

Absolute Maximum Ratings ($T_A = +25^\circ\text{C}$)

| | |
|---------------------------------------------------------------|-------------------|
| V_{DD} Supply Voltage between V_{DD} and GND | 3.6V |
| I^2C Bus Pin Voltage (SCL, SDA) and $\overline{\text{INT}}$ | -0.2V to 5.5V |
| I^2C Bus Pin Current (SCL, SDA) | <10mA |
| R_{ext} Pin Voltage | -0.2V to V_{DD} |
| ESD Rating | |
| Human Body Model | .2kV |
| Machine Model | .200V |

Thermal Information

| | |
|--------------------------------------|-----------------------------------------------------------------------------------------------------------------|
| Thermal Resistance (Typical, Note 4) | θ_{JA} ($^\circ\text{C}/\text{W}$) |
| 6 Lead ODFN | 88 |
| Maximum Die Temperature | +90 $^\circ\text{C}$ |
| Storage Temperature | -40 $^\circ\text{C}$ to +100 $^\circ\text{C}$ |
| Operating Temperature | -40 $^\circ\text{C}$ to +85 $^\circ\text{C}$ |
| Pb-free Reflow Profile | see link below |
| | http://www.intersil.com/pbfree/Pb-FreeReflow.asp |

CAUTION: Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

NOTE:

- θ_{JA} is measured in free air with the component mounted on a high effective thermal conductivity test board with "direct attach" features. See Tech Brief [TB379](#).

IMPORTANT NOTE: All parameters having Min/Max specifications are guaranteed. Typical values are for information purposes only. Unless otherwise noted, all tests are at the specified temperature and are pulsed tests, therefore: $T_J = T_C = T_A$

Electrical Specifications $V_{DD} = 3\text{V}$, $T_A = +25^\circ\text{C}$, $R_{EXT} = 100\text{k}\Omega$, unless otherwise specified. Internal Timing Mode operation (See "Principles of Operation" on page 3).

| PARAMETER | DESCRIPTION | CONDITION | MIN (Note 7) | TYP | MAX (Note 7) | UNIT |
|--------------------|------------------------------------|-----------------------------------------------------------|--------------|----------|--------------|---------------|
| $E_{e\text{-max}}$ | Maximum Detectable Light Intensity | @ Gain/Range = 4, and $R_{EXT} = 25\text{k}\Omega$ | | 128k | | lux |
| V_{DD} | Power Supply Range | | 2.5 | | 3.30 | V |
| I_{DD} | Supply Current | | | 0.25 | 0.33 | mA |
| I_{DD1} | Supply Current Disabled | Software disabled | | 0.1 | 1 | μA |
| f_{OSC1} | Internal Oscillator Frequency | Gain/Range = 1 or 2 | 308 | 342 | 377 | kHz |
| f_{OSC2} | Internal Oscillator Frequency | Gain/Range = 3 or 4 | 616 | 684 | 754 | kHz |
| f_{I2C} | I^2C Clock Rate | | | 1 to 400 | | kHz |
| DATA0 | Dark ADC Code | $E = 0$ lux, Gain/Range = 1 | | 0 | 6 | Counts |
| DATA1 | Full Scale ADC Code | | | 32767 | | Counts |
| DATA2 | Light Count output | $E = 300$ lux, fluorescent light, Gain/Range = 1 (Note 5) | 3300 | 4400 | 5500 | Counts |
| DATA3 | Light Count output | $E = 300$ lux, fluorescent light, Gain/Range = 2 (Note 5) | | 1100 | | Counts |
| DATA4 | Light Count output | $E = 300$ lux, fluorescent light, Gain/Range = 3 (Note 5) | | 275 | | Counts |
| DATA5 | Light Count output | $E = 300$ lux, fluorescent light, Gain/Range = 4 (Note 5) | | 69 | | Counts |
| V_{REF} | Voltage of R_{EXT} Pin | | 0.490 | 0.515 | 0.540 | V |
| V_{TL} | SCL and SDA Threshold LO | (Note 6) | | 1.05 | | V |
| V_{TH} | SCL and SDA Threshold HI | (Note 6) | | 1.95 | | V |
| I_{SDA} | SDA Current Sinking Capability | | 3 | 5 | | mA |
| I_{INT} | INT Current Sinking Capability | | 3 | 5 | | mA |

NOTES:

- Fluorescent light is substituted by a green LED during production.
- The voltage threshold levels of the SDA and SCL pins are V_{DD} dependent: $V_{TL} = 0.35 \cdot V_{DD}$. $V_{TH} = 0.65 \cdot V_{DD}$.
- Compliance to datasheet limits is assured by one or more methods: production test, characterization and/or design.

Pin Descriptions

| PIN NUMBER | PIN NAME | DESCRIPTION | |
|------------|-------------------------|--------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------|
| 1 | VDD | Positive supply; connect this pin to a regulated 2.5V to 3.3V supply | |
| 2 | GND | Ground pin. The thermal pad is connected to the GND pin | |
| 3 | REXT | External resistor pin for ADC reference; connect this pin to ground through a (nominal) 100kΩ resistor with 1% tolerance | |
| 4 | $\overline{\text{INT}}$ | Interrupt pin; LO for interrupt/alarming. The INT pin is an open drain. | |
| 5 | SCL | I ² C serial clock | The I ² C bus lines can pulled above VDD, 5.5V max. |
| 6 | SDA | I ² C serial data | |

Principles of Operation

Photodiodes

The ISL29013 contains two photodiode arrays which convert light into current. One diode is sensitive to both visible and infrared light, while the other one is only sensitive to infrared light. Using the infrared portion of the light as baseline, the visible light can be extracted. The spectral response vs wavelength is shown in Figure 6 in the “Typical Performance Curves” on page 11. After light is converted to current during the light data process, the current output is converted to digital by a single built-in integrating type signed 15-bit Analog-to-Digital Converter (ADC). An I²C command reads the visible light intensity in counts.

The converter is a charge-balancing integrating type signed 15-bit ADC. The chosen method for conversion is best for converting small current signals in the presence of an AC periodic noise. A 100ms integration time, for instance, highly rejects 50Hz and 60Hz power line noise simultaneously. See “Integration Time or Conversion Time” on page 7 and “Noise Rejection” on page 8.

The built-in ADC offers user flexibility in integration time or conversion time. There are two timing modes: Internal Timing Mode and External Timing Mode. In Internal Timing Mode, integration time is determined by an internal dual speed oscillator (f_{OSC}), and the n-bit ($n = 4, 8, 12, 16$) counter inside the ADC. In External Timing Mode, integration time is determined by the time between two consecutive I²C External Timing Mode commands. See External Timing Mode example. A good balancing act of integration time and resolution depending on the application is required for optimal results.

The ADC has four I²C programmable range select to dynamically accommodate various lighting conditions. For very dim conditions, the ADC can be configured at its lowest range. For very bright conditions, the ADC can be configured at its highest range.

Interrupt Function

The active low interrupt pin is an open drain pull-down configuration. The interrupt pin serves as an alarm or monitoring function to determine whether the ambient light exceeds the upper threshold or goes below the lower threshold. The user can also configure the persistency of the interrupt pin. This eliminates any false triggers such as noise or sudden spikes in ambient light conditions. An unexpected camera flash, for example, can be ignored by setting the persistency to 8 integration cycles.

I²C Interface

There are eight (8) 8-bit registers available inside the ISL29013. The command and control registers define the operation of the device. The command and control registers do not change until the registers are overwritten. There are two 8-bit registers that set the high and low interrupt thresholds. There are four 8-bit data Read Only registers. Two bytes for the sensor reading and another two bytes for the timer counts. The data registers contain the ADC's latest digital output, and the number of clock cycles in the previous integration period.

