

## TABLE OF CONTENTS

Features .....	1	Read/Write Sequence.....	16
Applications.....	1	Pointer Byte Bits .....	16
General Description .....	1	Input Shift Register .....	16
Functional Block Diagram .....	1	Default Readback Condition .....	17
Revision History .....	2	Multiple-DAC Write Sequence.....	17
Specifications.....	3	Multiple-DAC Readback Sequence .....	17
AC Characteristics.....	5	Write Operation.....	17
Timing Characteristics .....	5	Read Operation.....	17
Absolute Maximum Ratings.....	7	Double-Buffered Interface .....	18
ESD Caution.....	7	Power-Down Modes .....	18
Pin Configuration and Function Descriptions.....	8	Applications.....	20
Typical Performance Characteristics .....	9	Typical Application Circuit.....	20
Terminology .....	13	Bipolar Operation.....	20
Functional Description .....	15	Multiple Devices on One Bus .....	20
Digital-to-Analog Section .....	15	AD5305/AD5315/AD5325 as a Digitally Programmable	
Resistor String.....	15	Window Detector .....	21
DAC Reference Inputs .....	15	Coarse and Fine Adjustment Using the	
Output Amplifier.....	15	AD5305/AD5315/AD5325 .....	21
Power-On Reset .....	15	Power Supply Decoupling.....	21
Serial Interface .....	16	Outline Dimensions .....	23
		Ordering Guide .....	23

## REVISION HISTORY

### 5/06—Rev. F to Rev. G

Updated Format.....	Universal
Changes to Ordering Guide .....	24

### 10/04—Rev. E to Rev. F

Changes to Figure 6.....	11
Changes to Pointer Byte Bits Section.....	12
Changes to Figure 7.....	12

### 8/03—Rev. D to Rev. E

Added A Version.....	Universal
Changes to Features.....	1
Changes to Specifications .....	2
Changes to Absolute Maximum Ratings .....	5
Changes to Ordering Guide .....	5
Changes to TPC 21 .....	10

Added Octals Section to Table II.....	18
Updated Outline Dimensions.....	19

### 4/01—Rev. C to Rev. D

Edit to Features Section .....	1
Edit to Figure 6 .....	1
Edits to Right/Left and Double Sections	
of Pointer Byte Bits Section.....	11
Edit to Input Shift Register Section.....	12
Edit to Multiple-DAC Readback Sequence Section.....	12
Edits to Figure 7.....	12
Edits to Write Operation section.....	13
Edits to Figure 8.....	13
Edits to Read Operation section.....	14
Edits to Figure 9.....	14
Edits to Power-Down Modes section .....	15
Edits to Figure 12.....	16

## SPECIFICATIONS

$V_{DD} = 2.5\text{ V to }5.5\text{ V}$ ,  $V_{REF} = 2\text{ V}$ ,  $R_L = 2\text{ k}\Omega$  to GND,  $C_L = 200\text{ pF}$  to GND, all specifications  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.

Table 1.

