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# 1 Introduction

## 1.1 Document overview

This document describes the features of the family and options available within the family members, and highlights important electrical and physical characteristics of the device.

## 1.2 Description

This family of 32-bit system-on-chip (SoC) microcontrollers is the latest achievement in integrated automotive application controllers. It belongs to an expanding family of automotive-focused products designed to address the next wave of body electronics applications within the vehicle.

The advanced and cost-efficient e200z0h host processor core of this automotive controller family complies with the Power Architecture technology and only implements the VLE (variable-length encoding) APU (Auxiliary Processor Unit), providing improved code density. It operates at speeds of up to 64 MHz and offers high performance processing optimized for low power consumption. It capitalizes on the available development infrastructure of current Power Architecture devices and is supported with software drivers, operating systems and configuration code to assist with users implementations.

**Table 2. SPC560B54/6x family comparison<sup>(1)</sup>**

Feature	SPC560B54		SPC560B60			SPC560B64			
CPU	e200z0h								
Execution speed <sup>(2)</sup>	Up to 64 MHz								
Code flash memory	768 KB		1 MB			1.5 MB			
Data flash memory	64 (4 × 16) KB								
SRAM	64 KB		80 KB			96 KB			
MPU	8-entry								
eDMA	16 ch								
10-bit ADC	Yes								
dedicated <sup>(3)</sup>	7 ch	15 ch	7 ch	15 ch	29 ch	7 ch	15 ch	29 ch	29 ch
shared with 12-bit ADC	19 ch								
12-bit ADC	Yes								
dedicated <sup>(4)</sup>	5 ch								
shared with 10-bit ADC	19 ch								
Total timer I/O <sup>(5)</sup> eMIOS	37 ch, 16-bit	64 ch, 16-bit	37 ch, 16-bit	64 ch, 16-bit	64 ch, 16-bit	37 ch, 16-bit	64 ch, 6-bit	64 ch, 16-bit	64 ch, 16-bit
Counter / OPWM / ICOC <sup>(6)</sup>	10 ch								
O(I)PWM / OPWFMB / OPWMCB / ICOC <sup>(7)</sup>	7 ch								
O(I)PWM / ICOC <sup>(8)</sup>	7 ch	14 ch	7 ch	14 ch	14 ch	7 ch	14 ch	14 ch	14 ch

**Table 2. SPC560B54/6x family comparison<sup>(1)</sup> (continued)**

Feature	SPC560B54		SPC560B60			SPC560B64			
OPWM / ICOC <sup>(9)</sup>	13 ch	33 ch	13 ch	33 ch	33 ch	13 ch	33 ch	33 ch	33 ch
SCI (LINFlex)	4	8	4	8	10	4	8	10	10
SPI (DSPI)	3	5	3	5	6	3	5	6	6
CAN (FlexCAN)	6								
I2C	1								
32 KHz oscillator	Yes								
GPIO <sup>(10)</sup>	77	121	77	121	149	77	121	149	149
Debug	JTAG								N2+
Package	LQFP 100	LQFP 144	LQFP 100	LQFP 144	LQFP 176	LQFP 100	LQFP 144	LQFP 176	LBGA208 <sup>(11)</sup>

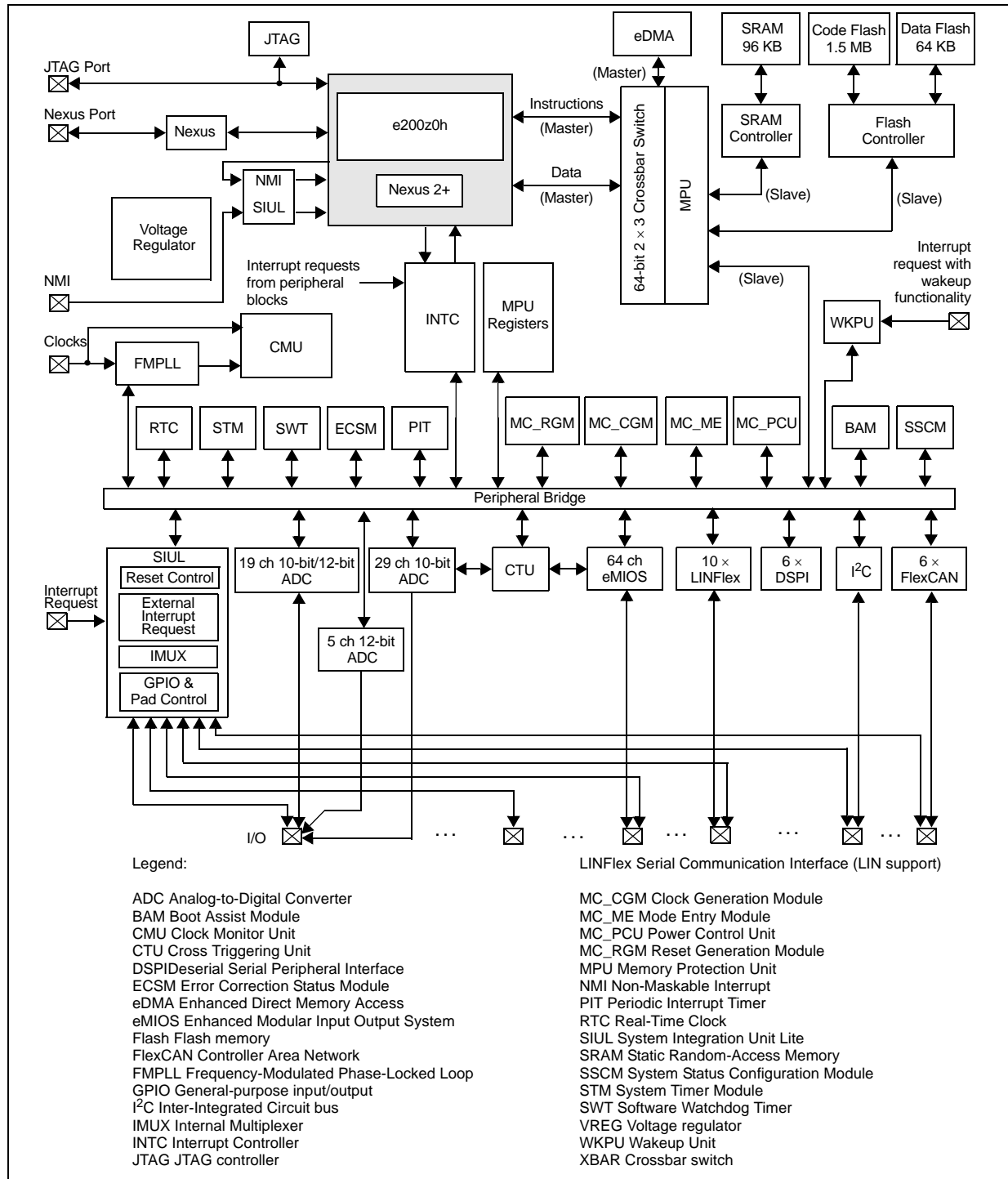
1. Feature set dependent on selected peripheral multiplexing; table shows example.
2. Based on 125 °C ambient operating temperature.
3. Not shared with 12-bit ADC, but possibly shared with other alternate functions.
4. Not shared with 10-bit ADC, but possibly shared with other alternate functions.
5. See the eMIOS section of the chip reference manual for information on the channel configuration and functions.
6. Each channel supports a range of modes including Modulus counters, PWM generation, Input Capture, Output Compare.
7. Each channel supports a range of modes including PWM generation with dead time, Input Capture, Output Compare.
8. Each channel supports a range of modes including PWM generation, Input Capture, Output Compare, Period and Pulse width measurement.
9. Each channel supports a range of modes including PWM generation, Input Capture, and Output Compare.
10. Maximum I/O count based on multiplexing with peripherals.
11. LBGA208 available only as development package for Nexus2+.



## 2 Block diagram

Figure 1 shows a top-level block diagram of the SPC560B54/6x.

Figure 1. SPC560B54/6x block diagram



[Table 3](#) summarizes the functions of the blocks present on the SPC560B54/6x.

**Table 3. SPC560B54/6x series block summary**

Block	Function
Analog-to-digital converter (ADC)	Converts analog voltages to digital values
Boot assist module (BAM)	A block of read-only memory containing VLE code which is executed according to the boot mode of the device
Clock generation module (MC_CGM)	Provides logic and control required for the generation of system and peripheral clocks
Clock monitor unit (CMU)	Monitors clock source (internal and external) integrity
Cross triggering unit (CTU)	Enables synchronization of ADC conversions with a timer event from the eMIOS or from the PIT
Crossbar switch (XBAR)	Supports simultaneous connections between two master ports and three slave ports. The crossbar supports a 32-bit address bus width and a 64-bit data bus width.
Deserial serial peripheral interface (DSPI)	Provides a synchronous serial interface for communication with external devices
Enhanced direct memory access (eDMA)	Performs complex data transfers with minimal intervention from a host processor via "n" programmable channels
Enhanced modular input output system (eMIOS)	Provides the functionality to generate or measure events
Error correction status module (ECSM)	Provides a myriad of miscellaneous control functions for the device including program-visible information about configuration and revision levels, a reset status register, wakeup control for exiting sleep modes, and optional features such as information on memory errors reported by error-correcting codes
Flash memory	Provides non-volatile storage for program code, constants and variables
FlexCAN (controller area network)	Supports the standard CAN communications protocol
Frequency-modulated phase-locked loop (FMPLL)	Generates high-speed system clocks and supports programmable frequency modulation
Inter-integrated circuit (I <sup>2</sup> C) bus	Two-wire bidirectional serial bus that provides a simple and efficient method of data exchange between devices
Internal multiplexer (IMUX) SIU subblock	Allows flexible mapping of peripheral interface on the different pins of the device
Interrupt controller (INTC)	Provides priority-based preemptive scheduling of interrupt requests
JTAG controller (JTAGC)	Provides the means to test chip functionality and connectivity while remaining transparent to system logic when not in test mode
LINFlex controller	Manages a high number of LIN (Local Interconnect Network protocol) messages efficiently with a minimum of CPU load
Memory protection unit (MPU)	Provides hardware access control for all memory references generated in a device

Table 3. SPC560B54/6x series block summary (continued)

Block	Function
Mode entry module (MC_ME)	Provides a mechanism for controlling the device operational mode and mode transition sequences in all functional states; also manages the power control unit, reset generation module and clock generation module, and holds the configuration, control and status registers accessible for applications
Non-maskable interrupt (NMI)	Handles external events that must produce an immediate response, such as power down detection
Periodic interrupt timer (PIT)	Produces periodic interrupts and triggers
Power control unit (MC_PCU)	Reduces the overall power consumption by disconnecting parts of the device from the power supply via a power switching device; device components are grouped into sections called "power domains" which are controlled by the PCU
Real-time counter (RTC)	A free running counter used for time keeping applications, the RTC can be configured to generate an interrupt at a predefined interval independent of the mode of operation (run mode or low-power mode)
Reset generation module (MC_RGM)	Centralizes reset sources and manages the device reset sequence of the device
Static random-access memory (SRAM)	Provides storage for program code, constants, and variables
System integration unit lite (SIUL)	Provides control over all the electrical pad controls and up to 32 ports with 16 bits of bidirectional, general-purpose input and output signals and supports up to 32 external interrupts with trigger event configuration
System status and configuration module (SSCM)	Provides system configuration and status data (such as memory size and status, device mode and security status), device identification data, debug status port enable and selection, and bus and peripheral abort enable/disable
System timer module (STM)	Provides a set of output compare events to support AUTOSAR (Automotive Open System Architecture) and operating system tasks
Software watchdog timer (SWT)	Provides protection from runaway code
Wakeup unit (WKPU)	The wakeup unit supports up to 27 external sources that can generate interrupts or wakeup events, of which 1 can cause non-maskable interrupt requests or wakeup events.

### 3 Package pinouts and signal descriptions

#### 3.1 Package pinouts

The available LQFP pinouts and the ballmap are provided in the following figures. For pin signal descriptions, please see [Table 6](#).

[Figure 2](#) shows the SPC560B54/6x in the LQFP176 package.

Figure 2. LQFP176 pin configuration

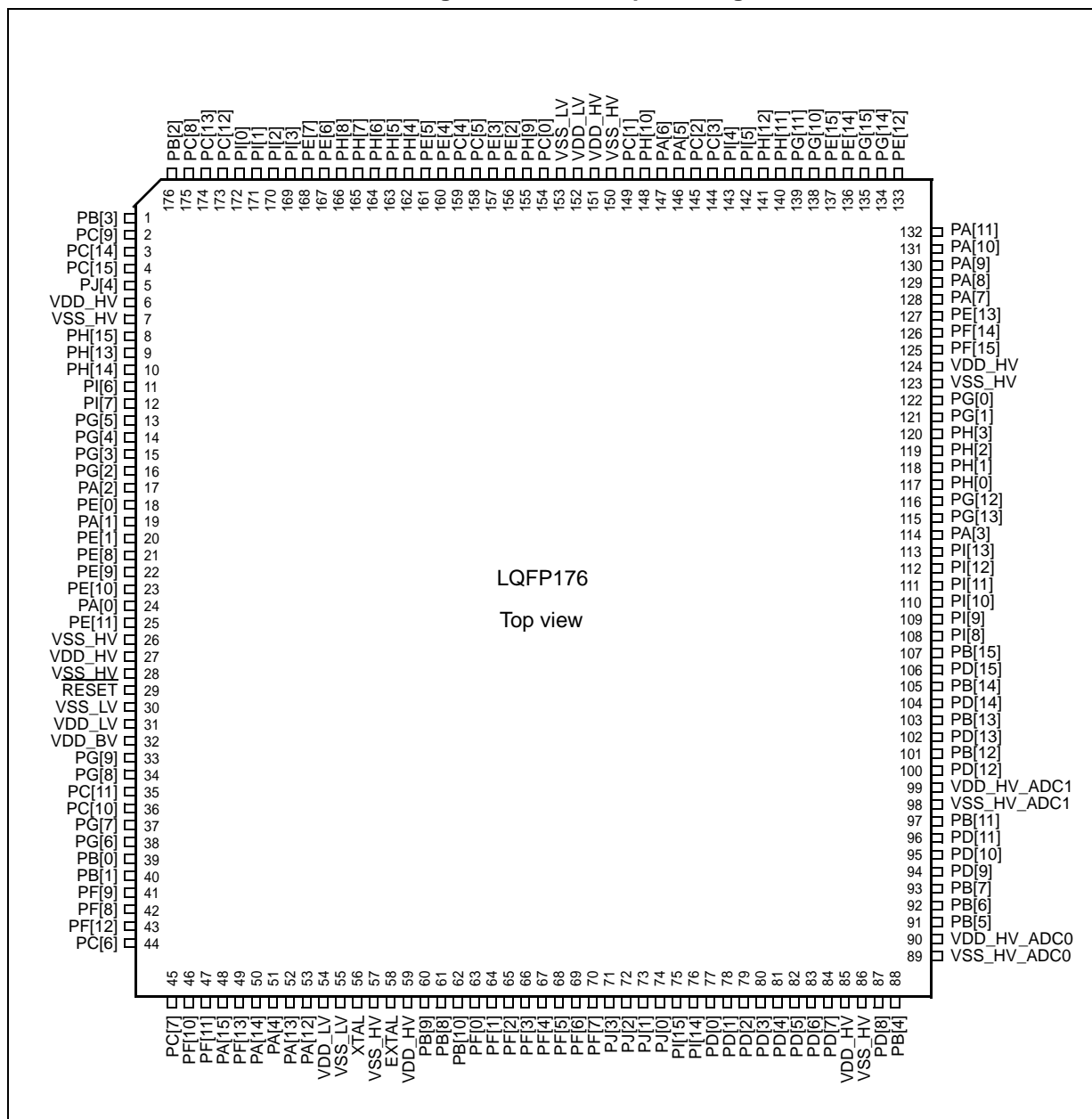


Figure 3 shows the SPC560B54/6x in the LQFP144 package.

Figure 3. LQFP144 pin configuration

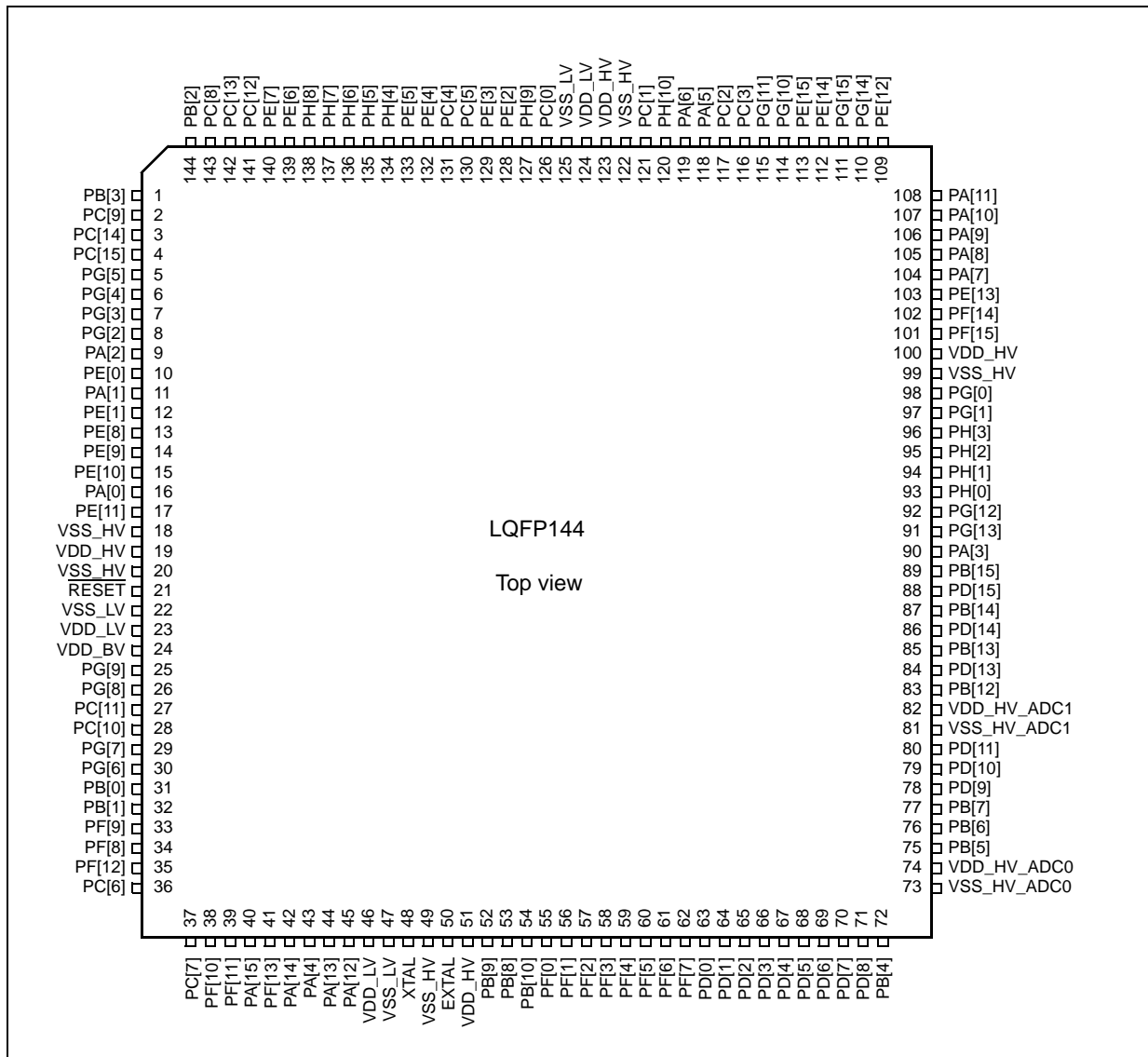


Figure 4 shows the SPC560B54/6x in the LQFP100 package.

Figure 4. LQFP100 pin configuration

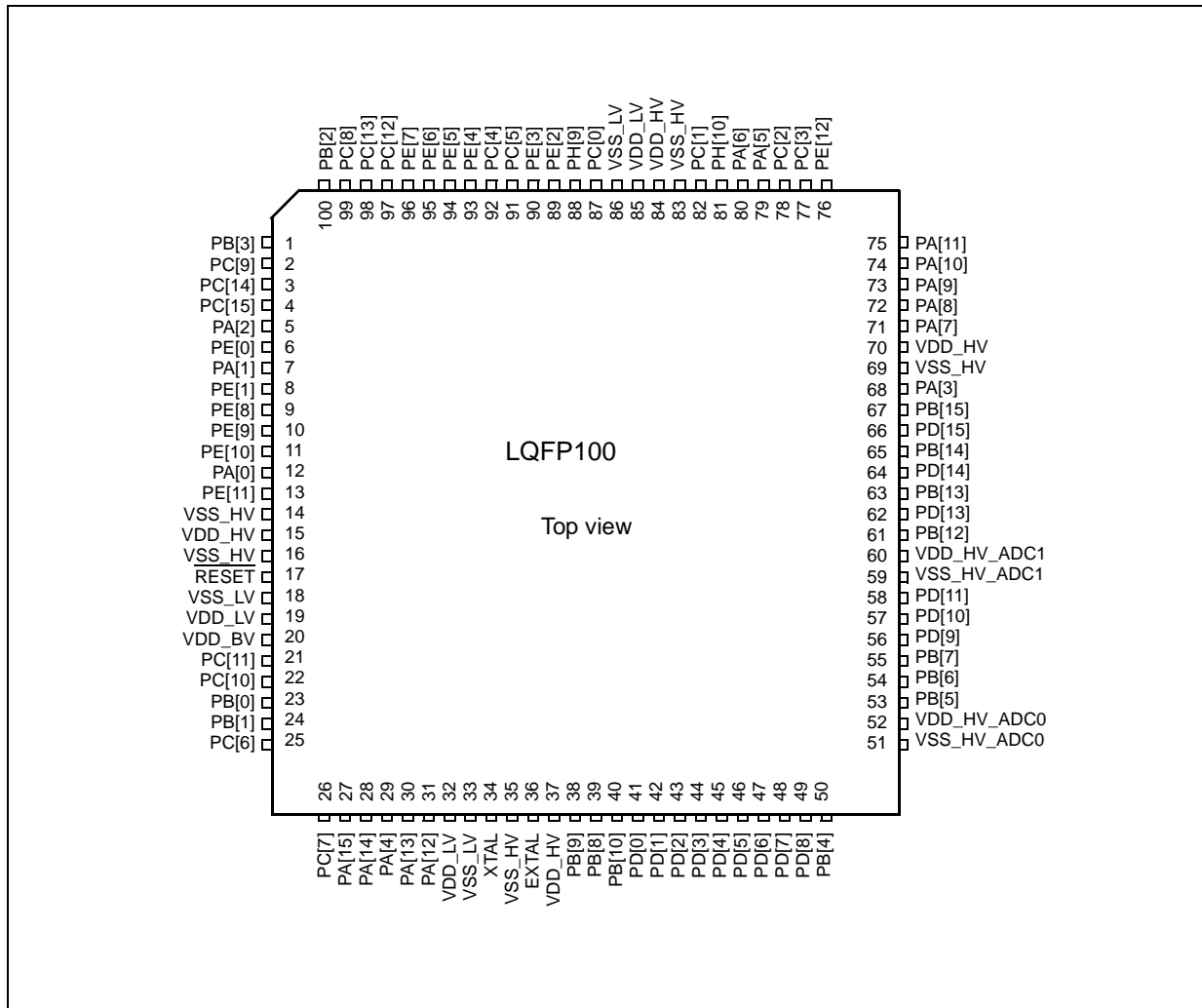


Figure 5 shows the SPC560B54/6x in the LBG208 package.

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16				
A	PC[8]	PC[13]	PH[15]	PJ[4]	PH[8]	PH[4]	PC[5]	PC[0]	PI[0]	PI[1]	PC[2]	PI[4]	PE[15]	PH[11]	NC	NC	A			
B	PC[9]	PB[2]	PH[13]	PC[12]	PE[6]	PH[5]	PC[4]	PH[9]	PH[10]	PI[2]	PC[3]	PG[11]	PG[15]	PG[14]	PA[11]	PA[10]	B			
C	PC[14]	VDD_H V	PB[3]	PE[7]	PH[7]	PE[5]	PE[3]	VSS_LV	PC[1]	PI[3]	PA[5]	PI[5]	PE[14]	PE[12]	PA[9]	PA[8]	C			
D	PH[14]	PI[6]	PC[15]	PI[7]	PH[6]	PE[4]	PE[2]	VDD_L V	VDD_H V	NC	PA[6]	PH[12]	PG[10]	PF[14]	PE[13]	PA[7]	D			
E	PG[4]	PG[5]	PG[3]	PG[2]									PG[1]	PG[0]	PF[15]	VDD_H V	E			
F	PE[0]	PA[2]	PA[1]	PE[1]									PH[0]	PH[1]	PH[3]	PH[2]	F			
G	PE[9]	PE[8]	PE[10]	PA[0]	VSS_H V				VSS_H V	VSS_H V	VSS_H V	VSS_H V	VDD_H V				PI[12]	PI[13]	MSEO	G
H	VSS_HV	PE[11]	VDD_H V	NC	VSS_H V				VSS_H V	VSS_H V	VSS_H V	VSS_H V	MDO3				MDO2	MDO0	MDO1	H
J	RESET	VSS_LV	NC	NC	VSS_H V				VSS_H V	VSS_H V	VSS_H V	VSS_H V	PI[8]				PI[9]	PI[10]	PI[11]	J
K	EVTI	NC	VDD_B V	VDD_L V	VSS_H V				VSS_H V	VSS_H V	VSS_H V	VSS_H V	VDD_H V_ADC 1		PG[12]	PA[3]	PG[13]	K		
L	PG[9]	PG[8]	NC	EVTO									PB[15]		PD[15]	PD[14]	PB[14]	L		
M	PG[7]	PG[6]	PC[10]	PC[11]									PB[13]		PD[13]	PD[12]	PB[12]	M		
N	PB[1]	PF[9]	PB[0]	VDD_H V	PJ[0]	PA[4]	VSS_LV	EXTAL	VDD_H V	PF[0]	PF[4]	VSS_H V_ADC 1	PB[11]	PD[10]	PD[9]	PD[11]	N			
P	PF[8]	PJ[3]	PC[7]	PJ[2]	PJ[1]	PA[14]	VDD_L V	XTAL	PB[10]	PF[1]	PF[5]	PD[0]	PD[3]	VDD_H V_ADC 0	PB[6]	PB[7]	P			
R	PF[12]	PC[6]	PF[10]	PF[11]	VDD_H V	PA[15]	PA[13]	PI[14]	XTAL32	PF[3]	PF[7]	PD[2]	PD[4]	PD[7]	VSS_H V_ADC 0	PB[5]	R			
T	NC	NC	NC	MCKO	NC	PF[13]	PA[12]	PI[15]	EXTAL 32	PF[2]	PF[6]	PD[1]	PD[5]	PD[6]	PD[8]	PB[4]	T			

NOTE: The LBG208 is available only as development package for Nexus 2+.

NC = Not connected

Figure 5. LBG208 configuration

### 3.2 Pad configuration during reset phases

All pads have a fixed configuration under reset.

During the power-up phase, all pads are forced to tristate.

After power-up phase, all pads are tristate with the following exceptions:

- PA[9] (FAB) is pull-down. Without external strong pull-up the device starts fetching from flash.
- PA[8], PC[0] and PH[9:10] are in input weak pull-up when out of reset.
- RESET pad is driven low by the device till 40 FIRC clock cycles after phase2 completion. Minimum phase3 duration is 40 FIRC cycles.
- Nexus output pads (MDO[n], MCKO, EVTO, MSEO) are forced to output.

### 3.3 Pad configuration during standby mode exit

Pad configuration (input buffer enable, pull enable) for low-power wakeup pads is controlled by both the SIUL and WKPU modules. During standby exit, all low power pads PA[0,1,2,4,15], PB[1,3,8,9,10]<sup>(a)</sup>, PC[7,9,11], PD[0,1], PE[0,9,11], PF[9,11,13]<sup>(b)</sup>, PG[3,5,7,9]<sup>(b)</sup>, PI[1,3]<sup>(c)</sup> are configured according to their respective configuration done in the WKPU module. All other pads will have the same configuration as expected after a reset.

The TDO pad has been moved into the STANDBY domain in order to allow low-power debug handshaking in STANDBY mode. However, no pull-resistor is active on the TDO pad while in STANDBY mode. At this time the pad is configured as an input. When no debugger is connected the TDO pad is floating causing additional current consumption.

To avoid the extra consumption TDO must be connected. An external pull-up resistor in the range of 47–100 kOhms should be added between the TDO pin and VDD. Only if the TDO pin is used as an application pin and a pull-up cannot be used should a pull-down resistor with the same value be used instead between the TDO pin and GND.

### 3.4 Voltage supply pins

Voltage supply pins are used to provide power to the device. Three dedicated VDD\_LV/VSS\_LV supply pairs are used for 1.2 V regulator stabilization.

**Table 4. Voltage supply pin descriptions**

Port pin	Function	Pin number			
		LQFP100	LQFP144	LQFP176	LBGA208
VDD_HV	Digital supply voltage	15, 37, 70, 84	19, 51, 100, 123	6, 27, 59, 85, 124, 151	C2, D9, E16, G13, H3, N4, N9, R5
VSS_HV	Digital ground	14, 16, 35, 69, 83	18, 20, 49, 99, 122	7, 26, 28, 57, 86, 123, 150	G7, G8, G9, G10, H7, H8, H9, H10, J7, J8, J9, J10, K7, K8, K9, K10
VDD_LV	1.2 V decoupling pins. Decoupling capacitor must be connected between these pins and the nearest V <sub>SS_LV</sub> pin. <sup>(1)</sup>	19, 32, 85	23, 46, 124	31, 54, 152	D8, K4, P7
VSS_LV	1.2 V decoupling pins. Decoupling capacitor must be connected between these pins and the nearest V <sub>DD_LV</sub> pin. <sup>(1)</sup>	18, 33, 86	22, 47, 125	30, 55, 153	C8, J2, N7

a. PB[8, 9] ports have wakeup functionality in all modes except STANDBY.

b. PF[9,11,13], PG[3,5,7,9], PI[1,3] are not available in the 100-pin LQFP.

c. PI[1,3] are not available in the 144-pin LQFP.



**Table 4. Voltage supply pin descriptions (continued)**

Port pin	Function	Pin number			
		LQFP100	LQFP144	LQFP176	LBGA208
VDD_BV	Internal regulator supply voltage	20	24	32	K3
VSS_HV_ADC0	Reference ground and analog ground for the A/D converter 0 (10-bit)	51	73	89	R15
VDD_HV_ADC0	Reference voltage and analog supply for the A/D converter 0 (10-bit)	52	74	90	P14
VSS_HV_ADC1	Reference ground and analog ground for the A/D converter 1 (12-bit)	59	81	98	N12
VDD_HV_ADC1	Reference voltage and analog supply for the A/D converter 1 (12-bit)	60	82	99	K13

1. A decoupling capacitor must be placed between each of the three VDD\_LV/VSS\_LV supply pairs to ensure stable voltage (see the recommended operating conditions in the device datasheet).

### 3.5 Pad types

In the device the following types of pads are available for system pins and functional port pins:

- S = Slow<sup>(d)</sup>
- M = Medium<sup>(d)</sup> (e)
- F = Fast<sup>(d)</sup> (e)
- I = Input only with analog feature<sup>(d)</sup>
- J = Input/Output ('S' pad) with analog feature
- X = Oscillator

### 3.6 System pins

The system pins are listed in [Table 5](#).

d. See the I/O pad electrical characteristics in the chip datasheet for details.

e. All medium and fast pads are in slow configuration by default at reset and can be configured as fast or medium. The only exception is PC[1] which is in medium configuration by default (see the PCR.SRC description in the chip reference manual, Pad Configuration Registers (PCR0–PCR148)).

**Table 5. System pin descriptions**

Port pin	Function	I/O direction	Pad type	RESET configuration	Pin number			
					LQFP 100	LQFP 144	LQFP 176	LBGA 208 <sup>(1)</sup>
RESET	Bidirectional reset with Schmitt-Trigger characteristics and noise filter.	I/O	M	Input weak pull-up after RGM PHASE2 and 40 FIRC cycles	17	21	29	J1
EXTAL	Analog output of the oscillator amplifier circuit, when the oscillator is not in bypass mode. Analog input for the clock generator when the oscillator is in bypass mode.	I/O	X	Tristate	36	50	58	N8
XTAL	Analog input of the oscillator amplifier circuit. Needs to be grounded if oscillator bypass mode is used.	I	X	Tristate	34	48	56	P8

1. LBGA208 available only as development package for Nexus2+.

### 3.7 Functional port pins

The functional port pins are listed in [Table 6](#).

