### **Ordering Information**

ACPL-W70L and ACPL-K73L are UL Recognized with 5000  $V_{rms}$  for 1 minute per UL1577.

Part Number	Option RoHS Compliant	Package	Surface Mount	Tape and Reel	UL 5000 V <sub>rms</sub> / 1 Minute Rating	IEC/EN/DIN EN 60747-5-5	Quantity
ACPL-W70L	-000E	SSO-6	X		X		100 per tube
	-500E		X	Х	X		1000 per reel
	-060E		X		X	X	100 per tube
	-560E		X	Х	Х	X	1000 per reel
ACPL-K73L	-000E	SSO-8	Х		Х		80 per tube
	-500E		X	Х	X		1000 per reel
	-060E		X		Х	X	80 per tube
	-560E		X	Х	Х	X	1000 per reel

To order, choose a part number from the part number column and combine with the desired option from the option column to form an order entry.

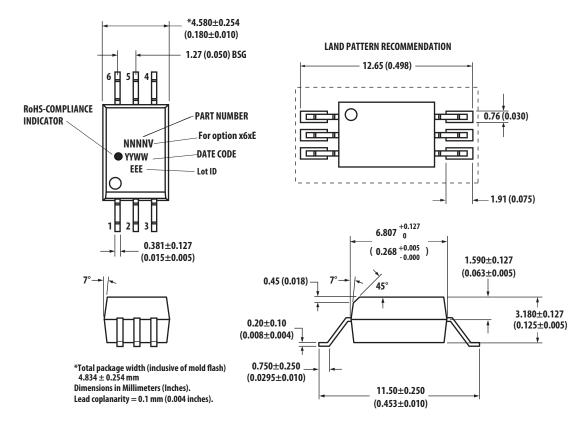
#### Example:

ACPL-W70L-500E to order product of stretched SO-6 package in Tape and Reel packaging in RoHS compliant.

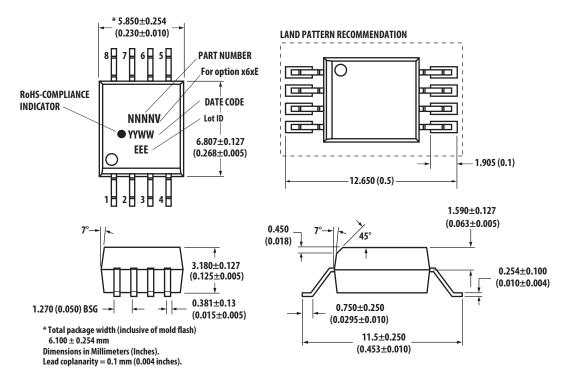
Option data sheets are available. Contact your Broadcom sales representative or authorized distributor for information.

## **Package Dimensions**

## ACPL-W70L (Stretched SO-6 Package)



#### ACPL-K73L (Stretched S0-8 Package)



#### **Solder Reflow Profile**

The recommended reflow soldering conditions are per JEDEC Standard J-STD-020 (latest revision). Non-halide flux should be used.

## **Regulatory Information**

The ACPL-W70L and ACPL-K73L are approved by the following organizations.

UL	Recognized under UL 1577, component recognition program, File E55361.		
CSA Approval under CSA Component Acceptance Notice #5, File CA 88324.			
IEC/EN/DIN EN 60747-5-5	Approved.		

## **Insulation and Safety Related Specifications**

Parameter	Symbol	Value	Units	Conditions
Minimum External Air Gap (Clearance)	L(101)	8.0	mm	Measured from input terminals to output terminals, shortest distance through air.
Minimum External Tracking (Creepage)	L(102)	8.0	mm	Measured from input terminals to output terminals, shortest distance path along body.
Minimum Internal Plastic Gap (Internal Clearance)		0.08	mm	Insulation thickness between emitter and detector; also known as distance through insulation.
Tracking Resistance (Comparative Tracking Index)	CTI	>175	V	VDE 0303-11/DIN EN 60112 (2010-05).
Isolation Group		Illa		Material Group (DIN VDE 0110, 1/89, Table 1).