The ISL29013's I²C interface slave address is hardwired internally as 1000100. When 1000100x with x as R or \overline{W} is sent after the Start condition, this device compares the first seven bits of this byte to its address and matches.

Figure 1 shows a sample one-byte read. Figure 2 shows a sample one-byte write. Figure 3 shows a sync_I²C timing diagram sample for externally controlled integration time. The I²C bus master always drives the SCL (clock) line, while either the master or the slave can drive the SDA (data) line. Figure 2 shows a sample write. Every I²C transaction begins with the master asserting a start condition (SDA falling while SCL remains high). The following byte is driven by the master, and includes the slave address and read/write bit. The receiving device is responsible for pulling SDA low during the acknowledgement period.

Every I²C transaction ends with the master asserting a stop condition (SDA rising while SCL remains high).

For more information about the I²C standard, please consult the Phillips® I²C specification documents.

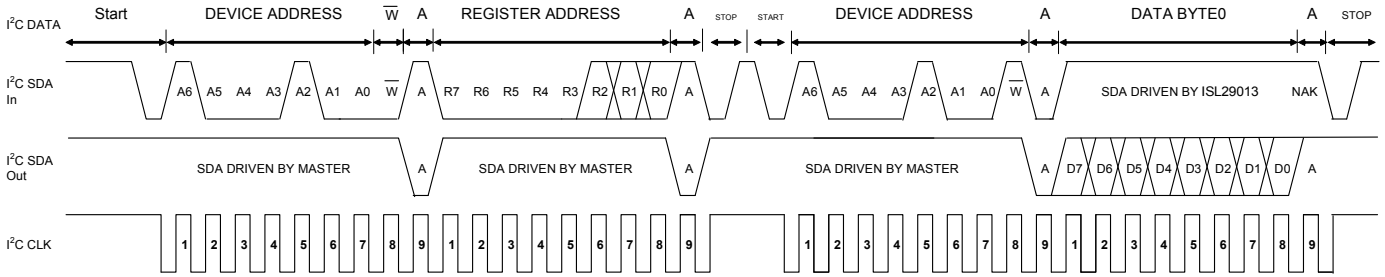


FIGURE 1. I²C READ TIMING DIAGRAM SAMPLE

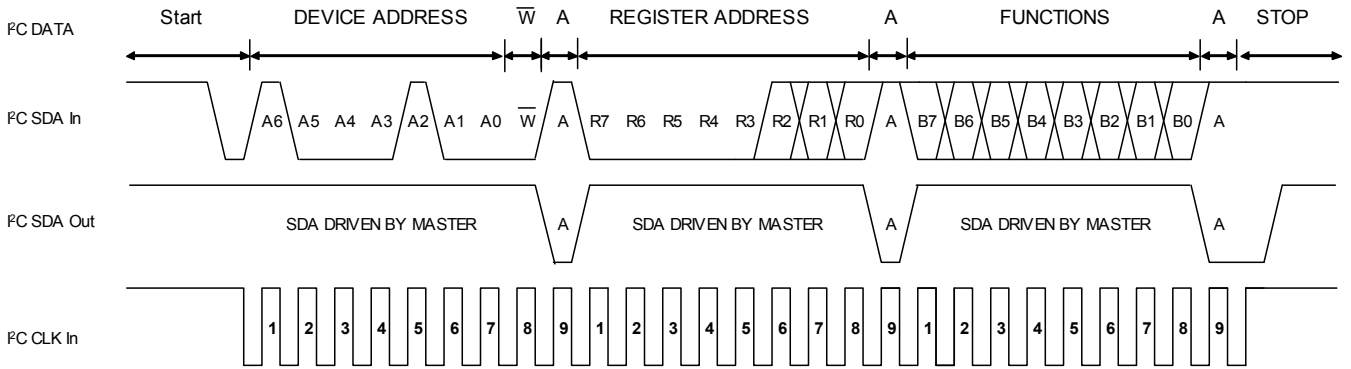


FIGURE 2. I²C WRITE TIMING DIAGRAM SAMPLE

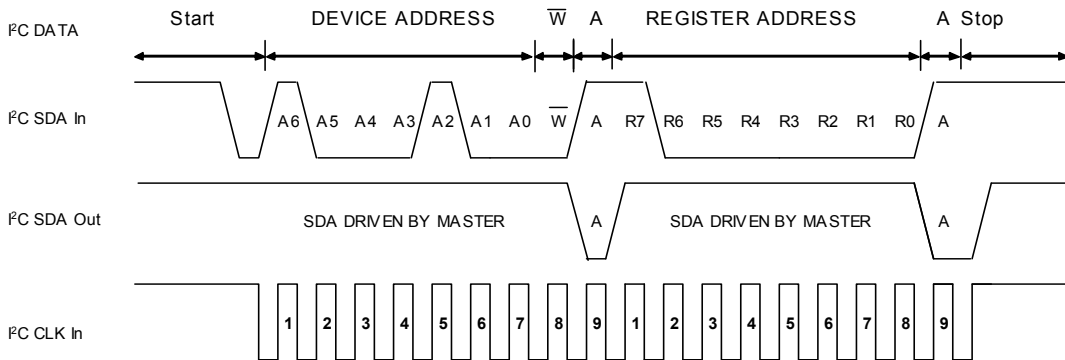


FIGURE 3. I²C SYNC_I²C TIMING DIAGRAM SAMPLE

Register Set

There are eight registers that are available in the ISL29013. Table 1 summarizes the available registers and their functions.

TABLE 1. REGISTER SET

| ADDR | REG NAME | BIT | | | | | | | | DEFAULT |
|------|------------------------|---------|---------|----------|---------|---------|---------|---------|---------|---------|
| | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| 00h | COMMAND | ADCE | ADCPD | TIMM | 0 | ADCM1 | ADCM0 | RES1 | RES0 | 00h |
| 01h | CONTROL | 0 | 0 | INT_FLAG | 0 | GAIN1 | GAIN0 | IC1 | IC0 | 00h |
| 02h | Interrupt Threshold_HI | ITH_HI7 | ITH_HI6 | ITH_HI5 | ITH_HI4 | ITH_HI3 | ITH_HI2 | ITH_HI1 | ITH_HI0 | FFh |
| 03h | Interrupt Threshold_LO | ITH_LO7 | ITH_LO6 | ITH_LO5 | ITH_LO4 | ITH_LO3 | ITH_LO2 | ITH_LO1 | ITH_LO0 | 00h |
| 04h | LSB SENSOR | S7 | S6 | S5 | S4 | S3 | S2 | S1 | S0 | 00h |
| 05h | MSB SENSOR | S15 | S14 | S13 | S12 | S11 | S10 | S9 | S8 | 00h |
| 06h | LSB TIMER | T7 | T6 | T5 | T4 | T3 | T2 | T1 | T0 | 00h |
| 07h | MSB TIMER | T15 | T14 | T13 | T12 | T11 | T10 | T9 | T8 | 00h |

TABLE 2. WRITE ONLY REGISTERS

| ADDRESS | REGISTER NAME | FUNCTIONS/ DESCRIPTION |
|------------|-----------------------|---------------------------------------------------------------------------------------------------------------------------------|
| b1xxx_xxxx | sync_I ² C | Writing a logic 1 to this address bit ends the current ADC-integration and starts another. Used only with External Timing Mode. |
| bx1xx_xxxx | clar_int | Writing a logic 1 to this address bit clears the interrupt. |

Command Register 00(hex)

The Read/Write command register has five functions:

1. Enable; Bit 7. This function either resets the ADC or enables the ADC in normal operation. A logic 0 disables ADC to reset-mode. A logic 1 enables ADC to normal operation.

