

integrated product identification code electronically identifies the device and manufacturer. This feature is used by industry-standard programming equipment to select the proper programming algorithms and voltages. The AT27BV512 programs in exactly the same way as a standard, 5V Atmel AT27C512R, and uses the same programming equipment.

#### 2. Pin configurations

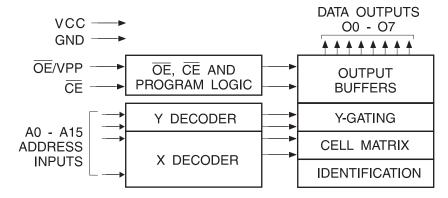
Pin name	Function	32-lead PLCC Top view	28-lead TSOP ( Type 1) Top view
A0 - A15	Addresses	A77 A12 A15 . NC . VCC	((
00 - 07	Outputs		OE/VPP 22 A11 23 21 A10 20 CE
CE	Chip enable	A6 5 0 28 DA9	A9 24 19 07 A8 25 18 06
OE/VPP	Output enable/Program supply	A4 🛘 7 27 🗘 A11	A13 26 17 05 A14 27 16 04
NC	No connect	A3 \( \text{8} \) 26 \( \text{NC} \) NC A2 \( \text{9} \) 25 \( \text{OE/VPP} \)	VCC 28 15 03 A15 1 14 GND
		A1	A12 2 13 02 A7 3 12 01 A6 4 11 00 A5 5 5 10 A0 A4 6 9 A1 A3 7 ( 8 A2
		Note: PLCC package pins 1	

#### 3. System considerations

Switching between active and standby conditions via the chip enable pin may produce transient voltage excursions. Unless accommodated by the system design, these transients may exceed datasheet limits, resulting in device non-conformance. At a minimum, a  $0.1\mu\text{F}$ , high-frequency, low inherent inductance, ceramic capacitor should be utilized for each device. This capacitor should be connected between the  $V_{CC}$  and ground terminals of the device, as close to the device as possible. Additionally, to stabilize the supply voltage level on printed circuit boards with large EPROM arrays, a  $4.7\mu\text{F}$  bulk electrolytic capacitor should be utilized, again connected between the  $V_{CC}$  and ground terminals. This capacitor should be positioned as close as possible to the point where the power supply is connected to the array.

and 17 are "don't connect."

Figure 3-1. Block diagram



#### 4. Absolute maximum ratings\*

Temperature under bias40°C to +85°C
Storage temperature65°C to +125°C
Voltage on any pin with respect to ground2.0V to +7.0V <sup>(1)</sup>
Voltage on A9 with respect to ground2.0V to +14.0V <sup>(1)</sup>
$V_{PP}$ supply voltage with respect to ground2.0V to +14.0V <sup>(1)</sup>

\*NOTICE: Stresses beyond those listed under "Absolute maximum ratings" may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended

periods may affect device reliability.

Note:

1. Minimum voltage is -0.6V DC, which may undershoot to -2.0V for pulses of less than 20ns. Maximum output pin voltage is  $V_{CC} + 0.75V$  DC, which may be exceeded if certain precautions are observed (consult application notes), and which may overshoot to +7.0V for pulses of less than 20ns.

#### 5. DC and AC characteristics

Table 5-1. Operating modes

Mode/Pin	Œ	OE/V <sub>PP</sub>	Ai	V <sub>CC</sub>	Outputs
Read <sup>(2)</sup>	V <sub>IL</sub>	V <sub>IL</sub>	Ai	V <sub>CC</sub>	D <sub>OUT</sub>
Output disable <sup>(2)</sup>	V <sub>IL</sub>	V <sub>IH</sub>	X <sup>(1)</sup>	V <sub>CC</sub>	High Z
Standby <sup>(2)</sup>	V <sub>IH</sub>	X	X	V <sub>CC</sub>	High Z
Rapid program <sup>(3)</sup>	V <sub>IL</sub>	V <sub>PP</sub>	Ai	V <sub>CC</sub>	D <sub>IN</sub>
PGM verify <sup>(3)</sup>	V <sub>IL</sub>	V <sub>IL</sub>	Ai	V <sub>CC</sub>	D <sub>OUT</sub>
PGM inhibit <sup>(3)</sup>	V <sub>IH</sub>	V <sub>PP</sub>	X	V <sub>CC</sub>	High Z
Product identification <sup>(3)(5)</sup>	V <sub>IL</sub>	V <sub>IL</sub>	$A9 = V_{H}^{(4)}$ $A0 = V_{IH} \text{ or } V_{IL}$ $A1 - A15 = V_{IL}$	V <sub>CC</sub>	Identification code