All Broadcom data sheets report the creepage and clearance inherent to the optocoupler component itself. These dimensions are needed as a starting point for the equipment designer when determining the circuit insulation requirements. However, once mounted on a printed circuit board, minimum creepage and clearance requirements must be met as specified for individual equipment standards. For creepage, the shortest distance path along the surface of a printed circuit board between the solder fillets of the input and output leads must be considered.

There are recommended techniques such as grooves and ribs that can be used on a printed circuit board to achieve desired creepage and clearances. Creepage and clearance distances also change depending on factors such as pollution degree and insulation level.

#### IEC/EN/DIN EN 60747-5-5 Insulation Characteristics<sup>a</sup>

Description <sup>a</sup>	Symbol	Option 060	Units
Installation Classification per DIN VDE 0110/1.89, Table 1			
for rated mains voltage ≤ 150 V <sub>rmsa</sub>		I – IV	
for rated mains voltage ≤ 300 V <sub>rms</sub>		I – IV	
for rated mains voltage ≤ 450 V <sub>rms</sub>		I – IV	
for rated mains voltage ≤ 600 V <sub>rms</sub>		I – IV	
for rated mains voltage ≤ 1000 V <sub>rms</sub>		I – III	
Climatic Classification		55/105/21	
Pollution Degree (DIN VDE 0110/1.89)		2	
Maximum Working Insulation Voltage	V <sub>IORM</sub>	1140	$V_{peak}$
Input to Output Test Voltage, Method b <sup>b</sup>	V <sub>PR</sub>	2137	$V_{peak}$
$V_{IORM}$ x 1.875 = $V_{PR}$ , 100% Production Test with $t_m$ = 1s, Partial Discharge < 5 pC			
Input to Output Test Voltage, Method a <sup>b</sup>	V <sub>PR</sub>	1824	V <sub>peak</sub>
$V_{IORM}$ x 1.6 = $V_{PR}$ , Type and Sample Test, $t_m$ = 10s, Partial Discharge < 5 pC			
Highest Allowable Overvoltage (Transient Overvoltage t <sub>ini</sub> = 60s)	V <sub>IOTM</sub>	8000	$V_{peak}$
Safety-limiting Values – Maximum Values Allowed in the Event of a Failure			
Case Temperature	T <sub>S</sub>	175	°C
Input Current <sup>b</sup>	I <sub>S, INPUT</sub>	230	mA
Output Power <sup>b</sup>	Ps, output	600	mW
Insulation Resistance at T <sub>S</sub> , V <sub>IO</sub> = 500V	R <sub>IO</sub>	>10 <sup>9</sup>	Ω

a. Isolation characteristics are guaranteed only within the safety maximum ratings, which must be ensured by protective circuits in application. Surface mount classification is class A in accordance with CECCOO802.

**NOTE:** These optocouplers are suitable for safe electrical isolation only within the safety limit data. Maintenance of the safety data must be ensured by means of protective circuits. The surface mount classification is Class A in accordance with CECC 00802.

b. Refer to the optocoupler section of the Isolation and Control Components Designer's Catalog, under Product Safety Regulations section IEC/EN/DIN EN 60747-5-5, for a detailed description of Method a and Method b partial discharge test profiles.

## **Absolute Maximum Ratings**

Parameter	Symbol	Min.	Max.	Units			
Storage Temperature	T <sub>S</sub>	<b>–</b> 55	+125	°C			
Ambient Operating Temperature	T <sub>A</sub>	-40	+105	°C			
Supply Voltage	V <sub>DD</sub>	0	6	V			
Output Voltage	V <sub>O</sub>	-0.5	V <sub>DD</sub> + 0.5	V			
Average Forward Input Current	I <sub>F</sub>	_	10	mA			
Average Output Current	Io	_	10	mA			
Lead Solder Temperature	26	260°C for 10 seconds, 1.6 mm below seating plane					
Solder Reflow Temperature Profile		See <blue>Solder Reflow Profile.</blue>					

# **Recommended Operating Conditions**

Parameter	Symbol	Min.	Max.	Units
Ambient Operating Temperature	T <sub>A</sub>	-40	+105	°C
Supply Voltages	$V_{DD}$	4.5	5.5	V
		3.0	3.6	V
Input Current (ON)	I <sub>F</sub>	4	8	mA
Supply Voltage Slew Rate <sup>a</sup>	SR	0.5	500	V/ms

a. Slew rate of supply voltage ramping is recommended to ensure no glitch more than 1V to appear at the output pin.