Table 6. Functional port pin descriptions

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP 100
Port A								
PA[0]	PCR[0]	AF0 AF1 AF2 AF3 —	GPIO[0] E0UC[0] CLKOUT E0UC[13] WKPU[19] <sup>(5)</sup>	SIUL eMIOS_0 MC_CGM eMIOS_0 WKPU	I/O I/O O I/O I	M	Tristate	12
PA[1]	PCR[1]	AF0 AF1 AF2 AF3 —	GPIO[1] E0UC[1] NMI <sup>(6)</sup> — WKPU[2] <sup>(5)</sup>	SIUL eMIOS_0 WKPU — WKPU	I/O I/O I — I	S	Tristate	7
PA[2]	PCR[2]	AF0 AF1 AF2 AF3 —	GPIO[2] E0UC[2] — MA[2] WKPU[3] <sup>(5)</sup>	SIUL eMIOS_0 — ADC_0 WKPU	I/O I/O — O I	S	Tristate	5
PA[3]	PCR[3]	AF0 AF1 AF2 AF3 — —	GPIO[3] E0UC[3] LIN5TX CS4_1 EIRQ[0] ADC1_S[0]	SIUL eMIOS_0 LINFlex_5 DSPI_1 SIUL ADC_1	I/O I/O O O I I	J	Tristate	68



**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PA[4]	PCR[4]	AF0 AF1 AF2 AF3 — —	GPIO[4] E0UC[4] — CS0_1 LIN5RX WKPU[9] <sup>(5)</sup>	SIUL eMIOS_0 — DSPI_1 LINFlex_5 WKPU	I/O I/O — I/O I I	S	Tristate	29
PA[5]	PCR[5]	AF0 AF1 AF2 AF3	GPIO[5] E0UC[5] LIN4TX —	SIUL eMIOS_0 LINFlex_4 —	I/O I/O O —	M	Tristate	79
PA[6]	PCR[6]	AF0 AF1 AF2 AF3 — —	GPIO[6] E0UC[6] — CS1_1 EIRQ[1] LIN4RX	SIUL eMIOS_0 — DSPI_1 SIUL LINFlex_4	I/O I/O — O I I	S	Tristate	80
PA[7]	PCR[7]	AF0 AF1 AF2 AF3 — —	GPIO[7] E0UC[7] LIN3TX — EIRQ[2] ADC1_S[1]	SIUL eMIOS_0 LINFlex_3 — SIUL ADC_1	I/O I/O O — I I	J	Tristate	71

Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PA[8]	PCR[8]	AF0 AF1 AF2 AF3 — N/A <sup>(7)</sup> —	GPIO[8] E0UC[8] E0UC[14] — EIRQ[3] ABS[0] LIN3RX	SIUL eMIOS_0 eMIOS_0 — SIUL BAM LINFlex_3	I/O I/O I/O — I I I	S	Input, weak pull- up	72
PA[9]	PCR[9]	AF0 AF1 AF2 AF3 N/A <sup>(7)</sup>	GPIO[9] E0UC[9] — CS2_1 FAB	SIUL eMIOS_0 — DSPI_1 BAM	I/O I/O — O I	S	Pull- down	73
PA[10]	PCR[10]	AF0 AF1 AF2 AF3 —	GPIO[10] E0UC[10] SDA LIN2TX ADC1_S[2]	SIUL eMIOS_0 I <sup>2</sup> C_0 LINFlex_2 ADC_1	I/O I/O I/O O I	J	Tristate	74
PA[11]	PCR[11]	AF0 AF1 AF2 AF3 — — —	GPIO[11] E0UC[11] SCL — EIRQ[16] LIN2RX ADC1_S[3]	SIUL eMIOS_0 I <sup>2</sup> C_0 — SIUL LINFlex_2 ADC_1	I/O I/O I/O — I I I	J	Tristate	75





**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PA[12]	PCR[12]	AF0	GPIO[12]	SIUL	I/O	S	Tristate	31
		AF1	—	—	—			
		AF2	E0UC[28]	eMIOS_0	I/O			
		AF3	CS3_1	DSPI_1	O			
		—	EIRQ[17]	SIUL	I			
		—	SIN_0	DSPI_0	I			
PA[13]	PCR[13]	AF0	GPIO[13]	SIUL	I/O	M	Tristate	30
		AF1	SOUT_0	DSPI_0	O			
		AF2	E0UC[29]	eMIOS_0	I/O			
		AF3	—	—	—			
		—	—	—	—			
PA[14]	PCR[14]	AF0	GPIO[14]	SIUL	I/O	M	Tristate	28
		AF1	SCK_0	DSPI_0	I/O			
		AF2	CS0_0	DSPI_0	I/O			
		AF3	E0UC[0]	eMIOS_0	I/O			
		—	EIRQ[4]	SIUL	I			
		—	—	—	—			
PA[15]	PCR[15]	AF0	GPIO[15]	SIUL	I/O	M	Tristate	27
		AF1	CS0_0	DSPI_0	I/O			
		AF2	SCK_0	DSPI_0	I/O			
		AF3	E0UC[1]	eMIOS_0	I/O			
		—	WKPU[10] <sup>(5)</sup>	WKPU	I			
		—	—	—	—			
<b>Port B</b>								
PB[0]	PCR[16]	AF0	GPIO[16]	SIUL	I/O	M	Tristate	23
		AF1	CAN0TX	FlexCAN_0	O			
		AF2	E0UC[30]	eMIOS_0	I/O			
		AF3	LIN0TX	LINFlex_0	O			

Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PB[1]	PCR[17]	AF0	GPIO[17]	SIUL	I/O	S	Tristate	24
		AF1	—	—	—			
		AF2	E0UC[31]	eMIOS_0	I/O			
		AF3	—	—	—			
		—	WKPU[4] <sup>(5)</sup>	WKPU	I			
		—	CAN0RX	FlexCAN_0	I			
—	LIN0RX	LINFlex_0	I					
PB[2]	PCR[18]	AF0	GPIO[18]	SIUL	I/O	M	Tristate	100
		AF1	LIN0TX	LINFlex_0	O			
		AF2	SDA	I <sup>2</sup> C_0	I/O			
		AF3	E0UC[30]	eMIOS_0	I/O			
PB[3]	PCR[19]	AF0	GPIO[19]	SIUL	I/O	S	Tristate	1
		AF1	E0UC[31]	eMIOS_0	I/O			
		AF2	SCL	I <sup>2</sup> C_0	I/O			
		AF3	—	—	—			
		—	WKPU[11] <sup>(5)</sup>	WKPU	I			
		—	LIN0RX	LINFlex_0	I			
PB[4]	PCR[20]	AF0	—	—	—	I	Tristate	50
		AF1	—	—	—			
		AF2	—	—	—			
		AF3	—	—	—			
		—	ADC0_P[0]	ADC_0	I			
		—	ADC1_P[0]	ADC_1	I			
—	GPIO[20]	SIUL	I					





**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PB[5]	PCR[21]	AF0	—	—	—	I	Tristate	53
		AF1	—	—	—			
		AF2	—	—	—			
		AF3	—	—	—			
		—	ADC0_P[1]	ADC_0	I			
		—	ADC1_P[1]	ADC_1	I			
		—	GPIO[21]	SIUL	I			
PB[6]	PCR[22]	AF0	—	—	—	I	Tristate	54
		AF1	—	—	—			
		AF2	—	—	—			
		AF3	—	—	—			
		—	ADC0_P[2]	ADC_0	I			
		—	ADC1_P[2]	ADC_1	I			
		—	GPIO[22]	SIUL	I			
PB[7]	PCR[23]	AF0	—	—	—	I	Tristate	55
		AF1	—	—	—			
		AF2	—	—	—			
		AF3	—	—	—			
		—	ADC0_P[3]	ADC_0	I			
		—	ADC1_P[3]	ADC_1	I			
		—	GPIO[23]	SIUL	I			



Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PB[8]	PCR[24]	AF0	GPIO[24]	SIUL	I	I	—	39
		AF1	—	—	—			
		AF2	—	—	—			
		AF3	—	—	—			
		—	OSC32K_XTAL <sup>(8)</sup>	OSC32K	—			
		—	WKPU[25] <sup>(5)</sup>	WKPU	I <sup>(9)</sup>			
		—	ADC0_S[0]	ADC_0	I			
—	ADC1_S[4]	ADC_1	I					
PB[9]	PCR[25]	AF0	GPIO[25]	SIUL	I	I	—	38
		AF1	—	—	—			
		AF2	—	—	—			
		AF3	—	—	—			
		—	OSC32K_EXTAL <sup>(8)</sup>	OSC32K	—			
		—	WKPU[26] <sup>(5)</sup>	WKPU	I <sup>(9)</sup>			
		—	ADC0_S[1]	ADC_0	I			
—	ADC1_S[5]	ADC_1	I					
PB[10]	PCR[26]	AF0	GPIO[26]	SIUL	I/O	J	Tristate	40
		AF1	—	—	—			
		AF2	—	—	—			
		AF3	—	—	—			
		—	WKPU[8] <sup>(5)</sup>	WKPU	I			
		—	ADC0_S[2]	ADC_0	I			
		—	ADC1_S[6]	ADC_1	I			



**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PB[11]	PCR[27]	AF0 AF1 AF2 AF3 —	GPIO[27] E0UC[3] — CS0_0 ADC0_S[3]	SIUL eMIOS_0 — DSPI_0 ADC_0	I/O I/O — I/O I	J	Tristate	—
PB[12]	PCR[28]	AF0 AF1 AF2 AF3 —	GPIO[28] E0UC[4] — CS1_0 ADC0_X[0]	SIUL eMIOS_0 — DSPI_0 ADC_0	I/O I/O — O I	J	Tristate	61
PB[13]	PCR[29]	AF0 AF1 AF2 AF3 —	GPIO[29] E0UC[5] — CS2_0 ADC0_X[1]	SIUL eMIOS_0 — DSPI_0 ADC_0	I/O I/O — O I	J	Tristate	63
PB[14]	PCR[30]	AF0 AF1 AF2 AF3 —	GPIO[30] E0UC[6] — CS3_0 ADC0_X[2]	SIUL eMIOS_0 — DSPI_0 ADC_0	I/O I/O — O I	J	Tristate	65
PB[15]	PCR[31]	AF0 AF1 AF2 AF3 —	GPIO[31] E0UC[7] — CS4_0 ADC0_X[3]	SIUL eMIOS_0 — DSPI_0 ADC_0	I/O I/O — O I	J	Tristate	67

Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
Port C								
PC[0] <sup>(10)</sup>	PCR[32]	AF0 AF1 AF2 AF3	GPIO[32] — TDI —	SIUL — JTAGC —	I/O — I —	M	Input, weak pull- up	87
PC[1] <sup>(10)</sup>	PCR[33]	AF0 AF1 AF2 AF3	GPIO[33] — TDO —	SIUL — JTAGC —	I/O — O —	F <sup>(11)</sup>	Tristate	82
PC[2]	PCR[34]	AF0 AF1 AF2 AF3 —	GPIO[34] SCK_1 CAN4TX DEBUG[0] EIRQ[5]	SIUL DSPI_1 FlexCAN_4 SSCM SIUL	I/O I/O O O I	M	Tristate	78
PC[3]	PCR[35]	AF0 AF1 AF2 AF3 — — —	GPIO[35] CS0_1 MA[0] DEBUG[1] EIRQ[6] CAN1RX CAN4RX	SIUL DSPI_1 ADC_0 SSCM SIUL FlexCAN_1 FlexCAN_4	I/O I/O O O I I I	S	Tristate	77



**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PC[4]	PCR[36]	AF0	GPIO[36]	SIUL	I/O	M	Tristate	92
		AF1	E1UC[31]	eMIOS_1	I/O			
		AF2	—	—	—			
		AF3	DEBUG[2]	SSCM	O			
		—	EIRQ[18]	SIUL	I			
		—	SIN_1	DSPI_1	I			
		—	CAN3RX	FlexCAN_3	I			
PC[5]	PCR[37]	AF0	GPIO[37]	SIUL	I/O	M	Tristate	91
		AF1	SOUT_1	DSPI_1	O			
		AF2	CAN3TX	FlexCAN_3	O			
		AF3	DEBUG[3]	SSCM	O			
		—	EIRQ[7]	SIUL	I			
PC[6]	PCR[38]	AF0	GPIO[38]	SIUL	I/O	S	Tristate	25
		AF1	LIN1TX	LINFlex_1	O			
		AF2	E1UC[28]	eMIOS_1	I/O			
		AF3	DEBUG[4]	SSCM	O			
PC[7]	PCR[39]	AF0	GPIO[39]	SIUL	I/O	S	Tristate	26
		AF1	—	—	—			
		AF2	E1UC[29]	eMIOS_1	I/O			
		AF3	DEBUG[5]	SSCM	O			
		—	LIN1RX	LINFlex_1	I			
		—	WKPU[12] <sup>(5)</sup>	WKPU	I			

Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PC[8]	PCR[40]	AF0	GPIO[40]	SIUL	I/O	S	Tristate	99
		AF1	LIN2TX	LINFlex_2	O			
		AF2	E0UC[3]	eMIOS_0	I/O			
		AF3	DEBUG[6]	SSCM	O			
PC[9]	PCR[41]	AF0	GPIO[41]	SIUL	I/O	S	Tristate	2
		AF1	—	—	—			
		AF2	E0UC[7]	eMIOS_0	I/O			
		AF3	DEBUG[7]	SSCM	O			
		—	WKPU[13] <sup>(5)</sup>	WKPU	I			
		—	LIN2RX	LINFlex_2	I			
PC[10]	PCR[42]	AF0	GPIO[42]	SIUL	I/O	M	Tristate	22
		AF1	CAN1TX	FlexCAN_1	O			
		AF2	CAN4TX	FlexCAN_4	O			
		AF3	MA[1]	ADC_0	O			
PC[11]	PCR[43]	AF0	GPIO[43]	SIUL	I/O	S	Tristate	21
		AF1	—	—	—			
		AF2	—	—	—			
		AF3	MA[2]	ADC_0	O			
		—	WKPU[5] <sup>(5)</sup>	WKPU	I			
		—	CAN1RX	FlexCAN_1	I			
		—	CAN4RX	FlexCAN_4	I			



**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PC[12]	PCR[44]	AF0 AF1 AF2 AF3 — —	GPIO[44] E0UC[12] — — EIRQ[19] SIN_2	SIUL eMIOS_0 — — SIUL DSPI_2	I/O I/O — — I I	M	Tristate	97
PC[13]	PCR[45]	AF0 AF1 AF2 AF3	GPIO[45] E0UC[13] SOUT_2 —	SIUL eMIOS_0 DSPI_2 —	I/O I/O O —	S	Tristate	98
PC[14]	PCR[46]	AF0 AF1 AF2 AF3 —	GPIO[46] E0UC[14] SCK_2 — EIRQ[8]	SIUL eMIOS_0 DSPI_2 — SIUL	I/O I/O I/O — I	S	Tristate	3
PC[15]	PCR[47]	AF0 AF1 AF2 AF3 —	GPIO[47] E0UC[15] CS0_2 — EIRQ[20]	SIUL eMIOS_0 DSPI_2 — SIUL	I/O I/O I/O — I	M	Tristate	4
Port D								

Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PD[0]	PCR[48]	AF0 AF1 AF2 AF3 — — —	GPIO[48] — — — WKPU[27] <sup>(5)</sup> ADC0_P[4] ADC1_P[4]	SIUL — — — WKPU ADC_0 ADC_1	 — — —     		Tristate	41
PD[1]	PCR[49]	AF0 AF1 AF2 AF3 — — —	GPIO[49] — — — WKPU[28] <sup>(5)</sup> ADC0_P[5] ADC1_P[5]	SIUL — — — WKPU ADC_0 ADC_1	 — — —     		Tristate	42
PD[2]	PCR[50]	AF0 AF1 AF2 AF3 — —	GPIO[50] — — — ADC0_P[6] ADC1_P[6]	SIUL — — — ADC_0 ADC_1	 — — —   		Tristate	43
PD[3]	PCR[51]	AF0 AF1 AF2 AF3 — —	GPIO[51] — — — ADC0_P[7] ADC1_P[7]	SIUL — — — ADC_0 ADC_1	 — — —   		Tristate	44





**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PD[4]	PCR[52]	AF0 AF1 AF2 AF3 — —	GPIO[52] — — — ADC0_P[8] ADC1_P[8]	SIUL — — — ADC_0 ADC_1	 — — —   	I	Tristate	45
PD[5]	PCR[53]	AF0 AF1 AF2 AF3 — —	GPIO[53] — — — ADC0_P[9] ADC1_P[9]	SIUL — — — ADC_0 ADC_1	 — — —   	I	Tristate	46
PD[6]	PCR[54]	AF0 AF1 AF2 AF3 — —	GPIO[54] — — — ADC0_P[10] ADC1_P[10]	SIUL — — — ADC_0 ADC_1	 — — —   	I	Tristate	47
PD[7]	PCR[55]	AF0 AF1 AF2 AF3 — —	GPIO[55] — — — ADC0_P[11] ADC1_P[11]	SIUL — — — ADC_0 ADC_1	 — — —   	I	Tristate	48



Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PD[8]	PCR[56]	AF0 AF1 AF2 AF3 — —	GPIO[56] — — — ADC0_P[12] ADC1_P[12]	SIUL — — — ADC_0 ADC_1	 — — —   	I	Tristate	49
PD[9]	PCR[57]	AF0 AF1 AF2 AF3 — —	GPIO[57] — — — ADC0_P[13] ADC1_P[13]	SIUL — — — ADC_0 ADC_1	 — — —   	I	Tristate	56
PD[10]	PCR[58]	AF0 AF1 AF2 AF3 — —	GPIO[58] — — — ADC0_P[14] ADC1_P[14]	SIUL — — — ADC_0 ADC_1	 — — —   	I	Tristate	57
PD[11]	PCR[59]	AF0 AF1 AF2 AF3 — —	GPIO[59] — — — ADC0_P[15] ADC1_P[15]	SIUL — — — ADC_0 ADC_1	 — — —   	I	Tristate	58





**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PD[12]	PCR[60]	AF0 AF1 AF2 AF3 —	GPIO[60] CS5_0 E0UC[24] — ADC0_S[4]	SIUL DSPI_0 eMIOS_0 — ADC_0	I/O O I/O — I	J	Tristate	—
PD[13]	PCR[61]	AF0 AF1 AF2 AF3 —	GPIO[61] CS0_1 E0UC[25] — ADC0_S[5]	SIUL DSPI_1 eMIOS_0 — ADC_0	I/O I/O I/O — I	J	Tristate	62
PD[14]	PCR[62]	AF0 AF1 AF2 AF3 —	GPIO[62] CS1_1 E0UC[26] — ADC0_S[6]	SIUL DSPI_1 eMIOS_0 — ADC_0	I/O O I/O — I	J	Tristate	64
PD[15]	PCR[63]	AF0 AF1 AF2 AF3 —	GPIO[63] CS2_1 E0UC[27] — ADC0_S[7]	SIUL DSPI_1 eMIOS_0 — ADC_0	I/O O I/O — I	J	Tristate	66
Port E								

Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PE[0]	PCR[64]	AF0 AF1 AF2 AF3 — —	GPIO[64] E0UC[16] — — WKPU[6] <sup>(5)</sup> CAN5RX	SIUL eMIOS_0 — — WKPU FlexCAN_5	I/O I/O — — I I	S	Tristate	6
PE[1]	PCR[65]	AF0 AF1 AF2 AF3	GPIO[65] E0UC[17] CAN5TX —	SIUL eMIOS_0 FlexCAN_5 —	I/O I/O O —	M	Tristate	8
PE[2]	PCR[66]	AF0 AF1 AF2 AF3 — —	GPIO[66] E0UC[18] — — EIRQ[21] SIN_1	SIUL eMIOS_0 — — SIUL DSPI_1	I/O I/O — — I I	M	Tristate	89
PE[3]	PCR[67]	AF0 AF1 AF2 AF3	GPIO[67] E0UC[19] SOUT_1 —	SIUL eMIOS_0 DSPI_1 —	I/O I/O O —	M	Tristate	90
PE[4]	PCR[68]	AF0 AF1 AF2 AF3 —	GPIO[68] E0UC[20] SCK_1 — EIRQ[9]	SIUL eMIOS_0 DSPI_1 — SIUL	I/O I/O I/O — I	M	Tristate	93



**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PE[5]	PCR[69]	AF0 AF1 AF2 AF3	GPIO[69] E0UC[21] CS0_1 MA[2]	SIUL eMIOS_0 DSPI_1 ADC_0	I/O I/O I/O O	M	Tristate	94
PE[6]	PCR[70]	AF0 AF1 AF2 AF3 —	GPIO[70] E0UC[22] CS3_0 MA[1] EIRQ[22]	SIUL eMIOS_0 DSPI_0 ADC_0 SIUL	I/O I/O O O I	M	Tristate	95
PE[7]	PCR[71]	AF0 AF1 AF2 AF3 —	GPIO[71] E0UC[23] CS2_0 MA[0] EIRQ[23]	SIUL eMIOS_0 DSPI_0 ADC_0 SIUL	I/O I/O O O I	M	Tristate	96
PE[8]	PCR[72]	AF0 AF1 AF2 AF3	GPIO[72] CAN2TX E0UC[22] CAN3TX	SIUL FlexCAN_2 eMIOS_0 FlexCAN_3	I/O O I/O O	M	Tristate	9
PE[9]	PCR[73]	AF0 AF1 AF2 AF3 — — —	GPIO[73] — E0UC[23] — WKPU[7] <sup>(5)</sup> CAN2RX CAN3RX	SIUL — eMIOS_0 — WKPU FlexCAN_2 FlexCAN_3	I/O — I/O — I I I	S	Tristate	10

Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PE[10]	PCR[74]	AF0 AF1 AF2 AF3 —	GPIO[74] LIN3TX CS3_1 E1UC[30] EIRQ[10]	SIUL LINFlex_3 DSPI_1 eMIOS_1 SIUL	I/O O O I/O I	S	Tristate	11
PE[11]	PCR[75]	AF0 AF1 AF2 AF3 — — —	GPIO[75] E0UC[24] CS4_1 — LIN3RX WKPU[14] <sup>(5)</sup>	SIUL eMIOS_0 DSPI_1 — LINFlex_3 WKPU	I/O I/O O — I I	S	Tristate	13
PE[12]	PCR[76]	AF0 AF1 AF2 AF3 — — —	GPIO[76] — E1UC[19] <sup>(12)</sup> — EIRQ[11] SIN_2 ADC1_S[7]	SIUL — eMIOS_1 — SIUL DSPI_2 ADC_1	I/O — I/O — I I I	J	Tristate	76
PE[13]	PCR[77]	AF0 AF1 AF2 AF3	GPIO[77] SOUT_2 E1UC[20] —	SIUL DSPI_2 eMIOS_1 —	I/O O I/O —	S	Tristate	—



**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PE[14]	PCR[78]	AF0 AF1 AF2 AF3 —	GPIO[78] SCK_2 E1UC[21] — EIRQ[12]	SIUL DSPI_2 eMIOS_1 — SIUL	I/O I/O I/O — I	S	Tristate	—
PE[15]	PCR[79]	AF0 AF1 AF2 AF3	GPIO[79] CS0_2 E1UC[22] —	SIUL DSPI_2 eMIOS_1 —	I/O I/O I/O —	M	Tristate	—
Port F								
PF[0]	PCR[80]	AF0 AF1 AF2 AF3 —	GPIO[80] E0UC[10] CS3_1 — ADC0_S[8]	SIUL eMIOS_0 DSPI_1 — ADC_0	I/O I/O O — I	J	Tristate	—
PF[1]	PCR[81]	AF0 AF1 AF2 AF3 —	GPIO[81] E0UC[11] CS4_1 — ADC0_S[9]	SIUL eMIOS_0 DSPI_1 — ADC_0	I/O I/O O — I	J	Tristate	—
PF[2]	PCR[82]	AF0 AF1 AF2 AF3 —	GPIO[82] E0UC[12] CS0_2 — ADC0_S[10]	SIUL eMIOS_0 DSPI_2 — ADC_0	I/O I/O I/O — I	J	Tristate	—

Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PF[3]	PCR[83]	AF0 AF1 AF2 AF3 —	GPIO[83] E0UC[13] CS1_2 — ADC0_S[11]	SIUL eMIOS_0 DSPI_2 — ADC_0	I/O I/O O — I	J	Tristate	—
PF[4]	PCR[84]	AF0 AF1 AF2 AF3 —	GPIO[84] E0UC[14] CS2_2 — ADC0_S[12]	SIUL eMIOS_0 DSPI_2 — ADC_0	I/O I/O O — I	J	Tristate	—
PF[5]	PCR[85]	AF0 AF1 AF2 AF3 —	GPIO[85] E0UC[22] CS3_2 — ADC0_S[13]	SIUL eMIOS_0 DSPI_2 — ADC_0	I/O I/O O — I	J	Tristate	—
PF[6]	PCR[86]	AF0 AF1 AF2 AF3 —	GPIO[86] E0UC[23] CS1_1 — ADC0_S[14]	SIUL eMIOS_0 DSPI_1 — ADC_0	I/O I/O O — I	J	Tristate	—
PF[7]	PCR[87]	AF0 AF1 AF2 AF3 —	GPIO[87] — CS2_1 — ADC0_S[15]	SIUL — DSPI_1 — ADC_0	I/O — O — I	J	Tristate	—





**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PF[8]	PCR[88]	AF0	GPIO[88]	SIUL	I/O	M	Tristate	—
		AF1	CAN3TX	FlexCAN_3	O			
		AF2	CS4_0	DSPI_0	O			
		AF3	CAN2TX	FlexCAN_2	O			
PF[9]	PCR[89]	AF0	GPIO[89]	SIUL	I/O	S	Tristate	—
		AF1	E1UC[1]	eMIOS_1	I/O			
		AF2	CS5_0	DSPI_0	O			
		AF3	—	—	—			
		—	WKPU[22] <sup>(5)</sup>	WKPU	I			
		—	CAN2RX	FlexCAN_2	I			
—	CAN3RX	FlexCAN_3	I					
PF[10]	PCR[90]	AF0	GPIO[90]	SIUL	I/O	M	Tristate	—
		AF1	CS1_0	DSPI_0	O			
		AF2	LIN4TX	LINFlex_4	O			
		AF3	E1UC[2]	eMIOS_1	I/O			
PF[11]	PCR[91]	AF0	GPIO[91]	SIUL	I/O	S	Tristate	—
		AF1	CS2_0	DSPI_0	O			
		AF2	E1UC[3]	eMIOS_1	I/O			
		AF3	—	—	—			
		—	WKPU[15] <sup>(5)</sup>	WKPU	I			
		—	LIN4RX	LINFlex_4	I			
PF[12]	PCR[92]	AF0	GPIO[92]	SIUL	I/O	M	Tristate	—
		AF1	E1UC[25]	eMIOS_1	I/O			
		AF2	LIN5TX	LINFlex_5	O			
		AF3	—	—	—			



Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PF[13]	PCR[93]	AF0	GPIO[93]	SIUL	I/O	S	Tristate	—
		AF1	E1UC[26]	eMIOS_1	I/O			
		AF2	—	—	—			
		AF3	—	—	—			
		—	WKPU[16] <sup>(5)</sup>	WKPU	I			
—	LIN5RX	LINFlex_5	I					
PF[14]	PCR[94]	AF0	GPIO[94]	SIUL	I/O	M	Tristate	—
		AF1	CAN4TX	FlexCAN_4	O			
		AF2	E1UC[27]	eMIOS_1	I/O			
		AF3	CAN1TX	FlexCAN_1	O			
PF[15]	PCR[95]	AF0	GPIO[95]	SIUL	I/O	S	Tristate	—
		AF1	E1UC[4]	eMIOS_1	I/O			
		AF2	—	—	—			
		AF3	—	—	—			
		—	EIRQ[13]	SIUL	I			
		—	CAN1RX	FlexCAN_1	I			
—	CAN4RX	FlexCAN_4	I					
Port G								
PG[0]	PCR[96]	AF0	GPIO[96]	SIUL	I/O	M	Tristate	—
		AF1	CAN5TX	FlexCAN_5	O			
		AF2	E1UC[23]	eMIOS_1	I/O			
		AF3	—	—	—			





**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PG[1]	PCR[97]	AF0 AF1 AF2 AF3 — —	GPIO[97] — E1UC[24] — EIRQ[14] CAN5RX	SIUL — eMIOS_1 — SIUL FlexCAN_5	I/O — I/O — I I	S	Tristate	—
PG[2]	PCR[98]	AF0 AF1 AF2 AF3	GPIO[98] E1UC[11] SOUT_3 —	SIUL eMIOS_1 DSPI_3 —	I/O I/O O —	M	Tristate	—
PG[3]	PCR[99]	AF0 AF1 AF2 AF3 —	GPIO[99] E1UC[12] CS0_3 — WKPU[17] <sup>(5)</sup>	SIUL eMIOS_1 DSPI_3 — WKPU	I/O I/O I/O — I	S	Tristate	—
PG[4]	PCR[100]	AF0 AF1 AF2 AF3	GPIO[100] E1UC[13] SCK_3 —	SIUL eMIOS_1 DSPI_3 —	I/O I/O I/O —	M	Tristate	—
PG[5]	PCR[101]	AF0 AF1 AF2 AF3 — —	GPIO[101] E1UC[14] — — WKPU[18] <sup>(5)</sup> SIN_3	SIUL eMIOS_1 — — WKPU DSPI_3	I/O I/O — — I I	S	Tristate	—

Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PG[6]	PCR[102]	AF0 AF1 AF2 AF3	GPIO[102] E1UC[15] LIN6TX —	SIUL eMIOS_1 LINFlex_6 —	I/O I/O O —	M	Tristate	—
PG[7]	PCR[103]	AF0 AF1 AF2 AF3 — —	GPIO[103] E1UC[16] E1UC[30] — WKPU[20] <sup>(5)</sup> LIN6RX	SIUL eMIOS_1 eMIOS_1 — WKPU LINFlex_6	I/O I/O I/O — I I	S	Tristate	—
PG[8]	PCR[104]	AF0 AF1 AF2 AF3 —	GPIO[104] E1UC[17] LIN7TX CS0_2 EIRQ[15]	SIUL eMIOS_1 LINFlex_7 DSPI_2 SIUL	I/O I/O O I/O I	S	Tristate	—
PG[9]	PCR[105]	AF0 AF1 AF2 AF3 — —	GPIO[105] E1UC[18] — SCK_2 WKPU[21] <sup>(5)</sup> LIN7RX	SIUL eMIOS_1 — DSPI_2 WKPU LINFlex_7	I/O I/O — I/O I I	S	Tristate	—



**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PG[10]	PCR[106]	AF0 AF1 AF2 AF3 —	GPIO[106] E0UC[24] E1UC[31] — SIN_4	SIUL eMIOS_0 eMIOS_1 — DSPI_4	I/O I/O I/O — I	S	Tristate	—
PG[11]	PCR[107]	AF0 AF1 AF2 AF3	GPIO[107] E0UC[25] CS0_4 —	SIUL eMIOS_0 DSPI_4 —	I/O I/O I/O —	M	Tristate	—
PG[12]	PCR[108]	AF0 AF1 AF2 AF3	GPIO[108] E0UC[26] SOUT_4 —	SIUL eMIOS_0 DSPI_4 —	I/O I/O O —	M	Tristate	—
PG[13]	PCR[109]	AF0 AF1 AF2 AF3	GPIO[109] E0UC[27] SCK_4 —	SIUL eMIOS_0 DSPI_4 —	I/O I/O I/O —	M	Tristate	—
PG[14]	PCR[110]	AF0 AF1 AF2 AF3	GPIO[110] E1UC[0] LIN8TX —	SIUL eMIOS_1 LINFlex_8 —	I/O I/O O —	S	Tristate	—

Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PG[15]	PCR[111]	AF0	GPIO[111]	SIUL	I/O	M	Tristate	—
		AF1	E1UC[1]	eMIOS_1	I/O			
		AF2	—	—	—			
		AF3	—	—	—			
		—	LIN8RX	LINFlex_8	I			
Port H								
PH[0]	PCR[112]	AF0	GPIO[112]	SIUL	I/O	M	Tristate	—
		AF1	E1UC[2]	eMIOS_1	I/O			
		AF2	—	—	—			
		AF3	—	—	—			
		—	SIN_1	DSPI_1	I			
PH[1]	PCR[113]	AF0	GPIO[113]	SIUL	I/O	M	Tristate	—
		AF1	E1UC[3]	eMIOS_1	I/O			
		AF2	SOUT_1	DSPI_1	O			
		AF3	—	—	—			
		—	—	—	—			
PH[2]	PCR[114]	AF0	GPIO[114]	SIUL	I/O	M	Tristate	—
		AF1	E1UC[4]	eMIOS_1	I/O			
		AF2	SCK_1	DSPI_1	I/O			
		AF3	—	—	—			
		—	—	—	—			
PH[3]	PCR[115]	AF0	GPIO[115]	SIUL	I/O	M	Tristate	—
		AF1	E1UC[5]	eMIOS_1	I/O			
		AF2	CS0_1	DSPI_1	I/O			
		AF3	—	—	—			
		—	—	—	—			





**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PH[4]	PCR[116]	AF0 AF1 AF2 AF3	GPIO[116] E1UC[6] — —	SIUL eMIOS_1 — —	I/O I/O — —	M	Tristate	—
PH[5]	PCR[117]	AF0 AF1 AF2 AF3	GPIO[117] E1UC[7] — —	SIUL eMIOS_1 — —	I/O I/O — —	S	Tristate	—
PH[6]	PCR[118]	AF0 AF1 AF2 AF3	GPIO[118] E1UC[8] — MA[2]	SIUL eMIOS_1 — ADC_0	I/O I/O — O	M	Tristate	—
PH[7]	PCR[119]	AF0 AF1 AF2 AF3	GPIO[119] E1UC[9] CS3_2 MA[1]	SIUL eMIOS_1 DSPI_2 ADC_0	I/O I/O O O	M	Tristate	—
PH[8]	PCR[120]	AF0 AF1 AF2 AF3	GPIO[120] E1UC[10] CS2_2 MA[0]	SIUL eMIOS_1 DSPI_2 ADC_0	I/O I/O O O	M	Tristate	—
PH[9] <sup>(10)</sup>	PCR[121]	AF0 AF1 AF2 AF3	GPIO[121] — TCK —	SIUL — JTAGC —	I/O — I —	S	Input, weak pull-up	88

Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PH[10] <sup>(10)</sup>	PCR[122]	AF0 AF1 AF2 AF3	GPIO[122] — TMS —	SIUL — JTAGC —	I/O — I —	M	Input, weak pull-up	81
PH[11]	PCR[123]	AF0 AF1 AF2 AF3	GPIO[123] SOUT_3 CS0_4 E1UC[5]	SIUL DSPI_3 DSPI_4 eMIOS_1	I/O O I/O I/O	M	Tristate	—
PH[12]	PCR[124]	AF0 AF1 AF2 AF3	GPIO[124] SCK_3 CS1_4 E1UC[25]	SIUL DSPI_3 DSPI_4 eMIOS_1	I/O I/O O I/O	M	Tristate	—
PH[13]	PCR[125]	AF0 AF1 AF2 AF3	GPIO[125] SOUT_4 CS0_3 E1UC[26]	SIUL DSPI_4 DSPI_3 eMIOS_1	I/O O I/O I/O	M	Tristate	—
PH[14]	PCR[126]	AF0 AF1 AF2 AF3	GPIO[126] SCK_4 CS1_3 E1UC[27]	SIUL DSPI_4 DSPI_3 eMIOS_1	I/O I/O O I/O	M	Tristate	—
PH[15]	PCR[127]	AF0 AF1 AF2 AF3	GPIO[127] SOUT_5 — E1UC[17]	SIUL DSPI_5 — eMIOS_1	I/O O — I/O	M	Tristate	—
Port I								



**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PI[0]	PCR[128]	AF0 AF1 AF2 AF3	GPIO[128] E0UC[28] LIN8TX —	SIUL eMIOS_0 LINFlex_8 —	I/O I/O O —	S	Tristate	—
PI[1]	PCR[129]	AF0 AF1 AF2 AF3 — —	GPIO[129] E0UC[29] — — WKPU[24] <sup>(5)</sup> LIN8RX	SIUL eMIOS_0 — — WKPU LINFlex_8	I/O I/O — — I I	S	Tristate	—
PI[2]	PCR[130]	AF0 AF1 AF2 AF3	GPIO[130] E0UC[30] LIN9TX —	SIUL eMIOS_0 LINFlex_9 —	I/O I/O O —	S	Tristate	—
PI[3]	PCR[131]	AF0 AF1 AF2 AF3 — —	GPIO[131] E0UC[31] — — WKPU[23] <sup>(5)</sup> LIN9RX	SIUL eMIOS_0 — — WKPU LINFlex_9	I/O I/O — — I I	S	Tristate	—
PI[4]	PCR[132]	AF0 AF1 AF2 AF3	GPIO[132] E1UC[28] SOUT_4 —	SIUL eMIOS_1 DSPI_4 —	I/O I/O O —	S	Tristate	—



Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PI[5]	PCR[133]	AF0 AF1 AF2 AF3	GPIO[133] E1UC[29] SCK_4 —	SIUL eMIOS_1 DSPI_4 —	I/O I/O I/O —	S	Tristate	—
PI[6]	PCR[134]	AF0 AF1 AF2 AF3	GPIO[134] E1UC[30] CS0_4 —	SIUL eMIOS_1 DSPI_4 —	I/O I/O I/O —	S	Tristate	—
PI[7]	PCR[135]	AF0 AF1 AF2 AF3	GPIO[135] E1UC[31] CS1_4 —	SIUL eMIOS_1 DSPI_4 —	I/O I/O O —	S	Tristate	—
PI[8]	PCR[136]	AF0 AF1 AF2 AF3 —	GPIO[136] — — — ADC0_S[16]	SIUL — — — ADC_0	I/O — — — I	J	Tristate	—
PI[9]	PCR[137]	AF0 AF1 AF2 AF3 —	GPIO[137] — — — ADC0_S[17]	SIUL — — — ADC_0	I/O — — — I	J	Tristate	—



**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PI[10]	PCR[138]	AF0	GPIO[138]	SIUL	I/O	J	Tristate	—
		AF1	—	—	—			
		AF2	—	—	—			
		AF3	—	—	—			
		—	ADC0_S[18]	ADC_0	I			
PI[11]	PCR[139]	AF0	GPIO[139]	SIUL	I/O	J	Tristate	—
		AF1	—	—	—			
		AF2	—	—	—			
		AF3	—	—	—			
		—	ADC0_S[19]	ADC_0	I			
—	SIN_3	DSPI_3	I					
PI[12]	PCR[140]	AF0	GPIO[140]	SIUL	I/O	J	Tristate	—
		AF1	CS0_3	DSPI_3	I/O			
		AF2	—	—	—			
		AF3	—	—	—			
		—	ADC0_S[20]	ADC_0	I			
PI[13]	PCR[141]	AF0	GPIO[141]	SIUL	I/O	J	Tristate	—
		AF1	CS1_3	DSPI_3	O			
		AF2	—	—	—			
		AF3	—	—	—			
		—	ADC0_S[21]	ADC_0	I			

Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PI[14]	PCR[142]	AF0	GPIO[142]	SIUL	I/O	J	Tristate	—
		AF1	—	—	—			
		AF2	—	—	—			
		AF3	—	—	—			
		—	ADC0_S[22]	ADC_0	I			
—	SIN_4	DSPI_4	I					
PI[15]	PCR[143]	AF0	GPIO[143]	SIUL	I/O	J	Tristate	—
		AF1	CS0_4	DSPI_4	I/O			
		AF2	—	—	—			
		AF3	—	—	—			
		—	ADC0_S[23]	ADC_0	I			
Port J								
PJ[0]	PCR[144]	AF0	GPIO[144]	SIUL	I/O	J	Tristate	—
		AF1	CS1_4	DSPI_4	O			
		AF2	—	—	—			
		AF3	—	—	—			
		—	ADC0_S[24]	ADC_0	I			
PJ[1]	PCR[145]	AF0	GPIO[145]	SIUL	I/O	J	Tristate	—
		AF1	—	—	—			
		AF2	—	—	—			
		AF3	—	—	—			
		—	ADC0_S[25]	ADC_0	I			
—	SIN_5	DSPI_5	I					



**Table 6. Functional port pin descriptions (continued)**

Port pin	PCR	Alternate function <sup>(1)</sup>	Function	Peripheral	I/O direction <sup>(2)</sup>	Pad type	RESET configuration <sup>(3)</sup>	LQFP
								100
PJ[2]	PCR[146]	AF0 AF1 AF2 AF3 —	GPIO[146] CS0_5 — — ADC0_S[26]	SIUL DSPI_5 — — ADC_0	I/O I/O — — I	J	Tristate	—
PJ[3]	PCR[147]	AF0 AF1 AF2 AF3 —	GPIO[147] CS1_5 — — ADC0_S[27]	SIUL DSPI_5 — — ADC_0	I/O O — — I	J	Tristate	—
PJ[4]	PCR[148]	AF0 AF1 AF2 AF3	GPIO[148] SCK_5 E1UC[18] —	SIUL DSPI_5 eMIOS_1 —	I/O I/O I/O —	M	Tristate	—

1. Alternate functions are chosen by setting the values of the PCR.PA bitfields inside the SIUL module. PCR.PA = 00 → AF0; PCR.PA = 11 → AF2. This is intended to select the output functions; to use one of the input functions, the PCR.IBE bit must be selected in the PCR.PA bitfields. For this reason, the value corresponding to an input only function is reported as “—”.
2. Multiple inputs are routed to all respective modules internally. The input of some modules must be configured by setting the values of the PCR.PA bitfields inside the SIUL module.
3. The RESET configuration applies during and after reset.
4. LBG208 available only as development package for Nexus2+
5. All WKPU pins also support external interrupt capability. See the WKPU chapter for further details.
6. NMI has higher priority than alternate function. When NMI is selected, the PCR.AF field is ignored.
7. “Not applicable” because these functions are available only while the device is booting. Refer to the BAM information for details.
8. Value of PCR.IBE bit must be 0.
9. This wake-up input cannot be used to exit STANDBY mode.

10. Out of reset all the functional pins except PC[0:1] and PH[9:10] are available to the user as GPIO. PC[0:1] are available as JTAG pins (TDI and TDO respectively). PH[9:10] are available as JTAG pins (TCK and TMS respectively). It is up to the user to configure these pins as GPIO when needed.
11. PC[1] is a fast/medium pad but is in medium configuration by default. This pad is in Alternate Function 2 mode after reset which has PCR.OBE is '1', but this setting has no impact as long as this pad stays in AF2 mode. After configuring this pad as GPIO (PCR.PA = 1) value of PCR.OBE = 1.
12. Not available in LQFP100 package.



### 3.8 Nexus 2+ pins

In the LPGA208 package, eight additional debug pins are available (see [Table 7](#)).

**Table 7. Nexus 2+ pin descriptions**

Port pin	Function	I/O direction	Pad type	Function after reset	Pin number		
					LQFP 100	LQFP 144	LPGA 208 <sup>(1)</sup>
MCKO	Message clock out	O	F	—	—	—	T4
MDO0	Message data out 0	O	M	—	—	—	H15
MDO1	Message data out 1	O	M	—	—	—	H16
MDO2	Message data out 2	O	M	—	—	—	H14
MDO3	Message data out 3	O	M	—	—	—	H13
EVTI	Event in	I	M	Pull-up	—	—	K1
EVTO	Event out	O	M	—	—	—	L4
MSEO	Message start/end out	O	M	—	—	—	G16

1. LPGA208 available only as development package for Nexus2+.

## 4 Electrical characteristics

This section contains electrical characteristics of the device as well as temperature and power considerations.

This product contains devices to protect the inputs against damage due to high static voltages. However, it is advisable to take precautions to avoid application of any voltage higher than the specified maximum rated voltages.

