SSM2019—SPECIFICATIONS (V_S = ±15 V and –40°C ≤ T_A ≤ +85°C, unless otherwise noted. Typical specifications apply at T_A = 25°C.)

Parameter	Symbol	Conditions	Min	Typ	Max	Unit
DISTORTION PERFORMANCE						
		V_O = 7 V rms				
		R_L = 2 kΩ				
Total Harmonic Distortion Plus Noise	THD + N	f = 1 kHz, G = 1000		0.017		%
		f = 1 kHz, G = 100		0.0085		%
		f = 1 kHz, G = 10		0.0035		%
		f = 1 kHz, G = 1		0.005		%
		BW = 80 kHz				
NOISE PERFORMANCE						
Input Referred Voltage Noise Density	e_n	f = 1 kHz, G = 1000		1.0		nV/√Hz
		f = 1 kHz, G = 100		1.7		nV/√Hz
		f = 1 kHz, G = 10		7		nV/√Hz
		f = 1 kHz, G = 1		50		nV/√Hz
Input Current Noise Density	i_n	f = 1 kHz, G = 1000		2		pA/√Hz
DYNAMIC RESPONSE						
Slew Rate	SR	G = 10		16		V/µs
		R_L = 2 kΩ				
		C_L = 100 pF				
Small Signal Bandwidth	$BW_{-3\ dB}$	G = 1000		200		kHz
		G = 100		1000		kHz
		G = 10		1600		kHz
		G = 1		2000		kHz
INPUT						
Input Offset Voltage	V_{IOS}			0.05	0.25	mV
Input Bias Current	I_B	V_{CM} = 0 V		3	10	µA
Input Offset Current	Ios	V_{CM} = 0 V		±0.001	±1.0	µA
Common-Mode Rejection	CMR	V_{CM} = ±12 V				
		G = 1000	110	130		dB
		G = 100	90	113		dB
		G = 10	70	94		dB
		G = 1	50	74		dB
Power Supply Rejection	PSR	V_S = ±5 V to ±18 V				
		G = 1000	110	124		dB
		G = 100	110	118		dB
		G = 10	90	101		dB
		G = 1	70	82		dB
Input Voltage Range	IVR		±12			V
Input Resistance	R_{IN}	Differential, G = 1000		1		MΩ
		G = 1		30		MΩ
		Common Mode, G = 1000		5.3		MΩ
		G = 1		7.1		MΩ
OUTPUT						
Output Voltage Swing	V_O	R_L = 2 kΩ, T_A = 25°C	±13.5	±13.9		V
Output Offset Voltage	V_{OOS}			4	30	mV
Maximum Capacitive Load Drive				5000		pF
Short Circuit Current Limit	I_{SC}	Output-to-Ground Short		±50		mA
Output Short Circuit Duration				Continuous		sec
GAIN						
Gain Accuracy	$R_G = \frac{10\ k\Omega}{G-1}$	T_A = 25°C				
		R_G = 10 Ω, G = 1000	0.5	0.1		dB
		R_G = 101 Ω, G = 100	0.5	0.2		dB
		R_G = 1.1 kΩ, G = 10	0.5	0.2		dB
		R_G = ∞, G = 1	0.1	0.2		dB
Maximum Gain	G			70		dB
REFERENCE INPUT						
Input Resistance				10		kΩ
Voltage Range				±12		V
Gain to Output				1		V/V
POWER SUPPLY						
Supply Voltage Range	V_S		±5		±18	V
Supply Current	I_{SY}	V_{CM} = 0 V, R_L = ∞		±4.6	±7.5	mA
		V_{CM} = 0 V, V_S = ±18 V, R_L = ∞		±4.7	±8.5	mA

Specifications subject to change without notice.