## **Electrical Specifications**

Over recommended temperature (T<sub>A</sub> =  $-40^{\circ}$ C to  $+105^{\circ}$ C), 3.0V  $\leq$  V<sub>DD</sub>  $\leq$  3.6V and 4.5V  $\leq$  V<sub>DD</sub>  $\leq$  5.5V.

All typical specifications are at  $T_A$  = +25°C,  $V_{DD}$  = +3.3V.

Parameter	Symbol	Part Number	Min.	Тур.	Max.	Units	Test Conditions
Input Forward Voltage	V <sub>F</sub>		1.2	1.5	1.85	V	I <sub>F</sub> = 6 mA
Input Reverse Breakdown Voltage	BV <sub>R</sub>		5.0	_	_	V	Ι <sub>R</sub> = 10 μΑ
Logic High Output Voltage	V <sub>OH</sub>		V <sub>DD</sub> – 1	V <sub>DD</sub> – 0.3	_	V	$I_F = 6 \text{ mA}, I_O = -4 \text{ mA},$ $V_{DD} = 3.3 \text{V}$
			V <sub>DD</sub> – 1	V <sub>DD</sub> – 0.2	_	V	$I_F = 6 \text{ mA}, I_O = -4 \text{ mA},$ $V_{DD} = 5V$
Logic Low Output Voltage	V <sub>OL</sub>		_	0.2	0.8	V	$I_F = 0 \text{ mA}, I_O = 4 \text{ mA},$ $V_{DD} = 3.3 \text{V}$
			_	0.2	0.8	V	I <sub>F</sub> = 0 mA, I <sub>O</sub> = 4 mA, V <sub>DD</sub> = 5V
Input Threshold Current	I <sub>TH</sub>		_	1	3	mA	I <sub>OL</sub> = 20 μA
Logic Low Output Supply Current	I <sub>DDL</sub>	ACPL-W70L	_	4.1	6.5	mA	I <sub>F</sub> = 0 mA
		ACPL-K73L	_	8.2	13	mA	I <sub>F</sub> = 0 mA
Logic Low Output Supply Current	I <sub>DDH</sub>	ACPL-W70L	_	3.8	6	mA	I <sub>F</sub> = 6 mA
		ACPL-K73L	_	7.6	12	mA	I <sub>F</sub> = 6 mA

#### **Switching Specifications**

Over recommended temperature (T<sub>A</sub> = -40°C to +105°C), 3.0V  $\leq$  V<sub>DD</sub>  $\leq$  3.6V and 4.5V  $\leq$  V<sub>DD</sub>  $\leq$  5.5V.

All typical specifications are at  $T_A = +25$ °C,  $V_{DD} = +3.3$ V.