Notes:

- X can be V<sub>IL</sub> or V<sub>IH</sub>.
- 2. Read, output disable, and standby modes require 2.7V  $\leq$  V<sub>CC</sub>  $\leq$  3.6V or 4.5V  $\leq$  V<sub>CC</sub>  $\leq$  5.5V.
- 3. Refer to programming characteristics. Programming modes require  $V_{CC} = 6.5V$ .
- 4.  $V_H = 12.0 \pm 0.5 V$ .
- 5. Two identifier bytes may be selected. All Ai inputs are held low  $(V_{IL})$  except A9, which is set to  $V_{H}$ , and A0, which is toggled low  $(V_{IL})$  to select the manufacturer's identification byte and high  $(V_{IH})$  to select the device code byte.

Table 5-2. DC and AC operating conditions for read operation

	Atmel AT27BV512-70
Operating temperature (case)	-40°C - 85°C
W. Tanana aranka	2.7V to 3.6V
V <sub>CC</sub> power supply	5V ± 10%





Table 5-3. DC and operating characteristics for read operation

Symbol	Parameter	Condition	Min	Max	Units
$V_{CC} = 2.7V$	to 3.6V				
ILI	Input load current	$V_{IN} = OV \text{ to } V_{CC}$		±1	μΑ
I <sub>LO</sub>	Output leakage current	V <sub>OUT</sub> = 0V to V <sub>CC</sub>		±5	μΑ
I <sub>PP1</sub> (2)	V <sub>PP</sub> <sup>(1)</sup> read/standby current	$V_{PP} = V_{CC}$		10	μΑ
	V (1)	$I_{SB1}$ (CMOS), $\overline{CE} = V_{CC\pm} 0.3V$		20	μΑ
I <sub>SB</sub>	V <sub>CC</sub> <sup>(1)</sup> standby current	$I_{SB2}$ (TTL), $\overline{CE}$ = 2.0 to $V_{CC}$ + 0.5V		100	μΑ
I <sub>CC</sub>	V <sub>CC</sub> active current	$f = 5MHz$ , $I_{OUT} = 0mA$ , $\overline{CE} = V_{IL}$ , $V_{CC} = 3.6V$		8	mA
.,		V <sub>CC</sub> = 3.0 to 3.6V	-0.6	0.8	V
$V_{IL}$	Input low voltage	V <sub>CC</sub> = 2.7 to 3.6V	-0.6	0.2 x V <sub>CC</sub>	V
		V <sub>CC</sub> = 3.0 to 3.6V	2.0	V <sub>CC</sub> + 0.5	V
$V_{IH}$	Input high voltage	V <sub>CC</sub> = 2.7 to 3.6V	0.7 x V <sub>CC</sub>	V <sub>CC</sub> + 0.5	V
		I <sub>OL</sub> = 2.0mA		0.4	V
$V_{OL}$	Output low voltage	$I_{OL} = 100 \mu A$		0.2	V
		I <sub>OL</sub> = 20µA		0.1	V
		I <sub>OH</sub> = -2.0mA	2.4		V
$V_{OH}$	Output high voltage	I <sub>OH</sub> = -100μA	V <sub>CC</sub> - 0.2		V
		I <sub>OH</sub> = -20μΑ	V <sub>CC</sub> - 0.1		V
$V_{CC} = 4.5V$	' to 5.5V		-	1	
ILI	Input load current	$V_{IN} = OV \text{ to } V_{CC}$		±1	μΑ
I <sub>LO</sub>	Output leakage current	V <sub>OUT</sub> = 0V to V <sub>CC</sub>		±5	μΑ
I <sub>PP1</sub> (2)	V <sub>PP</sub> <sup>(1)</sup> read/standby current	$V_{pp} = V_{CC}$		10	μΑ
	), (1)	$I_{SB1}$ (CMOS), $\overline{CE} = V_{CC} \pm 0.3V$		100	μΑ
I <sub>SB</sub>	V <sub>CC</sub> <sup>(1)</sup> standby current	$I_{SB2}$ (TTL), $\overline{CE}$ = 2.0 to $V_{CC}$ + 0.5V		1	mA
I <sub>CC</sub>	V <sub>CC</sub> active current	$f = 5MHz$ , $I_{OUT} = 0mA$ , $\overline{CE} = V_{IL}$		20	mA
V <sub>IL</sub>	Input low voltage		-0.6	0.8	V
V <sub>IH</sub>	Input high voltage		2.0	V <sub>CC</sub> + 0.5	V
V <sub>OL</sub>	Output low voltage	I <sub>OL</sub> = 2.1mA		0.4	V
V <sub>OH</sub>	Output high voltage	I <sub>OH</sub> = -400μA	2.4		V