ABSOLUTE MAXIMUM RATINGS[1]

Supply Voltage . . . . . ±19 V
Input Voltage . . . . . Supply Voltage
Output Short Circuit Duration . . . . . 10 sec
Storage Temperature Range . . . . . –65°C to +150°C
Junction Temperature (T_J) . . . . . –65°C to +150°C
Lead Temperature Range (Soldering, 60 sec) . . . . . 300°C
Operating Temperature Range . . . . . –40°C to +85°C
Thermal Resistance[2]
8-Lead PDIP (N) . . . . . θ_{JA} = 96°C/W
. . . . . θ_{JC} = 37°C/W
16-Lead SOIC (RW) . . . . . θ_{JA} = 92°C/W
. . . . . θ_{JC} = 27°C/W

NOTES

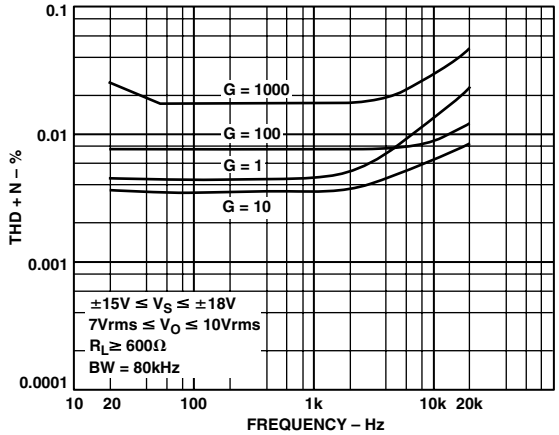
[1] Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

[2] θ_{JA} is specified for worst-case mounting conditions, i.e., θ_{JA} is specified for device in socket for PDIP; θ_{JA} is specified for device soldered to printed circuit board for SOIC package.

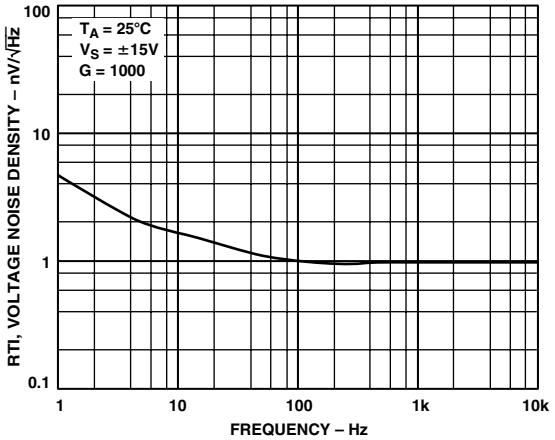
CAUTION

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the SSM2019 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.

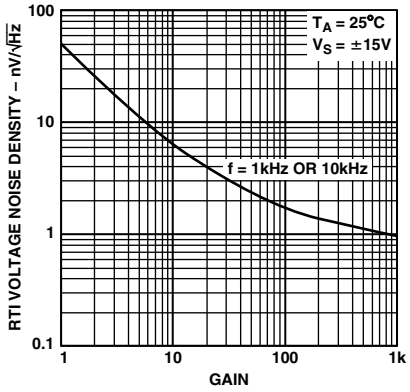
Typical Performance Characteristics



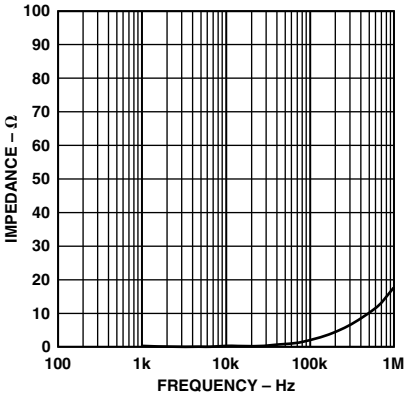
TPC 1. Typical THD + Noise vs. Gain



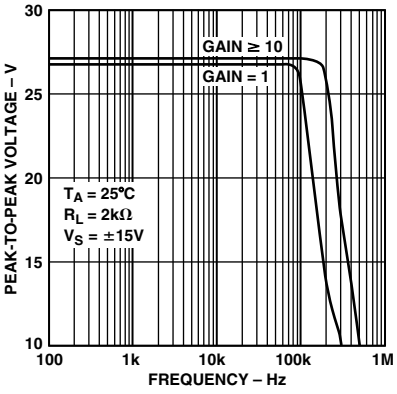
TPC 2. Voltage Noise Density vs. Frequency