TABLE 3. ENABLE

| BIT 7 | OPERATION |
|-------|------------------------------------------|
| 0 | disable ADC-core to reset-mode (default) |
| 1 | enable ADC-core to normal operation |

2. ADCPD; Bit 6. This function puts the device in a power down mode. A logic 0 puts the device in normal operation. A logic 1 powers down the device.

TABLE 4. ADCPD

| BIT 6 | OPERATION |
|-------|----------------------------|
| 0 | Normal operation (default) |
| 1 | Power Down |

3. Timing Mode; Bit 5. This function determines whether the integration time is done internally or externally. In Internal Timing Mode, integration time is determined by an internal dual speed oscillator (f_{OSC}), and the n-bit ($n = 4, 8, 12, 16$) counter inside the ADC. In External Timing Mode, integration time is determined by the time between three consecutive external-sync sync_I²C pulses commands.

TABLE 5. TIMING MODE

| BIT 5 | OPERATION |
|-------|------------------------------------------------------------------------------------------------------------------------------|
| 0 | Internal Timing Mode. Integration time is internally timed determined by f_{OSC} , R_{EXT} , and number of clock cycles. |
| 1 | External Timing Mode. Integration time is externally timed by the I ² C host. |

4. Photodiode Select Mode; Bits 3 and 2. Setting Bit 3 and Bit 2 to 1 and 0 enables ADC to give light count DATA output.

TABLE 6. PHOTODIODE SELECT MODE; BITS 2 AND 3

| BITS 3:2 | MODE |
|----------|-----------------------------------------------|
| 0:0 | Disable ADC |
| 0:1 | Disable ADC |
| 1:0 | Light count DATA output in signed (n-1) bit * |
| 1:1 | No operation. |

* $n = 4, 8, 12, 16$ depending on the number of clock cycles function.

5. Width; Bits 1 and 0. This function determines the number of clock cycles per conversion. Changing the number of clock cycles does more than just change the resolution of the device. It also changes the integration time, which is the period the device's analog-to-digital (A/D) converter samples the photodiode current signal for a lux measurement.

TABLE 7. WIDTH

| BITS 1:0 | NUMBER OF CLOCK CYCLES |
|----------|------------------------|
| 0:0 | $2^{16} = 65,536$ |
| 0:1 | $2^{12} = 4,096$ |
| 1:0 | $2^8 = 256$ |
| 1:1 | $2^4 = 16$ |

Control Register 01(hex)

The Read/Write control register has three functions:

1. Interrupt flag; Bit 5. This is the status bit of the interrupt. The bit is set to logic high when the interrupt thresholds have been triggered, and logic low when not yet triggered. Writing a logic low clears/resets the status bit.

TABLE 8. INTERRUPT FLAG

| BIT 5 | OPERATION |
|-------|-------------------------------------------|
| 0 | Interrupt is cleared or not triggered yet |
| 1 | Interrupt is triggered |

2. Range/Gain; Bits 3 and 2. The Full Scale Range can be adjusted by an external resistor R_{EXT} and/or it can be adjusted via I²C using the Gain/Range function. Gain/Range has four possible values, Range(k) where k is 1 through 4. Table 9 lists the possible values of Range(k) and the resulting FSR for some typical value R_{EXT} resistors.

TABLE 9. RANGE/GAIN TYPICAL FSR LUX RANGES

| BITS 3:2 | k | RANGE(k) | FSR LUX | FSR LUX | FSR LUX |
|----------|---|----------|----------------------------|---------------------------|----------------------------|
| | | | RANGE@ $R_{EXT} = 100k$ | RANGE@ $R_{EXT} = 50k$ | RANGE@ $R_{EXT} = 500k$ |
| 0:0 | 1 | 2,000 | 2,000 | 4,000 | 400 |
| 0:1 | 2 | 8,000 | 8,000 | 16,000 | 1,600 |
| 1:0 | 3 | 32,000 | 32,000 | 64,000 | 6,400 |
| 1:1 | 4 | 128,000 | 128,000 | 256,000 | 25,600 |

Interrupt persist; Bits 1 and 0. The interrupt pin and the interrupt flag is triggered/set when the data sensor reading is out of the interrupt threshold window after m consecutive number of integration cycles. The interrupt persist bits determine m.

TABLE 10. INTERRUPT PERSIST

| BITS 1:0 | NUMBER OF INTEGRATION CYCLES |
|----------|------------------------------|
| 0:0 | 1 |
| 0:1 | 4 |
| 1:0 | 8 |
| 1:1 | 16 |

Interrupt Threshold HI Register 02(hex)

This register sets the HI threshold for the interrupt pin and the interrupt flag. By default the Interrupt threshold HI is FF(hex). The 8-bit data written to the register represents the upper MSB of a 16-bit value. The LSB is always 00(hex).

Interrupt Threshold LO Register 03(hex)

This register sets the LO threshold for the interrupt pin and the interrupt flag. By default the Interrupt threshold LO is 00(hex). The 8-bit data written to the register represents the upper MSB of a 16-bit value. The LSB is always 00(hex).

Sensor Data Register 04(hex) and 05(hex)

When the device is configured to output a signed 15-bit data, the most significant byte is accessed at 04(hex), and the least significant byte can be accessed at 05(hex). The sensor data register is refreshed after very integration cycle.

Timer Data Register 06(hex) and 07(hex)

Note that the timer counter value is only available when using the External Timing Mode. The 06(hex) and 07(hex) are the LSB and MSB respectively of a 16-bit timer counter value corresponding to the most recent sensor reading. Each clock cycle increments the counter. At the end of each integration period, the value of this counter is made available over the I²C. This value can be used to eliminate noise introduced by slight timing errors caused by imprecise external timing. Microcontrollers, for example, often cannot provide high-accuracy command-to-command timing, and the timer counter value can be used to eliminate the resulting noise.

TABLE 11. DATA REGISTERS

| ADDRESS (hex) | CONTENTS |
|---------------|--------------------------------------------------------------------------------------------|
| 04 | Least-significant byte of most recent sensor reading. |
| 05 | Most-significant byte of most recent sensor reading. |
| 06 | Least-significant byte of timer counter value corresponding to most recent sensor reading. |
| 07 | Most-significant byte of timer counter value corresponding to most recent sensor reading. |

Calculating Lux

The ISL29013's output codes, DATA, are directly proportional to lux.

$$E = \alpha \times \text{DATA} \quad (\text{EQ. 1})$$

The proportionality constant α is determined by the Full Scale Range (FSR), and the n-bit ADC which is user defined in the command register. The proportionality constant can also be viewed as the resolution; The smallest lux measurement the device can measure is α .

$$\alpha = \frac{\text{FSR}}{2^n} \quad (\text{EQ. 2})$$

Full Scale Range (FSR), is determined by the software programmable Range/Gain, Range(k), in the command register and an external scaling resistor R_{EXT} which is referenced to 100k Ω .

$$\text{FSR} = \text{Range}(k) \times \frac{100k\Omega}{R_{EXT}} \quad (\text{EQ. 3})$$

The transfer function effectively for each timing mode becomes:

INTERNAL TIMING MODE

$$E = \frac{\text{Range}(k) \times \frac{100\text{k}\Omega}{R_{\text{EXT}}}}{2^n} \times \text{DATA} \quad (\text{EQ. 4})$$

EXTERNAL TIMING MODE

$$E = \frac{\text{Range}(k) \times \frac{100\text{k}\Omega}{R_{\text{EXT}}}}{\text{COUNTER}} \times \text{DATA} \quad (\text{EQ. 5})$$

$n = 3, 7, 11,$ or 15 . This is the number of clock cycles programmed in the command register.