Parameter <sup>2</sup>	A Version <sup>1</sup>			B Version <sup>1</sup>			Unit	Conditions/Comments	
	Min	Typ	Max	Min	Typ	Max			
DC PERFORMANCE <sup>3,4</sup>									
AD5305									
Resolution		8			8		Bits	Guaranteed monotonic by design over all codes	
Relative Accuracy		$\pm 0.15$	$\pm 1$		$\pm 0.15$	$\pm 0.625$	LSB		
Differential Nonlinearity		$\pm 0.02$	$\pm 0.25$		$\pm 0.02$	$\pm 0.25$	LSB		
AD5315									
Resolution		10			10		Bits	Guaranteed monotonic by design over all codes	
Relative Accuracy		$\pm 0.5$	$\pm 4$		$\pm 0.5$	$\pm 2.5$	LSB		
Differential Nonlinearity		$\pm 0.05$	$\pm 0.5$		$\pm 0.05$	$\pm 0.5$	LSB		
AD5325									
Resolution		12			12		Bits	Guaranteed monotonic by design over all codes	
Relative Accuracy		$\pm 2$	$\pm 16$		$\pm 2$	$\pm 10$	LSB		
Differential Nonlinearity		$\pm 0.2$	$\pm 1$		$\pm 0.2$	$\pm 1$	LSB		
Offset Error		$\pm 0.4$	$\pm 3$		$\pm 0.4$	$\pm 3$	% of FSR	Lower deadband exists only if offset error is negative	
Gain Error		$\pm 0.15$	$\pm 1$		$\pm 0.15$	$\pm 1$	% of FSR		
Lower Deadband		20	60		20	60	mV		
Offset Error Drift <sup>5</sup>		-12			-12		ppm of FSR/ $^{\circ}\text{C}$		
Gain Error Drift <sup>5</sup>		-5			-5		ppm of FSR/ $^{\circ}\text{C}$		
Power Supply Rejection Ratio <sup>5</sup>		-60			-60		dB		
DC Crosstalk <sup>5</sup>		200			200		$\mu\text{V}$		
$\Delta V_{DD} = \pm 10\%$									
$R_L = 2\text{ k}\Omega$ to GND or $V_{DD}$									
DAC REFERENCE INPUTS <sup>5</sup>									
$V_{REF}$ Input Range	0.25		$V_{DD}$	0.25		$V_{DD}$	V	Normal operation Power-down mode Frequency = 10 kHz	
$V_{REF}$ Input Impedance	37	45		37	45		k $\Omega$		
		>10			>10		M $\Omega$		
Reference Feedthrough		-90			-90		dB		
OUTPUT CHARACTERISTICS <sup>5</sup>									
Minimum Output Voltage <sup>6</sup>		0.001			0.001		V	A measure of the minimum and maximum drive capability of the output amplifier	
Maximum Output Voltage <sup>6</sup>		$V_{DD} - 0.001$			$V_{DD} - 0.001$		V		
DC Output Impedance		0.5			0.5		$\Omega$	$V_{DD} = 5\text{ V}$ $V_{DD} = 3\text{ V}$	
Short-Circuit Current		25			25		mA		
		16			16		mA		
Power-Up Time		2.5			2.5		$\mu\text{s}$	Coming out of power-down mode $V_{DD} = 5\text{ V}$	
		5			5		$\mu\text{s}$	Coming out of power-down mode $V_{DD} = 3\text{ V}$	

# AD5305/AD5315/AD5325

Parameter <sup>2</sup>	A Version <sup>1</sup>			B Version <sup>1</sup>			Unit	Conditions/Comments
	Min	Typ	Max	Min	Typ	Max		
<b>LOGIC INPUTS (A0)<sup>5</sup></b>								
Input Current			±1			±1	μA	
Input Low Voltage, V <sub>IL</sub>			0.8			0.8	V	V <sub>DD</sub> = 5 V ± 10%
			0.6			0.6	V	V <sub>DD</sub> = 3 V ± 10%
			0.5			0.5	V	V <sub>DD</sub> = 2.5 V
Input High Voltage, V <sub>IH</sub>	2.4			2.4			V	V <sub>DD</sub> = 5 V ± 10%
	2.1			2.1			V	V <sub>DD</sub> = 3 V ± 10%
	2.0			2.0			V	V <sub>DD</sub> = 2.5 V
Pin Capacitance		3			3		pF	
<b>LOGIC INPUTS (SCL, SDA)<sup>5</sup></b>								
Input High Voltage, V <sub>IH</sub>	0.7		V <sub>DD</sub> + 0.3	0.7		V <sub>DD</sub> + 0.3	V	SMBus compatible at V <sub>DD</sub> < 3.6 V
Input Low Voltage, V <sub>IL</sub>	-0.3		0.3 V <sub>DD</sub>	-0.3		0.3 V <sub>DD</sub>	V	SMBus compatible at V <sub>DD</sub> < 3.6 V
Input Leakage Current, I <sub>IN</sub>			±1			±1	μA	
Input Hysteresis, V <sub>HYST</sub>	0.05			0.05			V	
Input Capacitance, C <sub>IN</sub>		8			8		pF	
Glitch Rejection			50			50	ns	Input filtering suppresses noise spikes of less than 50 ns
<b>LOGIC OUTPUT (SDA)<sup>5</sup></b>								
Output Low Voltage, V <sub>OL</sub>			0.4			0.4	V	I <sub>SINK</sub> = 3 mA
			0.6			0.6	V	I <sub>SINK</sub> = 6 mA
Three-State Leakage Current			±1			±1	μA	
Three-State Output Capacitance		8			8		pF	
<b>POWER REQUIREMENTS</b>								
V <sub>DD</sub>	2.5		5.5	2.5		5.5	V	
I <sub>DD</sub> (Normal Mode) <sup>7</sup>								V <sub>IH</sub> = V <sub>DD</sub> and V <sub>IL</sub> = GND
V <sub>DD</sub> = 4.5 V to 5.5 V		600	900		600	900	μA	
V <sub>DD</sub> = 2.5 V to 3.6 V		500	700		500	700	μA	
I <sub>DD</sub> (Power-Down Mode)								V <sub>IH</sub> = V <sub>DD</sub> and V <sub>IL</sub> = GND
V <sub>DD</sub> = 4.5 V to 5.5 V		0.2	1		0.2	1	μA	I <sub>DD</sub> = 4 μA (maximum) during 0 readback on SDA
V <sub>DD</sub> = 2.5 V to 3.6 V		0.08	1		0.08	1	μA	I <sub>DD</sub> = 1.5 μA (maximum) during 0 readback on SDA