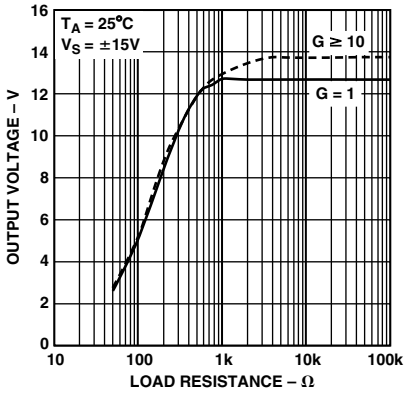
TPC 3. RTI Voltage Noise Density vs. Gain



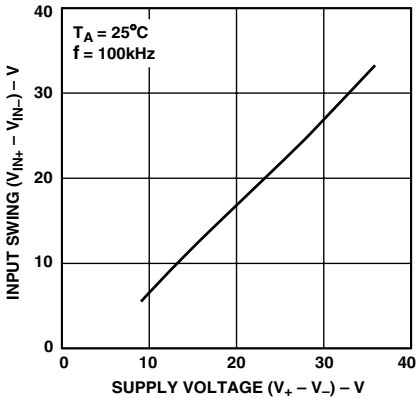
TPC 4. Output Impedance vs. Frequency



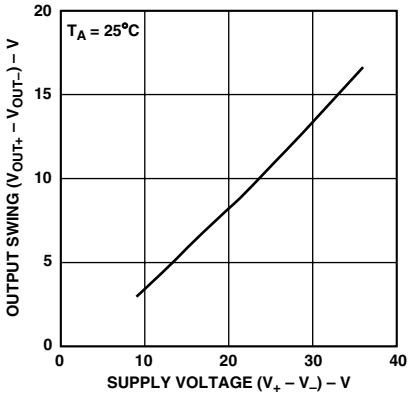
TPC 5. Maximum Output Swing vs. Frequency



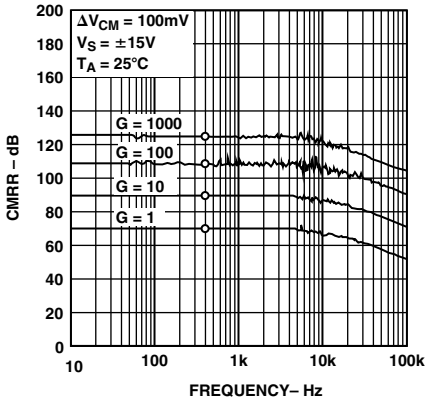
TPC 6. Output Voltage vs. Load Resistance



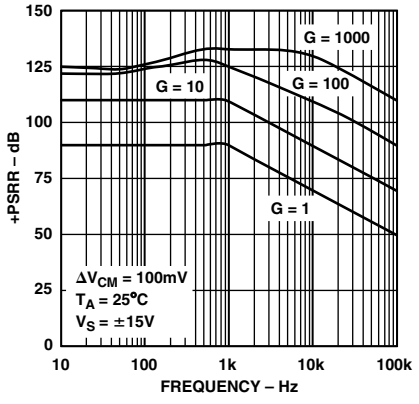
TPC 7. Input Voltage Range vs. Supply Voltage



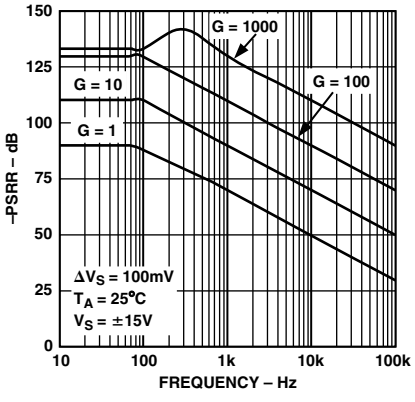
TPC 8. Output Voltage Range vs. Supply Voltage