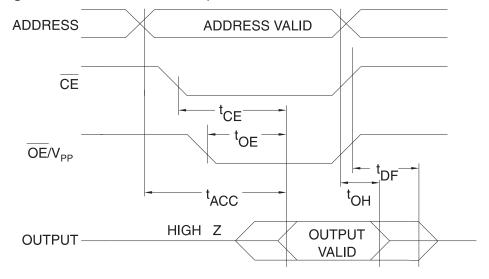
Notes: 1.  $V_{CC}$  must be applied simultaneously with or before  $\overline{OE}/V_{pp}$ , and removed simultaneously with or after  $\overline{OE}/V_{pp}$ .

<sup>2.</sup>  $V_{PP}$  may be connected directly to  $V_{CC}$ , except during programming. The supply current would then be the sum of  $I_{CC}$  and  $I_{PP}$ .

Table 5-4. AC characteristics for read operation

			Atmel AT27BV512-70		
Symbol	Parameter	Condition	Min	Max	Units
t <sub>ACC</sub> (3)	Address to output delay	$\overline{CE} = \overline{OE}/V_{PP} = V_{IL}$		70	ns
t <sub>CE</sub> <sup>(2)</sup>	CE to output delay	$\overline{OE}/V_{PP} = V_{IL}$		70	ns
t <sub>OE</sub> <sup>(2)(3)</sup>	ŌĒ/V <sub>PP</sub> to output delay	CE = V <sub>IL</sub>		50	ns
t <sub>DF</sub> <sup>(4)(5)</sup>	OE/V <sub>pp</sub> or CE high to output float, whichever occurred first			40	ns
t <sub>OH</sub>	Output hold from address, $\overline{\text{CE}}$ or $\overline{\text{OE}}/\text{V}_{\text{PP},}$ whichever occurred first		0		ns

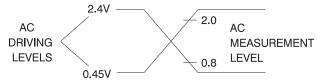
Figure 5-1. AC waveforms for read operation<sup>(1)</sup>



Notes: 1. Timing measurement references are 0.8V and 2.0V. Input AC drive levels are 0.45V and 2.4V, unless otherwise specified.

- 2.  $\overline{\text{OE}}/\text{V}_{PP}$  may be delayed up to  $t_{CE}$   $t_{OE}$  after the falling edge of  $\overline{\text{CE}}$  without impact on  $t_{CE}$ .
- 3.  $\overline{\text{OE}}/\text{V}_{PP}$  may be delayed up to  $t_{ACC}$   $t_{OE}$  after the address is valid without impact on  $t_{ACC}$ .
- 4. This parameter is only sampled, and is not 100% tested.
- 5. Output float is defined as the point when data is no longer driven.
- 6. When reading an Atmel AT27BV256, a  $0.1\mu F$  capacitor is required across  $V_{CC}$  and ground to suppress spurious voltage transients.