<sup>1</sup> Temperature range (A, B version): -40°C to +105°C; typical at +25°C.

<sup>2</sup> See the Terminology section.

<sup>3</sup> DC specifications tested with the outputs unloaded.

<sup>4</sup> Linearity is tested using a reduced code range: AD5305 (Code 8 to 248); AD5315 (Code 28 to 995); AD5325 (Code 115 to 3981).

<sup>5</sup> Guaranteed by design and characterization, not production tested.

<sup>6</sup> For the amplifier output to reach its minimum voltage, offset error must be negative; to reach its maximum voltage, V<sub>REF</sub> = V<sub>DD</sub> and offset plus gain error must be positive.

<sup>7</sup> I<sub>DD</sub> specification is valid for all DAC codes. Interface inactive. All DACs active and excluding load currents.

## AC CHARACTERISTICS

$V_{DD} = 2.5\text{ V to }5.5\text{ V}$ ,  $R_L = 2\text{ k}\Omega$  to GND,  $C_L = 200\text{ pF}$  to GND, all specifications  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.

**Table 2.**

Parameter <sup>2,3</sup>	A, B Version <sup>1</sup>			Unit	Conditions/Comments
	Min	Typ	Max		
Output Voltage Settling Time					$V_{REF} = V_{DD} = 5\text{ V}$
AD5305		6	8	$\mu\text{s}$	1/4 scale to 3/4 scale change (0x40 to 0xC0)
AD5315		7	9	$\mu\text{s}$	1/4 scale to 3/4 scale change (0x100 to 0x300)
AD5325		8	10	$\mu\text{s}$	1/4 scale to 3/4 scale change (0x400 to 0xC00)
Slew Rate		0.7		V/ $\mu\text{s}$	
Major-Code Transition Glitch Energy		12		nV-s	1 LSB change around major carry
Digital Feedthrough		1		nV-s	
Digital Crosstalk		1		nV-s	
DAC-to-DAC Crosstalk		3		nV-s	
Multiplying Bandwidth		200		kHz	$V_{REF} = 2\text{ V} \pm 0.1\text{ V p-p}$
Total Harmonic Distortion		-70		dB	$V_{REF} = 2.5\text{ V} \pm 0.1\text{ V p-p}$ , frequency = 10 kHz

<sup>1</sup> Temperature range (A, B version):  $-40^\circ\text{C}$  to  $+105^\circ\text{C}$ ; typical at  $+25^\circ\text{C}$ .

<sup>2</sup> Guaranteed by design and characterization, not production tested.