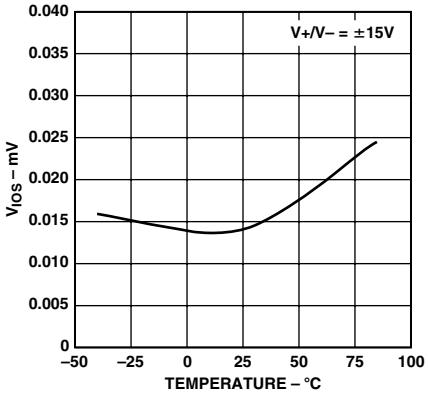
TPC 9. CMRR vs. Frequency



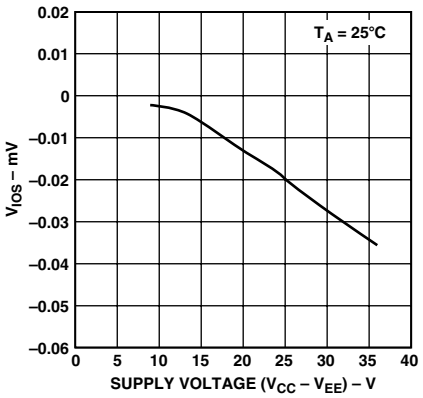
TPC 10. Positive PSRR vs. Frequency



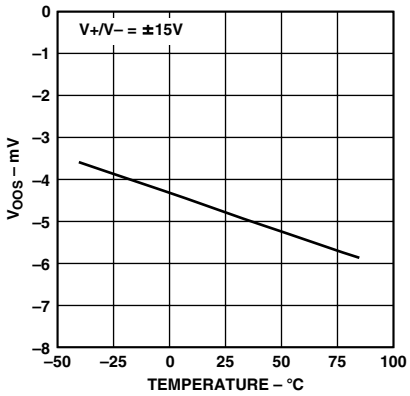
TPC 11. Negative PSRR vs. Frequency



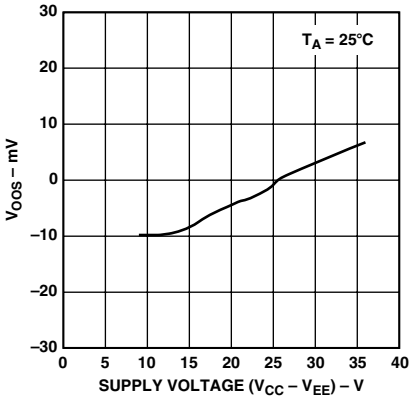
TPC 12. V_{IOS} vs. Temperature



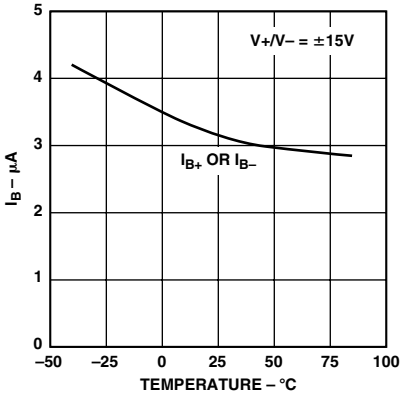
TPC 13. V_{IOS} vs. Supply Voltage



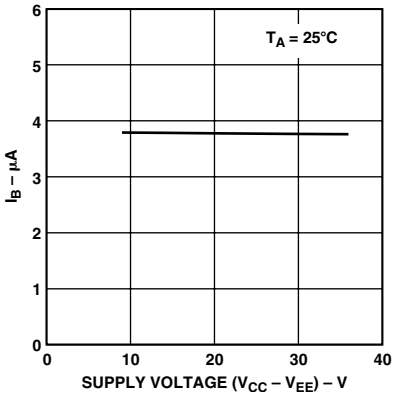
TPC 14. V_{OOS} vs. Temperature



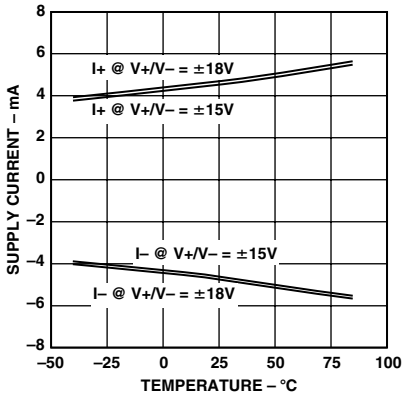
TPC 15. V_{OOS} vs. Supply Voltage



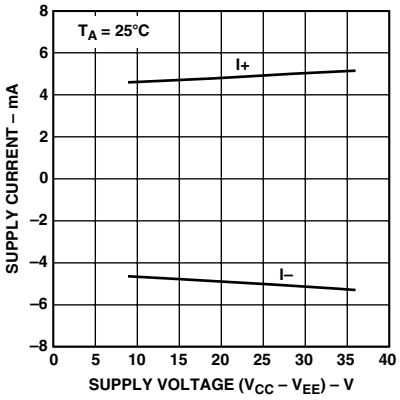
TPC 16. I_B vs. Temperature



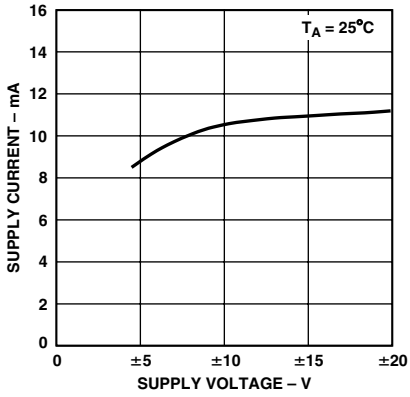
TPC 17. I_B vs. Supply Voltage



TPC 18. Supply Current vs. Temperature



TPC 19. Supply Current vs. Supply Voltage



TPC 20. I_{SY} vs. Supply Voltage

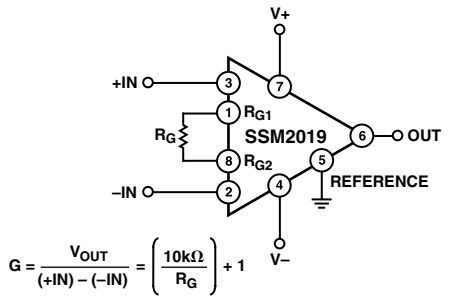


Figure 1. Basic Circuit Connections

GAIN

The SSM2019 only requires a single external resistor to set the voltage gain. The voltage gain, G, is:

$$G = \frac{10\ k\Omega}{R_G} + 1$$

and the external gain resistor, R_G, is:

$$R_G = \frac{10\ k\Omega}{G - 1}$$

For convenience, Table I lists various values of R_G for common gain levels.

Table I. Values of R_G for Various Gain Levels

R_G (Ω)	A_V	dB
NC	1	0
4.7 k	3.2	10
1.1 k	10	20
330	31.3	30
100	100	40
32	314	50
10	1000	60

The voltage gain can range from 1 to 3500. A gain set resistor is not required for unity gain applications. Metal film or wire-wound resistors are recommended for best results.

The total gain accuracy of the SSM2019 is determined by the tolerance of the external gain set resistor, R_G, combined with the gain equation accuracy of the SSM2019. Total gain drift combines the mismatch of the external gain set resistor drift with that of the internal resistors (20 ppm/°C typ).

Bandwidth of the SSM2019 is relatively independent of gain, as shown in Figure 2. For a voltage gain of 1000, the SSM2019 has a small-signal bandwidth of 200 kHz. At unity gain, the bandwidth of the SSM2019 exceeds 4 MHz.