Range(k) is the user defined range in the Gain/Range bit in the command register.

R_{EXT} is an external scaling resistor hardwired to the R_{EXT} pin.

DATA is the output sensor reading in number of counts available at the data register.

2^n represents the maximum number of counts possible in Internal Timing Mode. For the External Timing Mode the maximum number of counts is stored in the data register named COUNTER.

COUNTER is the number increments accrued for between integration time for External Timing Mode.

Gain/Range, Range(k)

The Gain/Range can be programmed in the control register to give Range(k) determining the FSR. Note that Range(k) is not the FSR (see Equation 3). Range(k) provides four constants depending on programmed k that will be scaled by R_{EXT} (see Table 9). Unlike R_{EXT} , Range(k) dynamically adjusts the FSR. This function is especially useful when light conditions are varying drastically while maintaining excellent resolution.

Number of Clock Cycles, n-bit ADC

The number of clock cycles determines “n” in the n-bit ADC; 2^n clock cycles is a n-bit ADC. n is programmable in the command register in the width function. Depending on the application, a good balance of speed, and resolution has to be considered when deciding for n. For fast and quick measurement, choose the smallest $n = 3$. For maximum resolution without regard of time, choose $n = 15$. Table 12 compares the trade-off between integration time and resolution. See Equations 10 and 11 for the relation between integration time and n. See Equation 3 for the relation of n and resolution.

TABLE 12. RESOLUTION AND INTEGRATION TIME SELECTION

| n | RANGE1 $f_{\text{OSC}} = 327\text{kHz}$ | | RANGE4 $f_{\text{OSC}} = 655\text{kHz}$ | |
|----|--------------------------------------------|-------------------------|--------------------------------------------|---------------------------|
| | t_{INT} (ms) | RESOLUTION LUX/COUNT | t_{INT} (ms) | RESOLUTION (LUX/COUNT) |
| 15 | 200 | 0.06 | 100 | 2 |

TABLE 12. RESOLUTION AND INTEGRATION TIME SELECTION

| n | RANGE1 $f_{\text{OSC}} = 327\text{kHz}$ | | RANGE4 $f_{\text{OSC}} = 655\text{kHz}$ | |
|----|--------------------------------------------|-------------------------|--------------------------------------------|---------------------------|
| | t_{INT} (ms) | RESOLUTION LUX/COUNT | t_{INT} (ms) | RESOLUTION (LUX/COUNT) |
| 11 | 12.8 | 1.0 | 6.4 | 62.5 |
| 7 | 0.8 | 15.6 | 0.4 | 1,000 |
| 3 | 0.05 | 250 | 0.025 | 16,000 |

$R_{\text{EXT}} = 100\text{k}\Omega$

External Scaling Resistor R_{EXT} and f_{OSC}

The ISL29013 uses an external resistor R_{EXT} to fix its internal oscillator frequency, f_{OSC} . Consequently, R_{EXT} determines the f_{OSC} , integration time and the FSR of the device. f_{OSC} , a dual speed mode oscillator, is inversely proportional to R_{EXT} . For user simplicity, the proportionality constant is referenced to fixed constants $100\text{k}\Omega$ and 655kHz in Equations 6 and 7:

$$f_{\text{OSC}1} = \frac{1}{2} \times \frac{100\text{k}\Omega}{R_{\text{EXT}}} \times 655\text{kHz} \quad (\text{EQ. 6})$$

$$f_{\text{OSC}2} = \frac{100\text{k}\Omega}{R_{\text{EXT}}} \times 655\text{kHz} \quad (\text{EQ. 7})$$

$f_{\text{OSC}1}$ is oscillator frequency when Range1 or Range2 are set. This is nominally 327kHz when R_{EXT} is $100\text{k}\Omega$.

$f_{\text{OSC}2}$ is the oscillator frequency when Range3 or Range4 are set. This is nominally 655kHz when R_{EXT} is $100\text{k}\Omega$.

When the Range/Gain bits are set to Range1 or Range2, f_{OSC} runs at half speed compared to when Range/Gain bits are set to Range3 and Range4 by using Equation 8:

$$f_{\text{OSC}1} = \frac{1}{2}(f_{\text{OSC}2}) \quad (\text{EQ. 8})$$

The automatic f_{OSC} adjustment feature allows significant improvement of signal-to-noise ratio when detecting very low lux signals.

Integration Time or Conversion Time

Integration time is the period during which the device’s analog-to-digital ADC converter samples the photodiode current signal for a lux measurement. Integration time, in other words, is the time to complete the conversion of analog photodiode current into a digital signal--number of counts.

Integration time affects the measurement resolution. For better resolution, use a longer integration time. For short and fast conversions use a shorter integration time.

The ISL29013 offers user flexibility in the integration time to balance resolution, speed and noise rejection. Integration time can be set internally or externally and can be programmed in the command register 00(hex) Bit 5.

INTEGRATION TIME IN INTERNAL TIMING MODE

This timing mode is programmed in the command register 00(hex) Bit 5. Most applications will be using this timing mode.

When using the Internal Timing Mode, f_{OSC} and n-bits resolution determine the integration time. t_{INT} is a function of the number of clock cycles and f_{OSC} as shown in Equation 9:

$$t_{INT} = 2^m \times \frac{1}{f_{OSC}} \quad \text{for Internal Timing Mode only} \quad (\text{EQ. 9})$$

$m = 4, 8, 12,$ and 16 . n is the number of bits of resolution.

2^m therefore is the number of clock cycles. n can be programmed at the command register 00(hex) Bits 1 and 0.

Since f_{OSC} is dual speed depending on the Gain/Range bit, t_{INT} is dual time. The integration time as a function of R_{EXT} is shown in Equation 10:

$$t_{INT}^1 = 2^m \times \frac{R_{EXT}}{327\text{kHz} \times 100\text{k}\Omega} \quad (\text{EQ. 10})$$

t_{INT}^1 is the integration time when the device is configured for Internal Timing Mode and Gain/Range is set to Range1 or Range2.

$$t_{INT}^2 = 2^m \times \frac{R_{EXT}}{655\text{kHz} \times 100\text{k}\Omega} \quad (\text{EQ. 11})$$

t_{INT}^2 is the integration time when the device is configured for Internal Timing Mode and Gain/Range is set to Range3 or Range4.

TABLE 13. INTEGRATION TIMES FOR TYPICAL REXT VALUES

| R _{EXT} (kΩ) | RANGE1 RANGE2 | | RANGE3 RANGE4 | |
|--------------------------|------------------|------------|------------------|-------|
| | n = 15-BIT | n = 11-BIT | n = 11-BIT | n = 3 |
| 50 | 100 | 6.4 | 3.2 | 0.013 |
| 100** | 200 | 13 | 6.5 | 0.025 |
| 200 | 400 | 26 | 13 | 0.050 |
| 500 | 1000 | 64 | 32 | 0.125 |

*Integration time in milliseconds

**Recommended R_{EXT} resistor value

INTEGRATION TIME IN EXTERNAL TIMING MODE

This timing mode is programmed in the command register 00(hex) Bit 5. External Timing Mode is recommended when integration time can be synchronized to an external signal such as a PWM to eliminate noise.