<sup>3</sup> See the Terminology section.

## TIMING CHARACTERISTICS

$V_{DD} = 2.5\text{ V to }5.5\text{ V}$ , all specifications  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.

**Table 3.**

Parameter <sup>1,2</sup>	Limit at $T_{MIN}$ , $T_{MAX}$ (A, B Version)	Unit	Conditions/Comments
$f_{SCL}$	400	kHz max	SCL clock frequency
$t_1$	2.5	$\mu\text{s}$ min	SCL cycle time
$t_2$	0.6	$\mu\text{s}$ min	$t_{HIGH}$ , SCL high time
$t_3$	1.3	$\mu\text{s}$ min	$t_{LOW}$ , SCL low time
$t_4$	0.6	$\mu\text{s}$ min	$t_{HD,STA}$ , start/repeated start condition hold time
$t_5$	100	ns min	$t_{SU,DAT}$ , data setup time
$t_6^3$	0.9	$\mu\text{s}$ max	$t_{HD,DAT}$ , data hold time
	0	$\mu\text{s}$ min	$t_{HD,DAT}$ , data hold time
$t_7$	0.6	$\mu\text{s}$ min	$t_{SU,STA}$ , setup time for repeated start
$t_8$	0.6	$\mu\text{s}$ min	$t_{SU,STO}$ , stop condition setup time
$t_9$	1.3	$\mu\text{s}$ min	$t_{BUF}$ , bus-free time between a stop and a start condition
$t_{10}$	300	ns max	$t_R$ , rise time of SCL and SDA when receiving
	0	ns min	$t_R$ , rise time of SCL and SDA when receiving (CMOS compatible)
$t_{11}$	250	ns max	$t_F$ , fall time of SDA when transmitting
	0	ns min	$t_F$ , fall time of SDA when receiving (CMOS compatible)
	300	ns max	$t_F$ , fall time of SCL and SDA when receiving
	$20 + 0.1 C_B^4$	ns min	$t_F$ , fall time of SCL and SDA when transmitting
$C_B^4$	400	pF max	Capacitive load for each bus line

<sup>1</sup> See Figure 2.

<sup>2</sup> Guaranteed by design and characterization; not production tested.

<sup>3</sup> A master device must provide a hold time of at least 300 ns for the SDA signal (referred to  $V_{IH}$  min of the SCL signal) in order to bridge the undefined region of SCL's falling edge.

<sup>4</sup>  $C_B$  is the total capacitance of one bus line in pF.  $t_R$  and  $t_F$  measured between  $0.3 V_{DD}$  and  $0.7 V_{DD}$ .

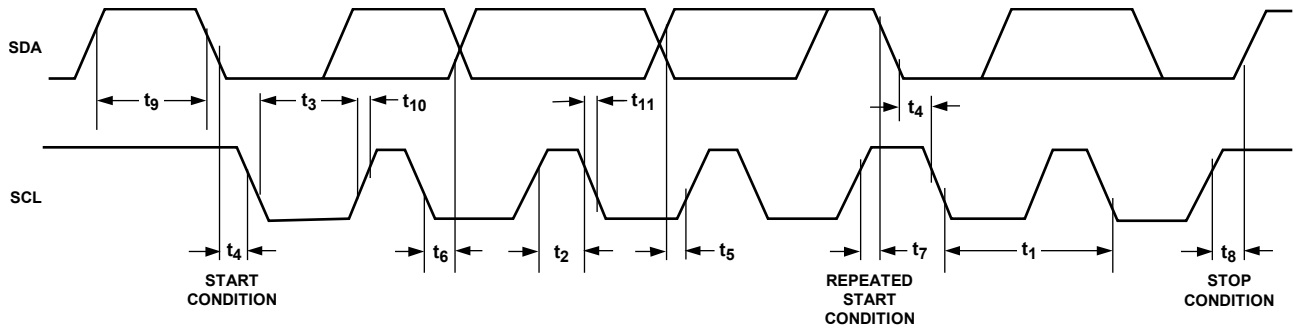


Figure 2. 2-Wire Serial Interface Timing Diagram

09930-012

## ABSOLUTE MAXIMUM RATINGS

$T_A = 25^\circ\text{C}$ , unless otherwise noted.