Figure 5-2. Input test waveform and measurement level

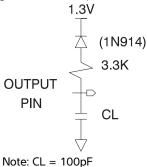


 $t_{R}$ ,  $t_{F}$  < 20 ns (10% to 90%)





Figure 5-3. Output test load



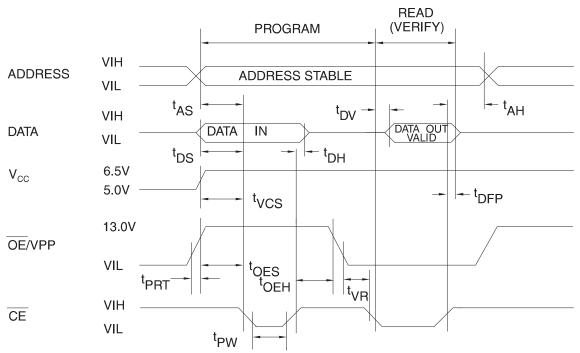
including jig capacitance.

Table 5-5. Pin capacitance f = 1MHz,  $T = 25^{\circ}C^{(1)}$ 

Symbol	Тур	Max	Units	Conditions
C <sub>IN</sub>	4	6	pF	$V_{IN} = OV$
C <sub>OUT</sub>	8	12	pF	V <sub>OUT</sub> = 0V

Note: 1. Typical values for nominal supply voltage. This parameter is only sampled, and is not 100% tested.

Figure 5-4. Programming waveforms<sup>(1)</sup>



Notes: 1. The input timing reference is 0.8V for  $V_{\rm IL}$  and 2.0V for  $V_{\rm IH}$ .

- 2.  $t_{\text{OE}}$  and  $t_{\text{DFP}}$  are characteristics of the device, but must be accommodated by the programmer.
- 3. When programming the Atmel AT27BV512, a  $0.1\mu F$  capacitor is required across  $V_{pp}$  and ground to suppress spurious voltage transients.

Table 5-6. DC programming characteristics

 $T_A = 25 \pm 5$ °C,  $V_{CC} = 6.5 \pm 0.25$ V,  $\overline{OE}/V_{PP} = 13.0 \pm 0.25$ V

			Limits		
Symbol	Parameter	Test conditions	Min	Max	Units
ILI	Input load current	$V_{IN} = V_{IL}, V_{IH}$		±10	μΑ
V <sub>IL</sub>	Input low level		-0.6	0.8	V
V <sub>IH</sub>	Input high level		2.0	V <sub>CC</sub> + 0.5	V
V <sub>OL</sub>	Output low voltage	$I_{OL} = 2.1 \text{mA}$		0.4	V
V <sub>OH</sub>	Output high voltage	Ι <sub>ΟΗ</sub> = -400μΑ	2.4		V
I <sub>CC2</sub>	V <sub>CC</sub> supply current (program and verify)			25	mA
I <sub>PP2</sub>	ŌĒ/V <sub>PP</sub> current	CE = V <sub>IL</sub>		25	mA
V <sub>ID</sub>	A9 product identification voltage		11.5	12.5	V

Table 5-7. AC programming characteristics

 $T_A = 25 \pm 5$ °C,  $V_{CC} = 6.5 \pm 0.25$ V,  $\overline{OE}/V_{PP} = 13.0 \pm 0.25$ V