To read the light count DATA output, the device needs three sync_I²C commands to complete one measurement. The 1st sync_I²C command starts the conversion of the diode array 1. The 2nd sync_I²C completes the conversion of diode array 1 and starts the conversion of diode array 2. The 3rd sync_I²C pulses ends the conversion of diode array 2, outputs the light count DATA, and starts over again to commence conversion of diode array 1.

The integration time, t_{INT} , is the sum of two identical time intervals between the three sync pulses. t_{INT} is determined by Equation 12:

$$t_{INT} = \frac{k_{OSC}}{f_{OSC}} \quad (\text{EQ. 12})$$

where K_{OSC} is the number of internal clock cycles obtained from Timer data register and f_{OSC} is the internal I²C operating frequency

The internal oscillator, f_{OSC} , operates identically in both the internal and external timing modes, with the same dependence on R_{EXT} . However, in External Timing Mode, the number of clock cycles per integration is no longer fixed at 2^n . The number of clock cycles varies with the chosen integration time, and is limited to $2^{16} = 65,536$. In order to avoid erroneous lux readings the integration time must be short enough not to allow an overflow in the counter register.

$$t_{INT} < \frac{65,535}{f_{OSC}} \quad (\text{EQ. 13})$$

$f_{OSC} = 327\text{kHz} \times 100\text{k}\Omega / R_{EXT}$. When Range/Gain is set to Range1 or Range2.

$f_{OSC} = 655\text{kHz} \times 100\text{k}\Omega / R_{EXT}$. When Range/Gain is set to Range3 or Range4.

Noise Rejection

In general, integrating type ADC's have excellent noise-rejection characteristics for periodic noise sources whose frequency is an integer multiple of the integration time. For instance, a 60Hz AC unwanted signal's sum from 0ms to $k \times 16.66\text{ms}$ ($k = 1, 2, \dots, k_i$) is zero. Similarly, setting the device's integration time to be an integer multiple of the periodic noise signal, greatly improves the light sensor output signal in the presence of noise.

Maximum Ambient Intensity Condition

The operation of ambient light sensing (ALS) within the ISL29013 utilizes two diodes, D1 and D2. The diodes are measured sequentially and their outputs are converted with an ADC. The output of the ALS is the difference between these two measurements. In typical applications, the ISL29013 is installed behind a dark cover window. In this low-light condition, both D1 and D2 operate linearly and the ALS output is linear as well (Figures 18 and 19). In brighter environments, however, D1 and D2 can be subject to saturation. As the ambient light grows bright enough to subject one or both diodes to saturation, the ALS count (output) decreases and eventually reaches zero in deep saturation (Figure 17). When using the ISL29013 in high lux applications, be sure to choose a low R_{EXT} to avoid saturation at Range4, the lowest gain. For example, $R_{EXT} = 25\text{k}\Omega$ is recommended with ambient light near 100,000 lux. If you are operating the ISL29013 at a lower range/higher gain and detect a zero output, the firmware should change the range and recheck the ALS count. One of two situations will be identified. If the output is nonzero, the ISL29013 is saturated. If the output remains zero, the ISL29013 is in a totally dark environment.

Unstable Ambient Light Condition

The ISL29013 sequentially measures the difference in the output of two diodes. That's suitable since most changes in ambient light are gradual and any difference between the ambient light conditions for D1 and D2 are negligible. However, it is possible to cause an abrupt change in brightness with a fast-moving hand over the sensor or passing a tree shadow in a fast moving car. To handle these anomalies, we suggest comparing several sequential readings and discarding any data with sudden changes.

Flat Window Lens Design

A window lens will surely limit the viewing angle of the ISL29013. The window lens should be placed directly on top of the device. The thickness of the lens should be kept at minimum to minimize loss of power due to reflection and also to minimize loss of loss due to absorption of energy in the plastic material. A thickness of $t = 1\text{mm}$ is recommended for a window lens design. The bigger the diameter of the window lens the wider the viewing angle is of the ISL29013. Table 14 shows the recommended dimensions of the optical window to ensure both 35° and 45° viewing angle. These dimensions are based on a window lens thickness of 1.0mm and a refractive index of 1.59 .

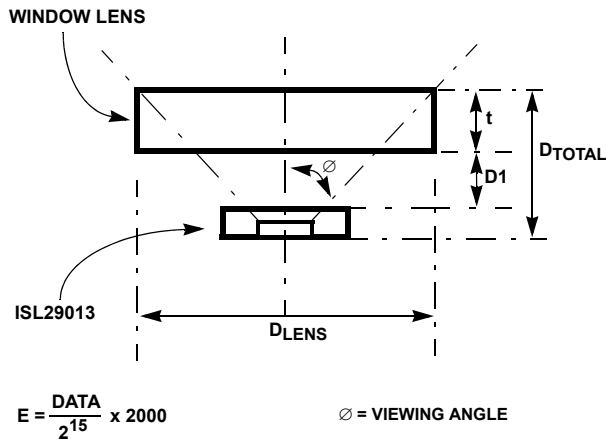


FIGURE 4. FLAT WINDOW LENS
TABLE 14. RECOMMENDED DIMENSIONS FOR A FLAT WINDOW DESIGN

| D_{TOTAL} | $D1$ | D_{LENS} @ 35° VIEWING ANGLE | D_{LENS} @ 45° VIEWING ANGLE |
|-------------|------|---------------------------------------|---------------------------------------|
| 1.5 | 0.50 | 2.25 | 3.75 |
| 2.0 | 1.00 | 3.00 | 4.75 |
| 2.5 | 1.50 | 3.75 | 5.75 |
| 3.0 | 2.00 | 4.30 | 6.75 |
| 3.5 | 2.50 | 5.00 | 7.75 |

$t = 1$ Thickness of lens
 $d1$ Distance between ISL29013 and inner edge of lens
 D_{LENS} Diameter of lens
 d_{TOTAL} Distance constraint between the ISL29013 and lens outer edge

* All dimensions are in mm.

Suggested PCB Footprint

It is important that the users check the "Surface Mount Assembly Guidelines for Optical Dual FlatPack No Lead (ODFN) Package" before starting ODFN product board mounting.

<http://www.intersil.com/data/tb/TB466.pdf>

Layout Considerations

The ISL29013 is relatively insensitive to layout. Like other I^2C devices, it is intended to provide excellent performance even in significantly noisy environments. There are only a few considerations that will ensure best performance.

Route the supply and I^2C traces as far as possible from all sources of noise. Use two power-supply decoupling capacitors, $4.7\mu\text{F}$ and $0.1\mu\text{F}$, placed close to the device.

Typical Circuit

A typical application for the ISL29013 is shown in Figure 5. The ISL29013's I²C address is internally hardwired as 1000100. The device can be tied onto a system's I²C bus together with other I²C compliant devices.

Soldering Considerations

Convection heating is recommended for reflow soldering; direct-infrared heating is not recommended. The plastic ODFN package does not require a custom reflow soldering profile, and is qualified to +260°C. A standard reflow soldering profile with a +260°C maximum is recommended.