**Table 4.**

Parameter <sup>1</sup>	Rating
$V_{DD}$ to GND	-0.3 V to +7 V
SCL, SDA to GND	-0.3 V to $V_{DD} + 0.3$ V
A0 to GND	-0.3 V to $V_{DD} + 0.3$ V
Reference Input Voltage to GND	-0.3 V to $V_{DD} + 0.3$ V
$V_{OUTA}$ to $V_{OUTD}$ to GND	-0.3 V to $V_{DD} + 0.3$ V
Operating Temperature Range	
Industrial (A, B Version)	-40°C to +105°C
Storage Temperature Range	-65°C to +150°C
Junction Temperature ( $T_J$ max)	150°C
MSOP	
Power Dissipation	$(T_J \text{ max} - T_A)/\theta_{JA}$
$\theta_{JA}$ Thermal Impedance	206°C/W
$\theta_{JC}$ Thermal Impedance	44°C/W
Reflow Soldering	
Peak Temperature	220°C
Time at Peak Temperature	10 sec to 40 sec

<sup>1</sup> Transient currents of up to 100 mA do not cause SCR latch-up.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### ESD CAUTION

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although this product features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



# AD5305/AD5315/AD5325

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

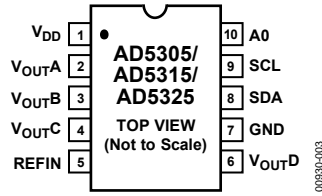


Figure 3. Pin Configuration

Table 5. Pin Function Descriptions

Pin No.	Mnemonic	Description
1	V <sub>DD</sub>	Power Supply Input. These parts can be operated from 2.5 V to 5.5 V and the supply should be decoupled to GND.
2	V <sub>OUTA</sub>	Buffered Analog Output Voltage from DAC A. The output amplifier has rail-to-rail operation.
3	V <sub>OUTB</sub>	Buffered Analog Output Voltage from DAC B. The output amplifier has rail-to-rail operation.
4	V <sub>OUTC</sub>	Buffered Analog Output Voltage from DAC C. The output amplifier has rail-to-rail operation.
5	REFIN	Reference Input Pin for All Four DACs. It has an input range from 0.25 V to V <sub>DD</sub> .
6	V <sub>OUTD</sub>	Buffered Analog Output Voltage from DAC D. The output amplifier has rail-to-rail operation.
7	GND	Ground Reference Point for All Circuitry on the Part.
8	SDA	Serial Data Line. This is used in conjunction with the SCL line to clock data into or out of the 16-bit input shift register. It is a bidirectional open-drain data line that should be pulled to the supply with an external pull-up resistor.
9	SCL	Serial Clock Line. This is used in conjunction with the SDA line to clock data into or out of the 16-bit input shift register. Clock rates of up to 400 kb/s can be accommodated in the 2-wire interface.
10	A0	Address Input. Sets the least significant bit of the 7-bit slave address.