			Lir	nits	
Symbol	Parameter	Test conditions <sup>(1)</sup>	Min	Max	Units
t <sub>AS</sub>	Address setup time		2		μs
t <sub>OES</sub>	ŌE/V <sub>pp</sub> setup time		2		μs
t <sub>OEH</sub>	ŌĒ/V <sub>PP</sub> hold time	Input rise and fall times:	2		μs
t <sub>DS</sub>	Data setup time	(10% to 90) 20 ns	2		μs
t <sub>AH</sub>	Address hold time	Input pulse levels:	0		μs
t <sub>DH</sub>	Data hold time	0.45V to 2.4V	2		μs
t <sub>DFP</sub>	CE high to output float delay <sup>(2)</sup>		0	130	ns
t <sub>VCS</sub>	V <sub>CC</sub> setup time	Input timing reference level:  0.8V to 2.0V	2		μs
t <sub>PW</sub>	CE program pulse width <sup>(3)</sup>	0.80 to 2.00	95	105	μs
t <sub>DV</sub>	Data valid from $\overline{\text{CE}}^{(2)}$	Output timing reference level:		1	μs
t <sub>VR</sub>	ŌĒ/V <sub>pp</sub> recovery time	0.8V to 2.0V	2		μs
t <sub>PRT</sub>	OE/V <sub>PP</sub> pulse rise time during programming		50		ns

Notes: 1.  $V_{CC}$  must be applied simultaneously with or before  $\overline{OE}/V_{PP}$  and removed simultaneously with or after  $\overline{OE}/V_{PP}$ .

- 2. This parameter is only sampled, and is not 100% tested. Output float is defined as the point where data is no longer driven. See timing diagram.
- 3. Program pulse width tolerance is  $100\mu \sec \pm 5\%$ .

Table 5-8. The Atmel AT27BV512 integrated product identification code<sup>(1)</sup>

		Pins				Hex				
Codes	A0	07	O6	O5	04	О3	02	01	00	Data
Manufacturer	0	0	0	0	1	1	1	1	0	1E
Device Type	1	0	0	0	0	1	1	0	1	0D

Note: 1. The Atmel AT27BV512 has the same product identification code as the Atmel AT27C512R. Both are programming compatible.

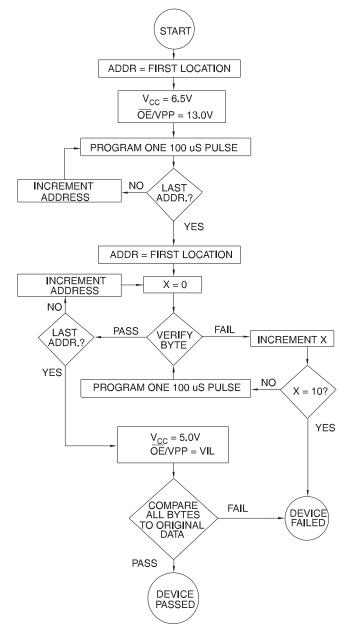




#### 6. Rapid programming algorithm

A 100 $\mu$ s  $\overline{\text{CE}}$  pulse width is used to program. The address is set to the first location.  $V_{CC}$  is raised to 6.5V and  $\overline{\text{OE}}/V_{PP}$  is raised to 13.0V. Each address is first programmed with one 100 $\mu$ s  $\overline{\text{CE}}$  pulse without verification. Then a verification/reprogramming loop is executed for each address. In the event a byte fails to pass verification, up to 10 successive 100 $\mu$ s pulses are applied with a verification after each pulse. If the byte fails to verify after 10 pulses have been applied, the part is considered failed. After the byte verifies properly, the next address is selected until all have been checked.  $\overline{\text{OE}}/V_{PP}$  is then lowered to  $V_{IL}$  and  $V_{CC}$  to 5.0V. All bytes are read again and compared with the original data to determine if the device passes or fails.

Figure 6-1. Rapid programming algorithm



# 7. Ordering Information

Green package option (Pb/halide-free)

t <sub>ACC</sub>	I <sub>CC</sub> (	mA)	Atmel ordering code	Package	Operation range	
(ns)	Active	Standby	Atmerordening code	Fackage	Орегацоптанде	
70	Q	0.02	AT27BV512-70JU	32J	Industrial	
70	0	0.02	AT27BV512-70TU	28T	(-40°C to 85°C)	

