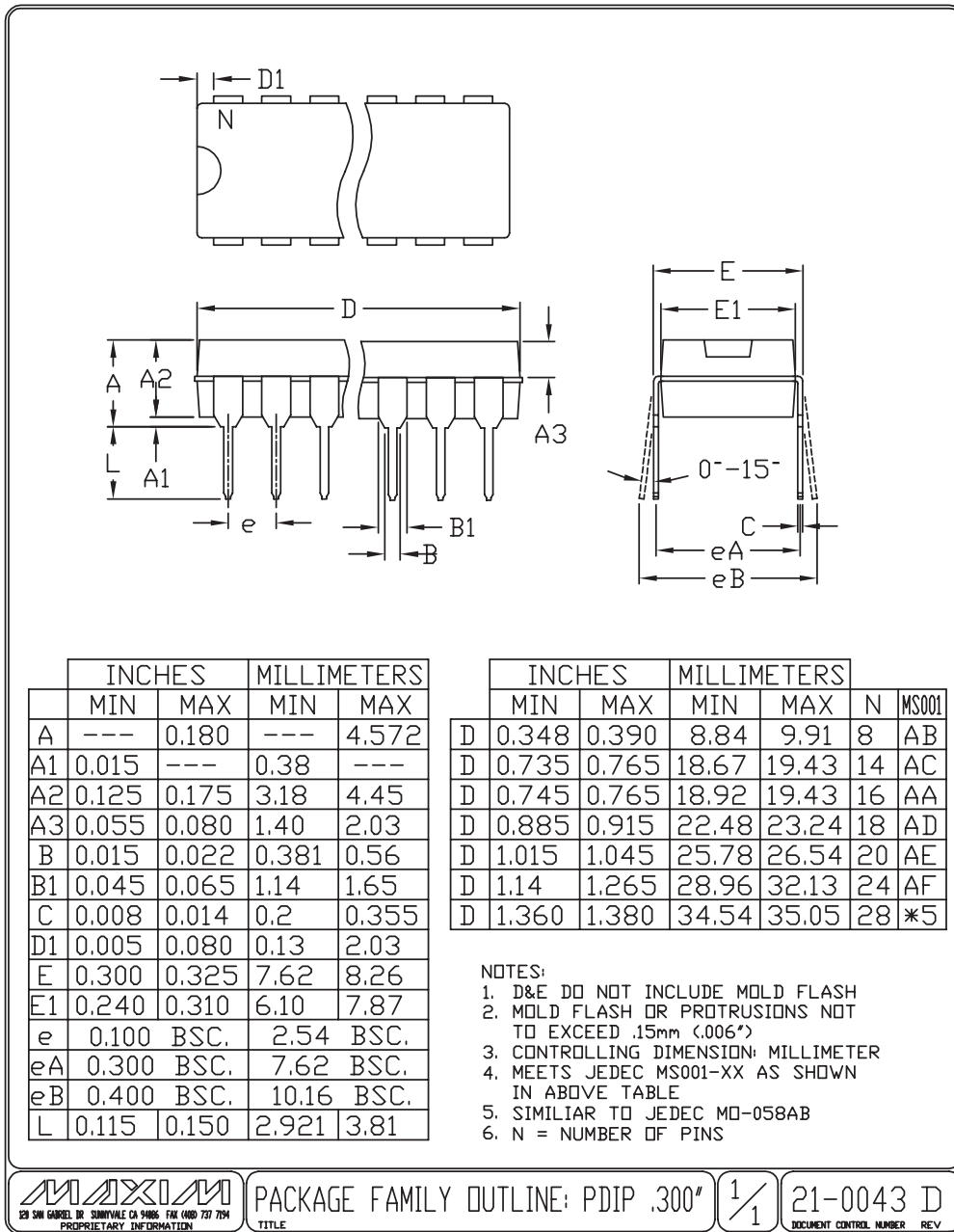
MAX3460-MAX3464



+5V, Fail-Safe, 20Mbps, Profibus RS-485/ RS-422 Transceivers

Package Information (continued)

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