Parameter	Symbol	Min.	Тур.	Max.	Units	Test Conditions
Propagation Delay Time to Logic Low Output <sup>a</sup>	t <sub>PHL</sub>	_	23	55	ns	I <sub>F</sub> = 6 mA, C <sub>L</sub> = 15 pF
						CMOS Signal Levels
Propagation Delay Time to Logic High Output <sup>a</sup>	t <sub>PLH</sub>	_	27	55	ns	I <sub>F</sub> = 6 mA, C <sub>L</sub> = 15 pF
						CMOS Signal Levels
Pulse Width	t <sub>PW</sub>	66.7	_	—	ns	_
Pulse Width Distortion <sup>b</sup>	PWD	0	4	25	ns	I <sub>F</sub> = 6 mA, C <sub>L</sub> = 15 pF
						CMOS Signal Levels
Propagation Delay Skew <sup>c</sup>	t <sub>PSK</sub>	_	_	40	ns	I <sub>F</sub> = 6 mA, C <sub>L</sub> = 15 pF
						CMOS Signal Levels
Output Rise Time (10% to 90%)	t <sub>R</sub>	_	3.5	_	ns	I <sub>F</sub> = 6 mA, C <sub>L</sub> = 15 pF
						CMOS Signal Levels
Output Fall Time (90% to 10%)	t <sub>F</sub>	_	3.5	_	ns	I <sub>F</sub> = 0 mA, C <sub>L</sub> = 15 pF
						CMOS Signal Levels
Common-Mode Transient Immunity at Logic High	CM <sub>H</sub>	10	15	_	kV/µs	V <sub>CM</sub> = 1000V, T <sub>A</sub> = 25°C,
Output <sup>d</sup>						I <sub>F</sub> = 6 mA
Common-Mode Transient Immunity at Logic Low	CM <sub>L</sub>	10	15	_	kV/µs	V <sub>CM</sub> = 1000V, T <sub>A</sub> = 25°C,
Output <sup>e</sup>						I <sub>F</sub> = 0 mA

a. t<sub>PHL</sub> propagation delay is measured from the 50% level on the rising edge of the input pulse to the 50% level on the falling edge of the V<sub>O</sub> signal.

- b. PWD is defined as  $|t_{PHL} t_{PLH}|$ .
- c. t<sub>PSK</sub> is equal to the magnitude of the worst-case difference in t<sub>PHL</sub> and/or t<sub>PLH</sub> that is seen between units at any given temperature within the recommended operating conditions.
- d. CM<sub>H</sub> is the maximum tolerable rate of rise of the common-mode voltage to assure that the output remains in a high logic state.
- e. CM<sub>L</sub> is the maximum tolerable rate of fall of the common-mode voltage to assure that the output remains in a low logic state.

### **Package Characteristics**

All typical at  $T_A = 25$ °C.

Parameter	Symbol	Min.	Тур.	Max.	Units	Test Conditions
Input-Output Insulation	I <sub>I-O</sub>	_	_	1.0	μA	45% RH, t = 5s, V <sub>I-O</sub> = 3 kV dc.
						T <sub>A</sub> = 25°C
Input-Output Momentary Withstand Voltage	V <sub>ISO</sub>	5000	_	_	V <sub>rms</sub>	RH ≤ 50%, t = 1 min., T <sub>A</sub> = 25°C
Input-Output Resistance	R <sub>I-O</sub>	_	10 <sup>12</sup>	_	Ω	V <sub>I-O</sub> = 500V dc
Input-Output Capacitance	C <sub>I-O</sub>	_	0.6	_	pF	f = 1 MHz, T <sub>A</sub> = 25°C

 $t_{\rm PLH}^{-}$  propagation delay is measured from the 50% level on the falling edge of the input pulse to the 50% level on the rising edge of the V<sub>O</sub> signal.

Figure 1: Typical Input Diode Forward Characteristic

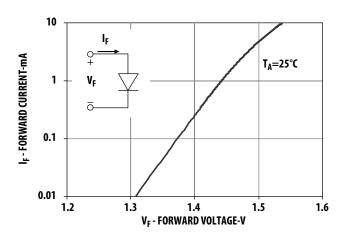


Figure 3: Typical Logic High Output Supply Current vs. Temperature for Dual Channel (ACPL-K73L)