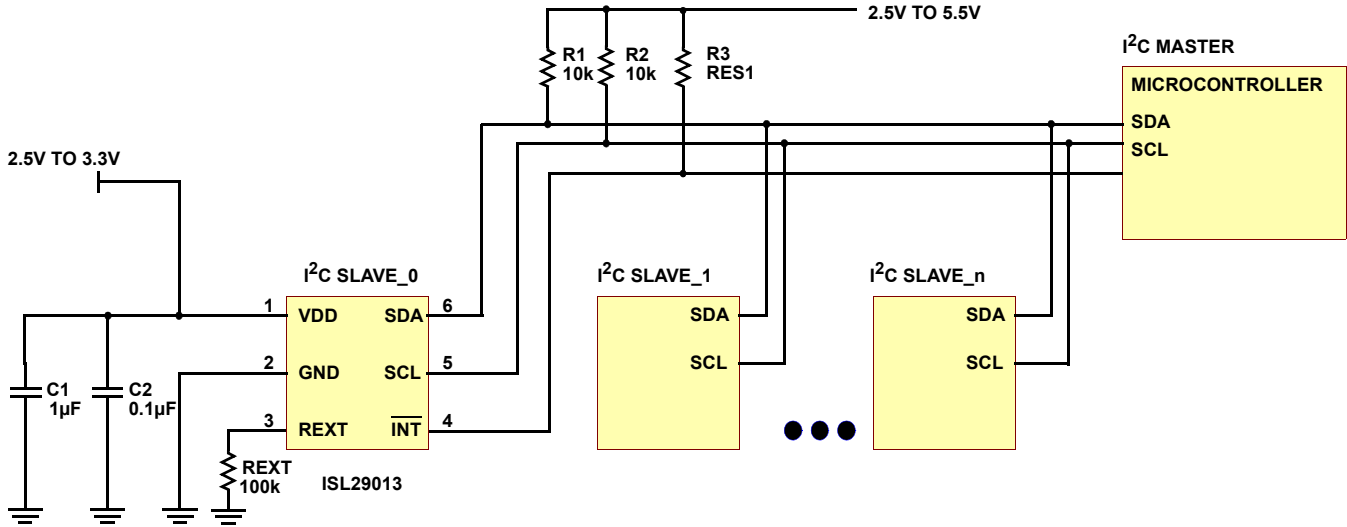


FIGURE 5. ISL29013 TYPICAL CIRCUIT

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Typical Performance Curves ($R_{EXT} = 100k\Omega$)

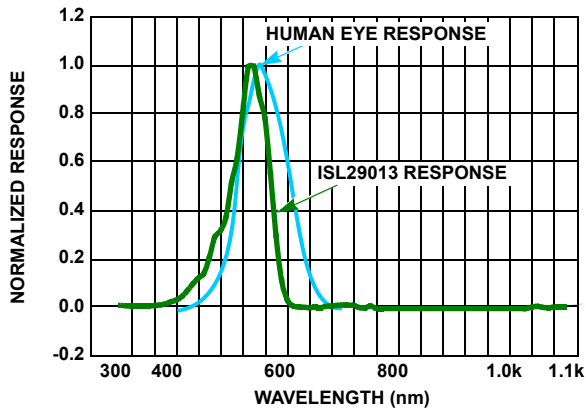


FIGURE 6. SPECTRAL RESPONSE

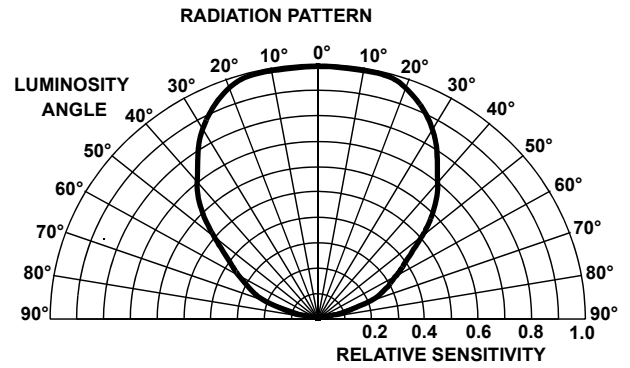


FIGURE 7. RADIATION PATTERN

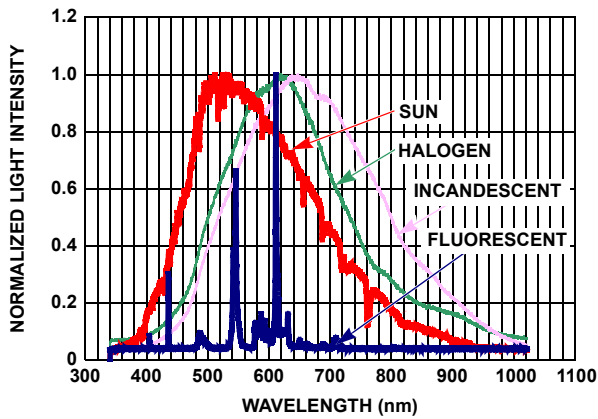


FIGURE 8. SPECTRUM OF LIGHT SOURCES FOR MEASUREMENT

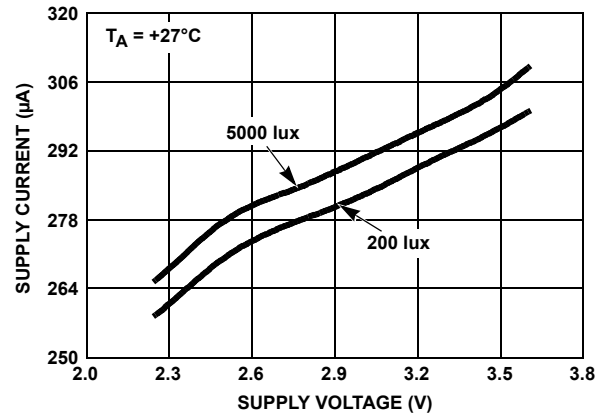


FIGURE 9. SUPPLY CURRENT vs SUPPLY VOLTAGE

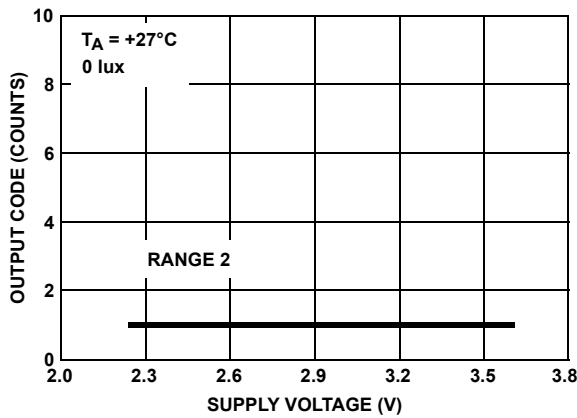


FIGURE 10. OUTPUT CODE FOR 0 LUX vs SUPPLY VOLTAGE

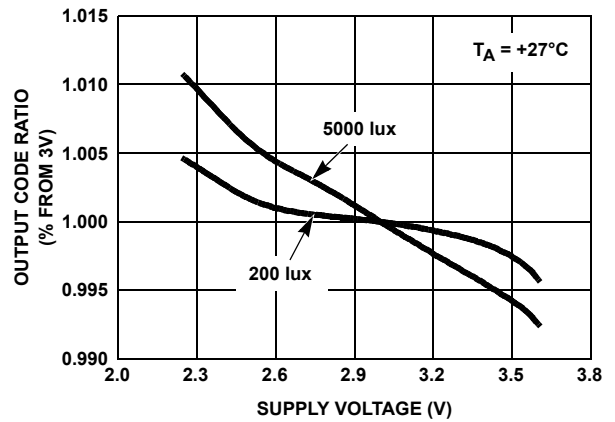


FIGURE 11. OUTPUT CODE vs SUPPLY VOLTAGE

Typical Performance Curves ($R_{EXT} = 100k\Omega$) (Continued)