# TYPICAL PERFORMANCE CHARACTERISTICS

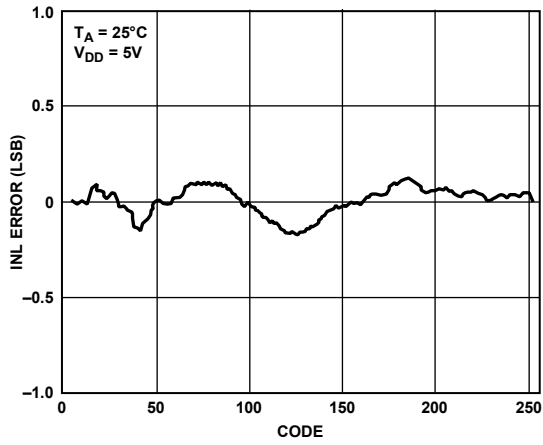


Figure 4. AD5305 Typical INL Plot

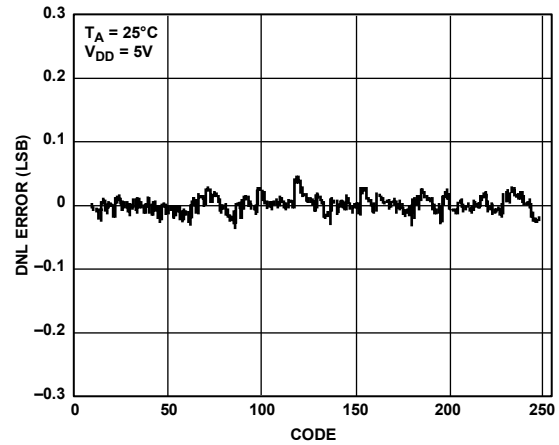


Figure 7. AD5305 Typical DNL Plot

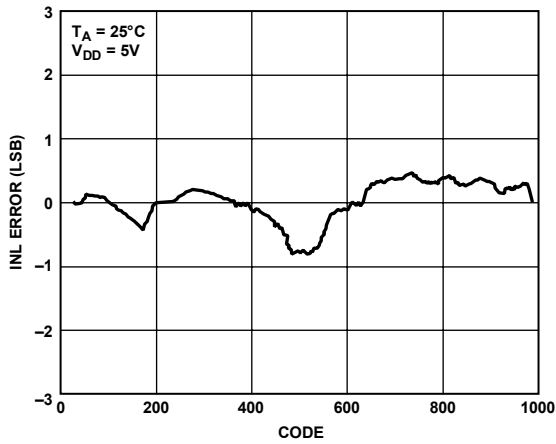


Figure 5. AD5315 Typical INL Plot

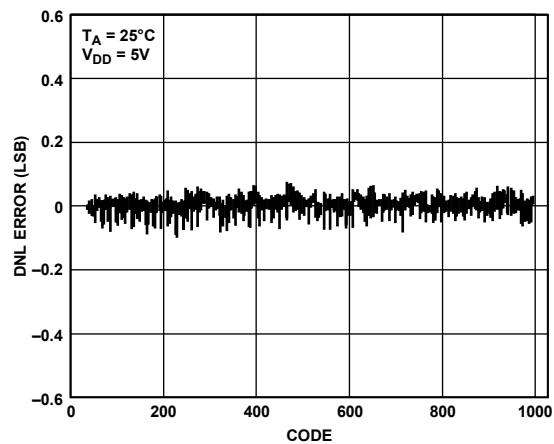


Figure 8. AD5315 Typical DNL Plot

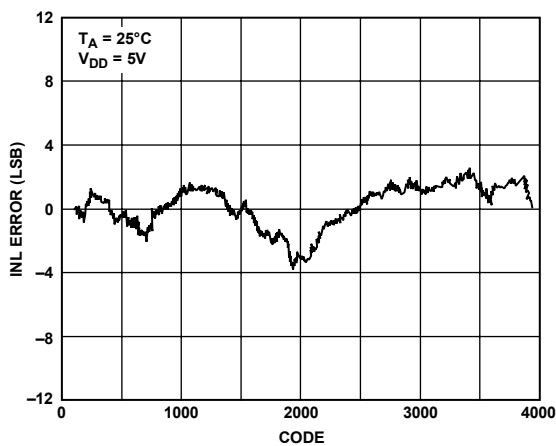


Figure 6. AD5325 Typical INL Plot

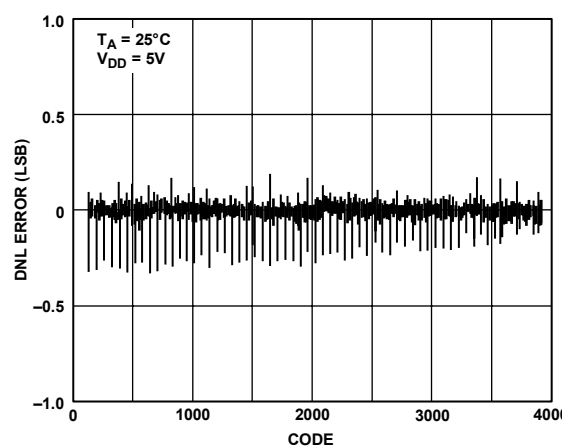