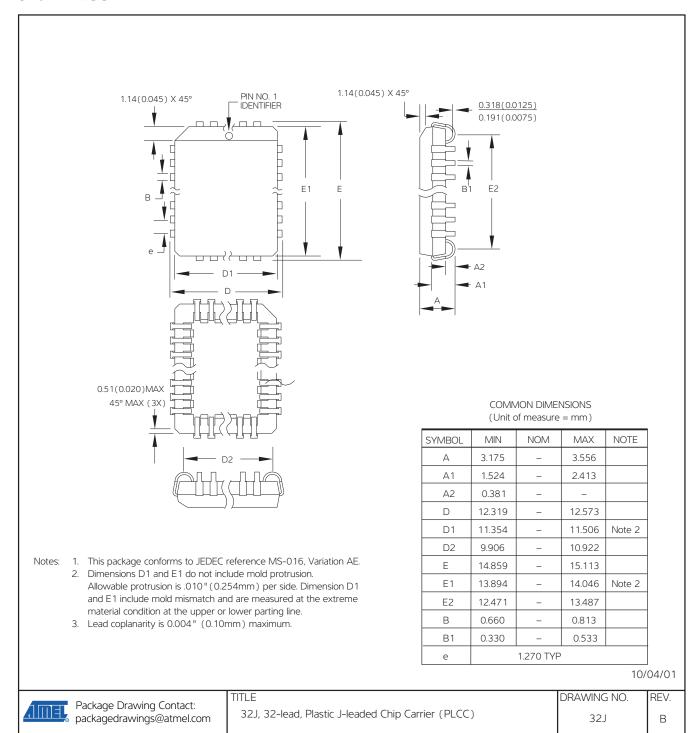
Package type		
32-lead, plastic, J-leaded chip carrier (PLCC)		
28T 28-lead, plastic, thin, small outline package (TSOP)		



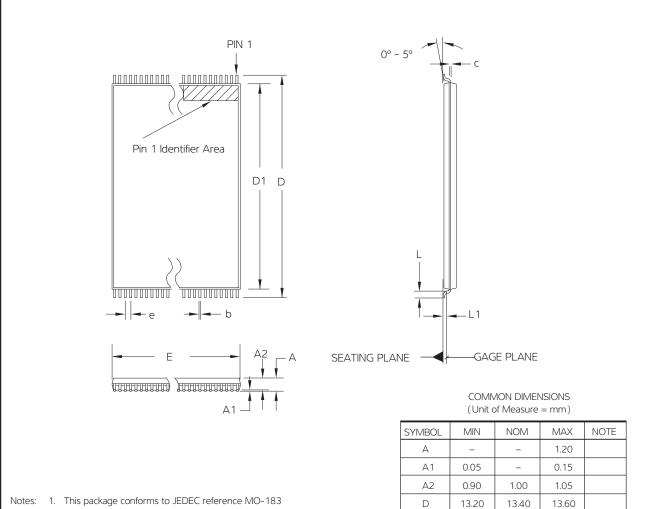


## 8. Packaging information

### 32J – PLCC



#### 28T - TSOP



- 2. Dimensions D1 and E do not include mold protrusion. Allowable protrusion on E is 0.15mm per side and on D1 is 0.25 mm per side.
- 3. Lead coplanarity is 0.10mm maximum

SYMBOL	MIN	NOM	MAX	NOTE
А	_	_	1.20	
Α1	0.05	-	0.15	
A2	0.90	1.00	1.05	
D	13.20	13.40	13.60	
D1	11.70	11.80	11.90	Note 2
Е	7.90	8.00	8.10	Note 2
L	0.50	0.60	0.70	
L1	0.25 BASIC			
b	0.17	0.22	0.27	
С	0.10	_	0.21	
е	0.55 BASIC			

12/06/02



Package Drawing Contact: packagedrawings@atmel.com TITLE 28T, 28-lead (8 x 13.4mm) Plastic Thin Small Outline Package, Type I (TSOP)

DRAWING NO. REV. 28T

 $\mathsf{C}$ 





# 9. Revision history

Doc. Rev.	Date	Comments
0602F	04/2011	Remove SOIC package
0602E	12/2007	



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