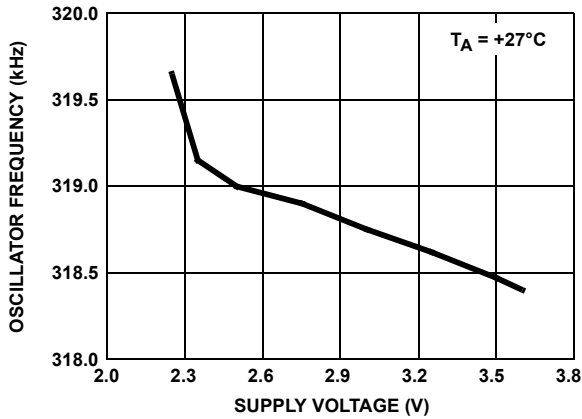


FIGURE 12. OSCILLATOR FREQUENCY vs SUPPLY VOLTAGE

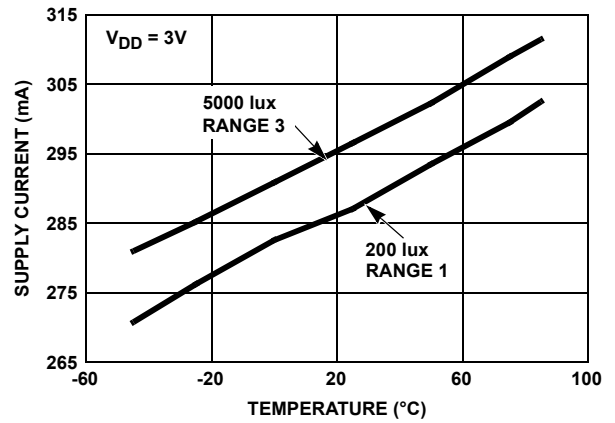


FIGURE 13. SUPPLY CURRENT vs TEMPERATURE

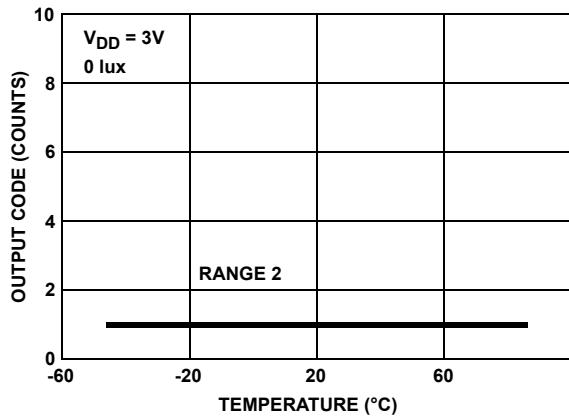


FIGURE 14. OUTPUT CODE FOR 0 LUX vs TEMPERATURE

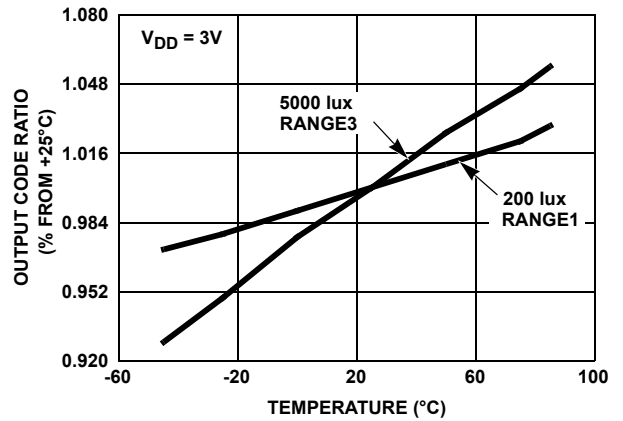


FIGURE 15. OUTPUT CODE vs TEMPERATURE

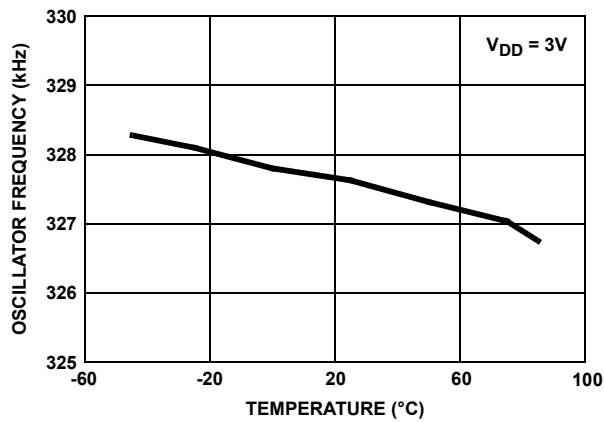


FIGURE 16. OSCILLATOR FREQUENCY vs TEMPERATURE

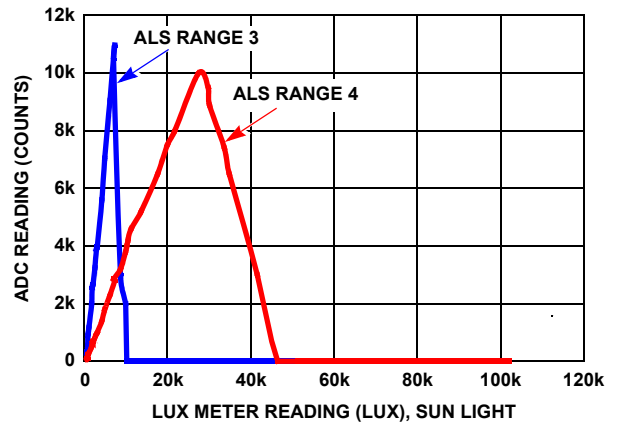


FIGURE 17. SATURATION CHARACTERISTICS

Typical Performance Curves ($R_{EXT} = 100k\Omega$) (Continued)