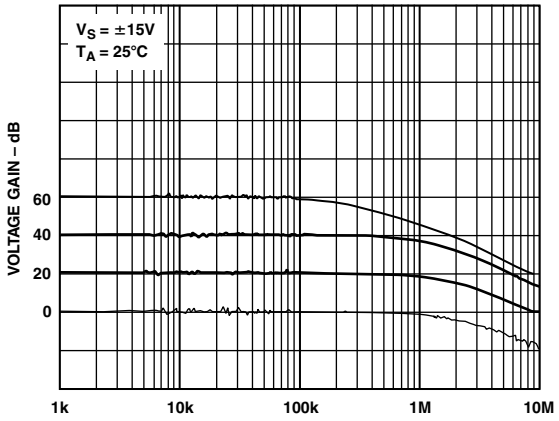


Figure 2. Bandwidth for Various Values of Gain

NOISE PERFORMANCE

The SSM2019 is a very low noise audio preamplifier exhibiting a typical voltage noise density of only 1 nV/√Hz at 1 kHz. The exceptionally low noise characteristics of the SSM2019 are in part achieved by operating the input transistors at high collector currents since the voltage noise is inversely proportional to the square root of the collector current. Current noise, however, is directly proportional to the square root of the collector current. As a result, the outstanding voltage noise performance of the SSM2019 is obtained at the expense of current noise performance. At low preamplifier gains, the effect of the SSM2019 voltage and current noise is insignificant.

The total noise of an audio preamplifier channel can be calculated by:

$$E_n = \sqrt{e_n^{\,2} + (i_n R_S)^2 + e_t^{\,2}}$$

where:

E_n = total input referred noise

e_n = amplifier voltage noise

i_n = amplifier current noise

R_S = source resistance

e_t = source resistance thermal noise

For a microphone preamplifier, using a typical microphone impedance of 150 Ω, the total input referred noise is:

$$E_n = \sqrt{(1\ nV\sqrt{Hz})^2 + 2(pA/\sqrt{Hz} \times 150\ \Omega)^2 + (1.6\ nV/\sqrt{Hz})^2} =$$

$$1.93\ nV/\sqrt{Hz}\ @\ 1\ kHz$$

where:

e_n = 1 nV/√Hz @ 1 kHz, SSM2019 e_n

i_n = 2 pA/√Hz @ 1 kHz, SSM2019 i_n

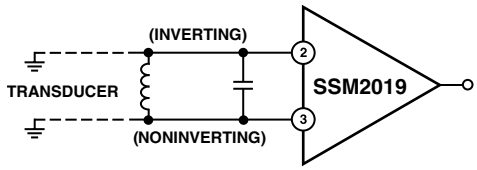
R_S = 150 Ω, microphone source impedance

e_t = 1.6 nV/√Hz @ 1 kHz, microphone thermal noise

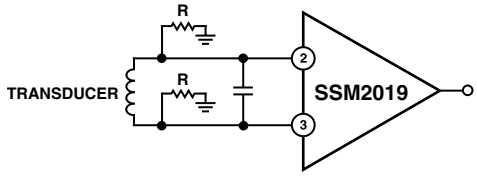
This total noise is extremely low and makes the SSM2019 virtually transparent to the user.

INPUTS

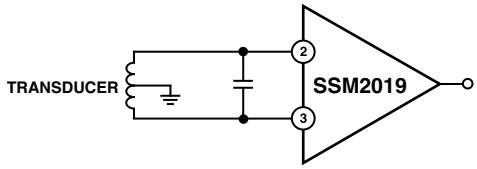
The SSM2019 has protection diodes across the base emitter junctions of the input transistors. These prevent accidental avalanche breakdown, which could seriously degrade noise performance. Additional clamp diodes are also provided to prevent the inputs from being forced too far beyond the supplies.



a. Single-Ended



b. Pseudo-Differential



c. True Differential

Figure 3. Three Ways of Interfacing Transducers for High Noise Immunity

Although the SSM2019 inputs are fully floating, care must be exercised to ensure that both inputs have a dc bias connection capable of maintaining them within the input common-mode range. The usual method of achieving this is to ground one side of the transducer as in Figure 3a. An alternative way is to float the transducer and use two resistors to set the bias point as in Figure 3b. The value of these resistors can be up to 10 kΩ, but they should be kept as small as possible to limit common-mode pickup. Noise contribution by resistors is negligible since it is attenuated by the transducer's impedance. Balanced transducers give the best noise immunity and interface directly as in Figure 3c.

For stability, it is required to put an RF bypass capacitor directly across the inputs, as shown in Figures 3 and 4. This capacitor should be placed as close as possible to the input terminals. Good RF practice should also be followed in layout and power supply bypassing, since the SSM2019 uses very high bandwidth devices.