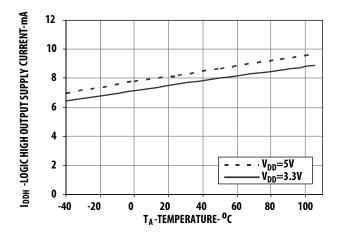


Figure 5: Typical Switching Speed vs. Pulse Input Current at 5V Supply Voltage

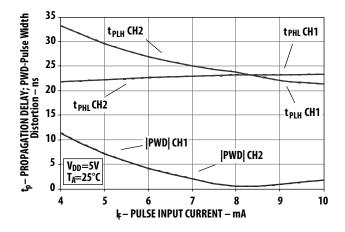


Figure 2: Typical Input Threshold Current vs. Temperature

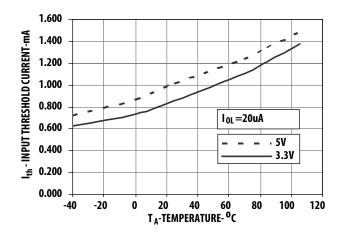


Figure 4: Typical Logic Low Output Supply Current vs. Temperature for Dual Channel (ACPL-K73L)

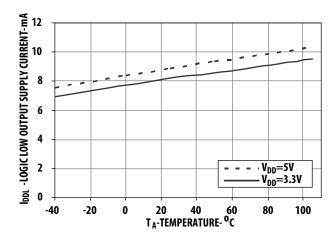


Figure 6: Typical Switching Speed vs. Pulse Input Current at 3.3V Supply Voltage

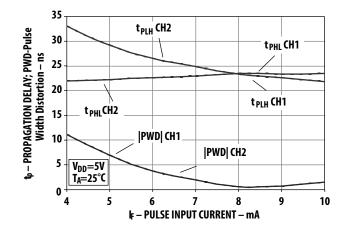
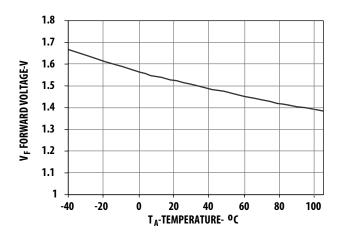


Figure 7: Typical V<sub>F</sub> vs. Temperature



## **Bypassing and PC Board Layout**

The ACPL-W70L and ACPL-K73L optocouplers are extremely easy to use. ACPL-W70L and ACPL-K73L provide CMOS logic output due to the high-speed CMOS IC technology used.

The external components required for proper operation are the input limiting resistor and the output bypass capacitor. Capacitor of 0.01  $\mu$ F to 0.1  $\mu$ F should be placed as close as possible to the power supply and ground pins of the optocoupler.

# Propagation Delay, Pulse-Width Distortion, and Propagation Delay Skew

Propagation delay is a figure of merit that describes how quickly a logic signal propagates through a system. The propagation delay from low to high (t<sub>PLH</sub>) is the amount of time required for an input signal to propagate to the output, causing the output to change from low to high.

Similarly, the propagation delay from high to low  $(t_{PHL})$  is the amount of time required for the input signal to propagate to the output, causing the output to change from high to low (see <Blue>Figure 9).

Pulse-width distortion (PWD) results when  $t_{PLH}$  and  $t_{PHL}$  differ in value. PWD is defined as the difference between  $t_{PLH}$  and  $t_{PHL}$ . This parameter determines the maximum data rate capability of a transmission system. PWD can be

expressed in percent by dividing the PWD (in ns) by the minimum pulse width (in ns) being transmitted. Typically, PWD on the order of 20% to 30% of the minimum pulse width is tolerable; the exact figure depends on the particular application (RS232, RS422, T-1, and so on).

Propagation delay skew,  $t_{PSK}$ , is an important parameter to consider in parallel data applications where synchronization of signals on parallel data lines is a concern. If the parallel data is being sent through a group of optocouplers, differences in propagation delays cause the data to arrive at the outputs of the optocouplers at different times. If this difference in propagation delays is large enough, it determines the maximum rate at which parallel data can be sent through the optocouplers.