To enhance reliability, unused inputs can be driven to an appropriate logic voltage level ( $V_{DD}$  or  $V_{SS}$ ). This could be done by the internal pull-up and pull-down, which is provided by the product for most general purpose pins.

The parameters listed in the following tables represent the characteristics of the device and its demands on the system.

In the tables where the device logic provides signals with their respective timing characteristics, the symbol “CC” for Controller Characteristics is included in the Symbol column.

In the tables where the external system must provide signals with their respective timing characteristics to the device, the symbol “SR” for System Requirement is included in the Symbol column.

### 4.1 Parameter classification

The electrical parameters shown in this supplement are guaranteed by various methods. To give the customer a better understanding, the classifications listed in [Table 8](#) are used and the parameters are tagged accordingly in the tables where appropriate.

**Table 8. Parameter classifications**

Classification tag	Tag description
P	Those parameters are guaranteed during production testing on each individual device.
C	Those parameters are achieved by the design characterization by measuring a statistically relevant sample size across process variations.
T	Those parameters are achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted. All values shown in the typical column are within this category.
D	Those parameters are derived mainly from simulations.

*Note:* The classification is shown in the column labeled “C” in the parameter tables where appropriate.

### 4.2 NVUSRO register

Bit values in the Non-Volatile User Options (NVUSRO) Register control portions of the device configuration, namely electrical parameters such as high voltage supply and oscillator margin, as well as digital functionality (watchdog enable/disable after reset).

For a detailed description of the NVUSRO register, please refer to the device reference manual.

#### 4.2.1 NVUSRO[**PAD3V5V**] field description

The DC electrical characteristics are dependent on the PAD3V5V bit value. [Table 9](#) shows how NVUSRO[**PAD3V5V**] controls the device configuration.

**Table 9. PAD3V5V field description<sup>(1)</sup>**

Value <sup>(2)</sup>	Description
0	High voltage supply is 5.0 V
1	High voltage supply is 3.3 V

1. See the device reference manual for more information on the NVUSRO register.
2. Default manufacturing value is '1'. Value can be programmed by customer in Shadow Flash.

#### 4.2.2 NVUSRO[**OSCILLATOR\_MARGIN**] field description

The fast external crystal oscillator consumption is dependent on the OSCILLATOR\_MARGIN bit value. [Table 10](#) shows how NVUSRO[**OSCILLATOR\_MARGIN**] controls the device configuration.

**Table 10. OSCILLATOR\_MARGIN field description<sup>(1)</sup>**

Value <sup>(2)</sup>	Description
0	Low consumption configuration (4 MHz/8 MHz)
1	High margin configuration (4 MHz/16 MHz)

1. See the device reference manual for more information on the NVUSRO register.
2. Default manufacturing value is '1'. Value can be programmed by customer in Shadow Flash.

#### 4.2.3 NVUSRO[**WATCHDOG\_EN**] field description

The watchdog enable/disable configuration after reset is dependent on the WATCHDOG\_EN bit value. [Table 11](#) shows how NVUSRO[**WATCHDOG\_EN**] controls the device configuration.

**Table 11. WATCHDOG\_EN field description**

Value <sup>(1)</sup>	Description
0	Disable after reset
1	Enable after reset

1. Default manufacturing value is '1'. Value can be programmed by customer in Shadow Flash.



### 4.3 Absolute maximum ratings

Table 12. Absolute maximum ratings

Symbol		Parameter	Conditions	Value		Unit
				Min	Max	
V <sub>SS</sub>	SR	Digital ground on VSS_HV pins	—	0	0	V
V <sub>DD</sub>	SR	Voltage on VDD_HV pins with respect to ground (V <sub>SS</sub> )	—	-0.3	6.0	V
V <sub>SS_LV</sub>	SR	Voltage on VSS_LV (low voltage digital supply) pins with respect to ground (V <sub>SS</sub> )	—	V <sub>SS</sub> - 0.1	V <sub>SS</sub> + 0.1	V
V <sub>DD_BV</sub>	SR	Voltage on VDD_BV (regulator supply) pin with respect to ground (V <sub>SS</sub> )	—	-0.3	6.0	V
			Relative to V <sub>DD</sub>	-0.3	V <sub>DD</sub> + 0.3	
V <sub>SS_ADC</sub>	SR	Voltage on VSS_HV_ADC0, VSS_HV_ADC1 (ADC reference) pins with respect to ground (V <sub>SS</sub> )	—	V <sub>SS</sub> - 0.1	V <sub>SS</sub> + 0.1	V
V <sub>DD_ADC</sub>	SR	Voltage on VDD_HV_ADC0, VDD_HV_ADC1 (ADC reference) pins with respect to ground (V <sub>SS</sub> )	—	-0.3	6.0	V
			Relative to V <sub>DD</sub>	V <sub>DD</sub> - 0.3	V <sub>DD</sub> + 0.3	
V <sub>IN</sub>	SR	Voltage on any GPIO pin with respect to ground (V <sub>SS</sub> )	—	-0.3	6.0	V
			Relative to V <sub>DD</sub>	—	V <sub>DD</sub> + 0.3	
I <sub>INJPAD</sub>	SR	Injected input current on any pin during overload condition	—	-10	10	mA
I <sub>INJSUM</sub>	SR	Absolute sum of all injected input currents during overload condition	—	-50	50	
I <sub>AVGSEG</sub>	SR	Sum of all the static I/O current within a supply segment	V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	—	70	mA
			V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1	—	64	
T <sub>STORAGE</sub>	SR	Storage temperature	—	-55	150	°C

*Note:* Stresses exceeding the recommended absolute maximum ratings may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification are not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. During overload conditions (V<sub>IN</sub> > V<sub>DD</sub> or V<sub>IN</sub> < V<sub>SS</sub>), the voltage on pins with respect to ground (V<sub>SS</sub>) must not exceed the recommended values.

## 4.4 Recommended operating conditions

Table 13. Recommended operating conditions (3.3 V)

Symbol		Parameter	Conditions	Value		Unit
				Min	Max	
$V_{SS}$	SR	Digital ground on VSS_HV pins	—	0	0	V
$V_{DD}^{(1)}$	SR	Voltage on VDD_HV pins with respect to ground ( $V_{SS}$ )	—	3.0	3.6	V
$V_{SS\_LV}^{(2)}$	SR	Voltage on VSS_LV (low voltage digital supply) pins with respect to ground ( $V_{SS}$ )	—	$V_{SS} - 0.1$	$V_{SS} + 0.1$	V
$V_{DD\_BV}^{(3)}$	SR	Voltage on VDD_BV pin (regulator supply) with respect to ground ( $V_{SS}$ )	—	3.0	3.6	V
			Relative to $V_{DD}$	$V_{DD} - 0.1$	$V_{DD} + 0.1$	
$V_{SS\_ADC}$	SR	Voltage on VSS_HV_ADC0, VSS_HV_ADC1 (ADC reference) pin with respect to ground ( $V_{SS}$ )	—	$V_{SS} - 0.1$	$V_{SS} + 0.1$	V
$V_{DD\_ADC}^{(4)}$	SR	Voltage on VDD_HV_ADC0, VDD_HV_ADC1 (ADC reference) with respect to ground ( $V_{SS}$ )	—	3.0 <sup>(5)</sup>	3.6	V
			Relative to $V_{DD}$	$V_{DD} - 0.1$	$V_{DD} + 0.1$	
$V_{IN}$	SR	Voltage on any GPIO pin with respect to ground ( $V_{SS}$ )	—	$V_{SS} - 0.1$	—	V
			Relative to $V_{DD}$	—	$V_{DD} + 0.1$	
$I_{INJPAD}$	SR	Injected input current on any pin during overload condition	—	-5	5	mA
$I_{INJSUM}$	SR	Absolute sum of all injected input currents during overload condition	—	-50	50	
$TV_{DD}$	SR	$V_{DD}$ slope to ensure correct power up <sup>(6)</sup>	—	3.0 <sup>(7)</sup>	$250 \times 10^3$ (0.25 [V/ $\mu$ s])	V/s

- 100 nF capacitance needs to be provided between each  $V_{DD}/V_{SS}$  pair.
- 330 nF capacitance needs to be provided between each  $V_{DD\_LV}/V_{SS\_LV}$  supply pair.
- 470 nF capacitance needs to be provided between  $V_{DD\_BV}$  and the nearest  $V_{SS\_LV}$  (higher value may be needed depending on external regulator characteristics). Supply ramp slope on  $V_{DD\_BV}$  should always be faster or equal to slope of  $V_{DD\_HV}$ . Otherwise, device may enter regulator bypass mode if slope on  $V_{DD\_BV}$  is slower.
- 100 nF capacitance needs to be provided between  $V_{DD\_ADC}/V_{SS\_ADC}$  pair.
- Full electrical specification cannot be guaranteed when voltage drops below 3.0 V. In particular, ADC electrical characteristics and I/Os DC electrical specification may not be guaranteed. When voltage drops below  $V_{LVDHVL}$ , device is reset.
- Guaranteed by device validation.
- Minimum value of  $TV_{DD}$  must be guaranteed until  $V_{DD}$  reaches 2.6 V (maximum value of  $V_{PORH}$ ).

Table 14. Recommended operating conditions (5.0 V)

Symbol		Parameter	Conditions	Value		Unit
				Min	Max	
$V_{SS}$	S R	Digital ground on VSS_HV pins	—	0	0	V
$V_{DD}^{(1)}$	S R	Voltage on VDD_HV pins with respect to ground ( $V_{SS}$ )	—	4.5	5.5	V
			Voltage drop <sup>(2)</sup>	3.0	5.5	
$V_{SS\_LV}^{(3)}$	S R	Voltage on VSS_LV (low voltage digital supply) pins with respect to ground ( $V_{SS}$ )	—	$V_{SS} - 0.1$	$V_{SS} + 0.1$	V
$V_{DD\_BV}^{(4)}$	S R	Voltage on VDD_BV pin (regulator supply) with respect to ground ( $V_{SS}$ )	—	4.5	5.5	V
			Voltage drop <sup>(2)</sup>	3.0	5.5	
			Relative to $V_{DD}$	3.0	$V_{DD} + 0.1$	
$V_{SS\_ADC}$	S R	Voltage on VSS_HV_ADC0, VSS_HV_ADC1 (ADC reference) pin with respect to ground ( $V_{SS}$ )	—	$V_{SS} - 0.1$	$V_{SS} + 0.1$	V
$V_{DD\_ADC}^{(5)}$	S R	Voltage on VDD_HV_ADC0, VDD_HV_ADC1 (ADC reference) with respect to ground ( $V_{SS}$ )	—	4.5	5.5	V
			Voltage drop <sup>(2)</sup>	3.0	5.5	
			Relative to $V_{DD}$	$V_{DD} - 0.1$	$V_{DD} + 0.1$	
$V_{IN}$	S R	Voltage on any GPIO pin with respect to ground ( $V_{SS}$ )	—	$V_{SS} - 0.1$	—	V
			Relative to $V_{DD}$	—	$V_{DD} + 0.1$	
$I_{INJPAD}$	S R	Injected input current on any pin during overload condition	—	-5	5	mA
$I_{INJSUM}$	S R	Absolute sum of all injected input currents during overload condition	—	-50	50	
$TV_{DD}$	S R	$V_{DD}$ slope to ensure correct power up <sup>(6)</sup>	—	3.0 <sup>(7)</sup>	$250 \times 10^3$ (0.25 [V/ $\mu$ s])	V/s

- 100 nF capacitance needs to be provided between each  $V_{DD}/V_{SS}$  pair.
- Full device operation is guaranteed by design when the voltage drops below 4.5 V down to 3.0 V. However, certain analog electrical characteristics will not be guaranteed to stay within the stated limits.
- 330 nF capacitance needs to be provided between each  $V_{DD\_LV}/V_{SS\_LV}$  supply pair.
- 470 nF capacitance needs to be provided between  $V_{DD\_BV}$  and the nearest  $V_{SS\_LV}$  (higher value may be needed depending on external regulator characteristics). While the supply voltage ramps up, the slope on  $V_{DD\_BV}$  should be less than  $0.9V_{DD\_HV}$  in order to ensure the device does not enter regulator bypass mode.
- 100 nF capacitance needs to be provided between  $V_{DD\_ADC}/V_{SS\_ADC}$  pair.
- Guaranteed by device validation.
- Minimum value of  $TV_{DD}$  must be guaranteed until  $V_{DD}$  reaches 2.6 V (maximum value of  $V_{PORH}$ ).

Note: RAM data retention is guaranteed with  $V_{DD\_LV}$  not below 1.08 V.

## 4.5 Thermal characteristics

### 4.5.1 External ballast resistor recommendations

External ballast resistor on  $V_{DD\_BV}$  pin helps in reducing the overall power dissipation inside the device. This resistor is required only when maximum power consumption exceeds the limit imposed by package thermal characteristics.

As stated in [Table 15](#) LQFP thermal characteristics, considering a thermal resistance of LQFP144 as  $48.3\text{ }^{\circ}\text{C/W}$ , at ambient temperature  $T_A = 125\text{ }^{\circ}\text{C}$ , the junction temperature  $T_j$  will cross  $150\text{ }^{\circ}\text{C}$  if the total power dissipation is greater than  $(150 - 125)/48.3 = 517\text{ mW}$ . Therefore, the total device current  $I_{DDMAX}$  at  $125\text{ }^{\circ}\text{C}/5.5\text{ V}$  must not exceed  $94.1\text{ mA}$  (i.e., PD/VDD). Assuming an average  $I_{DD}(V_{DD\_HV})$  of  $15\text{--}20\text{ mA}$  consumption typically during device RUN mode, the LV domain consumption  $I_{DD}(V_{DD\_BV})$  is thus limited to  $I_{DDMAX} - I_{DD}(V_{DD\_HV})$ , i.e.,  $80\text{ mA}$ .

Therefore, respecting the maximum power allowed as explained in [Section 4.5.2: Package thermal characteristics](#), it is recommended to use this resistor only in the  $125\text{ }^{\circ}\text{C}/5.5\text{ V}$  operating corner as per the following guidelines:

- If  $I_{DD}(V_{DD\_BV}) < 80\text{ mA}$ , then no resistor is required.
- If  $80\text{ mA} < I_{DD}(V_{DD\_BV}) < 90\text{ mA}$ , then  $4\text{ }\Omega$  resistor can be used.
- If  $I_{DD}(V_{DD\_BV}) > 90\text{ mA}$ , then  $8\text{ }\Omega$  resistor can be used.

Using resistance in the range of  $4\text{--}8\text{ }\Omega$ , the gain will be around  $10\text{--}20\%$  of total consumption on  $V_{DD\_BV}$ . For example, if  $8\text{ }\Omega$  resistor is used, then power consumption when  $I_{DD}(V_{DD\_BV})$  is  $110\text{ mA}$  is equivalent to power consumption when  $I_{DD}(V_{DD\_BV})$  is  $90\text{ mA}$  (approximately) when resistor not used.

In order to ensure correct power up, the minimum  $V_{DD\_BV}$  to be guaranteed is  $30\text{ ms/V}$ . If the supply ramp is slower than this value, then LVDHV3B monitoring ballast supply  $V_{DD\_BV}$  pin gets triggered leading to device reset. Until the supply reaches certain threshold, this low voltage detector (LVD) generates destructive reset event in the system. This threshold depends on the maximum  $I_{DD}(V_{DD\_BV})$  possible across the external resistor.

### 4.5.2 Package thermal characteristics

Table 15. LQFP thermal characteristics<sup>(1)</sup>

Symbol	C	Parameter	Conditions <sup>(2)</sup>	Pin count	Value			Unit	
					Min	Typ	Max		
$R_{\theta JA}$	CC	D	Thermal resistance, junction-to-ambient natural convection <sup>(3)</sup>	Single-layer board — 1s	100	—	—	64	$^{\circ}\text{C/W}$
					144	—	—	64	
					176	—	—	64	
				Four-layer board — 2s2p	100	—	—	49.7	
					144	—	—	48.3	
					176	—	—	47.3	

Table 15. LQFP thermal characteristics<sup>(1)</sup> (continued)

Symbol	C	Parameter	Conditions <sup>(2)</sup>	Pin count	Value			Unit
					Min	Typ	Max	
R <sub>θJB</sub>	CC	Thermal resistance, junction-to-board <sup>(4)</sup>	Single-layer board — 1s	100	—	—	36	°C/W
				144	—	—	38	
				176	—	—	38	
			Four-layer board — 2s2p	100	—	—	33.6	
				144	—	—	33.4	
				176	—	—	33.4	
R <sub>θJC</sub>	CC	Thermal resistance, junction-to-case <sup>(5)</sup>	Single-layer board — 1s	100	—	—	23	°C/W
				144	—	—	23	
				176	—	—	23	
			Four-layer board — 2s2p	100	—	—	19.8	
				144	—	—	19.2	
				176	—	—	18.8	

1. Thermal characteristics are targets based on simulation.
2. V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C.
3. Junction-to-ambient thermal resistance determined per JEDEC JESD51-3 and JESD51-6. Thermal test board meets JEDEC specification for this package. When Greek letters are not available, the symbols are typed as R<sub>thJA</sub> and R<sub>thJMA</sub>.
4. Junction-to-board thermal resistance determined per JEDEC JESD51-8. Thermal test board meets JEDEC specification for the specified package. When Greek letters are not available, the symbols are typed as R<sub>thJB</sub>.
5. Junction-to-case at the top of the package determined using MIL-STD 883 Method 1012.1. The cold plate temperature is used for the case temperature. Reported value includes the thermal resistance of the interface layer. When Greek letters are not available, the symbols are typed as R<sub>thJC</sub>.

### 4.5.3 Power considerations

The average chip-junction temperature, T<sub>J</sub>, in degrees Celsius, may be calculated using [Equation 1](#):

$$\text{Equation 1 } T_J = T_A + (P_D \times R_{\theta JA})$$

Where:

T<sub>A</sub> is the ambient temperature in °C.

R<sub>θJA</sub> is the package junction-to-ambient thermal resistance, in °C/W.

P<sub>D</sub> is the sum of P<sub>INT</sub> and P<sub>I/O</sub> (P<sub>D</sub> = P<sub>INT</sub> + P<sub>I/O</sub>).

P<sub>INT</sub> is the product of I<sub>DD</sub> and V<sub>DD</sub>, expressed in watts. This is the chip internal power.

P<sub>I/O</sub> represents the power dissipation on input and output pins; user determined.

Most of the time for the applications, P<sub>I/O</sub> < P<sub>INT</sub> and may be neglected. On the other hand, P<sub>I/O</sub> may be significant, if the device is configured to continuously drive external modules and/or memories.

An approximate relationship between P<sub>D</sub> and T<sub>J</sub> (if P<sub>I/O</sub> is neglected) is given by:

**Equation 2**  $P_D = K / (T_J + 273 \text{ °C})$

Therefore, solving equations <Cross Refs>1 and <Cross Refs>2:

**Equation 3**  $K = P_D \times (T_A + 273 \text{ °C}) + R_{\theta JA} \times P_D^2$

Where:

K is a constant for the particular part, which may be determined from [Equation 3](#) by measuring  $P_D$  (at equilibrium) for a known  $T_A$ . Using this value of K, the values of  $P_D$  and  $T_J$  may be obtained by solving equations [Equation 1](#) and [Equation 2](#) iteratively for any value of  $T_A$ .

## 4.6 I/O pad electrical characteristics

### 4.6.1 I/O pad types

The device provides four main I/O pad types depending on the associated alternate functions:

- Slow pads—are the most common pads, providing a good compromise between transition time and low electromagnetic emission.
- Medium pads—provide transition fast enough for the serial communication channels with controlled current to reduce electromagnetic emission.
- Fast pads—provide maximum speed. These are used for improved Nexus debugging capability.
- Input only pads—are associated with ADC channels and 32 kHz low power external crystal oscillator providing low input leakage.

Medium and Fast pads can use slow configuration to reduce electromagnetic emission, at the cost of reducing AC performance.

### 4.6.2 I/O input DC characteristics

[Table 16](#) provides input DC electrical characteristics as described in [Figure 6](#).

Figure 6. I/O input DC electrical characteristics definition

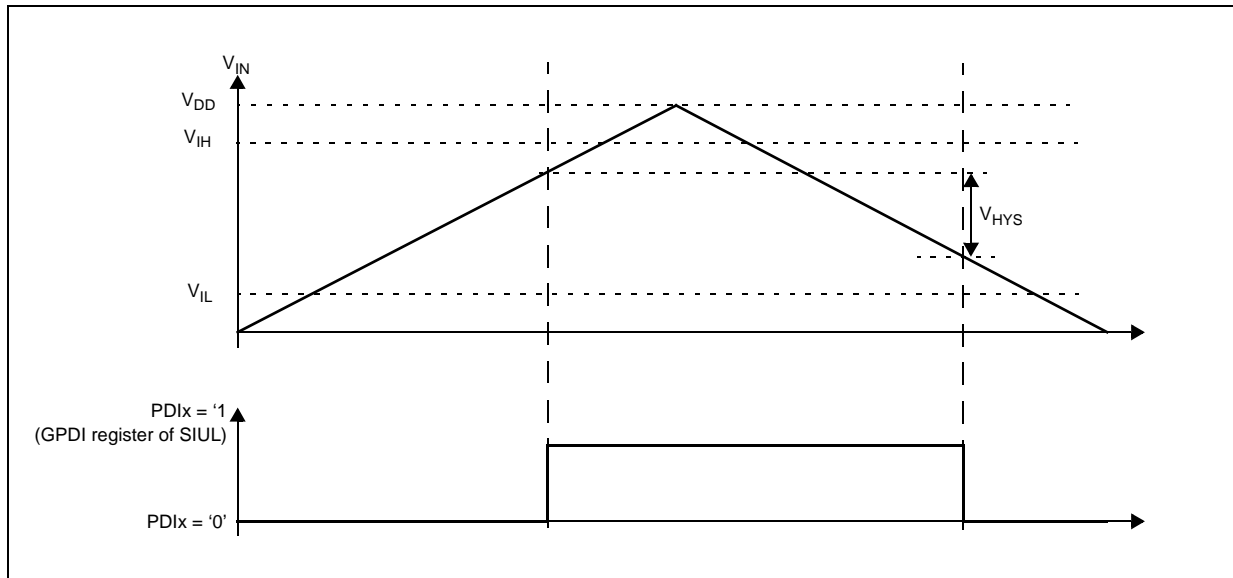


Table 16. I/O input DC electrical characteristics

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit		
				Min	Typ	Max			
$V_{IH}$	SR	P	Input high level CMOS (Schmitt Trigger)	—	—	—	V		
$V_{IL}$	SR	P	Input low level CMOS (Schmitt Trigger)	—	—	—			
$V_{HYS}$	CC	C	Input hysteresis CMOS (Schmitt Trigger)	—	—	—			
$I_{LKG}$	CC	D	Digital input leakage	No injection on adjacent pin	$T_A = -40\text{ °C}$	—	2	200	nA
					$T_A = 25\text{ °C}$	—	2	200	
					$T_A = 85\text{ °C}$	—	5	300	
					$T_A = 105\text{ °C}$	—	12	500	
					$T_A = 125\text{ °C}$	—	70	1000	
$W_{FI}^{(2)}$	SR	P	Wakeup input filtered pulse	—	—	40	ns		
$W_{NFI}^{(2)}$	SR	P	Wakeup input not filtered pulse	—	1000	—	ns		

1.  $V_{DD} = 3.3\text{ V} \pm 10\% / 5.0\text{ V} \pm 10\%$ ,  $T_A = -40\text{ to }125\text{ °C}$ , unless otherwise specified.

2. In the range from 40 to 1000 ns, pulses can be filtered or not filtered, according to operating temperature and voltage.

### 4.6.3 I/O output DC characteristics

The following tables provide DC characteristics for bidirectional pads:

- [Table 17](#) provides weak pull figures. Both pull-up and pull-down resistances are supported.
- [Table 18](#) provides output driver characteristics for I/O pads when in SLOW configuration.
- [Table 19](#) provides output driver characteristics for I/O pads when in MEDIUM configuration.
- [Table 20](#) provides output driver characteristics for I/O pads when in FAST configuration.

**Table 17. I/O pull-up/pull-down DC electrical characteristics**

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit	
				Min	Typ	Max		
I <sub>WPU</sub>	CC	P	V <sub>IN</sub> = V <sub>IL</sub> , V <sub>DD</sub> = 5.0 V ± 10%	PAD3V5V = 0	10	—	150	µA
		C		PAD3V5V = 1 <sup>(2)</sup>	10	—	250	
		P	V <sub>IN</sub> = V <sub>IL</sub> , V <sub>DD</sub> = 3.3 V ± 10%	PAD3V5V = 1	10	—	150	
I <sub>WPD</sub>	CC	P	V <sub>IN</sub> = V <sub>IH</sub> , V <sub>DD</sub> = 5.0 V ± 10%	PAD3V5V = 0	10	—	150	µA
		C		PAD3V5V = 1	10	—	250	
		P	V <sub>IN</sub> = V <sub>IH</sub> , V <sub>DD</sub> = 3.3 V ± 10%	PAD3V5V = 1	10	—	150	

1. V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C, unless otherwise specified.
2. The configuration PAD3V5 = 1 when V<sub>DD</sub> = 5 V is only a transient configuration during power-up. All pads but RESET and Nexus output (MDOx, EVTO, MCKO) are configured in input or in high impedance state.

**Table 18. SLOW configuration output buffer electrical characteristics**

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit	
				Min	Typ	Max		
V <sub>OH</sub>	CC	Output high level SLOW configuration	Push Pull	I <sub>OH</sub> = -2 mA, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0 (recommended)	0.8V <sub>DD</sub>	—	—	V
				I <sub>OH</sub> = -2 mA, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 1 <sup>(2)</sup>	0.8V <sub>DD</sub>	—	—	
				I <sub>OH</sub> = -1 mA, V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1 (recommended)	V <sub>DD</sub> - 0.8	—	—	



**Table 18. SLOW configuration output buffer electrical characteristics (continued)**

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit	
				Min	Typ	Max		
V <sub>OL</sub>	C	Output low level SLOW configuration	Push Pull	I <sub>OL</sub> = 2 mA, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0 (recommended)	—	—	0.1V <sub>DD</sub>	V
				I <sub>OL</sub> = 2 mA, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 1 <sup>(2)</sup>	—	—	0.1V <sub>DD</sub>	
				I <sub>OL</sub> = 1 mA, V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1 (recommended)	—	—	0.5	

- V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C, unless otherwise specified.
- The configuration PAD3V5 = 1 when V<sub>DD</sub> = 5 V is only a transient configuration during power-up. All pads but RESET and Nexus output (MDOx, EVTO, MCKO) are configured in input or in high impedance state.

**Table 19. MEDIUM configuration output buffer electrical characteristics**

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit	
				Min	Typ	Max		
V <sub>OH</sub>	CC	Output high level MEDIUM configuration	Push Pull	I <sub>OH</sub> = -3.8 mA, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	0.8V <sub>DD</sub>	—	—	V
				I <sub>OH</sub> = -2 mA, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0 (recommended)	0.8V <sub>DD</sub>	—	—	
				I <sub>OH</sub> = -1 mA, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 1 <sup>(2)</sup>	0.8V <sub>DD</sub>	—	—	
				I <sub>OH</sub> = -1 mA, V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1 (recommended)	V <sub>DD</sub> - 0.8	—	—	
				I <sub>OH</sub> = -100 µA, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	0.8V <sub>DD</sub>	—	—	
V <sub>OL</sub>	CC	Output low level MEDIUM configuration	Push Pull	I <sub>OL</sub> = 3.8 mA, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	—	—	0.2V <sub>DD</sub>	V
				I <sub>OL</sub> = 2 mA, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0 (recommended)	—	—	0.1V <sub>DD</sub>	
				I <sub>OL</sub> = 1 mA, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 1 <sup>(2)</sup>	—	—	0.1V <sub>DD</sub>	
				I <sub>OL</sub> = 1 mA, V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1 (recommended)	—	—	0.5	
				I <sub>OL</sub> = 100 µA, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	—	—	0.1V <sub>DD</sub>	

- $V_{DD} = 3.3\text{ V} \pm 10\% / 5.0\text{ V} \pm 10\%$ ,  $T_A = -40$  to  $125\text{ }^\circ\text{C}$ , unless otherwise specified.
- The configuration  $PAD3V5 = 1$  when  $V_{DD} = 5\text{ V}$  is only a transient configuration during power-up. All pads but RESET and Nexus output (MDOx, EVTO, MCKO) are configured in input or in high impedance state.

**Table 20. FAST configuration output buffer electrical characteristics**

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit	
				Min	Typ	Max		
$V_{OH}$	C C C	Output high level FAST configuration	Push Pull	$I_{OH} = -14\text{ mA}$ , $V_{DD} = 5.0\text{ V} \pm 10\%$ , $PAD3V5V = 0$ (recommended)	$0.8V_{DD}$	—	—	V
				$I_{OH} = -7\text{ mA}$ , $V_{DD} = 5.0\text{ V} \pm 10\%$ , $PAD3V5V = 1^{(2)}$	$0.8V_{DD}$	—	—	
				$I_{OH} = -11\text{ mA}$ , $V_{DD} = 3.3\text{ V} \pm 10\%$ , $PAD3V5V = 1$ (recommended)	$V_{DD} - 0.8$	—	—	
$V_{OL}$	C C C	Output low level FAST configuration	Push Pull	$I_{OL} = 14\text{ mA}$ , $V_{DD} = 5.0\text{ V} \pm 10\%$ , $PAD3V5V = 0$ (recommended)	—	—	$0.1V_{DD}$	V
				$I_{OL} = 7\text{ mA}$ , $V_{DD} = 5.0\text{ V} \pm 10\%$ , $PAD3V5V = 1^{(2)}$	—	—	$0.1V_{DD}$	
				$I_{OL} = 11\text{ mA}$ , $V_{DD} = 3.3\text{ V} \pm 10\%$ , $PAD3V5V = 1$ (recommended)	—	—	0.5	

- $V_{DD} = 3.3\text{ V} \pm 10\% / 5.0\text{ V} \pm 10\%$ ,  $T_A = -40$  to  $125\text{ }^\circ\text{C}$ , unless otherwise specified.
- The configuration  $PAD3V5 = 1$  when  $V_{DD} = 5\text{ V}$  is only a transient configuration during power-up. All pads but RESET and Nexus output (MDOx, EVTO, MCKO) are configured in input or in high impedance state.

#### 4.6.4 Output pin transition times

**Table 21. Output pin transition times**

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit		
				Min	Typ	Max			
$t_{tr}$	CC	Output transition time output pin <sup>(2)</sup> SLOW configuration	$C_L = 25\text{ pF}$	$V_{DD} = 5.0\text{ V} \pm 10\%$ , $PAD3V5V = 0$	—	—	50	ns	
					$C_L = 50\text{ pF}$	—	—		100
					$C_L = 100\text{ pF}$	—	—		125
			$C_L = 25\text{ pF}$	$V_{DD} = 3.3\text{ V} \pm 10\%$ , $PAD3V5V = 1$	—	—	50		
					$C_L = 50\text{ pF}$	—	—		100
					$C_L = 100\text{ pF}$	—	—		125

Table 21. Output pin transition times (continued)

Symbol	C	Parameter	Conditions <sup>(1)</sup>		Value			Unit
					Min	Typ	Max	
t <sub>tr</sub>	CC	Output transition time output pin <sup>(2)</sup> MEDIUM configuration	C <sub>L</sub> = 25 pF	V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	—	—	10	ns
			C <sub>L</sub> = 50 pF		—	—	20	
			C <sub>L</sub> = 100 pF		—	—	40	
			C <sub>L</sub> = 25 pF	V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1	—	—	12	
			C <sub>L</sub> = 50 pF		—	—	25	
			C <sub>L</sub> = 100 pF		—	—	40	
t <sub>tr</sub>	CC	Output transition time output pin <sup>(2)</sup> FAST configuration	C <sub>L</sub> = 25 pF	V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	—	—	4	ns
			C <sub>L</sub> = 50 pF		—	—	6	
			C <sub>L</sub> = 100 pF		—	—	12	
			C <sub>L</sub> = 25 pF	V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1	—	—	4	
			C <sub>L</sub> = 50 pF		—	—	7	
			C <sub>L</sub> = 100 pF		—	—	12	

1. V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C, unless otherwise specified.

2. C<sub>L</sub> includes device and package capacitances (C<sub>PKG</sub> < 5 pF).

### 4.6.5 I/O pad current specification

The I/O pads are distributed across the I/O supply segment. Each I/O supply segment is associated to a V<sub>DD</sub>/V<sub>SS</sub> supply pair as described in [Table 22](#).

[Table 23](#) provides I/O consumption figures.

In order to ensure device reliability, the average current of the I/O on a single segment should remain below the I<sub>AVGSEG</sub> maximum value.

Table 22. I/O supply segments

Package	Supply segment							
	1	2	3	4	5	6	7	8
LPGA208 (1)	Equivalent to LQFP176 segment pad distribution						MCKO	MDO /MSEO
LQFP176	pin7 – pin27	pin28 – pin57	pin59 – pin85	pin86 – pin123	pin124 – pin150	pin151 – pin6	—	—
LQFP144	pin20 – pin49	pin51 – pin99	pin100 – pin122	pin 123 – pin19	—	—	—	—
LQFP100	pin16 – pin35	pin37 – pin69	pin70 – pin83	pin84 – pin15	—	—	—	—

1. LPGA208 available only as development package for Nexus2+.

Table 23. I/O consumption

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit		
				Min	Typ	Max			
I <sub>SWTSLW</sub> <sup>(2)</sup>	CC	D	Dynamic I/O current for SLOW configuration C <sub>L</sub> = 25 pF	V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	—	—	20	mA	
				V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1	—	—	16		
I <sub>SWTMED</sub> <sup>(2)</sup>	CC	D	Dynamic I/O current for MEDIUM configuration C <sub>L</sub> = 25 pF	V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	—	—	29	mA	
				V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1	—	—	17		
I <sub>SWTFST</sub> <sup>(2)</sup>	CC	D	Dynamic I/O current for FAST configuration C <sub>L</sub> = 25 pF	V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	—	—	110	mA	
				V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1	—	—	50		
I <sub>RMSLW</sub>	CC	D	Root mean square I/O current for SLOW configuration	V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	C <sub>L</sub> = 25 pF, 2 MHz	—	—	2.3	mA
					C <sub>L</sub> = 25 pF, 4 MHz	—	—	3.2	
					C <sub>L</sub> = 100 pF, 2 MHz	—	—	6.6	
				V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1	C <sub>L</sub> = 25 pF, 2 MHz	—	—	1.6	
					C <sub>L</sub> = 25 pF, 4 MHz	—	—	2.3	
					C <sub>L</sub> = 100 pF, 2 MHz	—	—	4.7	
I <sub>RMSMED</sub>	CC	D	Root mean square I/O current for MEDIUM configuration	V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	C <sub>L</sub> = 25 pF, 13 MHz	—	—	6.6	mA
					C <sub>L</sub> = 25 pF, 40 MHz	—	—	13.4	
					C <sub>L</sub> = 100 pF, 13 MHz	—	—	18.3	
				V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1	C <sub>L</sub> = 25 pF, 13 MHz	—	—	5	
					C <sub>L</sub> = 25 pF, 40 MHz	—	—	8.5	
					C <sub>L</sub> = 100 pF, 13 MHz	—	—	11	
I <sub>RMSFST</sub>	CC	D	Root mean square I/O current for FAST configuration	V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	C <sub>L</sub> = 25 pF, 40 MHz	—	—	22	mA
					C <sub>L</sub> = 25 pF, 64 MHz	—	—	33	
					C <sub>L</sub> = 100 pF, 40 MHz	—	—	56	
				V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1	C <sub>L</sub> = 25 pF, 40 MHz	—	—	14	
					C <sub>L</sub> = 25 pF, 64 MHz	—	—	20	
					C <sub>L</sub> = 100 pF, 40 MHz	—	—	35	
I <sub>AVGSEG</sub>	SR	D	Sum of all the static I/O current within a supply segment	V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	—	—	70	mA	
				V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1	—	—	65		

1. V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C, unless otherwise specified
2. Stated maximum values represent peak consumption that lasts only a few ns during I/O transition.

Table 24 provides the weight of concurrent switching I/Os.



Due to the dynamic current limitations, the sum of the weight of concurrent switching I/Os on a single segment must not exceed 100% to ensure device functionality.