REFERENCE TERMINAL

The output signal is specified with respect to the reference terminal, which is normally connected to analog ground. The reference may also be used for offset correction or level shifting. A reference source resistance will reduce the common-mode rejection by the ratio of 5 kΩ/R_{REF}. If the reference source resistance is 1 Ω, then the CMR will be reduced to 74 dB (5 kΩ/1 Ω = 74 dB).

COMMON-MODE REJECTION

Ideally, a microphone preamplifier responds to only the difference between the two input signals and rejects common-mode voltages and noise. In practice, there is a small change in output voltage when both inputs experience the same common-mode voltage change; the ratio of these voltages is called the common-mode gain. Common-mode rejection (CMR) is the logarithm of the ratio of differential-mode gain to common-mode gain, expressed in dB.

PHANTOM POWERING

A typical phantom microphone powering circuit is shown in Figure 4. Z1 to Z4 provide transient overvoltage protection for the SSM2019 whenever microphones are plugged in or unplugged.

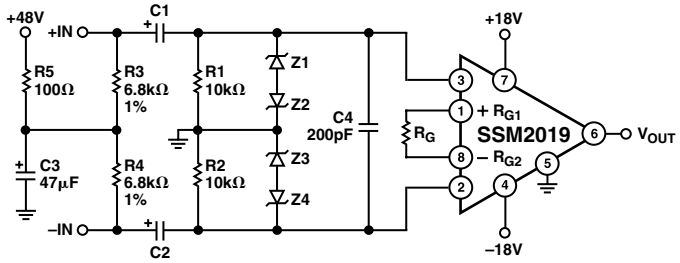


Figure 4. SSM2019 in Phantom Powered Microphone Circuit

BUS SUMMING AMPLIFIER

In addition to its use as a microphone preamplifier, the SSM2019 can be used as a very low noise summing amplifier. Such a circuit is particularly useful when many medium impedance outputs are summed together to produce a high effective noise gain.

The principle of the summing amplifier is to ground the SSM2019 inputs. Under these conditions, Pins 1 and 8 are ac virtual grounds sitting about 0.55 V below ground. To remove the 0.55 V offset, the circuit of Figure 5 is recommended.

A2 forms a "servo" amplifier feeding the SSM2019 inputs. This places Pins l and 8 at a true dc virtual ground. R4 in conjunction with C2 removes the voltage noise of A2, and in fact just about any operational amplifier will work well here since it is removed from the signal path. If the dc offset at Pins l and 8 is not too critical, then the servo loop can be replaced by the diode biasing scheme of Figure 5. If ac coupling is used throughout, then Pins 2 and 3 may be directly grounded.

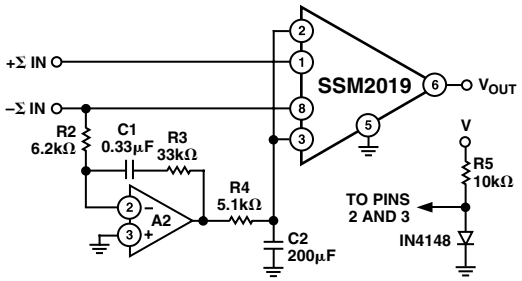
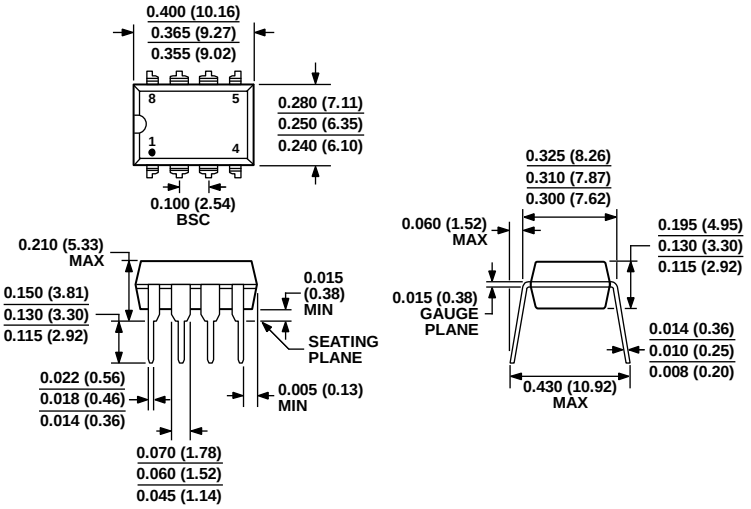