Propagation delay skew is defined as the difference between the minimum and maximum propagation delays, either  $t_{PLH}$  or  $t_{PHL}$ , for any given group of optocouplers that are operating under the same conditions (that is, the same supply voltage, output load, and operating temperature). As illustrated in <Blue>Figure 10, if the inputs of a group of optocouplers are switched either ON or OFF at the same time,  $t_{PSK}$  is the difference between the shortest propagation delay, either  $t_{PHL}$  or  $t_{PHL}$ , and the longest propagation delay, either  $t_{PHL}$  or  $t_{PHL}$ . As mentioned earlier,  $t_{PSK}$  can determine the maximum parallel data transmission rate.

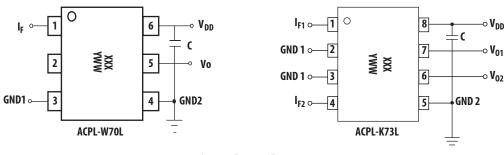
<Blue>Figure 10 is the timing diagram of a typical parallel data application with both the clock and the data lines being sent through optocouplers. The figure shows data and clock signals at the inputs and outputs of the optocouplers. To obtain the maximum data transmission rate, both edges of the clock signal are being used to clock the data; if only one edge were used, the clock signal would need to be twice as fast.

Propagation delay skew represents the uncertainty of where an edge might be after being sent through an optocoupler. <Blue>Figure 10 shows that there is uncertainty in both the data and the clock lines. It is important that these two areas of uncertainty not overlap; otherwise, the clock signal might arrive before all of the data outputs have settled, or some of the data outputs might start to change before the clock signal has arrived.

With these considerations, the absolute minimum pulse width that can be sent through optocouplers in a parallel application is twice  $t_{PSK}$ . A cautious design should use a slightly longer pulse width to ensure that any additional uncertainty in the rest of the circuit does not cause a problem.

The t<sub>PSK</sub> specified optocouplers offer the advantages of guaranteed specifications for propagation delays, pulse-width distortion, and propagation delay skew over the recommended temperature and power supply ranges.

Figure 8: Recommended Printed Circuit Board Layout



 $C=0.01 \mu F$  to  $0.1 \mu F$ 

Figure 9: Propagation Delay Skew Waveform

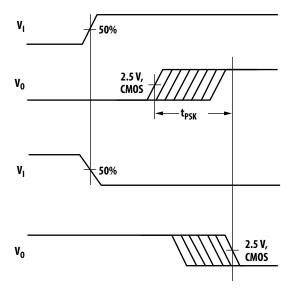
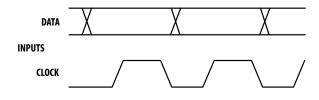
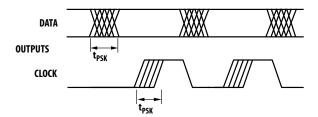


Figure 10: Parallel Data Transmission Example





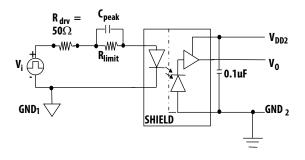
### **Powering Sequence**

V<sub>DD</sub> must achieve a minimum level of 3V before powering up the output connecting component.

#### **Input Limiting Resistor**

The ACPL-W70L and ACPL-K73L are direct current driven (<Blue>Figure 8), and thus eliminate the need for input power supply. To limit the amount of current flowing through the LED, it is recommended that a  $530\Omega$  resistor is connected in series with anode of LED (that is, Pin 1 for ACPL-W70L, Pin 1 and P4 for ACPL-K73L) at 5V input signal. At 3.3V input signal, it is recommended to connect a  $250\Omega$  resistor in series with anode of LED. The recommended limiting resistors is based on the assumption that the driver output impedance is  $50\Omega$  (as shown in <Blue>Figure 11).