Table 24. I/O weight<sup>(1)</sup>

Supply segment			Pad	LQFP176				LQFP144/100					
				Weight 5 V		Weight 3.3 V		Weight 5 V		Weight 3.3 V			
LQFP 176	LQFP 144	LQFP 100		SRC <sup>(2)</sup> = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1		
6	4	4	PB[3]	5%	—	6%	—	13%	—	15%	—		
			PC[9]	4%	—	5%	—	13%	—	15%	—		
			PC[14]	4%	—	4%	—	13%	—	15%	—		
			PC[15]	3%	4%	4%	4%	12%	18%	15%	16%		
	—	—	PJ[4]	3%	4%	3%	3%	—	—	—	—		
1	—	—	PH[15]	2%	3%	3%	3%	—	—	—	—		
			PH[13]	3%	4%	3%	4%	—	—	—	—		
			PH[14]	3%	4%	4%	4%	—	—	—	—		
			PI[6]	4%	—	4%	—	—	—	—	—	—	
			PI[7]	4%	—	4%	—	—	—	—	—	—	
	4	—	—	PG[5]	4%	—	5%	—	10%	—	12%	—	
				PG[4]	4%	6%	5%	5%	9%	13%	11%	12%	
				PG[3]	4%	—	5%	—	9%	—	11%	—	
				PG[2]	4%	6%	5%	5%	9%	12%	10%	11%	
		4	4	4	PA[2]	4%	—	5%	—	8%	—	10%	—
					PE[0]	4%	—	5%	—	8%	—	9%	—
					PA[1]	4%	—	5%	—	8%	—	9%	—
					PE[1]	4%	6%	5%	6%	7%	10%	9%	9%
					PE[8]	4%	6%	5%	6%	7%	10%	8%	9%
					PE[9]	4%	—	5%	—	6%	—	8%	—
PE[10]	4%	—	5%	—	6%	—	7%	—					
PA[0]	4%	6%	5%	5%	6%	8%	7%	7%					
PE[11]	4%	—	5%	—	5%	—	6%	—					

Table 24. I/O weight<sup>(1)</sup> (continued)

Supply segment			Pad	LQFP176				LQFP144/100			
				Weight 5 V		Weight 3.3 V		Weight 5 V		Weight 3.3 V	
LQFP 176	LQFP 144	LQFP 100		SRC <sup>(2)</sup> = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1
2	1	—	PG[9]	9%	—	10%	—	9%	—	10%	—
		—	PG[8]	9%	—	11%	—	9%	—	11%	—
		1	PC[11]	9%	—	11%	—	9%	—	11%	—
			PC[10]	9%	13%	11%	12%	9%	13%	11%	12%
		—	PG[7]	9%	—	11%	—	9%	—	11%	—
		—	PG[6]	10%	14%	11%	12%	10%	14%	11%	12%
		1	PB[0]	10%	14%	12%	12%	10%	14%	12%	12%
			PB[1]	10%	—	12%	—	10%	—	12%	—
		—	PF[9]	10%	—	12%	—	10%	—	12%	—
		—	PF[8]	10%	14%	12%	13%	10%	14%	12%	13%
		—	PF[12]	10%	15%	12%	13%	10%	15%	12%	13%
		1	PC[6]	10%	—	12%	—	10%	—	12%	—
			PC[7]	10%	—	12%	—	10%	—	12%	—
		—	PF[10]	10%	14%	11%	12%	10%	14%	11%	12%
		—	PF[11]	9%	—	11%	—	9%	—	11%	—
		1	PA[15]	8%	12%	10%	10%	8%	12%	10%	10%
		—	PF[13]	8%	—	10%	—	8%	—	10%	—
		1	PA[14]	8%	11%	9%	10%	8%	11%	9%	10%
			PA[4]	7%	—	9%	—	7%	—	9%	—
			PA[13]	7%	10%	8%	9%	7%	10%	8%	9%
PA[12]	7%		—	8%	—	7%	—	8%	—		

Table 24. I/O weight<sup>(1)</sup> (continued)

Supply segment			Pad	LQFP176				LQFP144/100				
				Weight 5 V		Weight 3.3 V		Weight 5 V		Weight 3.3 V		
LQFP 176	LQFP 144	LQFP 100		SRC <sup>(2)</sup> = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1	
3	2	2	PB[9]	1%	—	1%	—	1%	—	1%	—	
			PB[8]	1%	—	1%	—	1%	—	1%	—	
			PB[10]	5%	—	6%	—	6%	—	7%	—	
		—	PF[0]	5%	—	6%	—	6%	—	8%	—	
		—	PF[1]	5%	—	6%	—	7%	—	8%	—	
		—	PF[2]	6%	—	7%	—	7%	—	9%	—	
		—	PF[3]	6%	—	7%	—	8%	—	9%	—	
		—	PF[4]	6%	—	7%	—	8%	—	10%	—	
		—	PF[5]	6%	—	7%	—	9%	—	10%	—	
		—	PF[6]	6%	—	7%	—	9%	—	11%	—	
	—	PF[7]	6%	—	7%	—	9%	—	11%	—		
	—	—	PJ[3]	6%	—	7%	—	—	—	—	—	
	—	—	PJ[2]	6%	—	7%	—	—	—	—	—	
	—	—	PJ[1]	6%	—	7%	—	—	—	—	—	
	—	—	PJ[0]	6%	—	7%	—	—	—	—	—	
	—	—	PI[15]	6%	—	7%	—	—	—	—	—	
	—	—	PI[14]	6%	—	7%	—	—	—	—	—	
	2	2	2	PD[0]	1%	—	1%	—	1%	—	1%	—
	—			PD[1]	1%	—	1%	—	1%	—	1%	—
	—			PD[2]	1%	—	1%	—	1%	—	1%	—
—	PD[3]			1%	—	1%	—	1%	—	1%	—	
—	PD[4]			1%	—	1%	—	1%	—	1%	—	
—	PD[5]			1%	—	1%	—	1%	—	1%	—	
—	PD[6]			1%	—	1%	—	1%	—	2%	—	
—	PD[7]			1%	—	1%	—	1%	—	2%	—	

Table 24. I/O weight<sup>(1)</sup> (continued)

Supply segment			Pad	LQFP176				LQFP144/100			
				Weight 5 V		Weight 3.3 V		Weight 5 V		Weight 3.3 V	
LQFP 176	LQFP 144	LQFP 100		SRC <sup>(2)</sup> = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1
4	2	2	PD[8]	1%	—	1%	—	1%	—	2%	—
			PB[4]	1%	—	1%	—	1%	—	2%	—
			PB[5]	1%	—	1%	—	1%	—	2%	—
			PB[6]	1%	—	1%	—	1%	—	2%	—
			PB[7]	1%	—	1%	—	1%	—	2%	—
			PD[9]	1%	—	1%	—	1%	—	2%	—
			PD[10]	1%	—	1%	—	1%	—	2%	—
			PD[11]	1%	—	1%	—	1%	—	2%	—



Table 24. I/O weight<sup>(1)</sup> (continued)

Supply segment			Pad	LQFP176				LQFP144/100			
LQFP 176	LQFP 144	LQFP 100		Weight 5 V		Weight 3.3 V		Weight 5 V		Weight 3.3 V	
				SRC <sup>(2)</sup> = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1
4	—	—	PB[11]	1%	—	1%	—	—	—	—	—
	—	—	PD[12]	11%	—	13%	—	—	—	—	—
	2	2	PB[12]	11%	—	13%	—	15%	—	17%	—
			PD[13]	11%	—	13%	—	14%	—	17%	—
			PB[13]	11%	—	13%	—	14%	—	17%	—
			PD[14]	11%	—	13%	—	14%	—	17%	—
			PB[14]	11%	—	13%	—	14%	—	16%	—
			PD[15]	11%	—	13%	—	13%	—	16%	—
			PB[15]	11%	—	13%	—	13%	—	15%	—
	—	—	PI[8]	10%	—	12%	—	—	—	—	—
	—	—	PI[9]	10%	—	12%	—	—	—	—	—
	—	—	PI[10]	10%	—	12%	—	—	—	—	—
	—	—	PI[11]	10%	—	12%	—	—	—	—	—
	—	—	PI[12]	10%	—	12%	—	—	—	—	—
	—	—	PI[13]	10%	—	11%	—	—	—	—	—
	2	2	PA[3]	9%	—	11%	—	11%	—	13%	—
		—	PG[13]	9%	13%	11%	11%	10%	14%	12%	13%
		—	PG[12]	9%	13%	10%	11%	10%	14%	12%	12%
		—	PH[0]	6%	8%	7%	7%	6%	9%	7%	8%
		—	PH[1]	6%	8%	7%	7%	6%	8%	7%	7%
—		PH[2]	5%	7%	6%	6%	5%	7%	6%	7%	
—		PH[3]	5%	7%	5%	6%	5%	7%	6%	6%	
—		PG[1]	4%	—	5%	—	4%	—	5%	—	
—	PG[0]	4%	5%	4%	5%	4%	5%	4%	5%		

Table 24. I/O weight<sup>(1)</sup> (continued)

Supply segment			Pad	LQFP176				LQFP144/100			
				Weight 5 V		Weight 3.3 V		Weight 5 V		Weight 3.3 V	
LQFP 176	LQFP 144	LQFP 100		SRC <sup>(2)</sup> = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1
5	3	—	PF[15]	4%	—	4%	—	4%	—	4%	—
		—	PF[14]	4%	6%	5%	5%	4%	6%	5%	5%
		—	PE[13]	4%	—	5%	—	4%	—	5%	—
		3	PA[7]	5%	—	6%	—	5%	—	6%	—
			PA[8]	5%	—	6%	—	5%	—	6%	—
			PA[9]	6%	—	7%	—	6%	—	7%	—
			PA[10]	6%	—	8%	—	6%	—	8%	—
			PA[11]	8%	—	9%	—	8%	—	9%	—
		—	PE[12]	8%	—	9%	—	8%	—	9%	—
		—	PG[14]	8%	—	9%	—	8%	—	9%	—
		—	PG[15]	8%	11%	9%	10%	8%	11%	9%	10%
		—	PE[14]	8%	—	9%	—	8%	—	9%	—
		—	PE[15]	8%	11%	9%	10%	8%	11%	9%	10%
	—	PG[10]	8%	—	9%	—	8%	—	9%	—	
	—	PG[11]	7%	11%	9%	9%	7%	11%	9%	9%	
	—	—	PH[11]	7%	10%	9%	9%	—	—	—	—
	—	—	PH[12]	7%	10%	8%	9%	—	—	—	—
	—	—	PI[5]	7%	—	8%	—	—	—	—	—
	—	—	PI[4]	7%	—	8%	—	—	—	—	—
	3	3	PC[3]	6%	—	8%	—	6%	—	8%	—
PC[2]			6%	8%	7%	7%	6%	8%	7%	7%	
PA[5]			6%	8%	7%	7%	6%	8%	7%	7%	
PA[6]			5%	—	6%	—	5%	—	6%	—	
PH[10]			5%	7%	6%	6%	5%	7%	6%	6%	
PC[1]			5%	19%	5%	13%	5%	19%	5%	13%	

Table 24. I/O weight<sup>(1)</sup> (continued)

Supply segment			Pad	LQFP176				LQFP144/100			
				Weight 5 V		Weight 3.3 V		Weight 5 V		Weight 3.3 V	
LQFP 176	LQFP 144	LQFP 100		SRC <sup>(2)</sup> = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1
6	4	4	PC[0]	6%	9%	7%	8%	7%	10%	8%	8%
			PH[9]	7%	—	8%	—	7%	—	9%	—
			PE[2]	7%	10%	8%	9%	8%	11%	9%	10%
			PE[3]	7%	10%	9%	9%	8%	12%	10%	10%
			PC[5]	7%	11%	9%	9%	8%	12%	10%	11%
			PC[4]	8%	11%	9%	10%	9%	13%	10%	11%
			PE[4]	8%	11%	9%	10%	9%	13%	11%	12%
			PE[5]	8%	11%	10%	10%	9%	14%	11%	12%
		—	PH[4]	8%	12%	10%	10%	10%	14%	12%	12%
		—	PH[5]	8%	—	10%	—	10%	—	12%	—
		—	PH[6]	8%	12%	10%	11%	10%	15%	12%	13%
		—	PH[7]	9%	12%	10%	11%	11%	15%	13%	13%
	—	PH[8]	9%	12%	10%	11%	11%	16%	13%	14%	
	—	4	PE[6]	9%	12%	10%	11%	11%	16%	13%	14%
	PE[7]		9%	12%	10%	11%	11%	16%	14%	14%	
	—	—	PI[3]	9%	—	10%	—	—	—	—	—
	—	—	PI[2]	9%	—	10%	—	—	—	—	—
	—	—	PI[1]	9%	—	10%	—	—	—	—	—
	—	—	PI[0]	9%	—	10%	—	—	—	—	—
	—	4	4	PC[12]	8%	12%	10%	11%	12%	18%	15%
PC[13]	8%			—	10%	—	13%	—	15%	—	
PC[8]	8%			—	10%	—	13%	—	15%	—	
PB[2]	8%			11%	9%	10%	13%	18%	15%	16%	

1. V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C, unless otherwise specified.

2. SRC: "Slew Rate Control" bit in SIU\_PCRx.

### 4.7 RESET electrical characteristics

The device implements a dedicated bidirectional RESET pin.

Figure 7. Start-up reset requirements

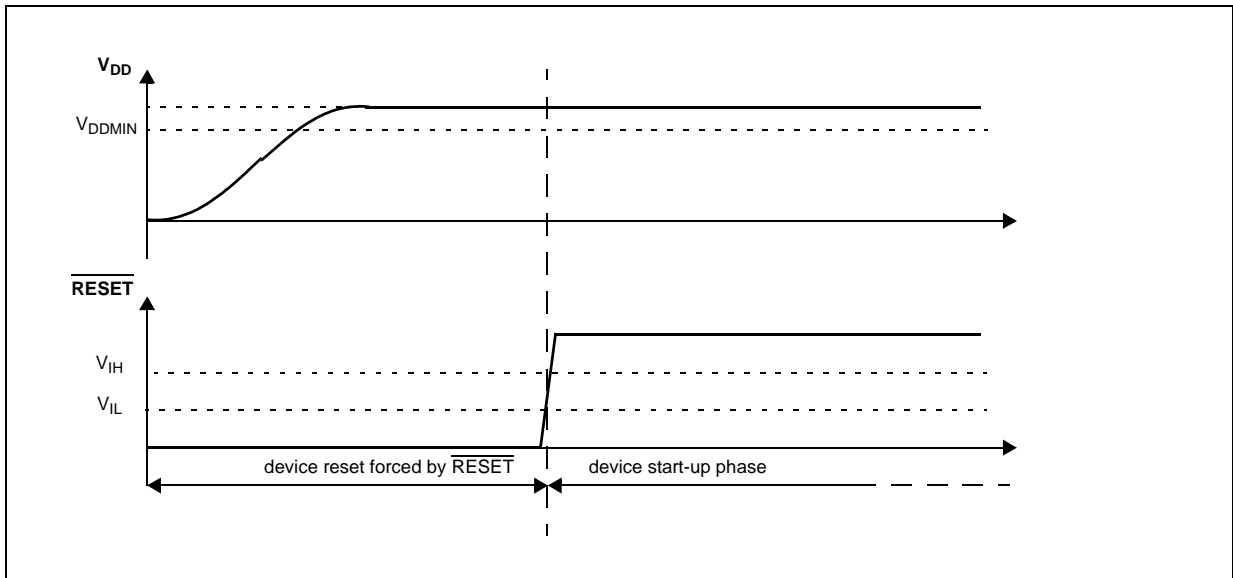


Figure 8. Noise filtering on reset signal

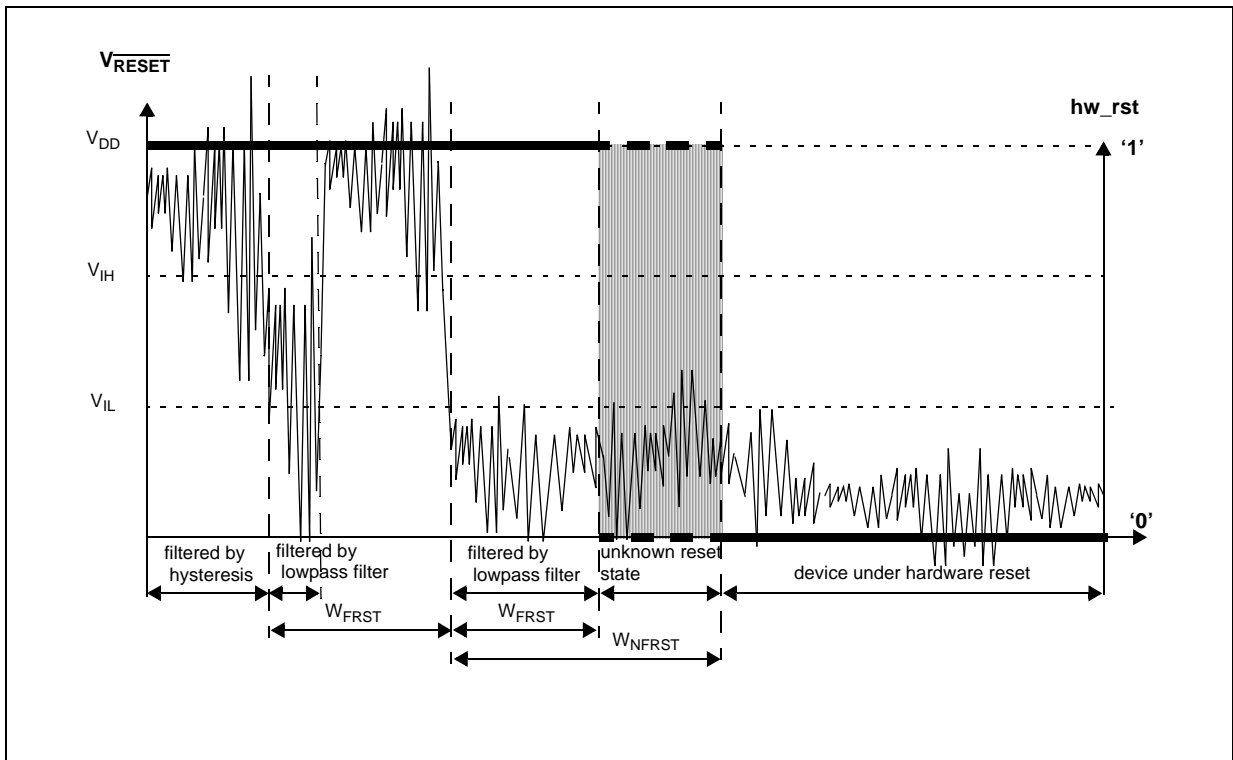


Table 25. Reset electrical characteristics

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit	
				Min	Typ	Max		
V <sub>IH</sub>	SR	P	Input High Level CMOS (Schmitt Trigger)	—	0.65V <sub>DD</sub>	—	V <sub>DD</sub> + 0.4	V
V <sub>IL</sub>	SR	P	Input low Level CMOS (Schmitt Trigger)	—	-0.4	—	0.35V <sub>DD</sub>	V
V <sub>HYS</sub>	CC	C	Input hysteresis CMOS (Schmitt Trigger)	—	0.1V <sub>DD</sub>	—	—	V
V <sub>OL</sub>	CC	P	Output low level	Push Pull, I <sub>OL</sub> = 2 mA, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0 (recommended)	—	—	0.1V <sub>DD</sub>	V
				Push Pull, I <sub>OL</sub> = 1 mA, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 1 <sup>(2)</sup>	—	—	0.1V <sub>DD</sub>	
				Push Pull, I <sub>OL</sub> = 1 mA, V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1 (recommended)	—	—	0.5	
t <sub>tr</sub>	CC	D	Output transition time output pin <sup>(3)</sup> MEDIUM configuration	C <sub>L</sub> = 25 pF, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	—	—	10	ns
				C <sub>L</sub> = 50 pF, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	—	—	20	
				C <sub>L</sub> = 100 pF, V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	—	—	40	
				C <sub>L</sub> = 25 pF, V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1	—	—	12	
				C <sub>L</sub> = 50 pF, V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1	—	—	25	
				C <sub>L</sub> = 100 pF, V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1	—	—	40	
W <sub>FRST</sub>	SR	P	RESE <sub>T</sub> input filtered pulse	—	—	—	40	ns
W <sub>NFRST</sub>	SR	P	RESE <sub>T</sub> input not filtered pulse	—	1000	—	—	ns
I <sub>WPUL</sub>	CC	P	Weak pull-up current absolute value	V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1	10	—	150	μA
		D		V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0	10	—	150	
		P		V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 1 <sup>(4)</sup>	10	—	250	

- V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C, unless otherwise specified.
- This is a transient configuration during power-up, up to the end of reset PHASE2 (refer to RGM module section of the device reference manual).
- C<sub>L</sub> includes device and package capacitance (C<sub>PKG</sub> < 5 pF).
- The configuration PAD3V5 = 1 when V<sub>DD</sub> = 5 V is only transient configuration during power-up. All pads but RESET and Nexus output (MDOx, EVTO, MCKO) are configured in input or in high impedance state.

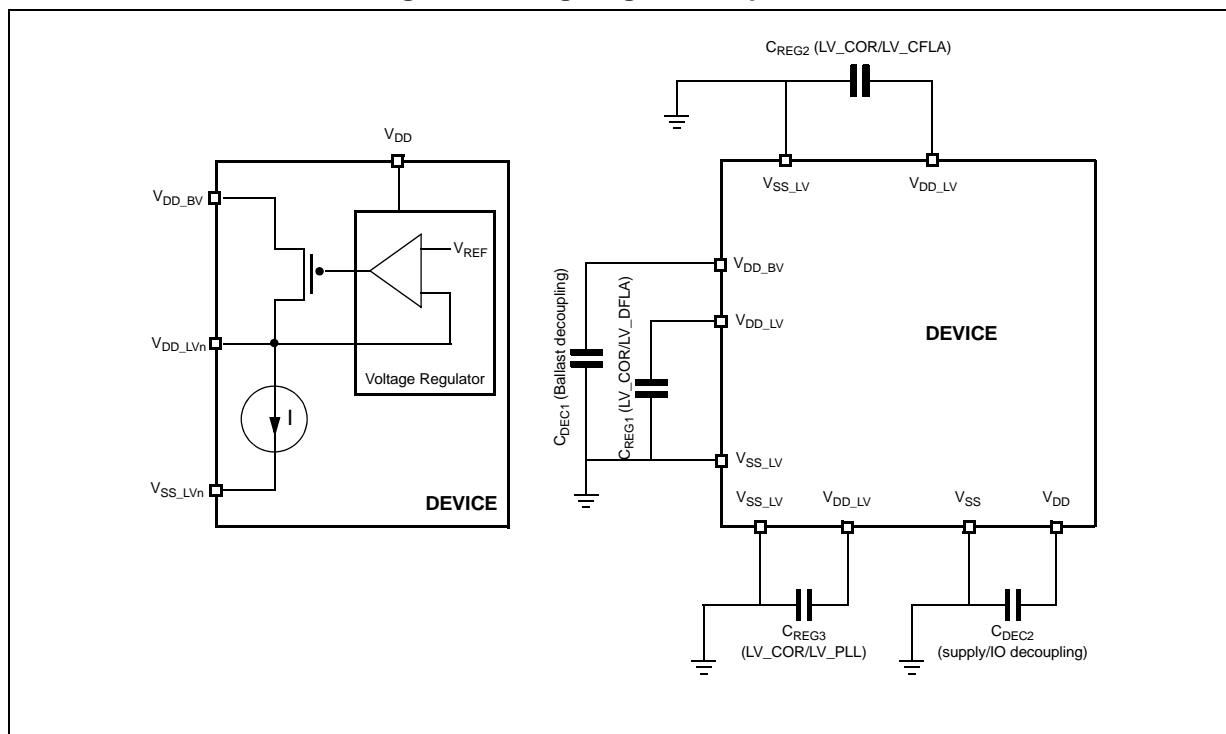
## 4.8 Power management electrical characteristics

### 4.8.1 Voltage regulator electrical characteristics

The device implements an internal voltage regulator to generate the low voltage core supply  $V_{DD\_LV}$  from the high voltage ballast supply  $V_{DD\_BV}$ . The regulator itself is supplied by the common I/O supply  $V_{DD}$ . The following supplies are involved:

- HV: High voltage external power supply for voltage regulator module. This must be provided externally through  $V_{DD}$  power pin.
- BV: High voltage external power supply for internal ballast module. This must be provided externally through  $V_{DD\_BV}$  power pin. Voltage values should be aligned with  $V_{DD}$ .
- LV: Low voltage internal power supply for core, FMPLL and Flash digital logic. This is generated by the internal voltage regulator but provided outside to connect stability capacitor. It is further split into four main domains to ensure noise isolation between critical LV modules within the device:
  - LV\_COR: Low voltage supply for the core. It is also used to provide supply for FMPLL through double bonding.
  - LV\_CFLA: Low voltage supply for code flash module. It is supplied with dedicated ballast and shorted to LV\_COR through double bonding.
  - LV\_DFLA: Low voltage supply for data flash module. It is supplied with dedicated ballast and shorted to LV\_COR through double bonding.
  - LV\_PLL: Low voltage supply for FMPLL. It is shorted to LV\_COR through double bonding.

Figure 9. Voltage regulator capacitance connection



The internal voltage regulator requires external capacitance ( $C_{REGn}$ ) to be connected to the device in order to provide a stable low voltage digital supply to the device. Capacitances should be placed on the board as near as possible to the associated pins. Care should also be taken to limit the serial inductance of the board to less than 5 nH.

Each decoupling capacitor must be placed between each of the three  $V_{DD\_LV}/V_{SS\_LV}$  supply pairs to ensure stable voltage (see [Section 4.4: Recommended operating conditions](#)).

**Table 26. Voltage regulator electrical characteristics**

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit	
				Min	Typ	Max		
$C_{REGn}$	SR	Internal voltage regulator external capacitance	—	200	—	500	nF	
$R_{REG}$	SR	Stability capacitor equivalent serial resistance	Range: 10 kHz to 20 MHz	—	—	0.2	W	
$C_{DEC1}$	SR	Decoupling capacitance <sup>(2)</sup> ballast	$V_{DD\_BV}/V_{SS\_LV}$ pair: $V_{DD\_BV} = 4.5\text{ V to }5.5\text{ V}$	100 <sup>(3)</sup>	470 <sup>(4)</sup>	—	nF	
			$V_{DD\_BV}/V_{SS\_LV}$ pair: $V_{DD\_BV} = 3\text{ V to }3.6\text{ V}$	400		—		
$C_{DEC2}$	SR	Decoupling capacitance regulator supply	$V_{DD}/V_{SS}$ pair	10	100	—	nF	
$V_{MREG}$	CC	T P	Main regulator output voltage	Before exiting from reset	—	1.32	—	V
			After trimming	1.16	1.28	—		
$I_{MREG}$	SR	Main regulator current provided to $V_{DD\_LV}$ domain	—	—	—	150	mA	
$I_{MREGINT}$	CC	D	Main regulator module current consumption	$I_{MREG} = 200\text{ mA}$	—	—	2	mA
			$I_{MREG} = 0\text{ mA}$	—	—	1		
$V_{LPREG}$	CC	P	Low-power regulator output voltage	After trimming	1.16	1.28	—	V
$I_{LPREG}$	SR	—	Low-power regulator current provided to $V_{DD\_LV}$ domain	—	—	—	15	mA
$I_{LPREGINT}$	CC	D	Low-power regulator module current consumption	$I_{LPREG} = 15\text{ mA};$ $T_A = 55\text{ °C}$	—	—	600	$\mu\text{A}$
				$I_{LPREG} = 0\text{ mA};$ $T_A = 55\text{ °C}$	—	5	—	
$V_{ULPREG}$	CC	P	Ultra low power regulator output voltage	After trimming	1.16	1.28	—	V
$I_{ULPREG}$	SR	—	Ultra low power regulator current provided to $V_{DD\_LV}$ domain	—	—	—	5	mA
$I_{ULPREGINT}$	CC	D	Ultra low power regulator module current consumption	$I_{ULPREG} = 5\text{ mA};$ $T_A = 55\text{ °C}$	—	—	100	$\mu\text{A}$
				$I_{ULPREG} = 0\text{ mA};$ $T_A = 55\text{ °C}$	—	2	—	
$I_{DD\_BV}$	CC	D	In-rush average current on $V_{DD\_BV}$ during power-up <sup>(5)</sup>	—	—	—	300 <sup>(6)</sup>	mA

1.  $V_{DD} = 3.3\text{ V} \pm 10\% / 5.0\text{ V} \pm 10\%$ ,  $T_A = -40$  to  $125\text{ }^\circ\text{C}$ , unless otherwise specified.
2. This capacitance value is driven by the constraints of the external voltage regulator supplying the  $V_{DD\_BV}$  voltage. A typical value is in the range of 470 nF.
3. This value is acceptable to guarantee operation from 4.5 V to 5.5 V.
4. External regulator and capacitance circuitry must be capable of providing  $I_{DD\_BV}$  while maintaining supply  $V_{DD\_BV}$  in operating range.
5. In-rush average current is seen only for short time during power-up and on standby exit (maximum 20  $\mu\text{s}$ , depending on external capacitances to be loaded).
6. The duration of the in-rush current depends on the capacitance placed on LV pins. BV decoupling capacitors must be sized accordingly. Refer to  $I_{MREG}$  value for minimum amount of current to be provided in cc.

#### 4.8.2 Low voltage detector electrical characteristics

The device implements a power-on reset (POR) module to ensure correct power-up initialization, as well as five low voltage detectors (LVDs) to monitor the  $V_{DD}$  and the  $V_{DD\_LV}$  voltage while device is supplied:

- POR monitors  $V_{DD}$  during the power-up phase to ensure device is maintained in a safe reset state (refer to RGM Destructive Event Status (RGM\_DES) Register flag F\_POR in device reference manual)
- LVDHV3 monitors  $V_{DD}$  to ensure device reset below minimum functional supply (refer to RGM Destructive Event Status (RGM\_DES) Register flag F\_LVD27 in device reference manual)
- LVDHV3B monitors  $V_{DD\_BV}$  to ensure device reset below minimum functional supply (refer to RGM Destructive Event Status (RGM\_DES) Register flag F\_LVD27\_VREG in device reference manual)
- LVDHV5 monitors  $V_{DD}$  when application uses device in the  $5.0\text{ V} \pm 10\%$  range (refer to RGM Functional Event Status (RGM\_FES) Register flag F\_LVD45 in device reference manual)
- LVDLVCOR monitors power domain No. 1 (refer to RGM Destructive Event Status (RGM\_DES) Register flag F\_LVD12\_PD1 in device reference manual)
- LVDLVBKP monitors power domain No. 0 (refer to RGM Destructive Event Status (RGM\_DES) Register flag F\_LVD12\_PD0 in device reference manual)

*Note:* When enabled, power domain No. 2 is monitored through LVDLVBKP.



Figure 10. Low voltage detector vs reset

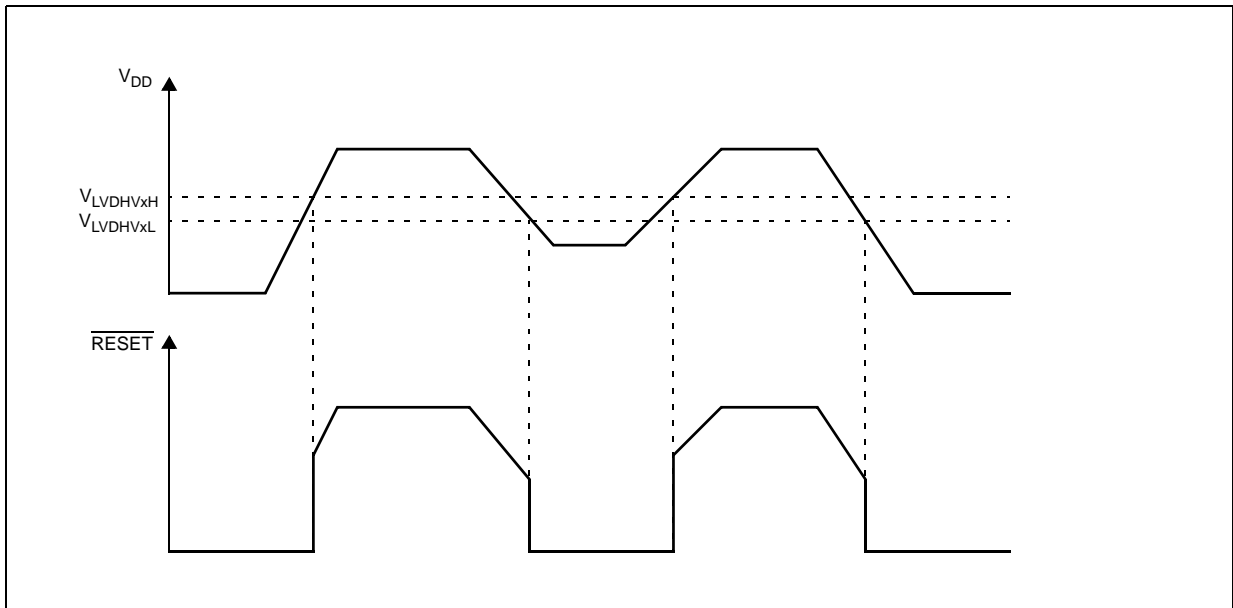


Table 27. Low voltage detector electrical characteristics

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit
				Min	Typ	Max	
V <sub>PORUP</sub>	SR	P	Supply for functional POR module	1.0	—	5.5	V
V <sub>PORH</sub>	CC	P	Power-on reset threshold	1.5	—	2.6	
V <sub>LVDHV3H</sub>	CC	T	LVDHV3 low voltage detector high threshold	—	—	2.95	
V <sub>LVDHV3L</sub>	CC	P	LVDHV3 low voltage detector low threshold	2.6	—	2.9	
V <sub>LVDHV3BH</sub>	CC	P	LVDHV3B low voltage detector high threshold	—	—	2.95	
V <sub>LVDHV3BL</sub>	CC	P	LVDHV3B low voltage detector low threshold	2.6	—	2.9	
V <sub>LVDHV5H</sub>	CC	T	LVDHV5 low voltage detector high threshold	—	—	4.5	
V <sub>LVDHV5L</sub>	CC	P	LVDHV5 low voltage detector low threshold	3.8	—	4.4	
V <sub>LVDLVCORL</sub>	CC	P	LVDLVCOR low voltage detector low threshold	1.08	—	1.16	
V <sub>LVDLVBKPL</sub>	CC	P	LVDLVBKP low voltage detector low threshold	1.08	—	1.16	

1. V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C, unless otherwise specified.

## 4.9 Power consumption

Table 28 provides DC electrical characteristics for significant application modes. These values are indicative values; actual consumption depends on the application.

Table 28. Power consumption on VDD\_BV and VDD\_HV

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit		
				Min	Typ	Max			
I <sub>DDMAX</sub> <sup>(2)</sup>	CC	D	RUN mode maximum average current	—	115	140 <sup>(3)</sup>	mA		
I <sub>DDRUN</sub> <sup>(4)</sup>	CC	T	RUN mode typical average current <sup>(5)</sup>	f <sub>CPU</sub> = 8 MHz	—	12	—	mA	
				f <sub>CPU</sub> = 16 MHz	—	27	—		
				f <sub>CPU</sub> = 32 MHz	—	43	—		
				f <sub>CPU</sub> = 48 MHz	—	56	100		
				f <sub>CPU</sub> = 64 MHz	—	70	125		
I <sub>DDHALT</sub>	CC	C	HALT mode current <sup>(6)</sup>	Slow internal RC oscillator (128 kHz) running	T <sub>A</sub> = 25 °C	—	10	18	mA
					T <sub>A</sub> = 125 °C	—	17	28	
I <sub>DDSTOP</sub>	CC	D	STOP mode current <sup>(7)</sup>	Slow internal RC oscillator (128 kHz) running	T <sub>A</sub> = 25 °C	—	350	900 <sup>(8)</sup>	μA
					T <sub>A</sub> = 55 °C	—	750	—	
					T <sub>A</sub> = 85 °C	—	2	7	mA
					T <sub>A</sub> = 105 °C	—	4	10	
					T <sub>A</sub> = 125 °C	—	7	14	
I <sub>DDSTDBY2</sub>	CC	D	STANDBY2 mode current <sup>(9)</sup>	Slow internal RC oscillator (128 kHz) running	T <sub>A</sub> = 25 °C	—	30	100	μA
					T <sub>A</sub> = 55 °C	—	75	—	
					T <sub>A</sub> = 85 °C	—	180	700	
					T <sub>A</sub> = 105 °C	—	315	1000	
					T <sub>A</sub> = 125 °C	—	560	1700	
I <sub>DDSTDBY1</sub>	CC	D	STANDBY1 mode current <sup>(10)</sup>	Slow internal RC oscillator (128 kHz) running	T <sub>A</sub> = 25 °C	—	20	60	μA
					T <sub>A</sub> = 55 °C	—	45	—	
					T <sub>A</sub> = 85 °C	—	100	350	
					T <sub>A</sub> = 105 °C	—	165	500	
					T <sub>A</sub> = 125 °C	—	280	900	

- V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C, unless otherwise specified.
- I<sub>DDMAX</sub> is drawn only from the VDD\_BV pin. Running consumption does not include I/Os toggling which is highly dependent on the application. The given value is thought to be a worst case value with all peripherals running, and code fetched from code flash while modify operation ongoing on data flash. Notice that this value can be significantly reduced by application: switch off not used peripherals (default), reduce peripheral frequency through internal prescaler, fetch from RAM most used functions, use low power mode when possible.
- Higher current may be sunk by device during power-up and standby exit. Please refer to in-rush average current in [Table 26](#).
- I<sub>DDRUN</sub> is drawn only from the VDD\_BV pin. RUN current measured with typical application with accesses on both Flash and RAM.
- Only for the “P” classification: Data and Code Flash in Normal Power. Code fetched from RAM: Serial IPs CAN and LIN in loop back mode, DSPI as Master, PLL as system clock (4 x Multiplier) peripherals on (eMIOS/CTU/ADC) and running at max frequency, periodic SW/WDG timer reset enabled.

6. Data Flash Power Down. Code Flash in Low Power. SIRC 128 kHz and FIRC 16 MHz on. 10 MHz XTAL clock. FlexCAN: instances: 0, 1, 2 ON (clocked but not reception or transmission), instances: 4, 5, 6 clocks gated. LINFlex: instances: 0, 1, 2 ON (clocked but not reception or transmission), instance: 3 to 9 clocks gated. eMIOS: instance: 0 ON (16 channels on PA[0]–PA[11] and PC[12]–PC[15]) with PWM 20 kHz, instance: 1 clock gated. DSPI: instance: 0 (clocked but no communication), instance: 1 to 5 clocks gated. RTC/API ON. PIT ON. STM ON. ADC1 OFF. ADC0 ON but no conversion except two analog watchdogs.
7. Only for the “P” classification: No clock, FIRC 16 MHz off, SIRC 128 kHz on, PLL off, HPVreg off, ULPVreg/LPVreg on. All possible peripherals off and clock gated. Flash in power down mode.
8. When going from RUN to STOP mode and the core consumption is > 6 mA, it is normal operation for the main regulator module to be kept on by the on-chip current monitoring circuit. This is most likely to occur with junction temperatures exceeding 125 °C and under these circumstances, it is possible for the current to initially exceed the maximum STOP specification by up to 2 mA. After entering stop, the application junction temperature will reduce to the ambient level and the main regulator will be automatically switched off when the load current is below 6 mA.
9. Only for the “P” classification: ULPreg on, HP/LPVreg off, 32 KB RAM on, device configured for minimum consumption, all possible modules switched off.
10. ULPreg on, HP/LPVreg off, 8 KB RAM on, device configured for minimum consumption, all possible modules switched off.

## 4.10 Flash memory electrical characteristics

### 4.10.1 Program/erase characteristics

Table 29 shows the program and erase characteristics.