Figure 5. Bus Summing Amplifier

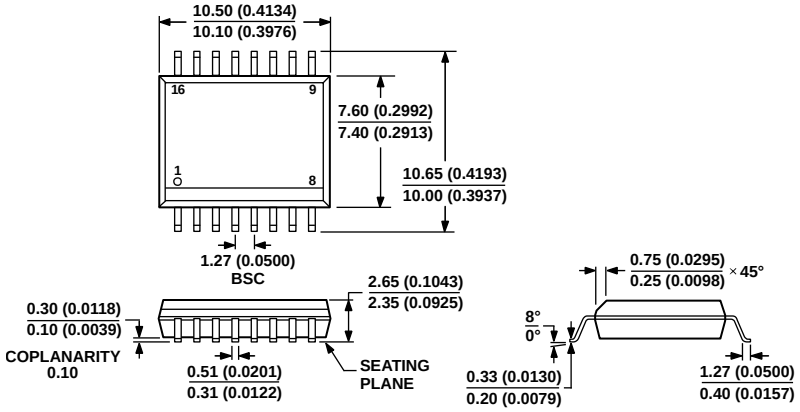
OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MS-001
CONTROLLING DIMENSIONS ARE IN INCHES; MILLIMETER DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF INCH EQUIVALENTS FOR REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN. CORNER LEADS MAY BE CONFIGURED AS WHOLE OR HALF LEADS.

070606-A

Figure 6. 8-Lead Plastic Dual In-Line Package [PDIP]
Narrow Body
(N-8)
Dimensions shown in inches and (millimeters)



COMPLIANT TO JEDEC STANDARDS MS-013-AA
CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

03-27-2007-B

Figure 7. 16-Lead Standard Small Outline Package [SOIC_W]
Wide Body
(RW-16)
Dimensions shown in millimeters and (inches)

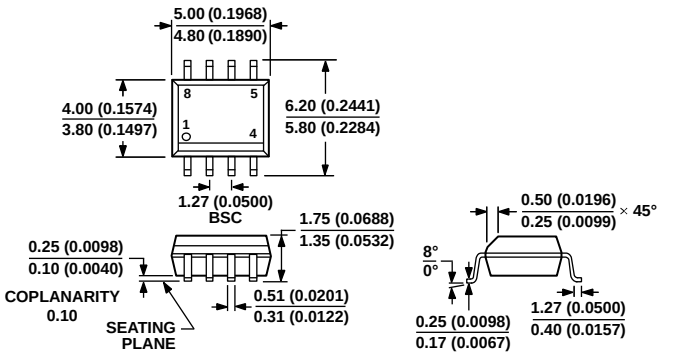


Figure 8. 8-Lead Standard Small Outline Package [SOIC_N]
Narrow Body
(RN-8)
Dimensions shown in millimeters and (inches)

ORDERING GUIDE

Model[1]	Temperature Range	Package Description	Package Option
SSM2019BNZ	–40°C to +85°C	8-Lead PDIP	N-8
SSM2019BRNZ	–40°C to +85°C	8-Lead SOIC_N	R-8
SSM2019BRNZRL	–40°C to +85°C	8-Lead SOIC_N, REEL	R-8
SSM2019BRWZ	–40°C to +85°C	16-Lead SOIC_W	RW-16
SSM2019BRWZRL	–40°C to +85°C	16-Lead SOIC_W, REEL	RW-16

[1] Z = RoHS Compliant Part

REVISION HISTORY

6/11—Rev. 0 to Rev. A

Updated Outline Dimensions 9
Changes to Ordering Guide 10

2/03—Revision 0: Initial Version

Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

Analog Devices Inc.:

SSM2019BRNZ SSM2019BRWZRL SSM2019BRNZRL SSM2019BRWZ SSM2019BNZ