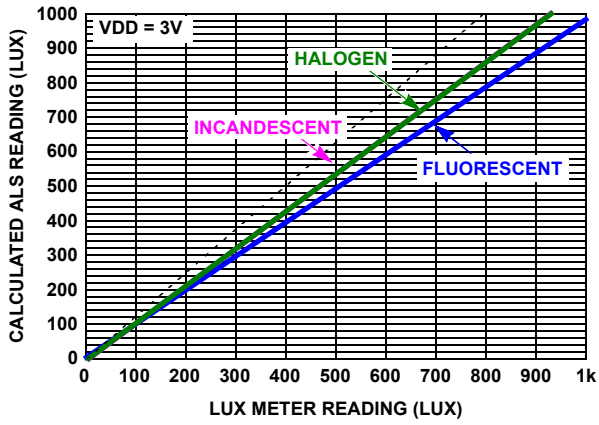


FIGURE 18. LIGHT SENSITIVITY vs LUX LEVEL

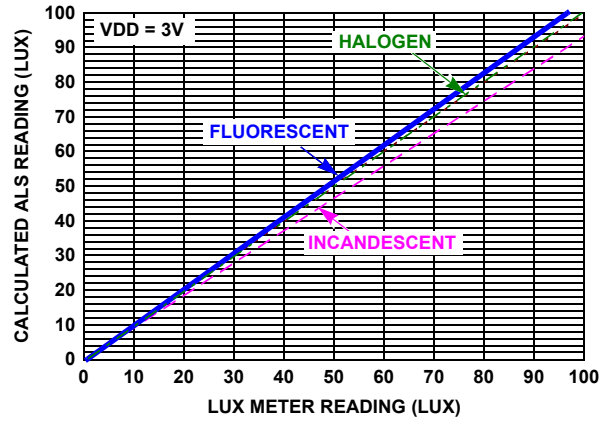


FIGURE 19. LIGHT SENSITIVITY vs LUX LEVEL

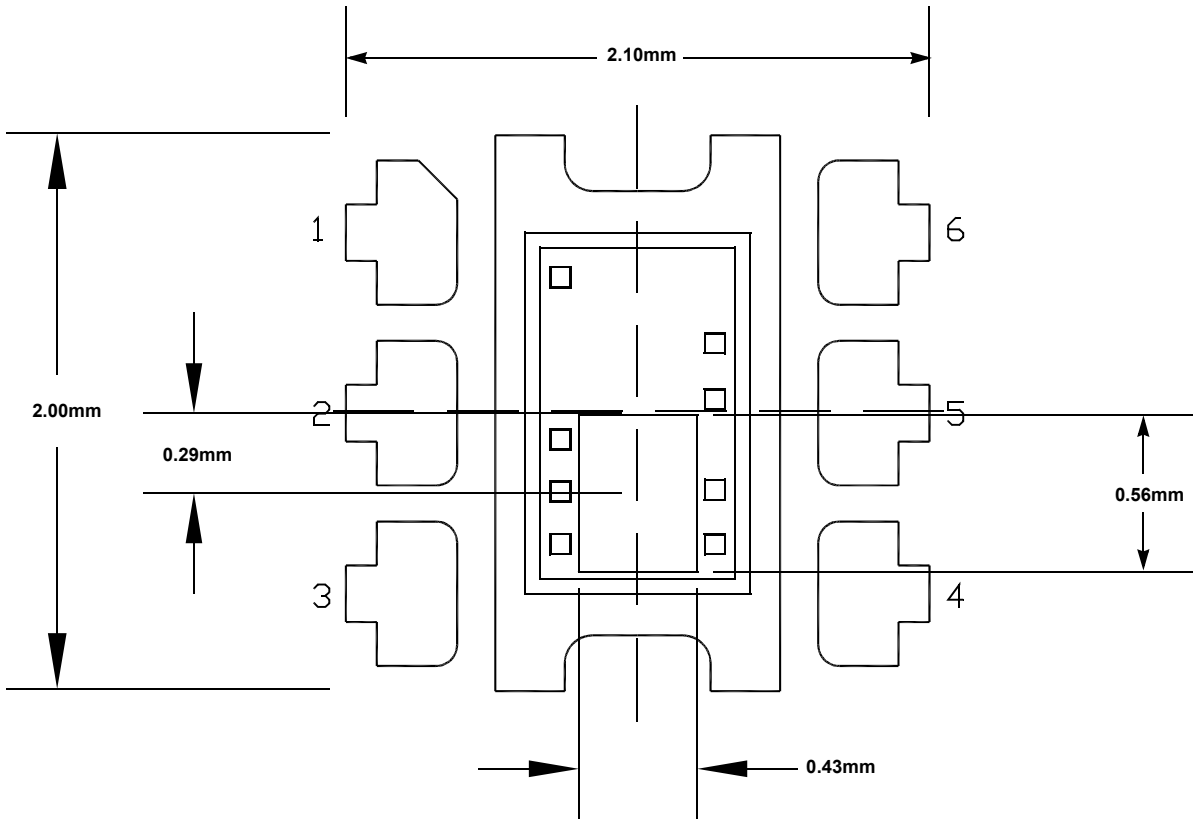


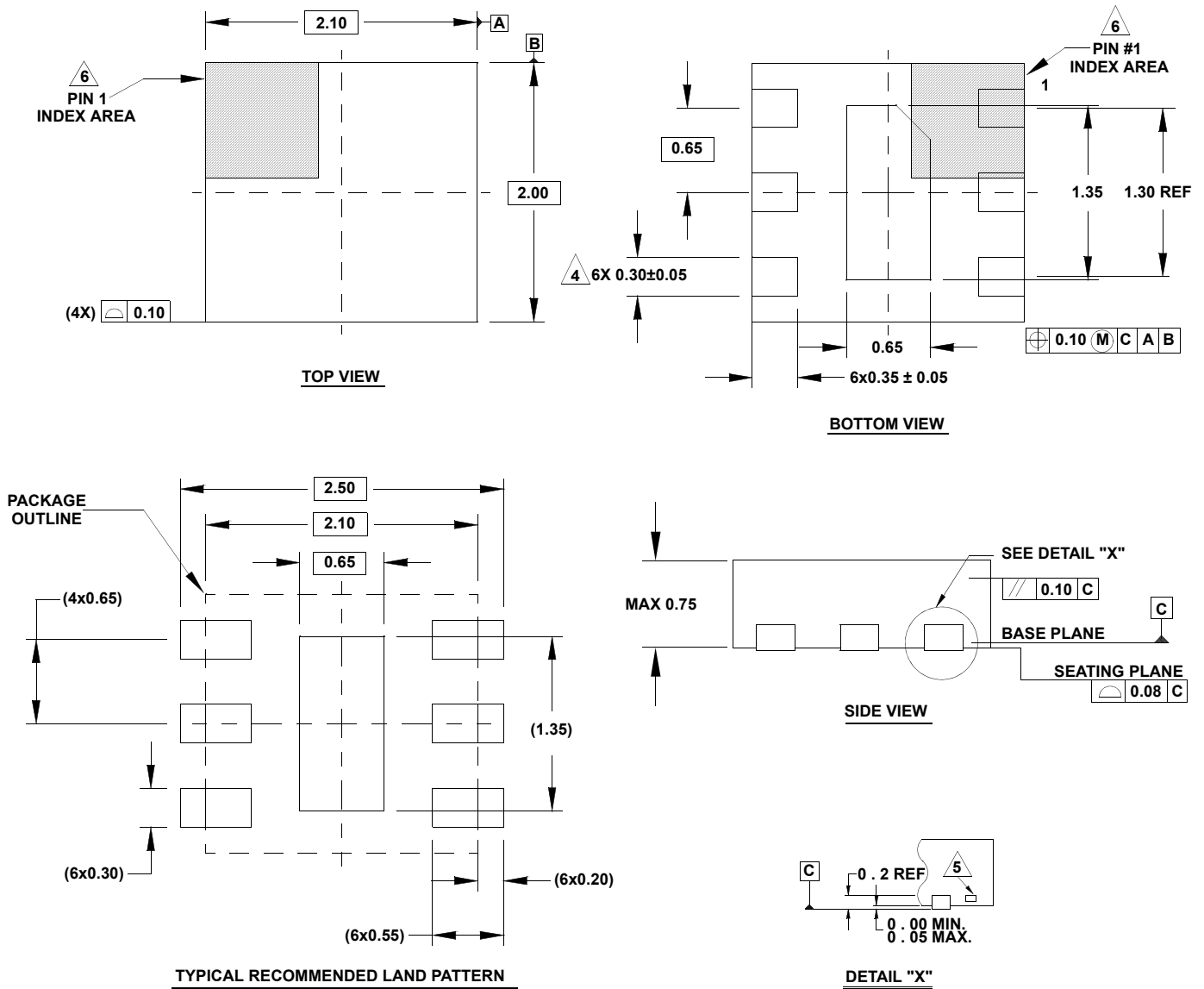
FIGURE 20. 6 LD ODFN SENSOR LOCATION OUTLINE

Package Outline Drawing

L6.2x2.1

6 LEAD OPTICAL DUAL FLAT NO-LEAD PLASTIC PACKAGE (ODFN)

Rev 3, 5/11



NOTES:

1. Dimensions are in millimeters.
Dimensions in () for Reference Only.
2. Dimensioning and tolerancing conform to ASME Y14.5m-1994.
3. Unless otherwise specified, tolerance : Decimal ± 0.05
4. Dimension applies to the metallized terminal and is measured between 0.15mm and 0.30mm from the terminal tip.
5. Tiebar shown (if present) is a non-functional feature.
6. The configuration of the pin #1 identifier is optional, but must be located within the zone indicated. The pin #1 identifier may be either a mold or mark feature.

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