Table 29. Program and erase specifications

Symbol	C	Parameter	Conditions	Value				Unit
				Min	Typ (1)	Initial max (2)	Max (3)	
t <sub>dwprogram</sub>	C	Double word (64 bits) program time <sup>(4)</sup>	Code Flash	—	18	50	500	µs
			Data Flash	—	22			
t <sub>16Kpperase</sub>		16 KB block preprogram and erase time	Code Flash	—	200	500	5000	ms
			Data Flash	—	300			
t <sub>32Kpperase</sub>		32 KB block preprogram and erase time	Code Flash	—	300	600	5000	ms
			Data Flash	—	400			
t <sub>128Kpperase</sub>		128 KB block preprogram and erase time	Code Flash	—	600	1300	7500	ms
			Data Flash	—	800			
t <sub>esus</sub>		D	Erase Suspend Latency	—	—	30	30	µs
t <sub>ESRT</sub>		C	Erase Suspend Request Rate <sup>(5)</sup>	Code Flash	20	—	—	—
	Data Flash			10	—	—	—	

1. Typical program and erase times assume nominal supply values and operation at 25 °C. All times are subject to change pending device characterization.
2. Initial factory condition: < 100 program/erase cycles, 25 °C, typical supply voltage.
3. The maximum program and erase times occur after the specified number of program/erase cycles. These maximum values are characterized but not guaranteed.
4. Actual hardware programming times. This does not include software overhead.
5. Time between erase suspend resume and the next erase suspend request.

Table 30. Flash module life

Symbol	C	Parameter	Conditions	Value			Unit	
				Min	Typ	Max		
P/E	CC	C	Number of program/erase cycles per block for 16 KB blocks over the operating temperature range ( $T_J$ )	—	100000	—	cycles	
P/E	CC	C	Number of program/erase cycles per block for 32 KB blocks over the operating temperature range ( $T_J$ )	—	10000	100000	cycles	
P/E	CC	C	Number of program/erase cycles per block for 128 KB blocks over the operating temperature range ( $T_J$ )	—	1000	100000	cycles	
Retention	CC	C	Minimum data retention at 85 °C average ambient temperature <sup>(1)</sup>	Blocks with 0–1000 P/E cycles	20	—	—	years
				Blocks with 1001–10000 P/E cycles	10	—	—	years
				Blocks with 10001–100000 P/E cycles	5	—	—	years

1. Ambient temperature averaged over duration of application, not to exceed recommended product operating temperature range.

ECC circuitry provides correction of single bit faults and is used to improve further automotive reliability results. Some units will experience single bit corrections throughout the life of the product with no impact to product reliability.

Table 31. Flash read access timing

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Max	Unit	
$f_{\text{READ}}$	CC	P	Maximum frequency for Flash reading	2 wait states	64	MHz
				1 wait state	40	
				0 wait states	20	

1.  $V_{\text{DD}} = 3.3 \text{ V} \pm 10\% / 5.0 \text{ V} \pm 10\%$ ,  $T_A = -40$  to  $125$  °C, unless otherwise specified.

#### 4.10.2 Flash power supply DC characteristics

Table 32 shows the power supply DC characteristics on external supply.

**Table 32. Flash power supply DC electrical characteristics**

Symbol	Parameter	Conditions <sup>(1)</sup>	Value			Unit	
			Min	Typ	Max		
I <sub>CFREAD</sub>	Sum of the current consumption on V <sub>DD_HV</sub> and V <sub>DD_BV</sub> on read access	Flash module read f <sub>CPU</sub> = 64 MHz	Code Flash	—	—	33	mA
I <sub>DFREAD</sub>			Data Flash	—	—	33	
I <sub>CFMOD</sub>	Sum of the current consumption on V <sub>DD_HV</sub> and V <sub>DD_BV</sub> on matrix modification (program/erase)	Program/Erase on-going while reading Flash registers f <sub>CPU</sub> = 64 MHz	Code Flash	—	—	52	mA
I <sub>DFMOD</sub>			Data Flash	—	—	33	
I <sub>CFLPW</sub>	Sum of the current consumption on V <sub>DD_HV</sub> and V <sub>DD_BV</sub> during Flash low power mode	—	Code Flash	—	—	1.1	mA
I <sub>DFLPW</sub>			Data Flash	—	—	900	
I <sub>CFPWD</sub>	Sum of the current consumption on V <sub>DD_HV</sub> and V <sub>DD_BV</sub> during Flash power down mode	—	Code Flash	—	—	150	μA
I <sub>DFPWD</sub>			Data Flash	—	—	150	

1. V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C, unless otherwise specified.

### 4.10.3 Start-up/Switch-off timings

**Table 33. Start-up time/Switch-off time**

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit
				Min	Typ	Max	
t <sub>FLARSTEXIT</sub>	CC	T	Delay for Flash module to exit reset mode	—	—	125	μs
t <sub>FLALPEXIT</sub>	CC	T	Delay for Flash module to exit low-power mode	—	—	0.5	
t <sub>FLAPDEXIT</sub>	CC	T	Delay for Flash module to exit power-down mode	—	—	30	
t <sub>FLALPENTRY</sub>	CC	T	Delay for Flash module to enter low-power mode	—	—	0.5	
t <sub>FLAPDENTRY</sub>	CC	T	Delay for Flash module to enter power-down mode	—	—	1.5	

1. V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C, unless otherwise specified.

## 4.11 Electromagnetic compatibility (EMC) characteristics

Susceptibility tests are performed on a sample basis during product characterization.

### 4.11.1 Designing hardened software to avoid noise problems

EMC characterization and optimization are performed at component level with a typical application environment and simplified MCU software. It should be noted that good EMC performance is highly dependent on the user application and the software in particular.

Therefore it is recommended that the user apply EMC software optimization and prequalification tests in relation with the EMC level requested for the application.

- Software recommendations – The software flowchart must include the management of runaway conditions such as:
  - Corrupted program counter
  - Unexpected reset
  - Critical data corruption (control registers...)
- Prequalification trials – Most of the common failures (unexpected reset and program counter corruption) can be reproduced by manually forcing a low state on the reset pin or the oscillator pins for 1 second.

To complete these trials, ESD stress can be applied directly on the device. When unexpected behavior is detected, the software can be hardened to prevent unrecoverable errors occurring (see application note *Software Techniques For Improving Microcontroller EMC Performance (AN1015)*).

### 4.11.2 Electromagnetic interference (EMI)

The product is monitored in terms of emission based on a typical application. This emission test conforms to the IEC61967-1 standard, which specifies the general conditions for EMI measurements.

**Table 34. EMI radiated emission measurement<sup>(1)(2)</sup>**

Symbol	C	Parameter	Conditions	Value			Unit		
				Min	Typ	Max			
—	SR	—	Scan range	0.15 0	—	1000	MHz		
f <sub>CPU</sub>	SR	—	Operating frequency	—	64	—	MHz		
V <sub>DD_LV</sub>	SR	—	LV operating voltages	—	1.28	—	V		
S <sub>EMI</sub>	CC	T	Peak level	V <sub>DD</sub> = 5 V, T <sub>A</sub> = 25 °C, LQFP144 package Test conforming to IEC 61967-2, f <sub>OSC</sub> = 8 MHz/f <sub>CPU</sub> = 64 MHz	No PLL frequency modulation	—	—	18	dBμV
					± 2% PLL frequency modulation	—	—	14	dBμV

1. EMI testing and I/O port waveforms per IEC 61967-1, -2, -4.
2. For information on conducted emission and susceptibility measurement (norm IEC 61967-4), please contact your local marketing representative.

### 4.11.3 Absolute maximum ratings (electrical sensitivity)

Based on two different tests (ESD and LU) using specific measurement methods, the product is stressed in order to determine its performance in terms of electrical sensitivity.

**4.11.3.1 Electrostatic discharge (ESD)**

Electrostatic discharges (a positive then a negative pulse separated by 1 second) are applied to the pins of each sample according to each pin combination. The sample size depends on the number of supply pins in the device (3 parts×(n + 1) supply pin). This test conforms to the AEC-Q100-002/-003/-011 standard. For more details, refer to the application note *Electrostatic Discharge Sensitivity Measurement* (AN1181).

**Table 35. ESD absolute maximum ratings<sup>(1)(2)</sup>**

Symbol	Ratings	Conditions	Class	Max value <sup>(3)</sup>	Unit
V <sub>ESD(HBM)</sub>	Electrostatic discharge voltage (Human Body Model)	T <sub>A</sub> = 25 °C conforming to AEC-Q100-002	H1C	2000	V
V <sub>ESD(MM)</sub>	Electrostatic discharge voltage (Machine Model)	T <sub>A</sub> = 25 °C conforming to AEC-Q100-003	M2	200	
V <sub>ESD(CDM)</sub>	Electrostatic discharge voltage (Charged Device Model)	T <sub>A</sub> = 25 °C conforming to AEC-Q100-011	C3A	500 750 (corners)	

1. All ESD testing is in conformity with CDF-AEC-Q100 Stress Test Qualification for Automotive Grade Integrated Circuits.
2. A device will be defined as a failure if after exposure to ESD pulses the device no longer meets the device specification requirements. Complete DC parametric and functional testing shall be performed per applicable device specification at room temperature followed by hot temperature, unless specified otherwise in the device specification.
3. Data based on characterization results, not tested in production

**4.11.3.2 Static latch-up (LU)**

Two complementary static tests are required on six parts to assess the latch-up performance:

- A supply overvoltage is applied to each power supply pin.
- A current injection is applied to each input, output and configurable I/O pin.

These tests are compliant with the EIA/JESD 78 IC latch-up standard.

**Table 36. Latch-up results**

Symbol	Parameter	Conditions	Class
LU	Static latch-up class	T <sub>A</sub> = 125 °C conforming to JESD 78	II level A

**4.12 Fast external crystal oscillator (4 to 16 MHz) electrical characteristics**

The device provides an oscillator/resonator driver. [Figure 11](#) describes a simple model of the internal oscillator driver and provides an example of a connection for an oscillator or a resonator.

[Table 37](#) provides the parameter description of 4 MHz to 16 MHz crystals used for the design simulations.

Figure 11. Crystal oscillator and resonator connection scheme

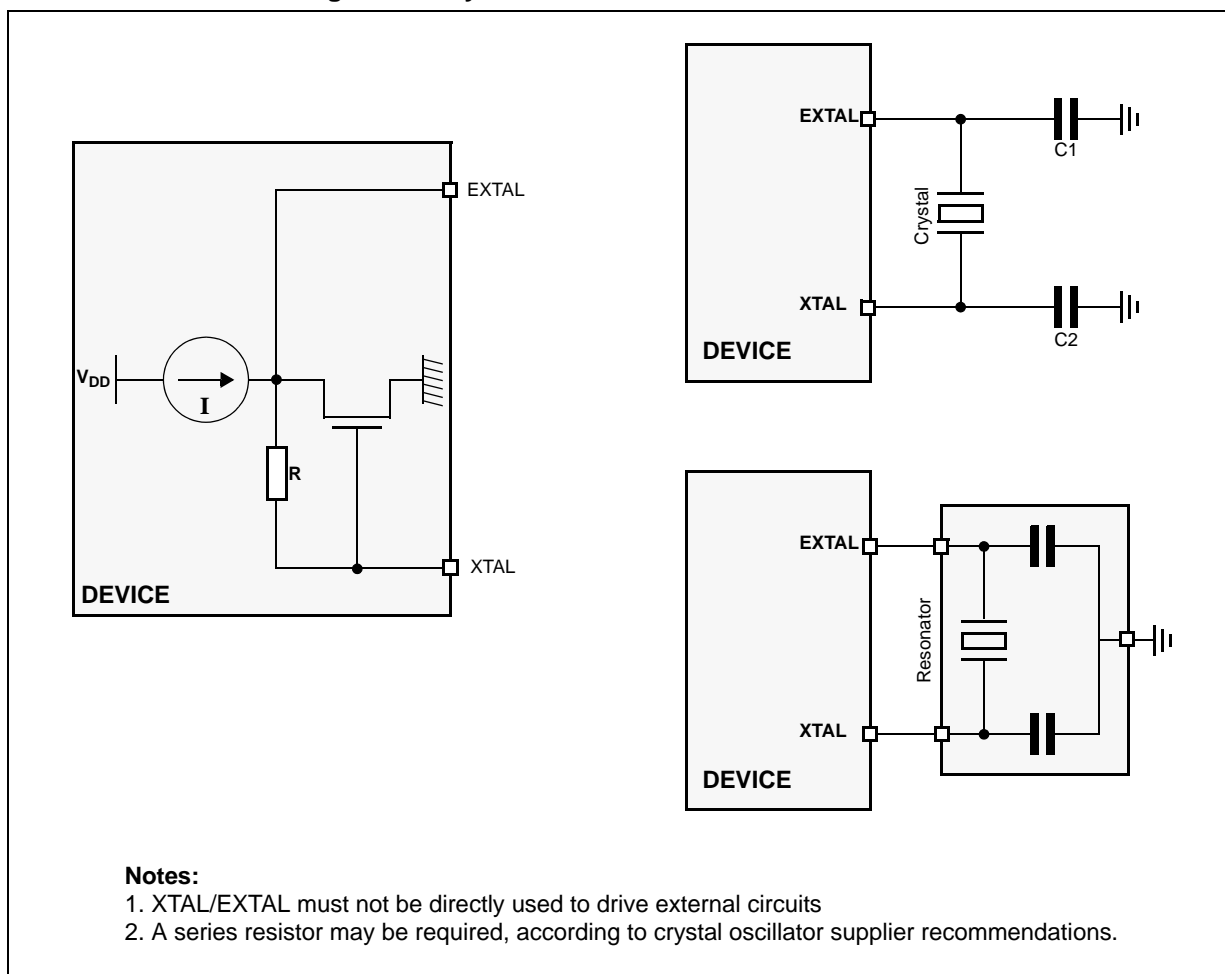


Table 37. Crystal description

Nominal frequency (MHz)	NDK crystal reference	Crystal equivalent series resistance ESR $\Omega$	Crystal motional capacitance ( $C_m$ ) fF	Crystal motional inductance ( $L_m$ ) mH	Load on xtalin/xtalout $C1 = C2$ (pF) <sup>(1)</sup>	Shunt capacitance between xtalout and xtalin $C0$ <sup>(2)</sup> (pF)
4	NX8045GB	300	2.68	591.0	21	2.93
8	NX5032GA	300	2.46	160.7	17	3.01
10		150	2.93	86.6	15	2.91
12		120	3.11	56.5	15	2.93
16		120	3.90	25.3	10	3.00

1. The values specified for C1 and C2 are the same as used in simulations. It should be ensured that the testing includes all the parasitics (from the board, probe, crystal, etc.) as the AC / transient behavior depends upon them.
2. The value of C0 specified here includes 2 pF additional capacitance for parasitics (to be seen with bond-pads, package, etc.).



Figure 12. Fast external crystal oscillator (4 to 16 MHz) timing diagram

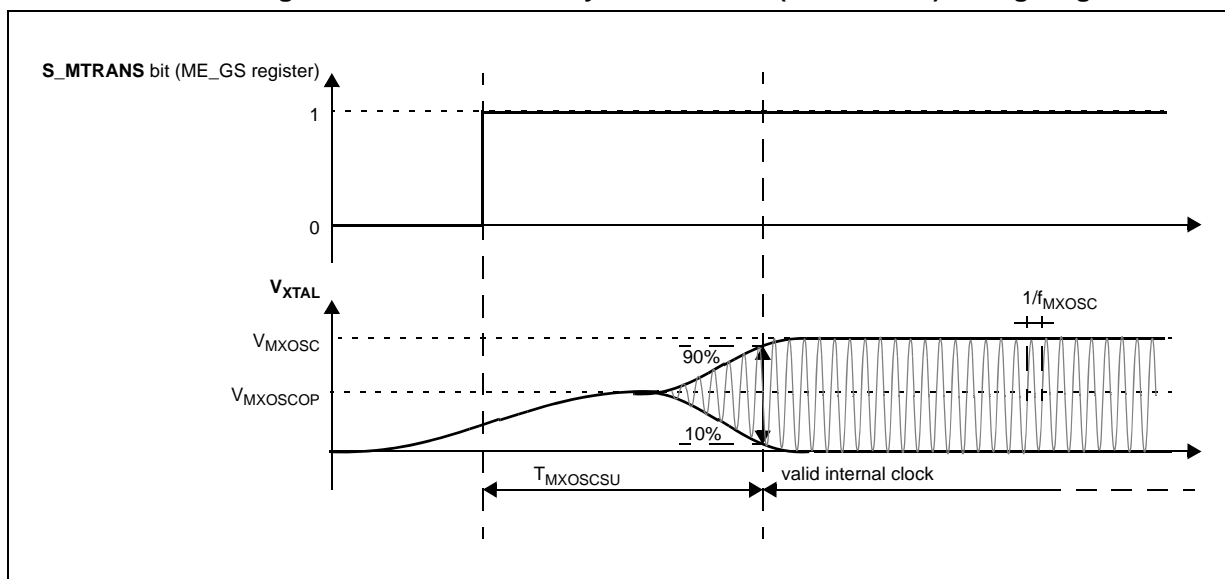


Table 38. Fast external crystal oscillator (4 to 16 MHz) electrical characteristics

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit
				Min	Typ	Max	
f <sub>FXOSC</sub>	S R	Fast external crystal oscillator frequency	—	4.0	—	16.0	MHz
g <sub>mFXOSC</sub>	C C	Fast external crystal oscillator transconductance	V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1 OSCILLATOR_MARGIN = 0	2.2	—	8.2	mA/ V
	C C		V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0 OSCILLATOR_MARGIN = 0	2.0	—	7.4	
	C C		V <sub>DD</sub> = 3.3 V ± 10%, PAD3V5V = 1 OSCILLATOR_MARGIN = 1	2.7	—	9.7	
	C C		V <sub>DD</sub> = 5.0 V ± 10%, PAD3V5V = 0 OSCILLATOR_MARGIN = 1	2.5	—	9.2	
V <sub>FXOSC</sub>	C C	Oscillation amplitude at EXTAL	f <sub>OSC</sub> = 4 MHz, OSCILLATOR_MARGIN = 0	1.3	—	—	V
			f <sub>OSC</sub> = 16 MHz, OSCILLATOR_MARGIN = 1	1.3	—	—	
V <sub>FXOSCOF</sub>	C C	Oscillation operating point	—	—	0.95	—	V

**Table 38. Fast external crystal oscillator (4 to 16 MHz) electrical characteristics (continued)**

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit
				Min	Typ	Max	
$I_{FXOSC}^{(2)}$	C C	T Fast external crystal oscillator consumption	—	—	2	3	mA
$t_{FXOSCSU}$	C C	T Fast external crystal oscillator start-up time	$f_{OSC} = 4 \text{ MHz}$ , OSCILLATOR_MARGIN = 0	—	—	6	ms
			$f_{OSC} = 16 \text{ MHz}$ , OSCILLATOR_MARGIN = 1	—	—	1.8	
$V_{IH}$	S R	P Input high level CMOS (Schmitt Trigger)	Oscillator bypass mode	$0.65V_{DD}$	—	$V_{DD} + \frac{0.4}{4}$	V
$V_{IL}$	S R	P Input low level CMOS (Schmitt Trigger)	Oscillator bypass mode	-0.4	—	$0.35V_{DD}$	V

- $V_{DD} = 3.3 \text{ V} \pm 10\% / 5.0 \text{ V} \pm 10\%$ ,  $T_A = -40 \text{ to } 125 \text{ }^\circ\text{C}$ , unless otherwise specified.
- Stated values take into account only analog module consumption but not the digital contributor (clock tree and enabled peripherals).

### 4.13 Slow external crystal oscillator (32 kHz) electrical characteristics

The device provides a low power oscillator/resonator driver.

**Figure 13. Crystal oscillator and resonator connection scheme**

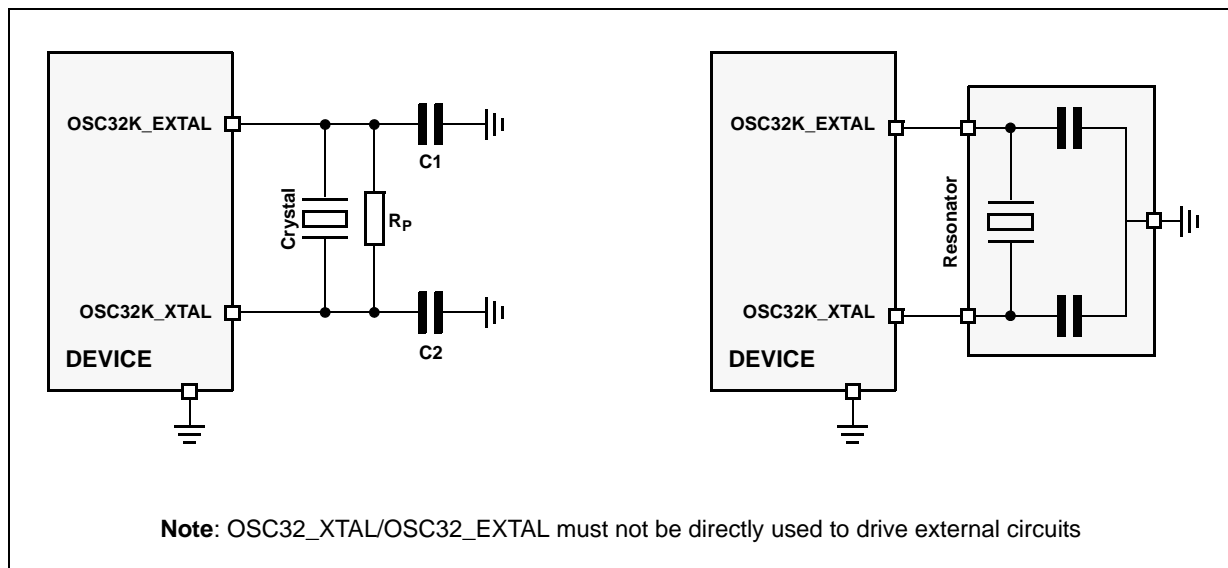


Figure 14. Equivalent circuit of a quartz crystal

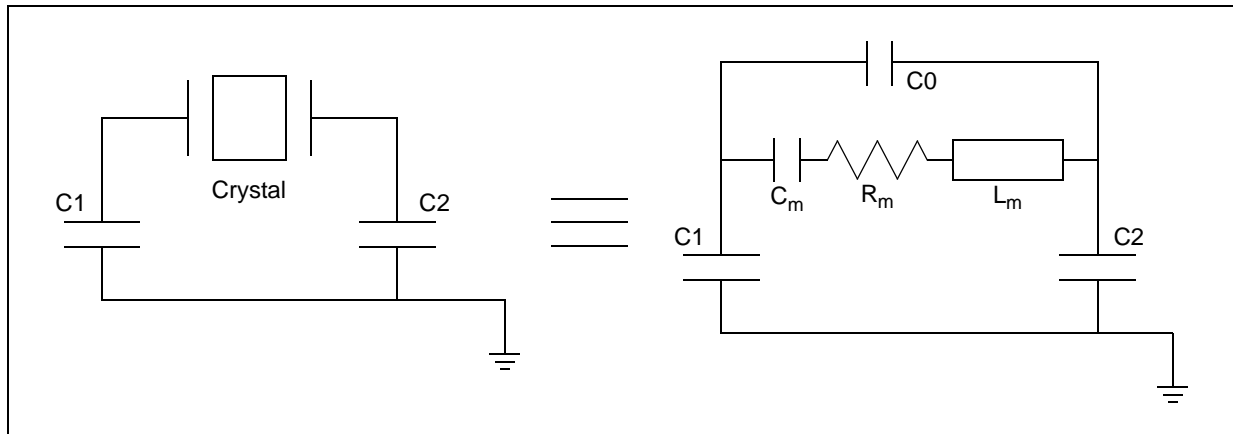


Table 39. Crystal motional characteristics<sup>(1)</sup>

Symbol	Parameter	Conditions	Value			Unit
			Min	Typ	Max	
$L_m$	Motional inductance	—	—	11.796	—	KH
$C_m$	Motional capacitance	—	—	2	—	fF
C1/C2	Load capacitance at OSC32K_XTAL and OSC32K_EXTAL with respect to ground <sup>(2)</sup>	—	18	—	28	pF
$R_m^{(3)}$	Motional resistance	AC coupled at $C_0 = 2.85 \text{ pF}^{(4)}$	—	—	65	kW
		AC coupled at $C_0 = 4.9 \text{ pF}^{(4)}$	—	—	50	
		AC coupled at $C_0 = 7.0 \text{ pF}^{(4)}$	—	—	35	
		AC coupled at $C_0 = 9.0 \text{ pF}^{(4)}$	—	—	30	

1. The crystal used is Epson Toyocom MC306.
2. This is the recommended range of load capacitance at OSC32K\_XTAL and OSC32K\_EXTAL with respect to ground. It includes all the parasitics due to board traces, crystal and package.
3. Maximum ESR ( $R_m$ ) of the crystal is 50 kΩ.
4.  $C_0$  Includes a parasitic capacitance of 2.0 pF between OSC32K\_XTAL and OSC32K\_EXTAL pins.

Figure 15. Slow external crystal oscillator (32 kHz) timing diagram

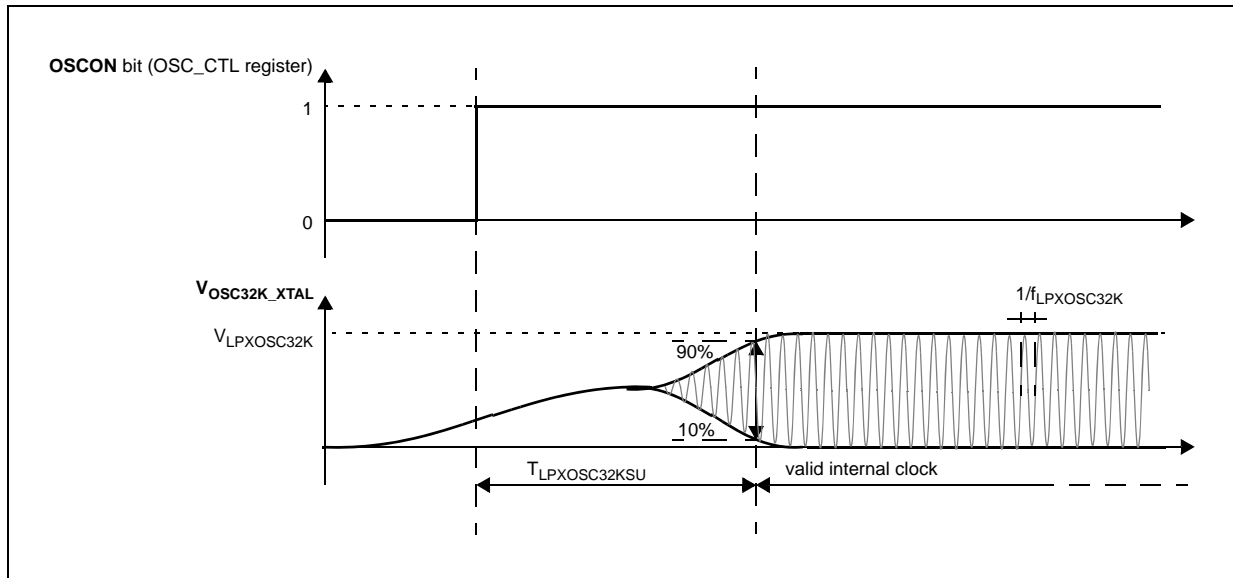


Table 40. Slow external crystal oscillator (32 kHz) electrical characteristics

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit
				Min	Typ	Max	
f <sub>SXOSC</sub>	S R	—	Slow external crystal oscillator frequency	32	32.768	40	kHz
V <sub>SXOSC</sub>	C C	T	Oscillation amplitude	—	2.1	—	V
I <sub>SXOSCBIAS</sub>	C C	T	Oscillation bias current	2.5			μA
I <sub>SXOSC</sub>	C C	T	Slow external crystal oscillator consumption	—	—	8	μA
t <sub>SXOSCSU</sub>	C C	T	Slow external crystal oscillator start-up time	—	—	2 <sup>(2)</sup>	s

1. V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C, unless otherwise specified. Values are specified for no neighbor GPIO pin activity. If oscillator is enabled (OSC32K\_XTAL and OSC32K\_EXTAL pins), neighboring pins should not toggle.
2. Start-up time has been measured with EPSON TOYOCOM MC306 crystal. Variation may be seen with other crystal.

#### 4.14 FMPLL electrical characteristics

The device provides a frequency modulated phase locked loop (FMPLL) module to generate a fast system clock from the main oscillator driver.

Table 41. FMPLL electrical characteristics

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit	
				Min	Typ	Max		
f <sub>PLLIN</sub>	SR	—	FMPLL reference clock <sup>(2)</sup>	—	4	—	64	MHz
Δ <sub>PLLIN</sub>	SR	—	FMPLL reference clock duty cycle <sup>(2)</sup>	—	40	—	60	%
f <sub>PLLOUT</sub>	CC	P	FMPLL output clock frequency	—	16	—	64	MHz
f <sub>VCO</sub> <sup>(3)</sup>	CC	P	VCO frequency without frequency modulation	—	256	—	512	MHz
		P	VCO frequency with frequency modulation	—	245.76	—	532.48	
f <sub>CPU</sub>	SR	—	System clock frequency	—	—	—	64	MHz
f <sub>FREE</sub>	CC	P	Free-running frequency	—	20	—	150	MHz
t <sub>LOCK</sub>	CC	P	FMPLL lock time	Stable oscillator (f <sub>PLLIN</sub> = 16 MHz)	—	40	100	μs
Δt <sub>STJIT</sub>	CC	—	FMPLL short term jitter <sup>(4)</sup>	f <sub>sys</sub> maximum	—4	—	4	%
Δt <sub>LTJIT</sub>	CC	—	FMPLL long term jitter	f <sub>PLLCLK</sub> at 64 MHz, 4000 cycles	—	—	10	ns
I <sub>PLL</sub>	CC	C	FMPLL consumption	T <sub>A</sub> = 25 °C	—	—	4	mA

1. V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C, unless otherwise specified
2. PLLIN clock retrieved directly from FXOSC clock. Input characteristics are granted when oscillator is used in functional mode. When bypass mode is used, oscillator input clock should verify f<sub>PLLIN</sub> and Δ<sub>PLLIN</sub>.
3. Frequency modulation is considered ± 4%.
4. Short term jitter is measured on the clock rising edge at cycle n and n+4.

### 4.15 Fast internal RC oscillator (16 MHz) electrical characteristics

The device provides a 16 MHz main internal RC oscillator. This is used as the default clock at the power-up of the device.

Table 42. Fast internal RC oscillator (16 MHz) electrical characteristics

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit	
				Min	Typ	Max		
f <sub>FIRC</sub>	CC	P	Fast internal RC oscillator high frequency	T <sub>A</sub> = 25 °C, trimmed	—	16	—	MHz
	SR	—	—	—	12	—	20	
I <sub>FIRCRUN</sub> <sup>(2)</sup>	CC	T	Fast internal RC oscillator high frequency current in running mode	T <sub>A</sub> = 25 °C, trimmed	—	—	200	μA
I <sub>FIRCPWD</sub>	CC	D	Fast internal RC oscillator high frequency current in power down mode	T <sub>A</sub> = 25 °C	—	—	10	μA

**Table 42. Fast internal RC oscillator (16 MHz) electrical characteristics (continued)**

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit		
				Min	Typ	Max			
I <sub>FIRCSTOP</sub>	CC	T	Fast internal RC oscillator high frequency and system clock current in stop mode	T <sub>A</sub> = 25 °C	sysclk = off	—	500	—	µA
					sysclk = 2 MHz	—	600	—	
					sysclk = 4 MHz	—	700	—	
					sysclk = 8 MHz	—	900	—	
					sysclk = 16 MHz	—	1250	—	
t <sub>FIRCSU</sub>	CC	C	Fast internal RC oscillator start-up time	V <sub>DD</sub> = 5.0 V ± 10%	—	1.1	2.0	µs	
Δ <sub>FIRCPRE</sub>	CC	C	Fast internal RC oscillator precision after software trimming of f <sub>FIRC</sub>	T <sub>A</sub> = 25 °C	-1	—	1	%	
Δ <sub>FIRCTRIM</sub>	CC	C	Fast internal RC oscillator trimming step	T <sub>A</sub> = 25 °C	—	1.6	—	%	
Δ <sub>FIRCVAR</sub>	CC	C	Fast internal RC oscillator variation over temperature and supply with respect to f <sub>FIRC</sub> at T <sub>A</sub> = 25 °C in high-frequency configuration	—	-5	—	5	%	

1. V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C, unless otherwise specified.
2. This does not include consumption linked to clock tree toggling and peripherals consumption when RC oscillator is ON.

### 4.16 Slow internal RC oscillator (128 kHz) electrical characteristics

The device provides a 128 kHz low power internal RC oscillator. This can be used as the reference clock for the RTC module.

**Table 43. Slow internal RC oscillator (128 kHz) electrical characteristics**

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit	
				Min	Typ	Max		
f <sub>SIRC</sub>	CC	P	Slow internal RC oscillator low frequency	T <sub>A</sub> = 25 °C, trimmed	—	128	—	kHz
	SR	—	—	—	100	—	150	
I <sub>SIRC</sub> <sup>(2)</sup>	CC	C	Slow internal RC oscillator low frequency current	T <sub>A</sub> = 25 °C, trimmed	—	—	5	µA
t <sub>SIRCSU</sub>	CC	P	Slow internal RC oscillator start-up time	T <sub>A</sub> = 25 °C, V <sub>DD</sub> = 5.0 V ± 10%	—	8	12	µs

**Table 43. Slow internal RC oscillator (128 kHz) electrical characteristics (continued)**

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit	
				Min	Typ	Max		
$\Delta_{SIRC\text{PRE}}$	CC	C	Slow internal RC oscillator precision after software trimming of $f_{SIRC}$	$T_A = 25\text{ }^\circ\text{C}$	-2	—	2	%
$\Delta_{SIRC\text{TRIM}}$	CC	C	Slow internal RC oscillator trimming step	—	—	2.7	—	
$\Delta_{SIRC\text{VAR}}$	CC	C	Slow internal RC oscillator variation in temperature and supply with respect to $f_{SIRC}$ at $T_A = 55\text{ }^\circ\text{C}$ in high frequency configuration	High frequency configuration	-10	—	10	%

1.  $V_{DD} = 3.3\text{ V} \pm 10\% / 5.0\text{ V} \pm 10\%$ ,  $T_A = -40\text{ to }125\text{ }^\circ\text{C}$ , unless otherwise specified.

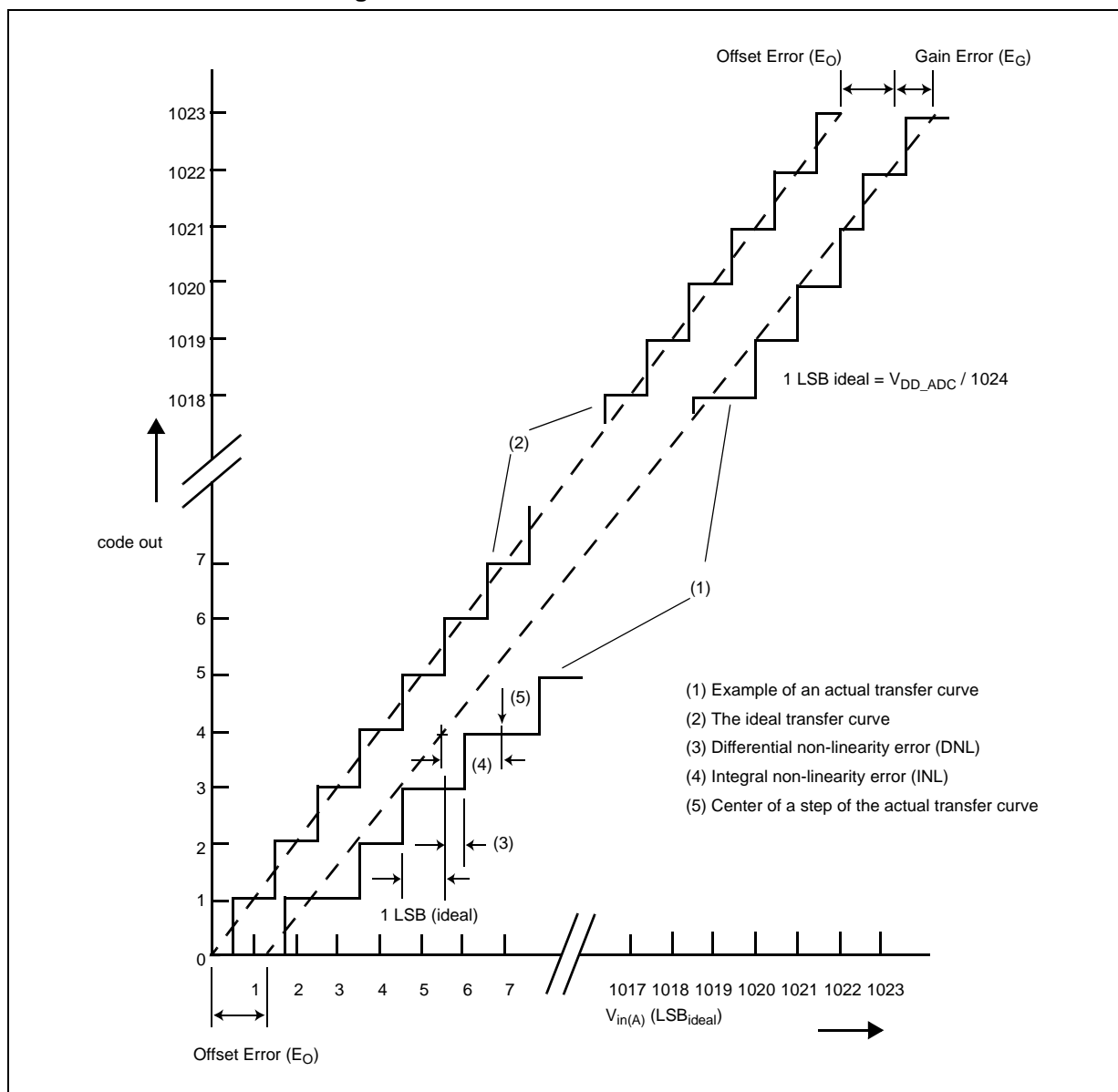
2. This does not include consumption linked to clock tree toggling and peripherals consumption when RC oscillator is ON.