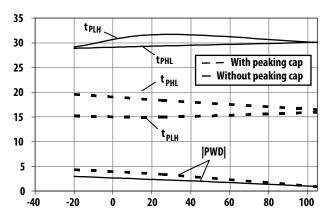
Figure 11: Connection of Peaking Capacitor ( $C_{peak}$ ) in Parallel of the Input Limiting Resistor ( $R_{llimit}$ ) to Improve Speed Performance



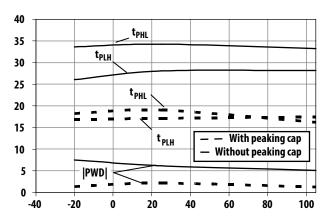
#### **Speed Improvement**

A peaking capacitor can be placed across the input current limit resistor (<Blue>Figure 11) to achieve enhanced speed performance. The value of the peaking cap is dependent on the rise and fall time of the input signal and supply voltages and LED input driving current ( $I_F$ ). <Blue>Figure 12 shows significant improvement of propagation delay and pulse width distortion with added 100-pF peak capacitor at driving current of 6 mA and 5V power supply.

Figure 12: Improvement of t<sub>p</sub> and PWD with Added 100-pF Peaking Capacitor in Parallel of Input Limiting Resistor



(i) 
$$V_{DD2} = 5V$$
,  $C_{peak} = 100$  pF,  $R_{limit} = 530\Omega$ 



(ii) 
$$V_{DD2} = 3.3V$$
,  $C_{peak} = 100 pF$ ,  $R_{limit} = 250\Omega$ 

AC-equivalent circuit.

## Common-Mode Rejection for ACPL-W70L AND ACPL-K73L

<Blue>Figure 13 shows the recommended driving circuit for the ACPL-W70L and ACPL-K73L for optimal common-mode rejection performance. Two LED-current setting resistors are used instead of one. This is to balance the common-mode impedance at LED anode and cathode. Common-mode transients can capacitively couple from the LED anode (or cathode) to the output-side ground causing current to be shunted away from the LED (which can be bad if the LED is on) or conversely cause current to be injected into the LED (bad if the LED is meant to be off). <Blue>Figure 14 shows the parasitic capacitances that exist between LED anode/cathode and output ground ( $C_{LA}$  and  $C_{LC}$ ). Also shown in <Blue>Figure 14 on the input side is an

<Blue>Table 1 indicates the directions of  $I_{LP}$  and  $I_{LN}$  flow depending on the direction of the common-mode transient. For transients occurring when the LED is on, common-mode rejection (CM<sub>L</sub>, since the output is in the low state) depends upon the amount of LED current drive ( $I_F$ ).

For conditions where  $I_F$  is close to the switching threshold ( $I_{TH}$ ),  $CM_L$  also depends on the extent that  $I_{LP}$  and  $I_{LN}$  balance each other. In other words, any condition where common-mode transients cause a momentary decrease in  $I_F$  (that is, when  $dV_{CM}/dt>0$  and  $|I_{FP}| > |I_{FN}|$ , referring to <Blue>Table 1) causes common-mode failure for transients that are fast enough.

Likewise, for common-mode transients that occur when the LED is off (that is,  $CM_H$ , since the output is high), if an imbalance between  $I_{LP}$  and  $I_{LN}$  results in a transient  $I_F$  equal to or greater than the switching threshold of the optocoupler, the transient  $\emph{signal}$  can cause the output to spike below 2V (which constitutes a  $CM_H$  failure).

By using the recommended circuit in <Blue>Figure 13, good  $CM_R$  can be achieved. The resistors recommended in <Blue>Figure 13 include both the output impedance of the logic driver circuit and the external limiting resistor. The balanced  $I_{LED}$ -setting resistors help equalize the commonmode voltage change at anode and cathode to reduce the amount by which  $I_{LED}$  is modulated from transient coupling through  $C_{LA}$  and  $C_{LC}$ .