## 4.17 ADC electrical characteristics

### 4.17.1 Introduction

The device provides two Successive Approximation Register (SAR) analog-to-digital converters (10-bit and 12-bit).

Figure 16. ADC\_0 characteristic and error definitions



### 4.17.2 Input impedance and ADC accuracy

In the following analysis, the input circuit corresponding to the precise channels is considered.

To preserve the accuracy of the A/D converter, it is necessary that analog input pins have low AC impedance. Placing a capacitor with good high frequency characteristics at the input pin of the device can be effective: the capacitor should be as large as possible, ideally infinite. This capacitor contributes to attenuating the noise present on the input pin; furthermore, it sources charge during the sampling phase, when the analog signal source is a high-impedance source.

A real filter can typically be obtained by using a series resistance with a capacitor on the input pin (simple RC filter). The RC filtering may be limited according to the value of source



impedance of the transducer or circuit supplying the analog signal to be measured. The filter at the input pins must be designed taking into account the dynamic characteristics of the input signal (bandwidth) and the equivalent input impedance of the ADC itself.

In fact a current sink contributor is represented by the charge sharing effects with the sampling capacitance: being  $C_S$  and  $C_{p2}$  substantially two switched capacitances, with a frequency equal to the conversion rate of the ADC, it can be seen as a resistive path to ground. For instance, assuming a conversion rate of 1 MHz, with  $C_S+C_{p2}$  equal to 3 pF, a resistance of 330 kΩ is obtained ( $R_{EQ} = 1 / (f_c \times (C_S+C_{p2}))$ ), where  $f_c$  represents the conversion rate at the considered channel). To minimize the error induced by the voltage partitioning between this resistance (sampled voltage on  $C_S+C_{p2}$ ) and the sum of  $R_S + R_F$ , the external circuit must be designed to respect the [Equation 4](#):

**Equation 4**

$$V_A \cdot \frac{R_S + R_F}{R_{EQ}} < \frac{1}{2} \text{LSB}$$

[Equation 4](#) generates a constraint for external network design, in particular on a resistive path.

**Figure 17. Input equivalent circuit (precise channels)**

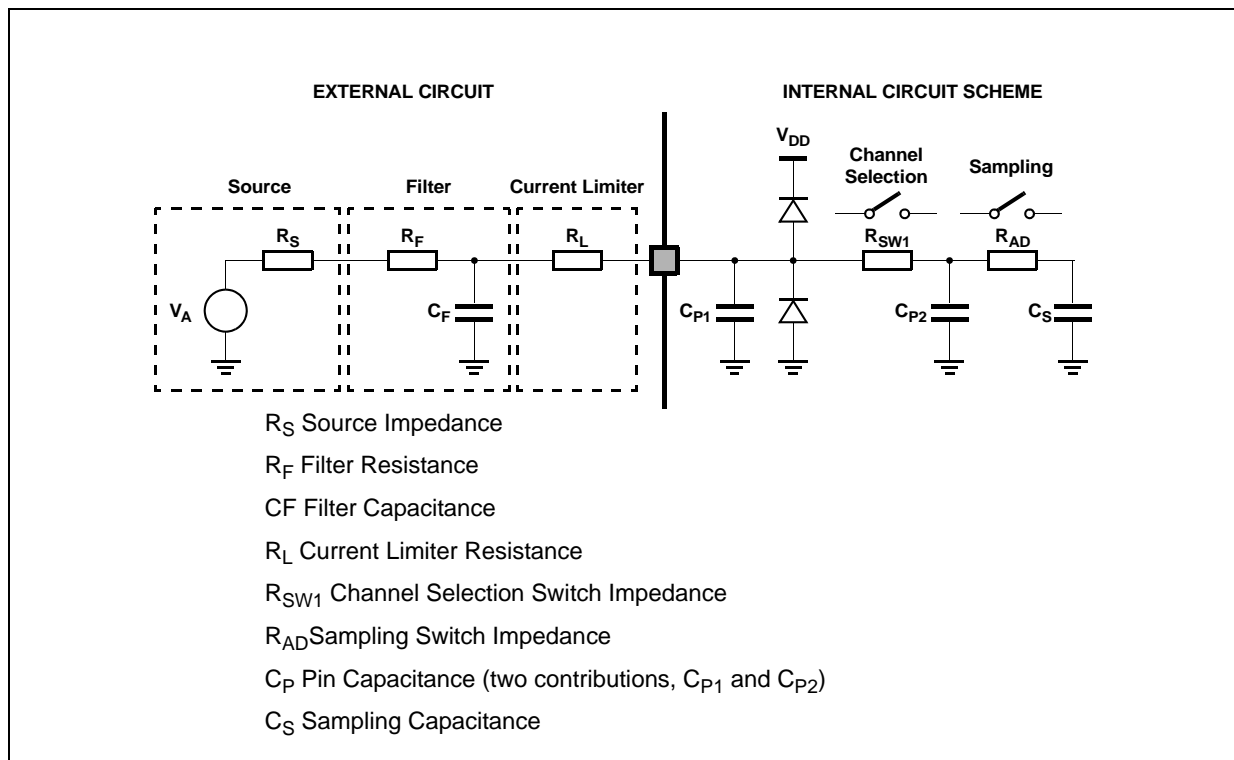
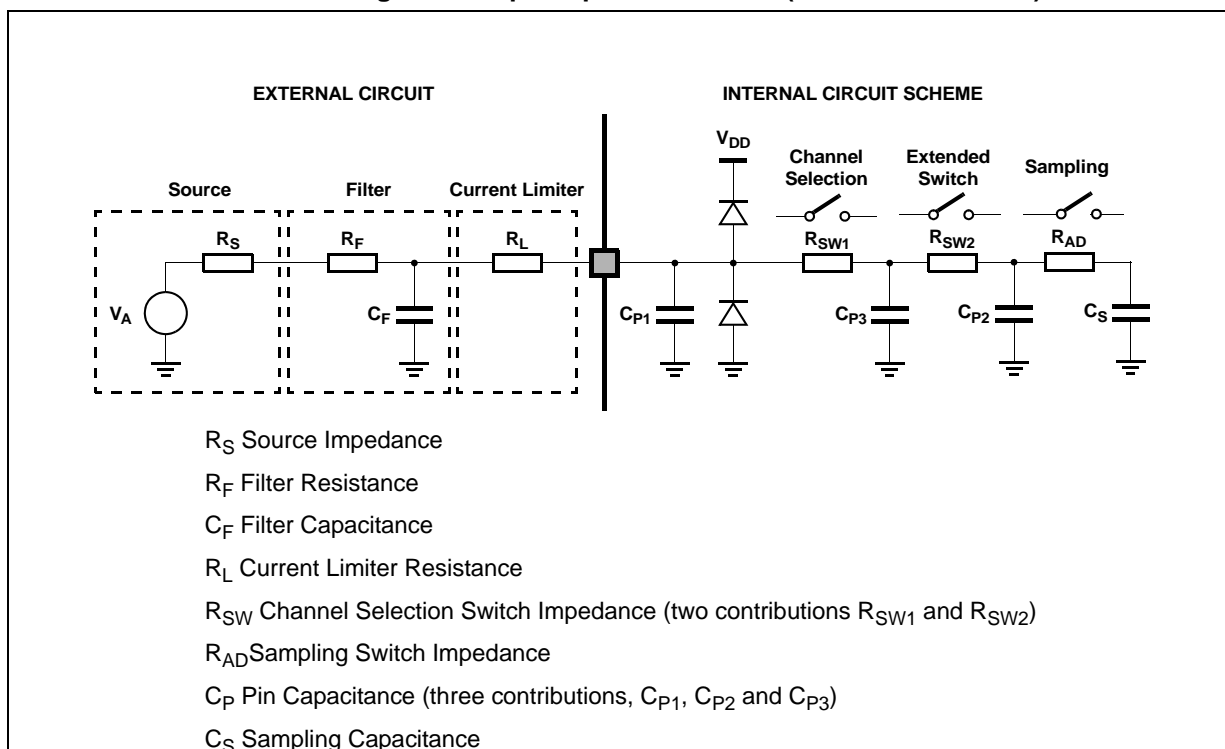
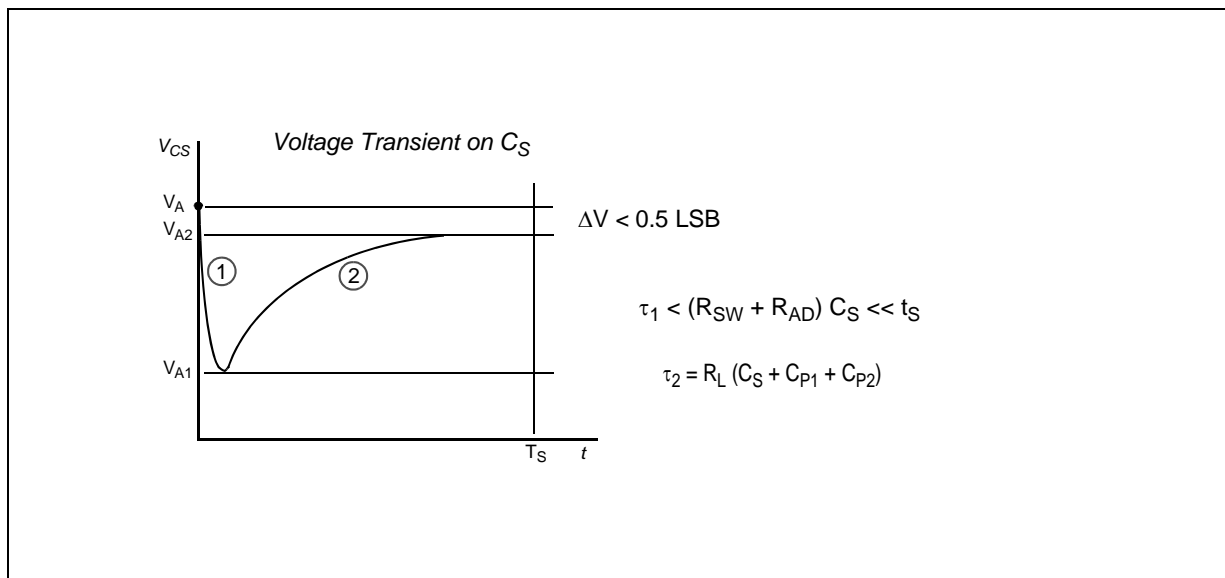


Figure 18. Input equivalent circuit (extended channels)



A second aspect involving the capacitance network shall be considered. Assuming the three capacitances  $C_F$ ,  $C_{P1}$  and  $C_{P2}$  are initially charged at the source voltage  $V_A$  (refer to the equivalent circuit reported in Figure 17): A charge sharing phenomenon is installed when the sampling phase is started (A/D switch close).

Figure 19. Transient behavior during sampling phase



In particular two different transient periods can be distinguished:

1. A first and quick charge transfer from the internal capacitance  $C_{P1}$  and  $C_{P2}$  to the sampling capacitance  $C_S$  occurs ( $C_S$  is supposed initially completely discharged): considering a worst case (since the time constant in reality would be faster) in which  $C_{P2}$  is reported in parallel to  $C_{P1}$  (call  $C_P = C_{P1} + C_{P2}$ ), the two capacitances  $C_P$  and  $C_S$  are in series, and the time constant is

**Equation 5**

$$\tau_1 = (R_{SW} + R_{AD}) \cdot \frac{C_P \cdot C_S}{C_P + C_S}$$

[Equation 5](#) can again be simplified considering only  $C_S$  as an additional worst condition. In reality, the transient is faster, but the A/D converter circuitry has been designed to be robust also in the very worst case: the sampling time  $t_s$  is always much longer than the internal time constant:

**Equation 6**

$$\tau_1 < (R_{SW} + R_{AD}) \cdot C_S \ll t_s$$

The charge of  $C_{P1}$  and  $C_{P2}$  is redistributed also on  $C_S$ , determining a new value of the voltage  $V_{A1}$  on the capacitance according to [Equation 7](#):

**Equation 7**

$$V_{A1} \cdot (C_S + C_{P1} + C_{P2}) = V_A \cdot (C_{P1} + C_{P2})$$

2. A second charge transfer involves also  $C_F$  (that is typically bigger than the on-chip capacitance) through the resistance  $R_L$ : again considering the worst case in which  $C_{P2}$  and  $C_S$  were in parallel to  $C_{P1}$  (since the time constant in reality would be faster), the time constant is:

**Equation 8**

$$\tau_2 < R_L \cdot (C_S + C_{P1} + C_{P2})$$

In this case, the time constant depends on the external circuit: in particular imposing that the transient is completed well before the end of sampling time  $t_s$ , a constraints on  $R_L$  sizing is obtained:

**Equation 9 ADC\_0 (10-bit)**

$$8.5 \cdot \tau_2 = 8.5 \cdot R_L \cdot (C_S + C_{P1} + C_{P2}) < t_s$$

**Equation 10 ADC\_1 (12-bit)**

$$10 \cdot \tau_2 = 10 \cdot R_L \cdot (C_S + C_{P1} + C_{P2}) < t_s$$

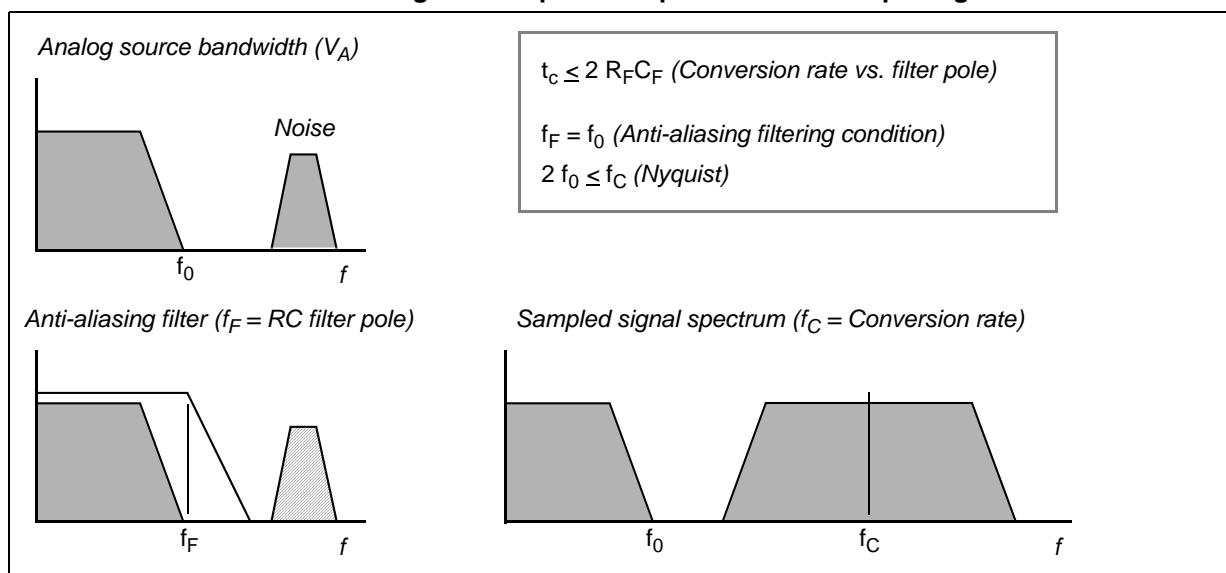
Of course,  $R_L$  shall be sized also according to the current limitation constraints, in combination with  $R_S$  (source impedance) and  $R_F$  (filter resistance). Being  $C_F$  definitively bigger than  $C_{P1}$ ,  $C_{P2}$  and  $C_S$ , then the final voltage  $V_{A2}$  (at the end of the charge transfer transient) will be much higher than  $V_{A1}$ . [Equation 11](#) must be respected (charge balance assuming now  $C_S$  already charged at  $V_{A1}$ ):

**Equation 11**

$$V_{A2} \cdot (C_S + C_{P1} + C_{P2} + C_F) = V_A \cdot C_F + V_{A1} \cdot (C_{P1} + C_{P2} + C_S)$$

The two transients above are not influenced by the voltage source that, due to the presence of the  $R_F C_F$  filter, is not able to provide the extra charge to compensate the voltage drop on  $C_S$  with respect to the ideal source  $V_A$ ; the time constant  $R_F C_F$  of the filter is very high with respect to the sampling time ( $t_s$ ). The filter is typically designed to act as antialiasing.

**Figure 20. Spectral representation of input signal**



Calling  $f_0$  the bandwidth of the source signal (and as a consequence the cut-off frequency of the antialiasing filter,  $f_F$ ), according to the Nyquist theorem the conversion rate  $f_C$  must be at least  $2f_0$ ; it means that the constant time of the filter is greater than or at least equal to twice the conversion period ( $t_c$ ). Again the conversion period  $t_c$  is longer than the sampling time  $t_s$ , which is just a portion of it, even when fixed channel continuous conversion mode is selected (fastest conversion rate at a specific channel): in conclusion it is evident that the time constant of the filter  $R_F C_F$  is definitively much higher than the sampling time  $t_s$ , so the charge level on  $C_S$  cannot be modified by the analog signal source during the time in which the sampling switch is closed.

The considerations above lead to impose new constraints on the external circuit, to reduce the accuracy error due to the voltage drop on  $C_S$ ; from the two charge balance equations above, it is simple to derive [Equation 12](#) between the ideal and real sampled voltage on  $C_S$ :

**Equation 12**

$$\frac{V_{A2}}{V_A} = \frac{C_{P1} + C_{P2} + C_F}{C_{P1} + C_{P2} + C_F + C_S}$$

From this formula, in the worst case (when  $V_A$  is maximum, that is for instance 5 V), assuming to accept a maximum error of half a count, a constraint is evident on  $C_F$  value:

**Equation 13 ADC\_0 (10-bit)**

$$C_F > 2048 \cdot C_S$$

Equation 14 ADC\_1 (12-bit)

$$C_F > 8192 \cdot C_S$$

4.17.3 ADC electrical characteristics

Table 44. ADC input leakage current

Symbol	C	Parameter	Conditions	Value			Unit
				Min	Typ	Max	
I <sub>LKG</sub>	CC	Input leakage current	T <sub>A</sub> = -40 °C	—	1	70	nA
			T <sub>A</sub> = 25 °C	—	1	70	
			T <sub>A</sub> = 85 °C		3	100	
			T <sub>A</sub> = 105 °C	—	8	200	
			T <sub>A</sub> = 125 °C	—	45	400	

Table 45. ADC\_0 conversion characteristics (10-bit ADC\_0)

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit	
				Min	Typ	Max		
V <sub>SS_ADC0</sub>	SR	—	Voltage on VSS_HV_ADC0 (ADC_0 reference) pin with respect to ground (V <sub>SS</sub> ) <sup>(2)</sup>	—			V	
V <sub>DD_ADC0</sub>	SR	—	Voltage on VDD_HV_ADC pin (ADC reference) with respect to ground (V <sub>SS</sub> )	—			V	
V <sub>AINx</sub>	SR	—	Analog input voltage <sup>(3)</sup>	V <sub>SS_ADC0</sub> - 0.1	—	V <sub>DD_ADC0</sub> + 0.1	V	
I <sub>ADC0pwr</sub>	SR	—	ADC_0 consumption in power down mode	—	—	50	µA	
I <sub>ADC0run</sub>	SR	—	ADC_0 consumption in running mode	—	—	5	mA	
f <sub>ADC0</sub>	SR	—	ADC_0 analog frequency	6	—	32 + 4%	MHz	
Δ <sub>ADC0_SYS</sub>	SR	—	ADC_0 digital clock duty cycle (ipg_clk)	ADCLKSEL = 1 <sup>(4)</sup>	45	—	55	%
t <sub>ADC0_PU</sub>	SR	—	ADC_0 power up delay	—	—	1.5	µs	
t <sub>ADC0_S</sub>	CC	T	Sampling time <sup>(5)</sup>	f <sub>ADC</sub> = 32 MHz, INPSAMP = 17	0.5	—	µs	
				f <sub>ADC</sub> = 6 MHz, INPSAMP = 255	—	—		42
t <sub>ADC0_C</sub>	CC	P	Conversion time <sup>(6)</sup>	f <sub>ADC</sub> = 32 MHz, INPCMP = 2	0.625	—	µs	
C <sub>S</sub>	CC	D	ADC_0 input sampling capacitance	—	—	3	pF	



Table 45. ADC\_0 conversion characteristics (10-bit ADC\_0) (continued)

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit		
				Min	Typ	Max			
C <sub>P1</sub>	CC	D	ADC_0 input pin capacitance 1	—	—	3	pF		
C <sub>P2</sub>	CC	D	ADC_0 input pin capacitance 2	—	—	1	pF		
C <sub>P3</sub>	CC	D	ADC_0 input pin capacitance 3	—	—	1	pF		
R <sub>SW1</sub>	CC	D	Internal resistance of analog source	—	—	3	kΩ		
R <sub>SW2</sub>	CC	D	Internal resistance of analog source	—	—	2	kΩ		
R <sub>AD</sub>	CC	D	Internal resistance of analog source	—	—	2	kΩ		
I <sub>INJ</sub>	SR	—	Input current Injection	Current injection on one ADC_0 input, different from the converted one	V <sub>DD</sub> = 3.3 V ± 10%	-5	—	5	mA
				V <sub>DD</sub> = 5.0 V ± 10%	-5	—	5		
INL	CC	T	Absolute integral nonlinearity	No overload	—	0.5	1.5	LSB	
DNL	CC	T	Absolute differential nonlinearity	No overload	—	0.5	1.0	LSB	
E <sub>O</sub>	CC	T	Absolute offset error	—	—	0.5	—	LSB	
E <sub>G</sub>	CC	T	Absolute gain error	—	—	0.6	—	LSB	
TUEP	CC	P	Total unadjusted error <sup>(7)</sup> for precise channels, input only pins	Without current injection	-2	0.6	2	LSB	
		T		With current injection	-3	—	3		
TUEx	CC	T	Total unadjusted error <sup>(7)</sup> for extended channel	Without current injection	-3	1	3	LSB	
		T		With current injection	-4	—	4		

- V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C, unless otherwise specified.
- Analog and digital V<sub>SS</sub> **must** be common (to be tied together externally).
- V<sub>AINx</sub> may exceed V<sub>SS\_ADC0</sub> and V<sub>DD\_ADC0</sub> limits, remaining on absolute maximum ratings, but the results of the conversion will be clamped respectively to 0x000 or 0x3FF.
- Duty cycle is ensured by using system clock without prescaling. When ADCLKSEL = 0, the duty cycle is ensured by internal divider by 2.
- During the sampling time the input capacitance C<sub>S</sub> can be charged/discharged by the external source. The internal resistance of the analog source must allow the capacitance to reach its final voltage level within t<sub>ADC0\_S</sub>. After the end of the sampling time t<sub>ADC0\_S</sub>, changes of the analog input voltage have no effect on the conversion result. Values for the sampling clock t<sub>ADC0\_S</sub> depend on programming.
- This parameter does not include the sampling time t<sub>ADC0\_S</sub>, but only the time for determining the digital result and the time to load the result's register with the conversion result.
- Total Unadjusted Error: The maximum error that occurs without adjusting Offset and Gain errors. This error is a combination of Offset, Gain and Integral Linearity errors.

Figure 21. ADC\_1 characteristic and error definitions

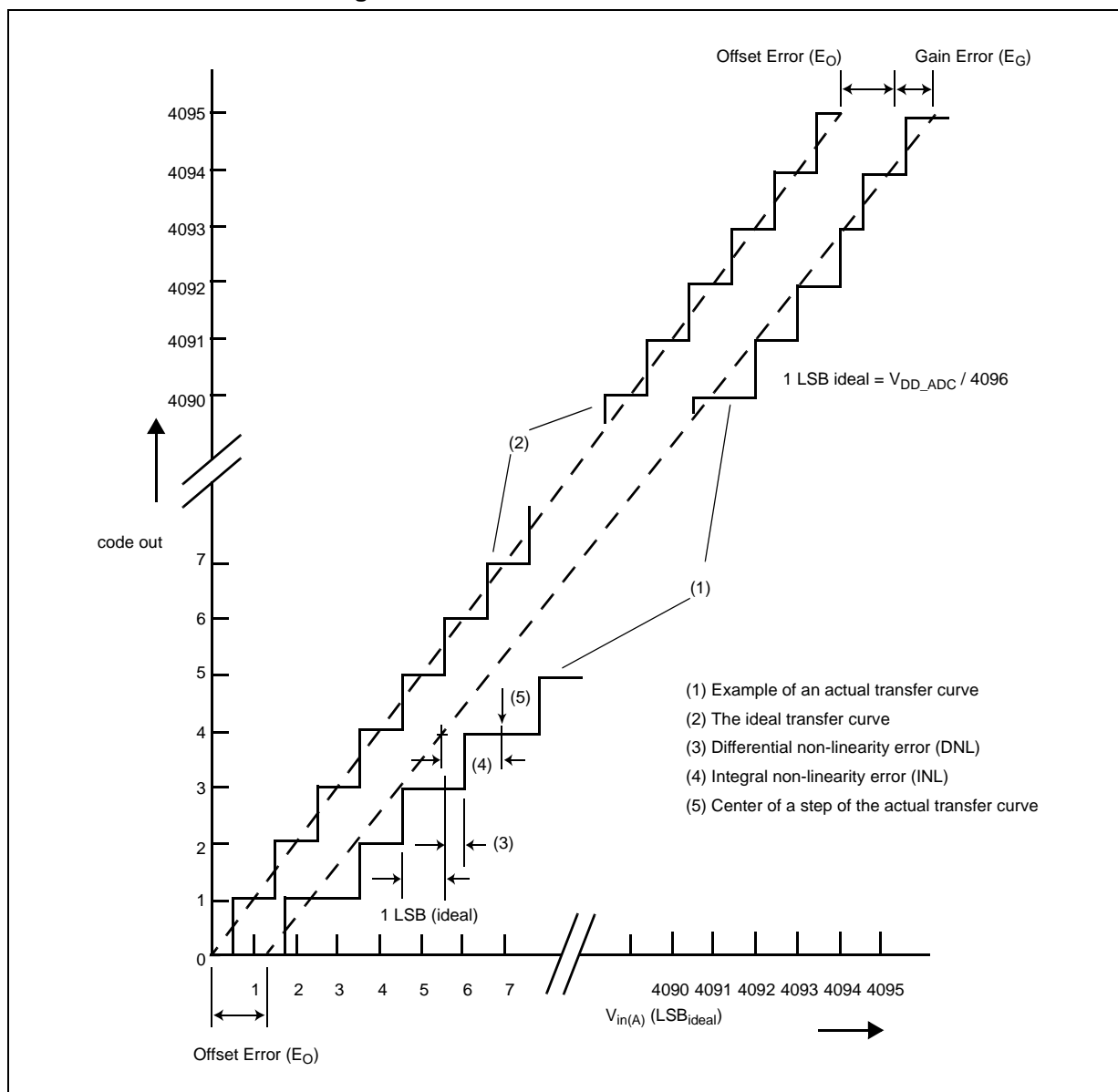


Table 46. ADC\_1 conversion characteristics (12-bit ADC\_1)

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit
				Min	Typ	Max	
V <sub>SS_ADC1</sub>	SR	Voltage on VSS_HV_ADC1 (ADC_1 reference) pin with respect to ground (V <sub>SS</sub> ) <sup>(2)</sup>	—	-0.1	—	0.1	V
V <sub>DD_ADC1</sub>	SR	Voltage on VDD_HV_ADC1 pin (ADC_1 reference) with respect to ground (V <sub>SS</sub> )	—	V <sub>DD</sub> - 0.1	—	V <sub>DD</sub> + 0.1	V
V <sub>AINx</sub>	SR	Analog input voltage <sup>(3)</sup>	—	V <sub>SS_ADC1</sub> - 0.1	—	V <sub>DD_ADC1</sub> + 0.1	V

Table 46. ADC\_1 conversion characteristics (12-bit ADC\_1) (continued)

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit	
				Min	Typ	Max		
$I_{ADC1pwd}$	SR	—	ADC_1 consumption in power down mode	—	—	50	$\mu$ A	
$I_{ADC1run}$	SR	—	ADC_1 consumption in running mode	—	—	6	mA	
$f_{ADC1}$	SR	—	ADC_1 analog frequency	$V_{DD} = 3.3$ V	3.33	—	20 + 4%	MHz
				$V_{DD} = 5$ V	3.33	—	32 + 4%	
$t_{ADC1\_PU}$	SR	—	ADC_1 power up delay	—	—	1.5	$\mu$ s	
$t_{ADC1\_S}$	CC	T	Sampling time <sup>(4)</sup>	$f_{ADC1} = 20$ MHz, $V_{DD} = 3.3$ V INPSAMP = 12	600	—	—	ns
			Sampling time <sup>(4)</sup>	$f_{ADC1} = 32$ MHz, $V_{DD} = 5.0$ V INPSAMP = 17	500	—	—	
			Sampling time <sup>(4)</sup>	$f_{ADC1} = 3.33$ MHz, $V_{DD} = 3.3$ V INPSAMP = 255	—	—	76.2	$\mu$ s
			Sampling time <sup>(4)</sup>	$f_{ADC1} = 3.33$ MHz, $V_{DD} = 5.0$ V INPSAMP = 255	—	—	76.2	
$t_{ADC1\_C}$	CC	P	Conversion time <sup>(5)</sup>	$f_{ADC1} = 20$ MHz, $V_{DD} = 3.3$ V INPCMP = 0	2.4	—	—	$\mu$ s
			Conversion time <sup>(5)</sup>	$f_{ADC1} = 32$ MHz, $V_{DD} = 5.0$ V INPCMP = 0	1.5	—	—	$\mu$ s
			Conversion time <sup>(5)</sup>	$f_{ADC1} = 13.33$ MHz, $V_{DD} = 3.3$ V INPCMP = 0	—	—	3.6	$\mu$ s
			Conversion time <sup>(5)</sup>	$f_{ADC1} = 13.33$ MHz, $V_{DD} = 5.0$ V INPCMP = 0	—	—	3.6	$\mu$ s
$\Delta_{ADC1\_SYS}$	SR	—	ADC_1 digital clock duty cycle	ADCLKSEL = 1 <sup>(6)</sup>	45	—	55	%
$C_S$	CC	D	ADC_1 input sampling capacitance	—	—	5	pF	
$C_{P1}$	CC	D	ADC_1 input pin capacitance 1	—	—	3	pF	
$C_{P2}$	CC	D	ADC_1 input pin capacitance 2	—	—	1	pF	
$C_{P3}$	CC	D	ADC_1 input pin capacitance 3	—	—	1.5	pF	
$R_{SW1}$	CC	D	Internal resistance of analog source	—	—	1	k $\Omega$	
$R_{SW2}$	CC	D	Internal resistance of analog source	—	—	2	k $\Omega$	
$R_{AD}$	CC	D	Internal resistance of analog source	—	—	0.3	k $\Omega$	



Table 46. ADC\_1 conversion characteristics (12-bit ADC\_1) (continued)

Symbol	C	Parameter	Conditions <sup>(1)</sup>	Value			Unit		
				Min	Typ	Max			
I <sub>INJ</sub>	SR	—	Input current Injection	Current injection on one ADC_1 input, different from the converted one	V <sub>DD</sub> = 3.3 V ± 10%	-5	—	5	mA
				V <sub>DD</sub> = 5.0 V ± 10%	-5	—	5		
INLP	CC	T	Absolute integral nonlinearity – Precise channels	No overload	—	1	3	LSB	
INLX	CC	T	Absolute integral nonlinearity – Extended channels	No overload	—	1.5	5	LSB	
DNL	CC	T	Absolute differential nonlinearity	No overload	—	0.5	1	LSB	
E <sub>O</sub>	CC	T	Absolute offset error	—	—	2	—	LSB	
E <sub>G</sub>	CC	T	Absolute gain error	—	—	2	—	LSB	
TUEP <sup>(7)</sup>	CC	P	Total unadjusted error for precise channels, input only pins	Without current injection	-6	—	6	LSB	
		T		With current injection	-8	—	8		
TUEX <sup>(7)</sup>	CC	T	Total unadjusted error for extended channel	Without current injection	-10	—	10	LSB	
		T		With current injection	-12	—	12		

- V<sub>DD</sub> = 3.3 V ± 10% / 5.0 V ± 10%, T<sub>A</sub> = -40 to 125 °C, unless otherwise specified
- Analog and digital V<sub>SS</sub> **must** be common (to be tied together externally).
- V<sub>AINx</sub> may exceed V<sub>SS\_ADC1</sub> and V<sub>DD\_ADC1</sub> limits, remaining on absolute maximum ratings, but the results of the conversion will be clamped respectively to 0x000 or 0xFF.
- During the sampling time the input capacitance C<sub>S</sub> can be charged/discharged by the external source. The internal resistance of the analog source must allow the capacitance to reach its final voltage level within t<sub>ADC1\_S</sub>. After the end of the sampling time t<sub>ADC1\_S</sub>, changes of the analog input voltage have no effect on the conversion result. Values for the sampling clock t<sub>ADC1\_S</sub> depend on programming.
- This parameter does not include the sampling time t<sub>ADC1\_S</sub>, but only the time for determining the digital result and the time to load the result's register with the conversion result.
- Duty cycle is ensured by using system clock without prescaling. When ADCLKSEL = 0, the duty cycle is ensured by internal divider by 2.
- Total Unadjusted Error: The maximum error that occurs without adjusting Offset and Gain errors. This error is a combination of Offset, Gain and Integral Linearity errors.

## 4.18 On-chip peripherals

### 4.18.1 Current consumption

Table 47. On-chip peripherals current consumption<sup>(1)</sup>

Symbol	C	Parameter	Conditions		Typical value <sup>(2)</sup>	Unit
$I_{DD\_BV(CAN)}$	CC	CAN (FlexCAN) supply current on $V_{DD\_BV}$	Bitrate: 500 Kbyte/s	Total (static + dynamic) consumption: – FlexCAN in loop-back mode – XTAL at 8 MHz used as CAN engine clock source – Message sending period is 580 $\mu$ s	$8 * f_{periph} + 85$	$\mu$ A
			Bitrate: 125 Kbyte/s		$8 * f_{periph} + 27$	
$I_{DD\_BV(eMIOS)}$	CC	eMIOS supply current on $V_{DD\_BV}$	Static consumption: – eMIOS channel OFF – Global prescaler enabled		$29 * f_{periph}$	$\mu$ A
			Dynamic consumption: – It does not change varying the frequency (0.003 mA)		3	
$I_{DD\_BV(SCI)}$	CC	SCI (LINFlex) supply current on $V_{DD\_BV}$	Total (static + dynamic) consumption: – LIN mode – Baudrate: 20 Kbyte/s		$5 * f_{periph} + 31$	$\mu$ A
$I_{DD\_BV(SPI)}$	CC	SPI (DSPI) supply current on $V_{DD\_BV}$	Ballast static consumption (only clocked)		1	$\mu$ A
			Ballast dynamic consumption (continuous communication): – Baudrate: 2 Mbit/s – Transmission every 8 $\mu$ s – Frame: 16 bits		$16 * f_{periph}$	
$I_{DD\_BV(ADC\_0/ADC\_1)}$	CC	ADC_0/ADC_1 supply current on $V_{DD\_BV}$	$V_{DD} = 5.5$ V	Ballast static consumption (no conversion) <sup>(3)</sup>	$41 * f_{periph}$	$\mu$ A
				Ballast dynamic consumption (continuous conversion) <sup>(3)</sup>	$46 * f_{periph}$	
$I_{DD\_HV\_ADC0}$	CC	ADC_0 supply current on $V_{DD\_HV\_ADC0}$	$V_{DD} = 5.5$ V	Analog static consumption (no conversion)	200	$\mu$ A
				Analog dynamic consumption (continuous conversion)	3	mA
$I_{DD\_HV\_ADC1}$	CC	ADC_1 supply current on $V_{DD\_HV\_ADC1}$	$V_{DD} = 5.5$ V	Analog static consumption (no conversion)	$300 * f_{periph}$	$\mu$ A
				Analog dynamic consumption (continuous conversion)	4	mA

Table 47. On-chip peripherals current consumption<sup>(1)</sup> (continued)

Symbol	C	Parameter	Conditions		Typical value <sup>(2)</sup>	Unit
$I_{DD\_HV(FLASH)}$	CC	CFlash + DFlash supply current on $V_{DD\_HV}$	$V_{DD} = 5.5\text{ V}$	—	12	mA
$I_{DD\_HV(PLL)}$	CC	PLL supply current on $V_{DD\_HV}$	$V_{DD} = 5.5\text{ V}$	—	$30 * f_{periph}$	$\mu\text{A}$

1. Operating conditions:  $T_A = 25\text{ °C}$ ,  $f_{periph} = 8\text{ MHz to }64\text{ MHz}$ .
2.  $f_{periph}$  is an absolute value.
3. During the conversion, the total current consumption is given from the sum of the static and dynamic consumption, i.e.,  $(41 + 46) * f_{periph}$ .



## 4.18.2 DSPI characteristics

Table 48. DSPI characteristics<sup>(1)</sup>

No.	Symbol	C	Parameter		DSPI0/DSPI1/DSPI3/DSPI5			Min	
					Min	Typ	Max		
1	$t_{SCK}$	SR	D	SCK cycle time	Master mode (MTFE = 0)	125	—	—	33
			D		Slave mode (MTFE = 0)	125	—	—	33
			D		Master mode (MTFE = 1)	83	—	—	12
			D		Slave mode (MTFE = 1)	83	—	—	12
—	$f_{DSPI}$	SR	D	DSPI digital controller frequency	—	—	$f_{CPU}$	—	
—	$\Delta t_{CSC}$	CC	D	Internal delay between pad associated to SCK and pad associated to CSn in master mode for CSn1->0	Master mode	—	—	130 <sup>(2)</sup>	—
—	$\Delta t_{ASC}$	CC	D	Internal delay between pad associated to SCK and pad associated to CSn in master mode for CSn1->1	Master mode	—	—	130 <sup>(3)</sup>	—
2	$t_{CSCext}^{(4)}$	SR	D	CS to SCK delay	Slave mode	32	—	—	32
3	$t_{ASCext}^{(5)}$	SR	D	After SCK delay	Slave mode	$1/f_{DSPI} + 5$	—	—	$1/f_{DSPI}$
4	$t_{SDC}$	CC	D	SCK duty cycle	Master mode	—	$t_{SCK}/2$	—	—
		SR	D		Slave mode	$t_{SCK}/2$	—	—	$t_{SCK}$
5	$t_A$	SR	D	Slave access time	Slave mode	—	—	$1/f_{DSPI} + 70$	—
6	$t_{DI}$	SR	D	Slave SOUT disable time	Slave mode	7	—	—	7
7	$t_{PCSC}$	SR	D	PCSx to $\overline{PCSS}$ time	—	0	—	—	0
8	$t_{PASC}$	SR	D	$\overline{PCSS}$ to PCSx time	—	0	—	—	0

Table 48. DSPI characteristics<sup>(1)</sup> (continued)

No.	Symbol	C	Parameter	DSPI0/DSPI1/DSPI3/DSPI5			Min		
				Min	Typ	Max			
9	t <sub>SUI</sub>	SR	D	Data setup time for inputs	Master mode	43	—	—	14
					Slave mode	5	—	—	5
10	t <sub>HI</sub>	SR	D	Data hold time for inputs	Master mode	0	—	—	0
					Slave mode	2 <sup>(6)</sup>	—	—	2 <sup>(6)</sup>
11	t <sub>SUO</sub> <sup>(7)</sup>	CC	D	Data valid after SCK edge	Master mode	—	—	32	—
					Slave mode	—	—	52	—
12	t <sub>HO</sub> <sup>(7)</sup>	CC	D	Data hold time for outputs	Master mode	0	—	—	0
					Slave mode	8	—	—	13

- Operating conditions: C<sub>L</sub> = 10 to 50 pF, Slew<sub>IN</sub> = 3.5 to 15 ns.
- Maximum value is reached when CSn pad is configured as SLOW pad while SCK pad is configured as MEDIUM. A positive value means that the delay is measured with respect to the external SCK. DSPI2 has only SLOW SCK available.
- Maximum value is reached when CSn pad is configured as MEDIUM pad while SCK pad is configured as SLOW. A positive value means that the delay is measured with respect to the external SCK. DSPI0 and DSPI1 have only MEDIUM SCK available.
- The t<sub>CSC</sub> delay value is configurable through a register. When configuring t<sub>CSC</sub> (using PCSSCK and CSSCK fields in DSPI\_CTARx registers), the external SCK and internal SCK must be higher than Δt<sub>CSC</sub> to ensure positive t<sub>CSCext</sub>.
- The t<sub>ASC</sub> delay value is configurable through a register. When configuring t<sub>ASC</sub> (using PASC and ASC fields in DSPI\_CTARx registers), the external SCK and internal SCK must be higher than Δt<sub>ASC</sub> to ensure positive t<sub>ASCext</sub>.
- This delay value corresponds to SMPL\_PT = 00b which is bit field 9 and 8 of DSPI\_MCR register.
- SCK and SOUT are configured as MEDIUM pad.



Figure 22. DSPI classic SPI timing — master, CPHA = 0

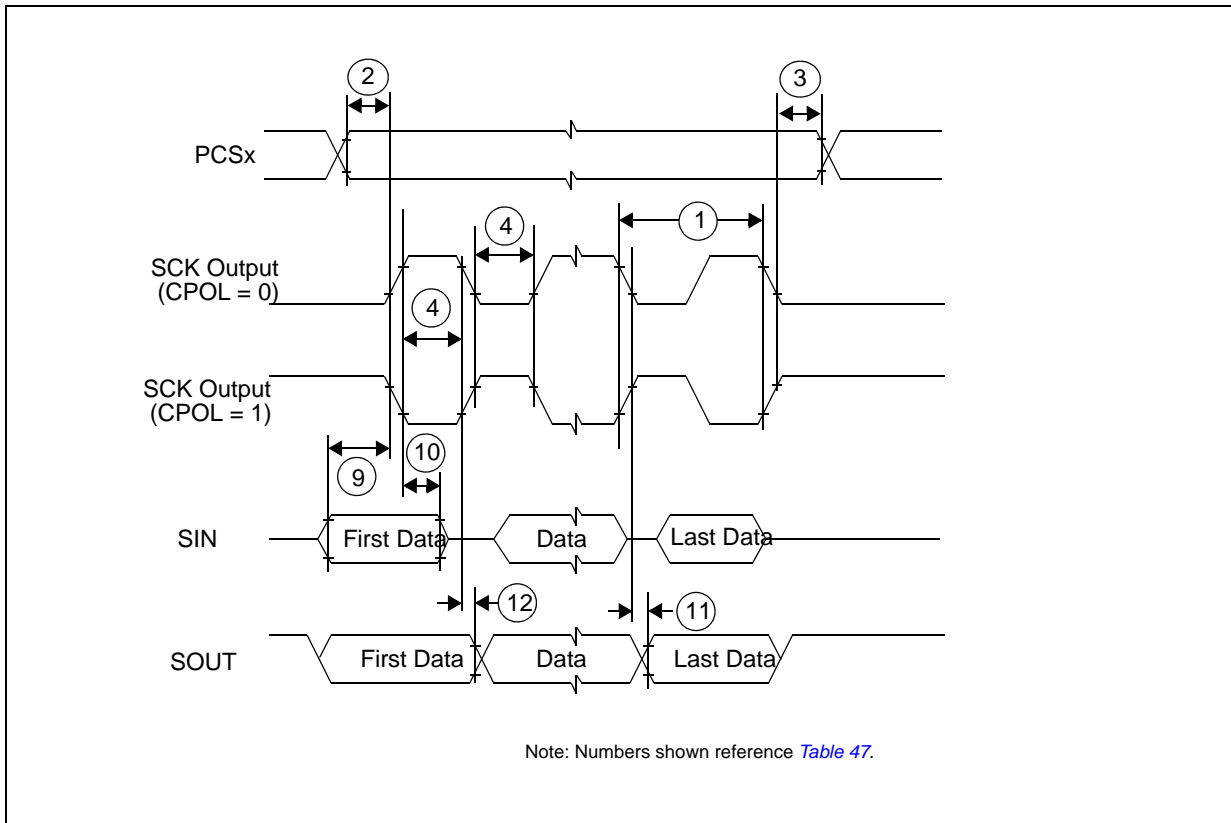


Figure 23. DSPI classic SPI timing — master, CPHA = 1

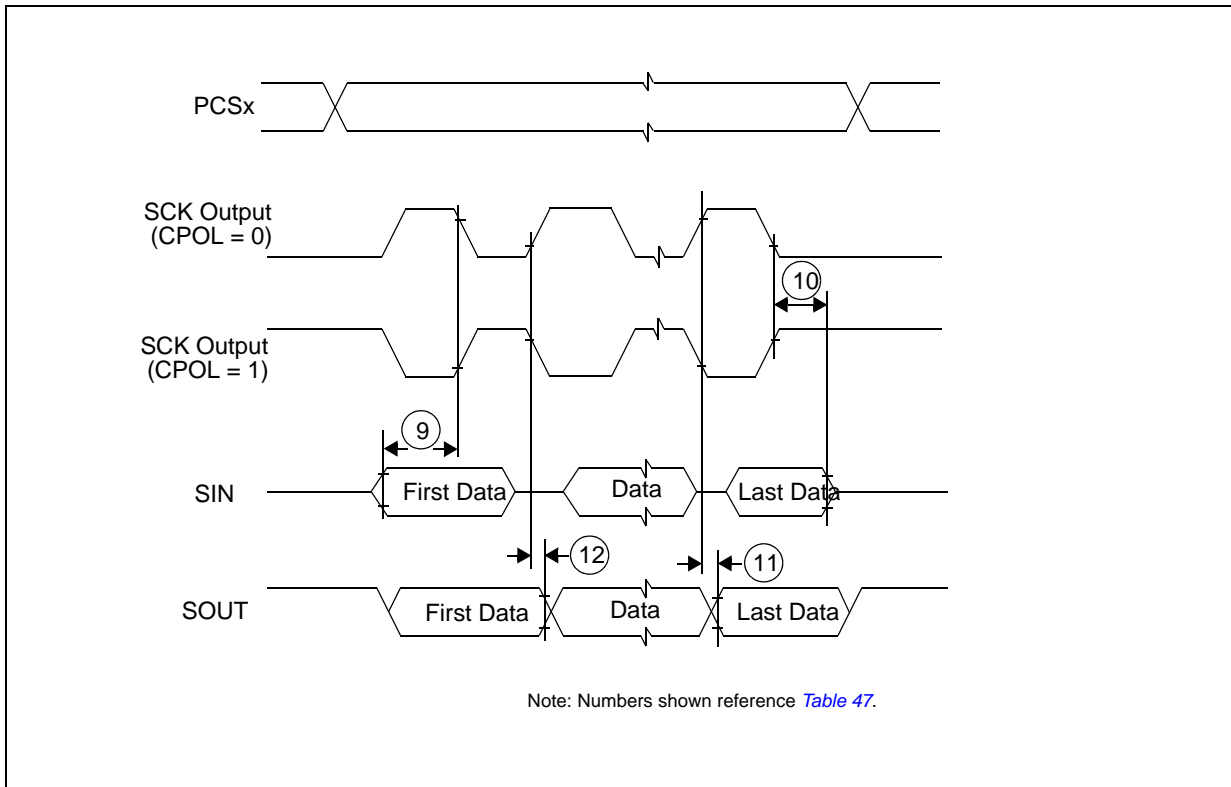


Figure 24. DSPI classic SPI timing — slave, CPHA = 0

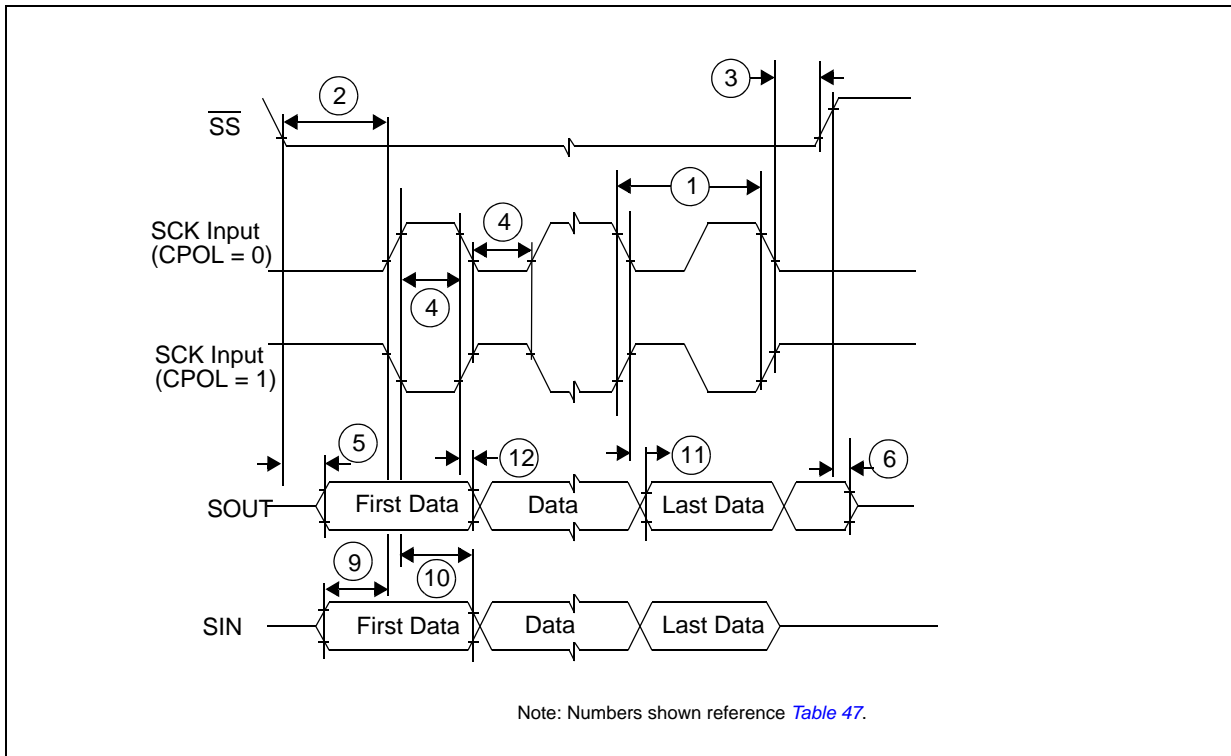


Figure 25. DSPI classic SPI timing — slave, CPHA = 1

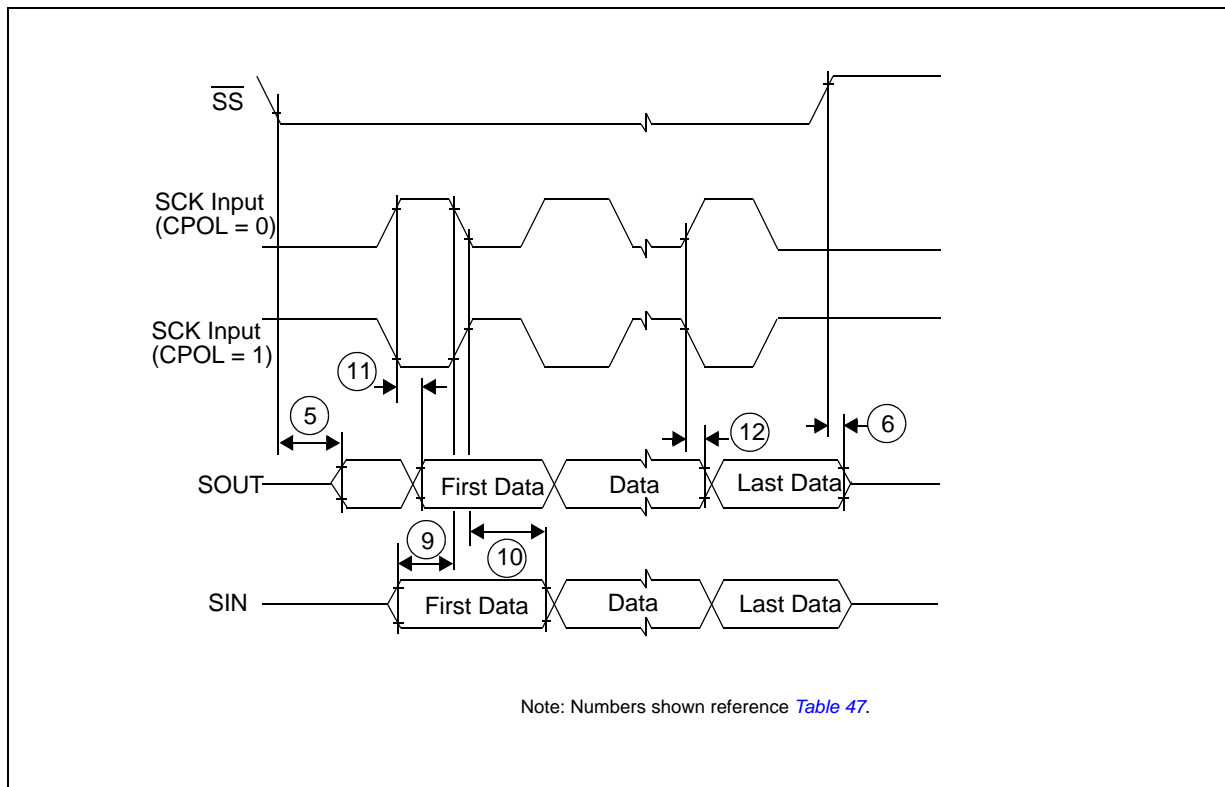


Figure 26. DSPI modified transfer format timing — master, CPHA = 0

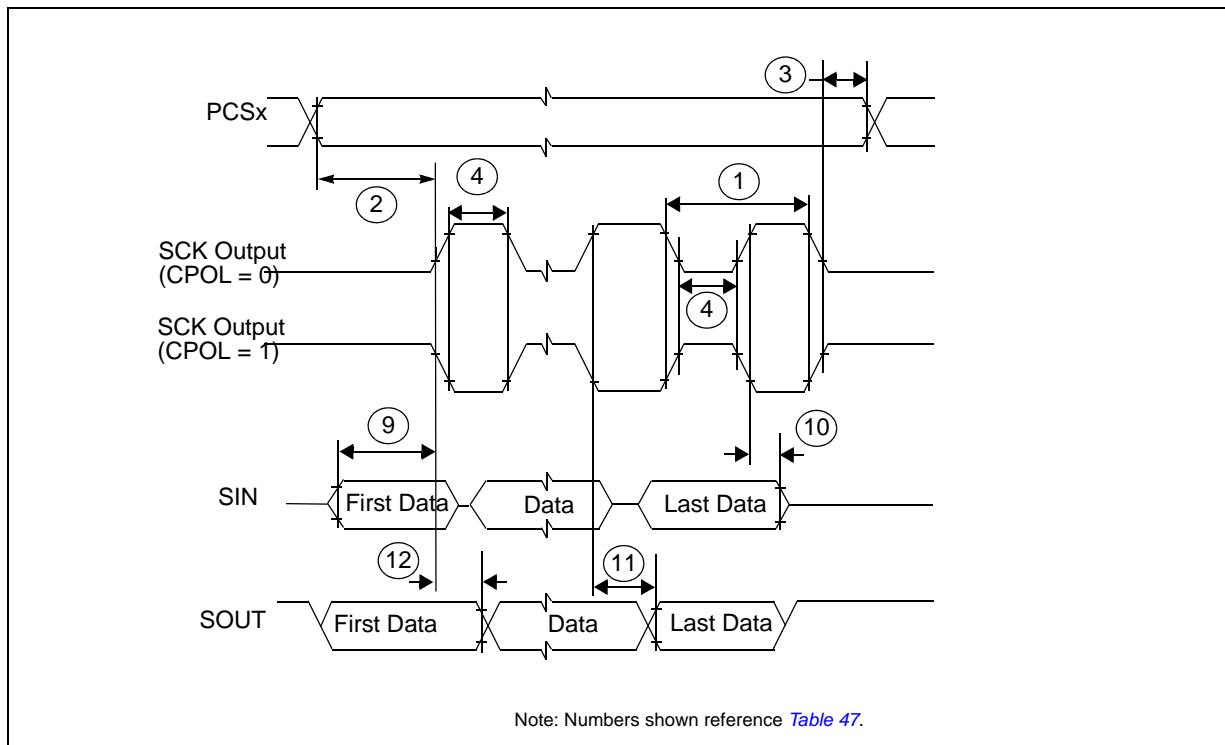




Figure 27. DSPI modified transfer format timing — master, CPHA = 1

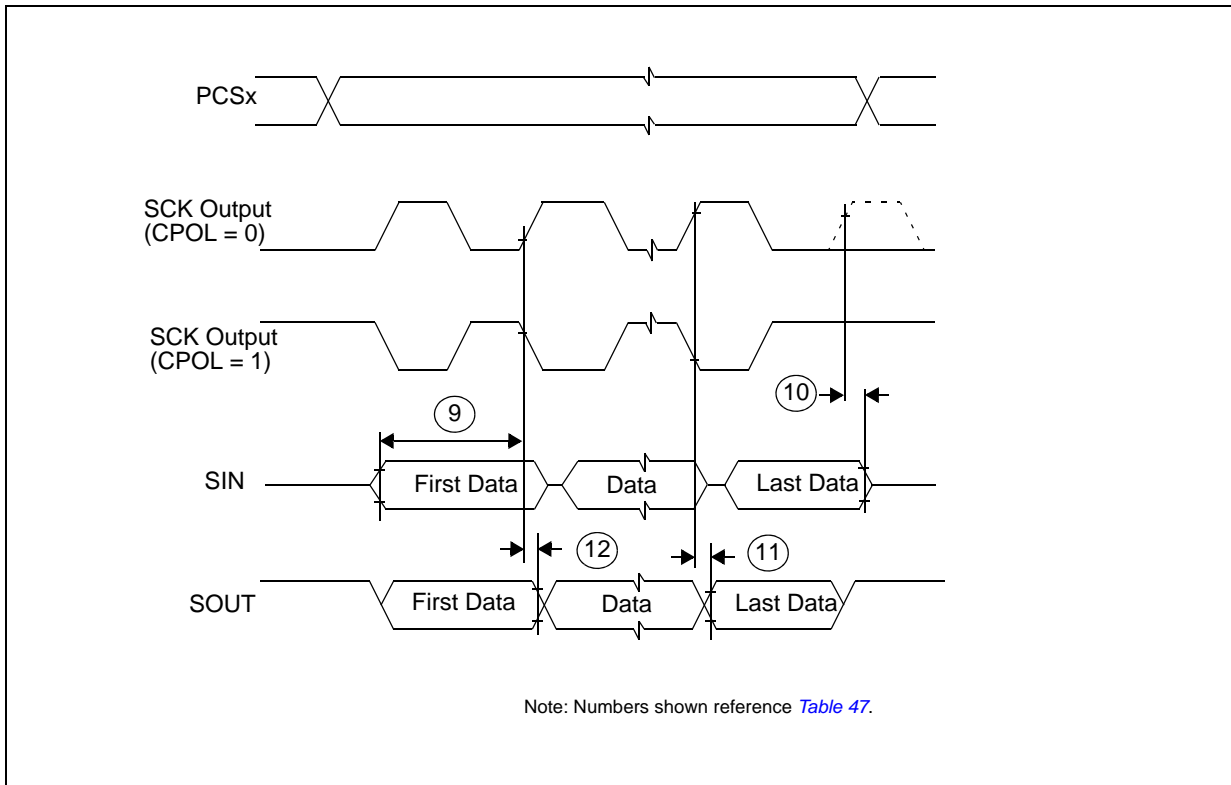


Figure 28. DSPI modified transfer format timing — slave, CPHA = 0

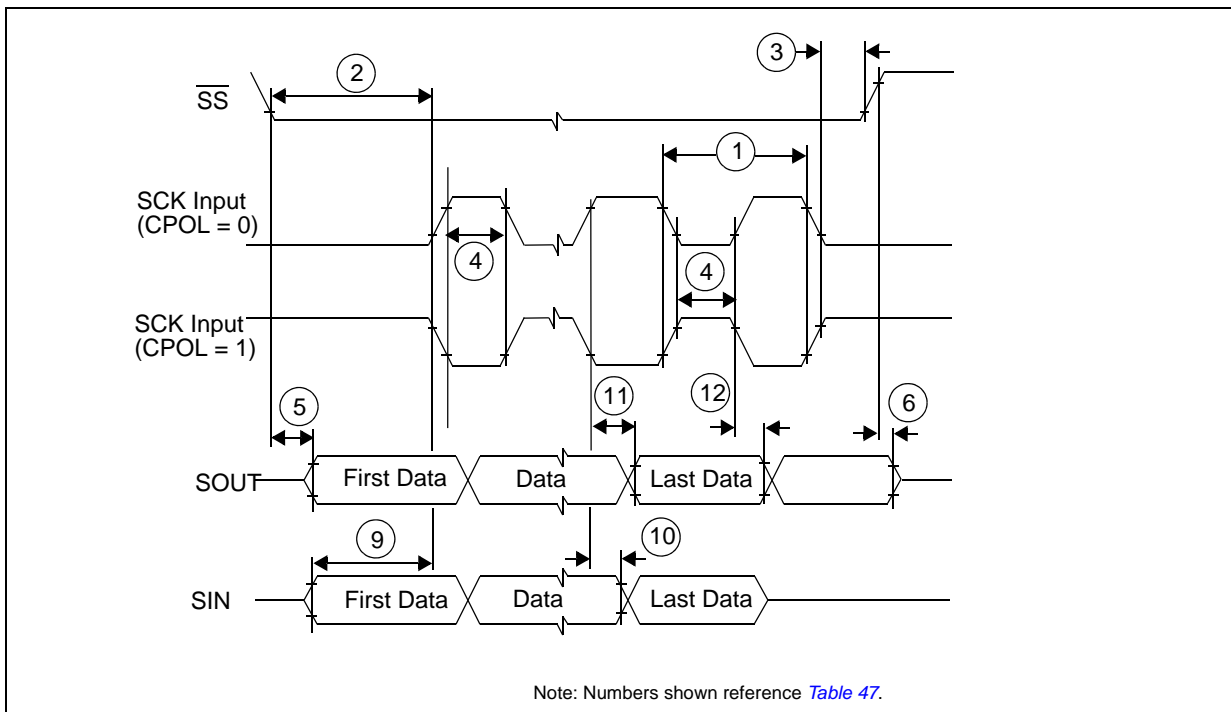


Figure 29. DSPI modified transfer format timing — slave, CPHA = 1

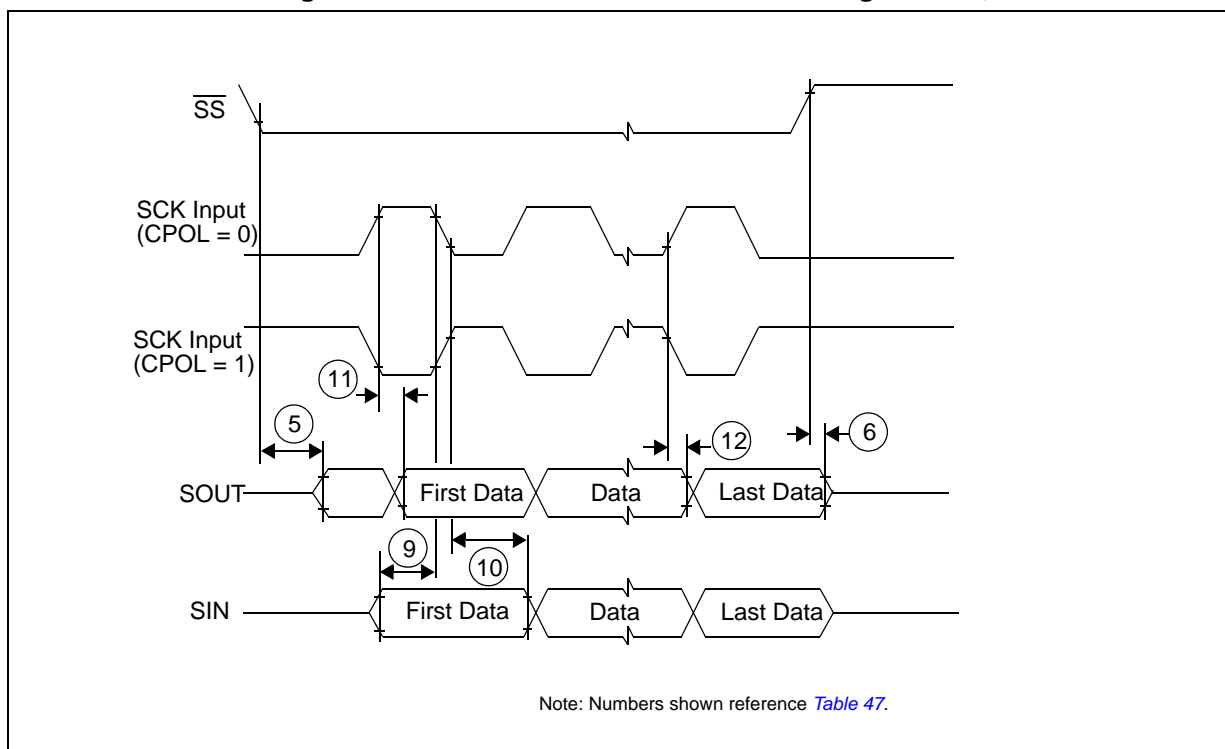
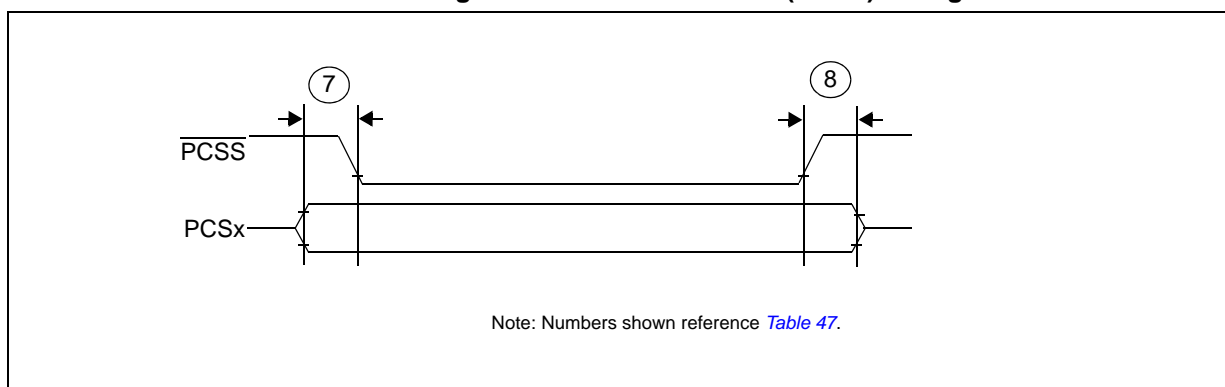


Figure 30. DSPI PCS strobe (PCSS) timing



### 4.18.3 Nexus characteristics

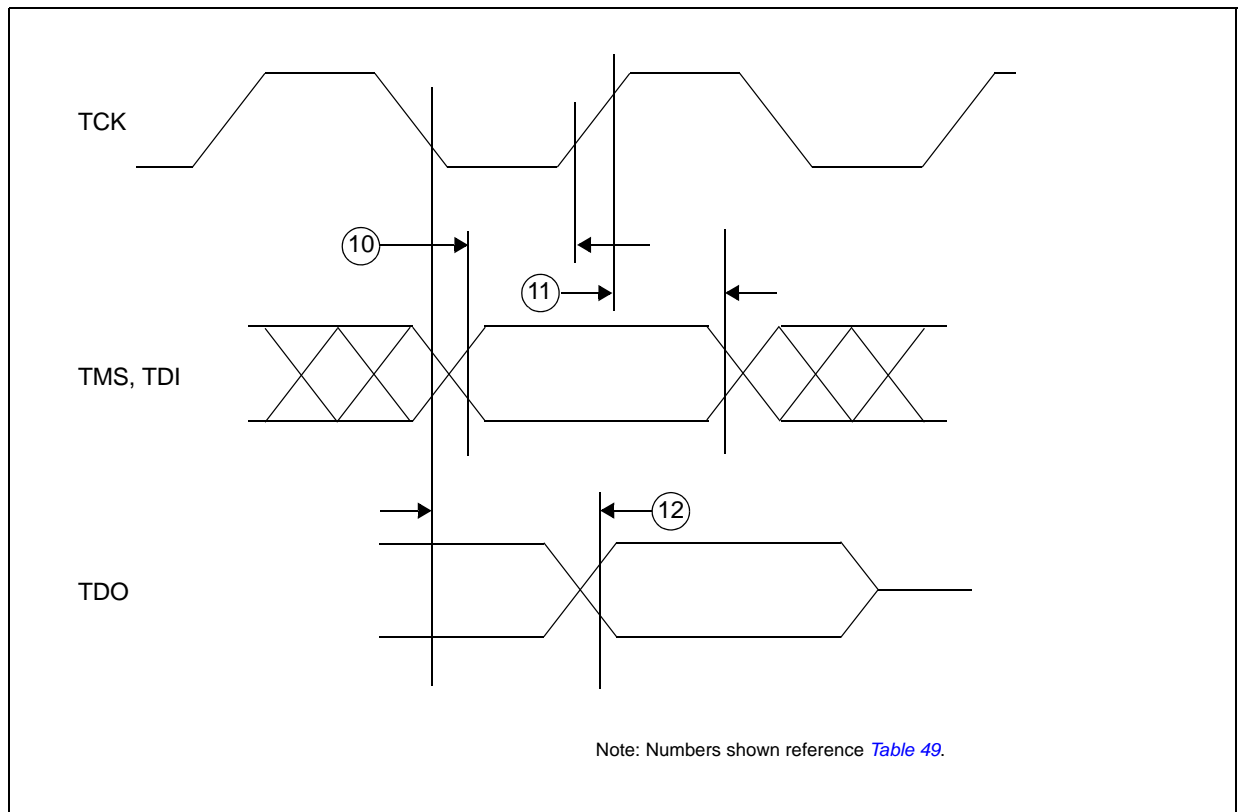
Table 49. Nexus characteristics

No.	Symbol	C	Parameter	Value			Unit
				Min	Typ	Max	
1	$t_{TCYC}$	CC	D	TCK cycle time			ns
2	$t_{MCYC}$	CC	D	MCKO cycle time			ns
3	$t_{MDOV}$	CC	D	MCKO low to MDO data valid			ns
4	$t_{MSEOV}$	CC	D	MCKO low to MSEO_b data valid			ns

Table 49. Nexus characteristics (continued)

No.	Symbol	C	Parameter	Value			Unit	
				Min	Typ	Max		
5	$t_{EVTOV}$	CC	D	MCKO low to EVTO data valid	—	—	8	ns
6	$t_{NTDIS}$	CC	D	TDI data setup time	15	—	—	ns
	$t_{NTMSS}$	CC	D	TMS data setup time	15	—	—	ns
7	$t_{NTDIH}$	CC	D	TDI data hold time	5	—	—	ns
	$t_{NTMSH}$	CC	D	TMS data hold time	5	—	—	ns
8	$t_{TDOV}$	CC	D	TCK low to TDO data valid	35	—	—	ns
9	$t_{TDOI}$	CC	D	TCK low to TDO data invalid	6	—	—	ns

Figure 31. Nexus TDI, TMS, TDO timing

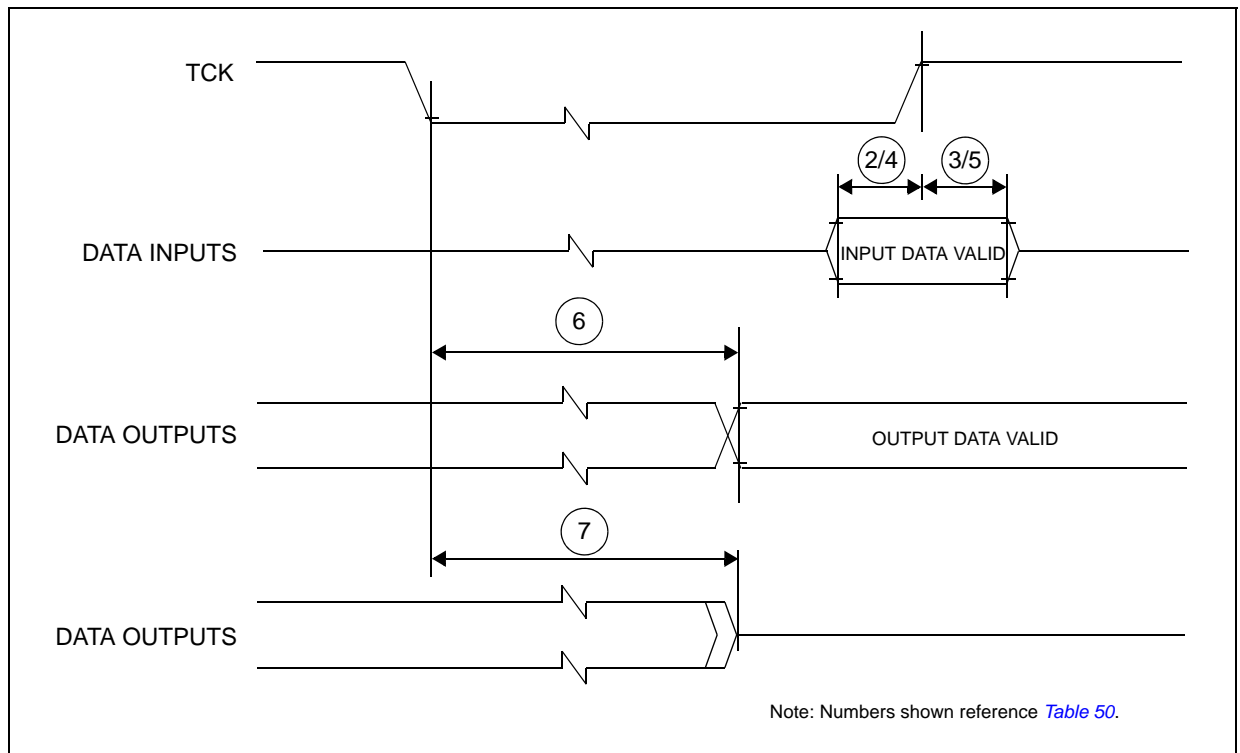


4.18.4 JTAG characteristics

Table 50. JTAG characteristics

No.	Symbol	C	Parameter	Value			Unit	
				Min	Typ	Max		
1	$t_{JCYC}$	CC	D	TCK cycle time	64	—	—	ns
2	$t_{TDIS}$	CC	D	TDI setup time	15	—	—	ns
3	$t_{TDIH}$	CC	D	TDI hold time	5	—	—	ns
4	$t_{TMSS}$	CC	D	TMS setup time	15	—	—	ns
5	$t_{TMSh}$	CC	D	TMS hold time	5	—	—	ns
6	$t_{TDOV}$	CC	D	TCK low to TDO valid	—	—	33	ns
7	$t_{TDOI}$	CC	D	TCK low to TDO invalid	6	—	—	ns

Figure 32. Timing diagram — JTAG boundary scan



## 5 Package characteristics

### 5.1 ECOPACK®

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: [www.st.com](http://www.st.com). ECOPACK® is an ST trademark.