Figure 13: Recommended Drive Circuit for ACPL-W70L and ACPL-K73L for High-CM<sub>R</sub>

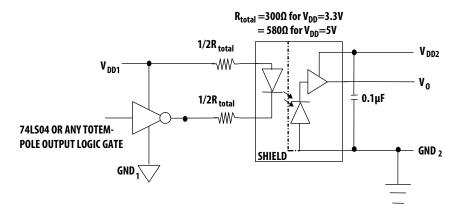


Figure 14: AC Equivalent of ACPL-W70L and ACPL-K73L

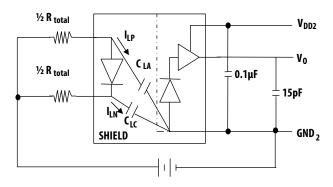


Table 1: Effects of Common-Mode Pulse Direction on Transient ILED

If dV <sub>CM</sub> /dt Is:	Then I <sub>LP</sub> Flows:	And I <sub>LN</sub> Flows:	If  I <sub>LP</sub>   <  I <sub>LN</sub>  , LED I <sub>F</sub> Current Is Momentarily:	If  I <sub>LP</sub>   >  I <sub>LN</sub>  , LED I <sub>F</sub> Current Is Momentarily:
Positive (>0)	Away from LED	Away from LED	Increased	Decreased
	anode through C <sub>LA</sub>	cathode through C <sub>LC</sub>		
Negative (<0)	Toward LED	Toward LED	Decreased	Increased
	anode through C <sub>LA</sub>	cathode through C <sub>LC</sub>		

#### **CMR** with Other Drive Circuits

CMR performance with drive circuits other than that shown in <Blue>Figure 13 can be enhanced by following these guidelines:

- 1. Use of drive circuits where current is shunted from the LED in the LED OFF state (as shown in <Blue>Figure 15 and <Blue>Figure 16). This is beneficial for good CM<sub>H</sub>.
- 2. Use of typical  $I_{EH}$  = 6 mA per data sheet recommendation.

Using any one of the drive circuits in <Blue>Figure 15, <Blue>Figure 16, and <Blue>Figure 17 with  $I_F = 6$  mA results in a typical CMR of 10 kV/s for ACPL-W70L and ACPL-K73L, as long as the PC board layout practices are followed. <Blue>Figure 15 shows a circuit that can be used with any totem-pole-output TTL/LSTTL/HCMOS logic gate. The buffer PNP transistor allows the circuit to be used with logic devices that have low current-sinking capability. It also helps maintain the driving-gate power-supply current at a constant level to minimize ground shifting for other devices connected to the input-supply ground.

Figure 15: TTL Interface Circuit for the ACPI-W70L Families

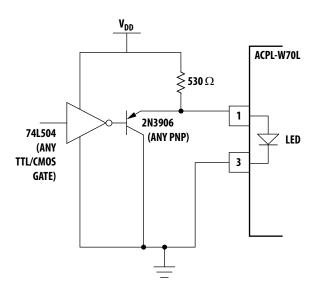


Figure 16: TTL Open-Collector/Open Drain Gate Drive Circuit for ACPL-W70L Families

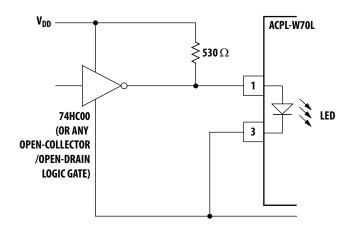
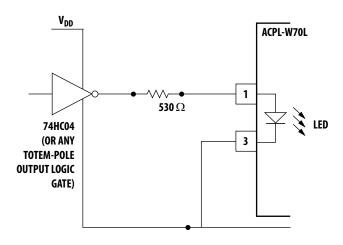
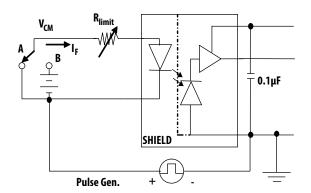


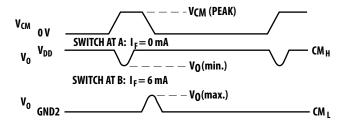
Figure 17: CMOS Gate Drive Circuit for ACPL-W70L Families



When using an open-collector TTL or open-drain CMOS logic gate, the circuit in <Blue>Figure 16 can be used. When using a CMOS gate to drive the optocoupler, the circuit shown in <Blue>Figure 17, where the resistor is recommended to connect to the anode of the LED, can be used.

Figure 18: Test Circuit for Common-Mode Transient Immunity and Typical Waveforms





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