### 5.2 Package mechanical data

#### 5.2.1 LQFP176

Figure 33. LQFP176 package mechanical drawing

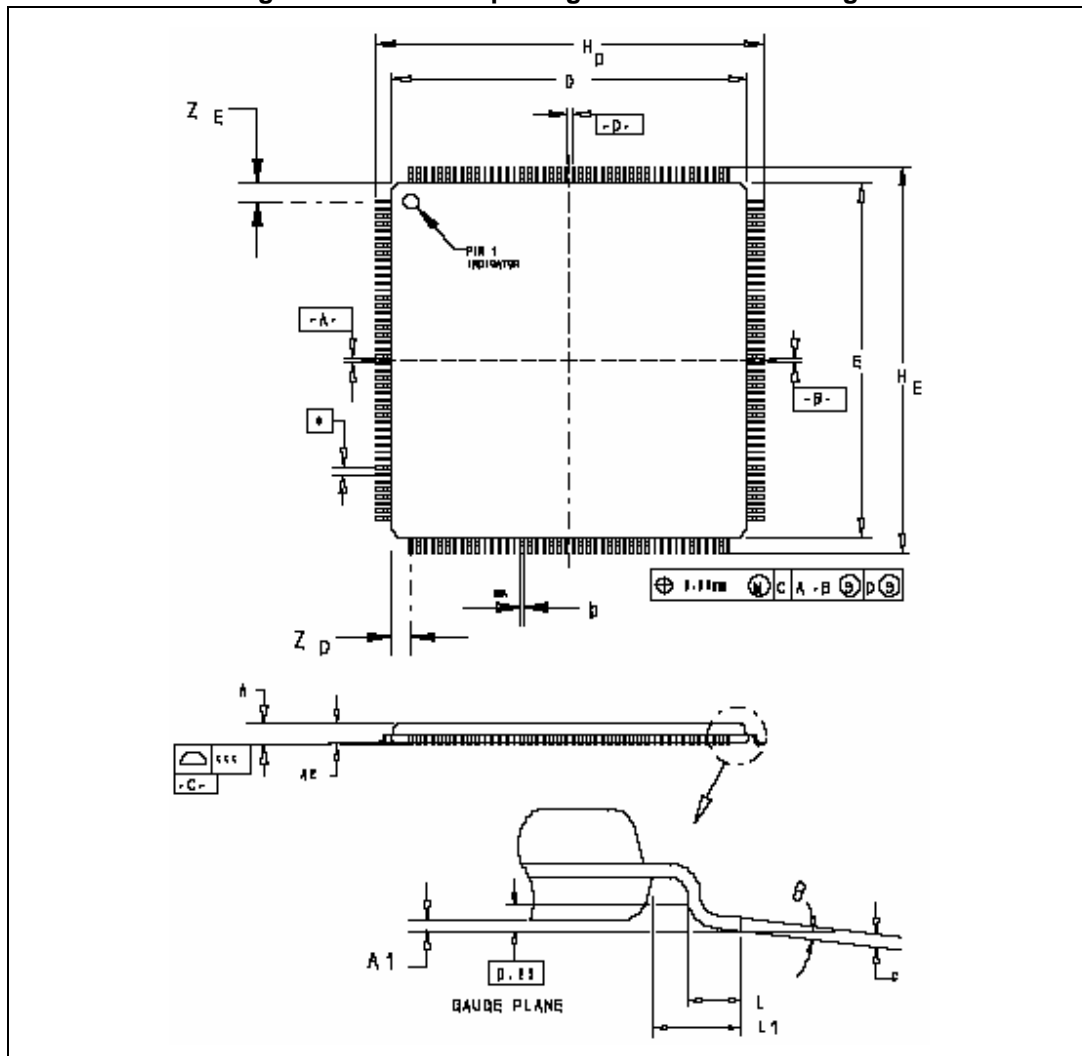


Table 51. LQFP176 mechanical data<sup>(1)</sup>

Symbol	mm			inches <sup>(2)</sup>		
	Min	Typ	Max	Min	Typ	Max
A	1.400	—	1.600		—	0.063
A1	0.050	—	0.150	0.002	—	
A2	1.350	—	1.450	0.053	—	0.057
b	0.170	—	0.270	0.007	—	0.011
C	0.090	—	0.200	0.004	—	0.008
D	23.900	—	24.100	0.941	—	0.949
E	23.900	—	24.100	0.941	—	0.949
e	—	0.500	—	—	0.020	—
HD	25.900	—	26.100	1.020	—	1.028
HE	25.900	—	26.100	1.020	—	1.028
L <sup>(3)</sup>	0.450	—	0.750	0.018	—	0.030
L1	—	1.000	—	—	0.039	—
ZD	—	1.250	—	—	0.049	—
ZE	—	1.250	—	—	0.049	—
q	0°	—	7°	0°	—	7°
Tolerance	mm			inches		
ccc	0.080			0.0031		

1. Controlling dimension: millimeter.
2. Values in inches are converted from mm and rounded to 4 decimal digits.
3. L dimension is measured at gauge plane at 0.25 mm above the seating plane.

5.2.2 LQFP144

Figure 34. LQFP144 package mechanical drawing

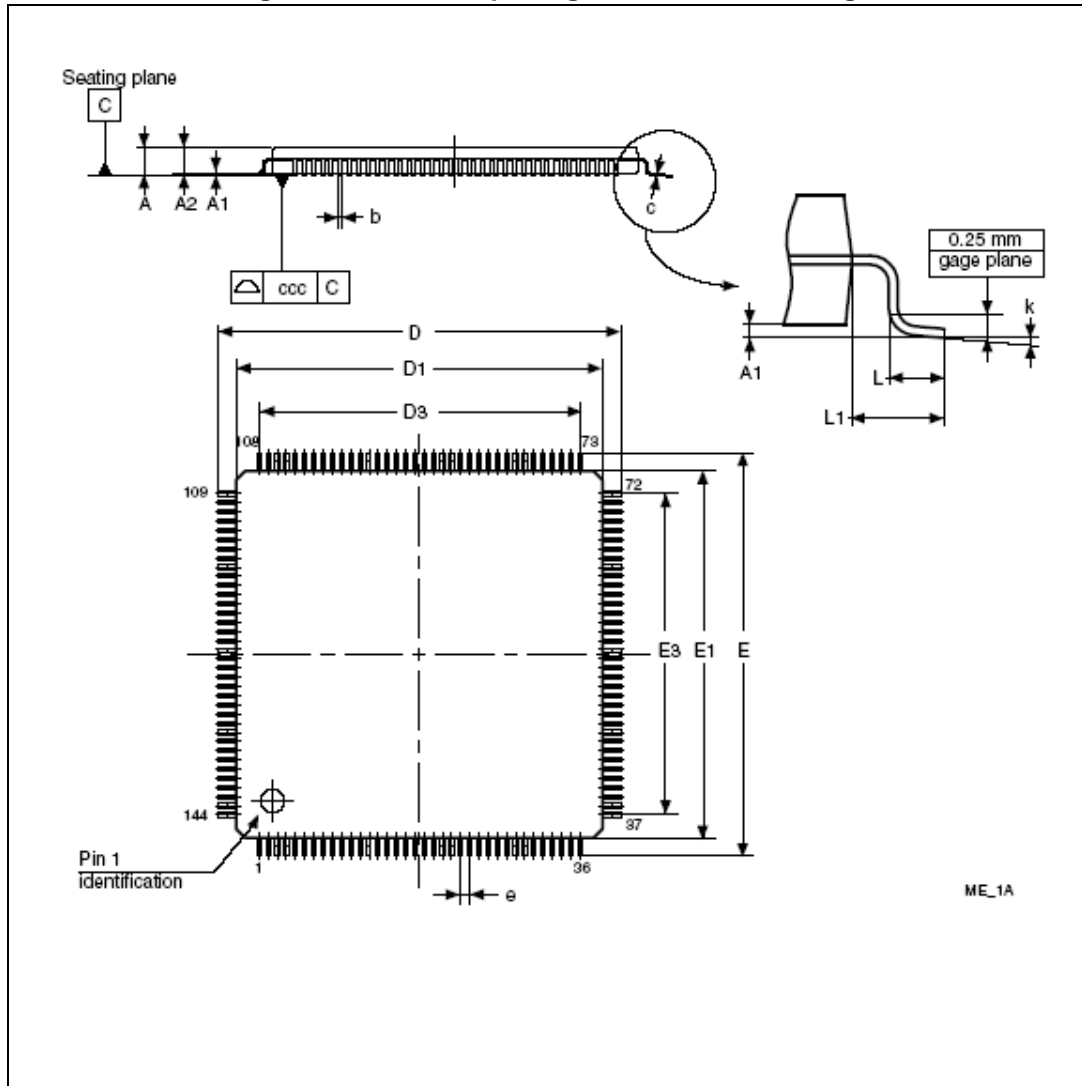


Table 52. LQFP144 mechanical data

Symbol	mm			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
A	—	—	1.600	—	—	0.0630
A1	0.050	—	0.150	0.0020	—	0.0059
A2	1.350	1.400	1.450	0.0531	0.0551	0.0571
b	0.170	0.220	0.270	0.0067	0.0087	0.0106
c	0.090	—	0.200	0.0035	—	0.0079
D	21.800	22.000	22.200	0.8583	0.8661	0.8740

Table 52. LQFP144 mechanical data (continued)

Symbol	mm			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
D1	19.800	20.000	20.200	0.7795	0.7874	0.7953
D3	—	17.500	—	—	0.6890	—
E	21.800	22.000	22.200	0.8583	0.8661	0.8740
E1	19.800	20.000	20.200	0.7795	0.7874	0.7953
E3	—	17.500	—	—	0.6890	—
e	—	0.500	—	—	0.0197	—
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	—	1.000	—	—	0.0394	—
k	0.0 °	3.5 °	7.0°	3.5 °	0.0 °	7.0 °
Tolerance	mm			inches		
ccc	0.080			0.0031		

1. Values in inches are converted from mm and rounded to 4 decimal digits.



5.2.3 LQFP100

Figure 35. LQFP100 package mechanical drawing

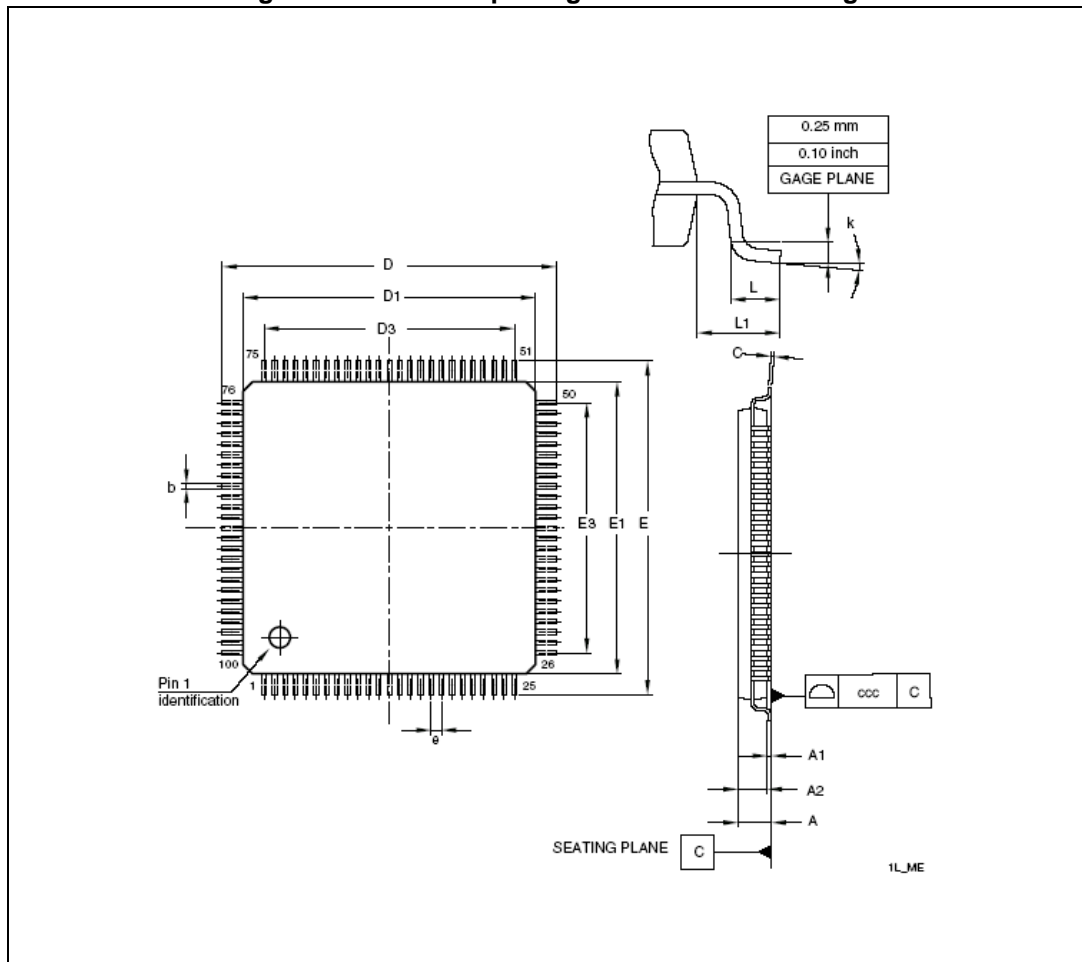


Table 53. LQFP100 mechanical data

Symbol	mm			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
A	—	—	1.600	—	—	0.0630
A1	0.050	—	0.150	0.0020	—	0.0059
A2	1.350	1.400	1.450	0.0531	0.0551	0.0571
b	0.170	0.220	0.270	0.0067	0.0087	0.0106
c	0.090	—	0.200	0.0035	—	0.0079
D	15.800	16.000	16.200	0.6220	0.6299	0.6378
D1	13.800	14.000	14.200	0.5433	0.5512	0.5591
D3	—	12.000	—	—	0.4724	—
E	15.800	16.000	16.200	0.6220	0.6299	0.6378

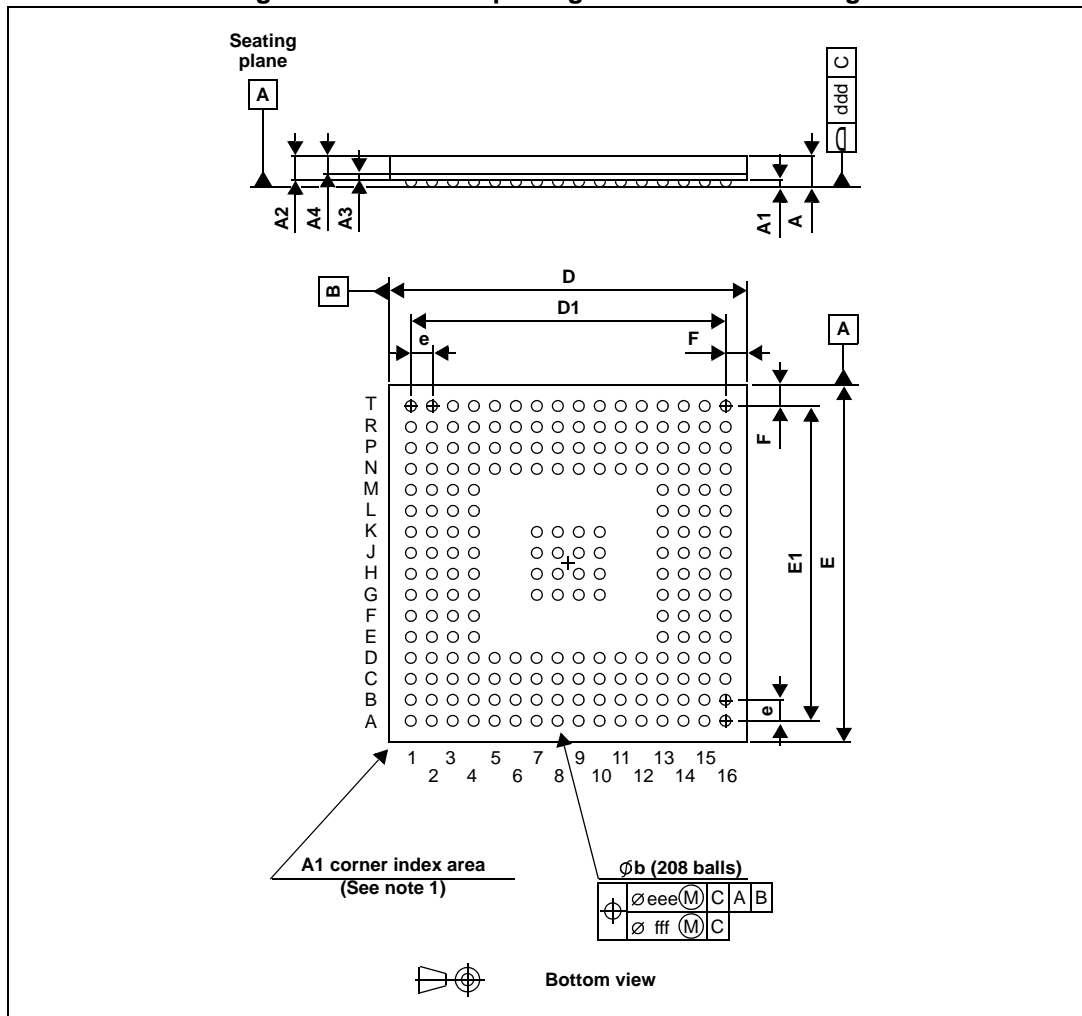
Table 53. LQFP100 mechanical data (continued)

Symbol	mm			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
E1	13.800	14.000	14.200	0.5433	0.5512	0.5591
E3	—	12.000	—	—	0.4724	—
e	—	0.500	—	—	0.0197	—
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	—	1.000	—	—	0.0394	—
k	0.0 °	3.5 °	7.0 °	0.0 °	3.5 °	7.0 °
Tolerance	mm			inches		
ccc	0.080			0.0031		

1. Values in inches are converted from mm and rounded to 4 decimal digits.

5.2.4 LPGA208

Figure 36. LPGA208 package mechanical drawing



1. The terminal A1 corner must be identified on the top surface by using a corner chamfer, ink or metalized markings, or other feature of package body or integral heatslug. A distinguishing feature is allowable on the bottom surface of the package to identify the terminal A1 corner. Exact shape of each corner is optional.

Table 54. LPGA208 mechanical data

Symbol	mm			inches <sup>(1)</sup>			Notes
	Min	Typ	Max	Min	Typ	Max	
A	—	—	1.70	—	—	0.0669	(2)
A1	0.30	—	—	0.0118	—	—	—
A2	—	1.085	—	—	0.0427	—	—
A3	—	0.30	—	—	0.0118	—	—
A4	—	—	0.80	—	—	0.0315	—
b	0.50	0.60	0.70	0.0197	0.0236	0.0276	(3)

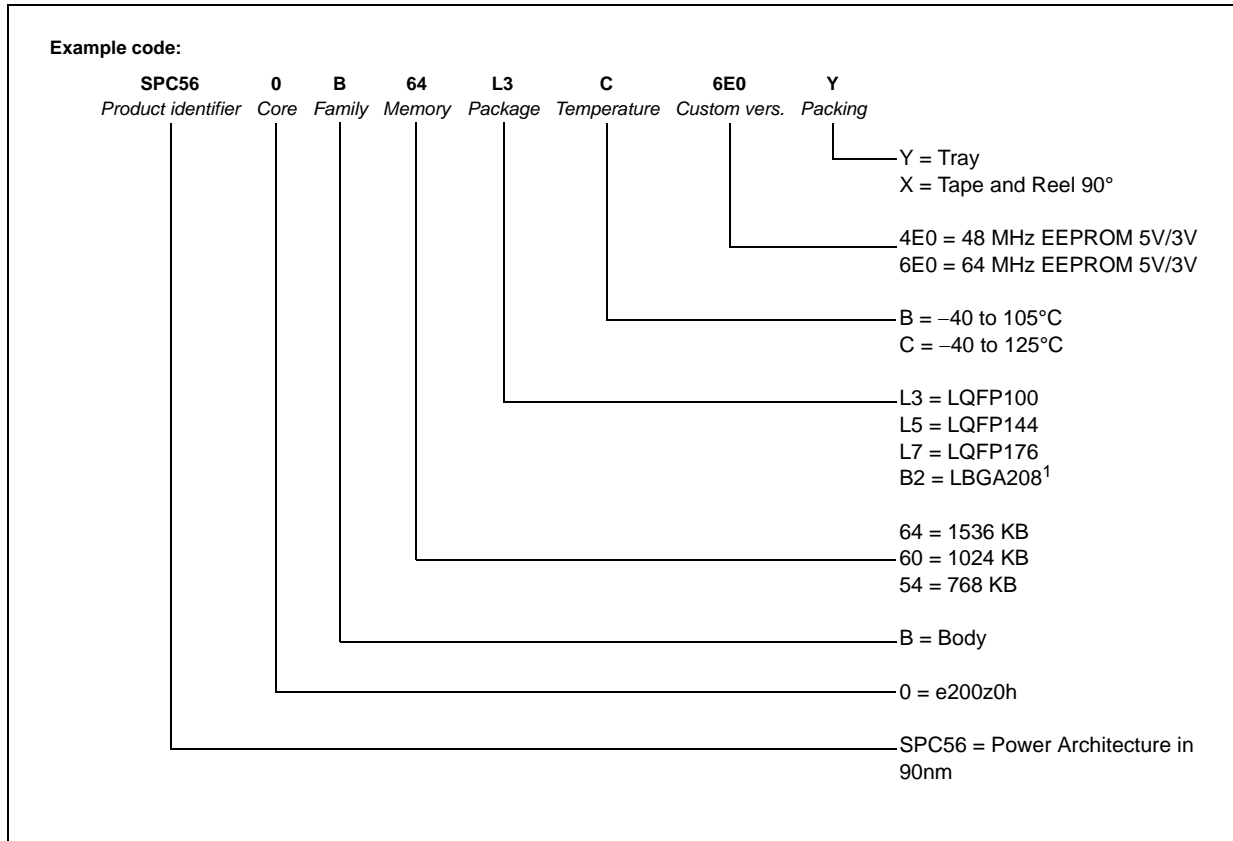
Table 54. LBGA208 mechanical data (continued)

Symbol	mm			inches <sup>(1)</sup>			Notes
	Min	Typ	Max	Min	Typ	Max	
D	16.80	17.00	17.20	0.6614	0.6693	0.6772	—
D1	—	15.00	—	—	0.5906	—	—
E	16.80	17.00	17.20	0.6614	0.6693	0.6772	—
E1	—	15.00	—	—	0.5906	—	—
e	—	1.00	—	—	0.0394	—	—
F	—	1.00	—	—	0.0394	—	—
ddd	—	—	0.20	—	—	0.0079	—
eee	—	—	0.25	—	—	0.0098	(4)
fff	—	—	0.10	—	—	0.0039	(5)

1. Values in inches are converted from mm and rounded to 4 decimal digits.
2. LBGA stands for **Low profile Ball Grid Array**.
  - Low profile: The total profile height (Dim A) is measured from the seating plane to the top of the component
  - The maximum total package height is calculated by the following methodology:  
 $A2 (Typ) + A1 (Typ) + \sqrt{A1^2 + A3^2 + A4^2}$  tolerance values
  - Low profile:  $1.20 \text{ mm} < A \leq 1.70 \text{ mm}$
3. The typical ball diameter before mounting is 0.60mm.
4. The tolerance of position that controls the location of the pattern of balls with respect to datums A and B. For each ball there is a cylindrical tolerance zone eee perpendicular to datum C and located on true position with respect to datums A and B as defined by e. The axis perpendicular to datum C of each ball must lie within this tolerance zone.
5. The tolerance of position that controls the location of the balls within the matrix with respect to each other. For each ball there is a cylindrical tolerance zone fff perpendicular to datum C and located on true position as defined by e. The axis perpendicular to datum C of each ball must lie within this tolerance zone. Each tolerance zone fff in the array is contained entirely in the respective zone eee above. The axis of each ball must lie simultaneously in both tolerance zones.

# 6 Ordering information

Figure 37. Commercial product code structure



1. LBGA208 is available only as development package for Nexus2+.

## Appendix A Abbreviations

[Table 55](#) lists abbreviations used but not defined elsewhere in this document.

**Table 55. Abbreviations**

Abbreviation	Meaning
CMOS	Complementary metal oxide semiconductor
CPHA	Clock phase
CPOL	Clock polarity
CS	Peripheral chip select
EVTO	Event out
MCKO	Message clock out
MDO	Message data out
MSEO	Message start/end out
MTFE	Modified timing format enable
SCK	Serial communications clock
SOUT	Serial data out
TBD	To be defined
TCK	Test clock input
TDI	Test data input
TDO	Test data output
TMS	Test mode select

## Revision history

[Table 56](#) summarizes revisions to this document.

**Table 56. Revision history**

Date	Revision	Changes
12-Jan-2009	1	Initial release
07-Dec-2009	2	Updated Device Summary-added LBGA208 Part number Updated Features Replaced 27 IRQs in place of 23 ADC features External Ballast resistor support conditions Updated device summary-added 208 BGA details Updated block diagram to include WKUP Updated block diagram to include 5 ch ADC 12 -bit Updated Block summary table Updated LQFP 144, 176 and 100 pinouts. Applied new naming convention for ADC signals as ADCx_P[x] and ADCx_S[x] Section 1, "General description Updated SPC560B54/60/64 device comparison table Updated block diagram-aligned with 512k Updated block summary-aligned with 512k Section 2, "Package pinouts Updated 100,144,176,208 packages according to cut2.0 changes Added Section 3.5.1, "External ballast resistor recommendations Added NVUSRO [WATCHDOG_EN] field description Updated Absolute maximum ratings Updated LQFP thermal characteristics Updated I/O supply segments Updated Voltage regulator capacitance connection Updated Low voltage monitor electrical characteristics Updated Low voltage power domain electrical characteristics Updated DC electrical characteristics Updated Program/Erase specifications Updated Conversion characteristics (10 bit ADC) Updated FMPLL electrical characteristics Updated Fast RC oscillator electrical characteristics-aligned with SPC560B4x/B5x/C4x/C5x Updated On-chip peripherals current consumption Updated ADC characteristics and error definitions diagram Updated ADC conversion characteristics (10 bit and 12 bit) Added ADC characteristics and error definitions diagram for 12 bit ADC

Table 56. Revision history (continued)

Date	Revision	Changes
23-Feb-2010	3	<p>Updated Features</p> <p>Updated block diagram to connect peripherals to pad I/O</p> <p>Updated block summary to include ADC 12-bit</p> <p>Updated 144, 176 and 100 pinouts to adjust format issues</p> <p>Table 26 Flash module life-retention value changed from 1-5 to 5 yrs</p> <p>Minor editing changes</p>
13-Sep-2010	4	<p>Editorial changes and improvements.</p> <p>Cover page: removed LPGA208 package silhouette</p> <p>Updated "Features" section</p> <p><a href="#">Table 2</a>: updated footnote concerning LPGA208</p> <p>In the block diagram:</p> <ul style="list-style-type: none"> <li>– Added "5ch 12-bit ADC" block.</li> <li>– Updated Legend.</li> <li>– Added "Interrupt request with wakeup functionality" as an input to the WKPU block.</li> </ul> <p><a href="#">Figure 2</a>: removed alternate functions</p> <p><a href="#">Figure 3</a>: removed alternate functions</p> <p><a href="#">Figure 4</a>: removed alternate functions</p> <p><a href="#">Table 3</a>: added contents concerning the following blocks: CMU, eDMA, ECSM, MC_ME, MC_PCU, NMI, SSCM, SWT and WKPU</p> <p>Added <a href="#">Section 3.2, Pin muxing</a></p> <p><a href="#">Section 4: Electrical characteristics</a>: removed "Caution" note</p> <p><a href="#">Section 4.2: NVUSRO register</a>: removed "NVUSRO[WATCHDOG_EN] field description" section</p> <p><a href="#">Table 12</a>: <math>V_{IN}</math>: removed min value in "relative to <math>V_{DD}</math>" row</p> <p><a href="#">Table 13</a></p> <ul style="list-style-type: none"> <li>– <math>TV_{DD}</math>: contents merged into one row</li> <li>– <math>V_{DD\_BV}</math>: changed min value in "relative to <math>V_{DD}</math>" row</li> </ul> <p><a href="#">Section 4.5: Thermal characteristics</a></p> <ul style="list-style-type: none"> <li>– <a href="#">Section 4.5.1: External ballast resistor recommendations</a>: added new paragraph about power supply</li> <li>– <a href="#">Table 15</a>: added <math>R_{\theta JB}</math> and <math>R_{\theta JC}</math> rows</li> <li>– Removed "LPGA208 thermal characteristics" table</li> </ul> <p><a href="#">Table 16</a>: rewrote parameter description of <math>W_{FI}</math> and <math>W_{NFI}</math></p> <p><a href="#">Section 4.6.5: I/O pad current specification</a></p> <ul style="list-style-type: none"> <li>– Removed <math>I_{DYNSEG}</math> information</li> <li>– Updated "I/O supply segments" table</li> </ul> <p><a href="#">Table 23</a>: removed <math>I_{DYNSEG}</math> row</p> <p>Added <a href="#">Table 24</a></p>



Table 56. Revision history (continued)

Date	Revision	Changes
13-Sep-2010	4 (cont.)	<p><a href="#">Table 26</a></p> <ul style="list-style-type: none"> <li>– Updated all values</li> <li>– Removed I<sub>VREGREF</sub> and I<sub>VREDLVD12</sub> rows</li> <li>– Added the footnote “The duration of the in-rush current depends on the capacitance placed on LV pins. BV decaps must be sized accordingly. Refer to IMREG value for minimum amount of current to be provided in cc.” to the I<sub>DD_BV</sub> specification.</li> </ul> <p><a href="#">Table 27</a></p> <ul style="list-style-type: none"> <li>– Updated V<sub>PORH</sub> min/max value</li> <li>– Updated V<sub>LVDLVCORL</sub> min value</li> </ul> <p>Updated <a href="#">Table 28</a></p> <p><a href="#">Table 29</a></p> <ul style="list-style-type: none"> <li>– T<sub>dwprogram</sub>: added initial max value</li> <li>– Inserted T<sub>eslat</sub> row</li> </ul> <p><a href="#">Table 30</a>: removed the “To be confirmed” footnote In the “Crystal oscillator and resonator connection scheme” figure, removed R<sub>p</sub>.</p> <p><a href="#">Table 40</a></p> <ul style="list-style-type: none"> <li>– Removed g<sub>mSXOSC</sub> row</li> <li>– I<sub>SXOSCBIAS</sub>: added min/typ/max value</li> </ul> <p><a href="#">Table 41</a>:</p> <ul style="list-style-type: none"> <li>– Added f<sub>VCO</sub> row</li> <li>– Added Δt<sub>STJIT</sub> row</li> </ul> <p><a href="#">Table 42</a></p> <ul style="list-style-type: none"> <li>– I<sub>FIRCPWD</sub>: removed row for T<sub>A</sub> = 55 °C</li> <li>– Updated T<sub>FIRCSU</sub> row</li> </ul> <p><a href="#">Table 45</a>: Added two rows: I<sub>ADC0pwd</sub> and I<sub>ADC0run</sub></p> <p><a href="#">Table 46</a></p> <ul style="list-style-type: none"> <li>– Added two rows: I<sub>ADC1pwd</sub> and I<sub>ADC1run</sub></li> <li>– Updated values of f<sub>ADC_1</sub> and t<sub>ADC1_PU</sub></li> <li>– Updated t<sub>ADC1_C</sub> row</li> </ul> <p>Updated <a href="#">Table 47</a></p> <p>Updated <a href="#">Table 48</a></p> <p>Added <a href="#">Table 55</a></p>
29-Oct- 2010	5	<p>Removed “Preliminary—Subject to Change Without Notice” marking. This data sheet contains specifications based on characterization data.</p> <p>Updated <a href="#">Table 55</a></p> <p>Added <a href="#">Table 56</a></p> <p>Updated <a href="#">Figure 37</a></p>

**Table 56. Revision history (continued)**

Date	Revision	Changes
12-Sep- 2011	6	<p>Editorial and formatting changes throughout                      Replaced instances of “e200z0” with “e200z0h”                      Device family comparison table:</p> <ul style="list-style-type: none"> <li>– added 1 MB code flash LQFP100 version</li> <li>– added 1.5 MB code flash LQFP144 version</li> <li>– removed 768 KB code flash LQFP176 version</li> <li>– changed LINFlex count for 144-pin LQFP—was ‘6’; is ‘8’</li> <li>– changed LINFlex count for 176-pin LQFP—was ‘8’; is ‘10’</li> <li>– replaced 105 °C with 125 °C in footnote 2</li> </ul> <p>SPC560B54/6x block diagram: added GPIO and VREG to legend                      SPC560B54/6x series block summary: added acronym “JTAGC”; in WKPU function changed “up to 18 external sources” to “up to 27 external sources”                      LQFP144 pin configuration: for pins 37–72, restored the pin labels that existed prior to 27 July 2010                      LQFP176 pin configuration: corrected name of pin 4: was EPC[15]; is PC[15]                      Added following sections:</p> <ul style="list-style-type: none"> <li>– Pad configuration during reset phases</li> <li>– Pad configuration during standby mode exit</li> <li>– Voltage supply pins</li> <li>– Pad types</li> <li>– System pins</li> <li>– Functional port pins</li> <li>– Nexus 2+ pins</li> </ul> <p>Section “NVUSRO register”: edited content to separate configuration into electrical parameters and digital functionality; updated footnote describing default value of ‘1’ in field descriptions NVUSRO[PAD3V5V] and NVUSRO[OSCILLATOR_MARGIN]                      Added section “NVUSRO[WATCHDOG_EN] field description”                      Tables “Absolute maximum ratings” and “Recommended operating conditions (3.3 V)”: replaced “VSS_HV_ADC0, VSS_HV_ADC1” with “VDD_HV_ADC0, VDD_HV_ADC1” in V<sub>DD_ADC</sub> parameter description                      “Recommended operating conditions (5.0 V)” table: replaced “VSS_HV_ADC0, VSS_HV_ADC1” with “VDD_HV_ADC0, VDD_HV_ADC1” in V<sub>DD_ADC</sub> parameter description; changed 3.6V to 3.0V in footnote 2                      Section “External ballast resistor recommendations”: replaced “low voltage monitor” with “low voltage detector (LVD)”                      “I/O input DC electrical characteristics” table: updated I<sub>LKG</sub> characteristics                      “MEDIUM configuration output buffer electrical characteristics” table: changed “I<sub>OH</sub> = 100 μA” to “I<sub>OL</sub> = 100 μA” in V<sub>OL</sub> conditions                      I/O weight: updated table (includes replacing instances of bit “SRE” with “SRC”)                      “Reset electrical characteristics” table: updated parameter classification for  I<sub>WPUL</sub>                        Updated voltage regulator electrical characteristics</p> <p>Section “Low voltage detector electrical characteristics”: changed title (was “Voltage monitor electrical characteristics”); changed “as well as four low voltage detectors” to “as well as five low voltage detectors”; added event status flag names found in RGM chapter of device reference manual to POR module and LVD descriptions; replaced instances of “Low voltage monitor” with “Low voltage detector”; updated values for V<sub>LVDLVBKPL</sub> and V<sub>LVDLVCORL</sub>                      Updated section “Power consumption”</p>

Table 56. Revision history (continued)

Date	Revision	Changes
12-Sep-2011 (continued)	6 (continued)	<p>Section "Program/erase characteristics": removed table "FLASH_BIU settings vs. frequency of operation" and associated introduction</p> <p>"Program and erase specifications" table: updated symbols</p> <p>PFCRn settings vs. frequency of operation: replaced "FLASH_BIU" with "PFCRn" in table title; updated field names and frequencies</p> <p>"Flash power supply DC electrical characteristics" table: deleted footnote 2</p> <p>Crystal oscillator and resonator connection scheme: inserted footnote about possibly requiring a series resistor</p> <p>Fast external crystal oscillator (4 to 16 MHz) electrical characteristics: updated parameter classification for <math>V_{FXOSCOP}</math></p> <p>Slow external crystal oscillator (32 kHz) electrical characteristics: updated footnote 1</p> <p>Section "ADC electrical characteristics": updated symbols for offset error and gain error</p> <p>Section "Input impedance and ADC accuracy": changed "<math>V_A/V_{A2}</math>" to "<math>V_{A2}/V_A</math>" in Equation 11</p> <p>ADC input leakage current: updated <math>I_{LKG}</math> characteristics</p> <p>ADC_0 conversion characteristics table: replaced instances of "ADCx_conf_sample_input" with "INPSAMP"; replaced instances of "ADCx_conf_comp" with "INPCMP"</p> <p>ADC_1 characteristic and error definitions: replaced "AVDD" with "<math>V_{DD\_ADC}</math>"</p> <p>ADC_1 conversion characteristics table: replaced instances of "ADCx_conf_sample_input" with "INPSAMP"; replaced instances of "ADCx_conf_comp" with "INPCMP"</p> <p>Updated "On-chip peripherals current consumption" table</p> <p>Removed order codes tables.</p>
18-Sep-2013	7	Updated Disclaimer.
05-May-2014	8	<p><a href="#">Table 13: Recommended operating conditions (3.3 V)</a>, added minimum value of <math>T_{VDD}</math> and footnote about it.</p> <p><a href="#">Table 14: Recommended operating conditions (5.0 V)</a>, added minimum value of <math>T_{VDD}</math> and footnote about it.</p> <p><a href="#">Table 21: Output pin transition times</a>, replaced <math>T_{tr}</math> with <math>t_{tr}</math></p> <p><a href="#">Table 25: Reset electrical characteristics</a>, replaced <math>T_{tr}</math> with <math>t_{tr}</math></p> <p>Updated <a href="#">Section 4.17.2: Input impedance and ADC accuracy</a></p> <p><a href="#">Table 27: Low voltage detector electrical characteristics</a>, changed <math>V_{LVDHV3L}(\min)</math> and <math>V_{LVDHV3BL}(\min)</math> from 2.7 V to 2.6 V.</p> <p><a href="#">Table 29: Program and erase specifications</a>, added footnote about <math>t_{ESRT}</math></p> <p><a href="#">Table 41: FMPLL electrical characteristics</a>, deleted footnote relative to maximum value of <math>f_{CPU}</math></p> <p><a href="#">Table 45: ADC_0 conversion characteristics (10-bit ADC_0)</a>, changed <math>I_{ADC0run}</math> value from 40 mA to 5 mA.</p> <p><a href="#">Table 48: DSPI characteristics</a>, in the heading row, replaced DSPI0/DSPI1/DSPI5/DSPI6 with DSPI0/DSPI1/DSPI3/DSPI5.</p>
22-Jan-2016	9	<p>In <a href="#">Table 1: Device summary</a>, added SPC560B64L3 for 1.5 MB code flash devices.</p> <p>In <a href="#">Table 2: SPC560B54/6x family comparison</a>, added column relating to "LQFP100" package in SPC560B64 devices.</p> <p>In <a href="#">Table 28: Power consumption on VDD_BV and VDD_HV</a>:</p> <ul style="list-style-type: none"> <li>– changed footnote 2 "Running consumption does not include I/Os..." to "<math>I_{DDMAX}</math> is drawn only from the VDD_BV pin. Running consumption does not include I/Os..."</li> <li>– changed footnote 4 "RUN current measured with..." to "<math>I_{DDRUN}</math> is drawn only from the VDD_BV pin. RUN current measured with..."</li> </ul>

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