Figure 9. AD5325 Typical DNL Plot



# AD5305/AD5315/AD5325

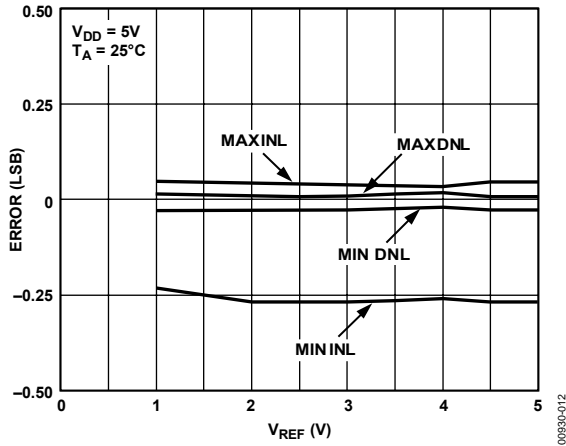


Figure 10. AD5305 INL and DNL Error vs.  $V_{REF}$

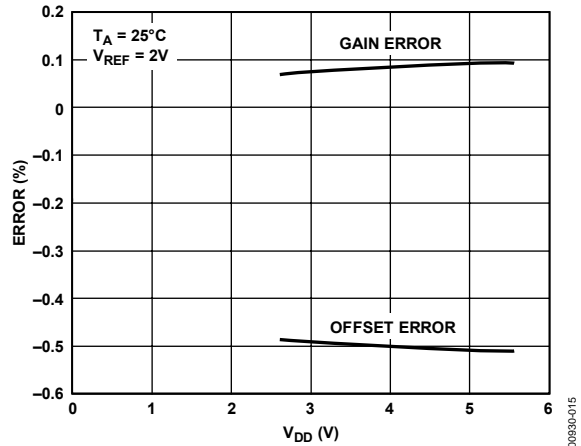


Figure 13. Offset Error and Gain Error vs.  $V_{DD}$

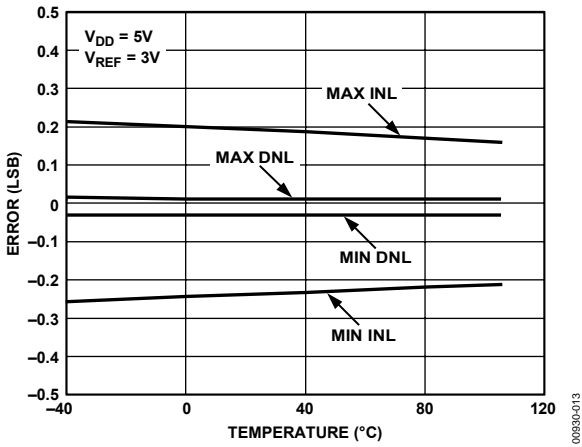


Figure 11. AD5305 INL and DNL Error vs. Temperature

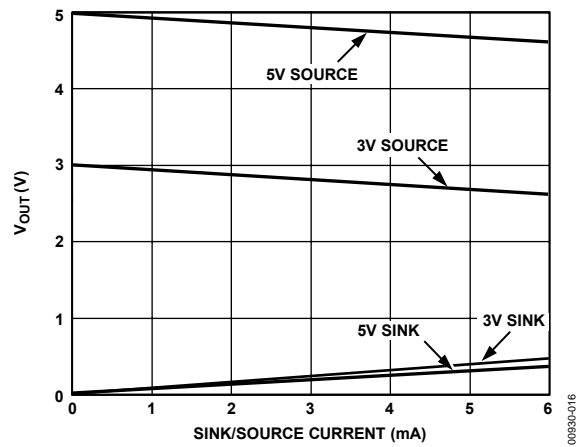


Figure 14.  $V_{OUT}$  Source and Sink Current Capability

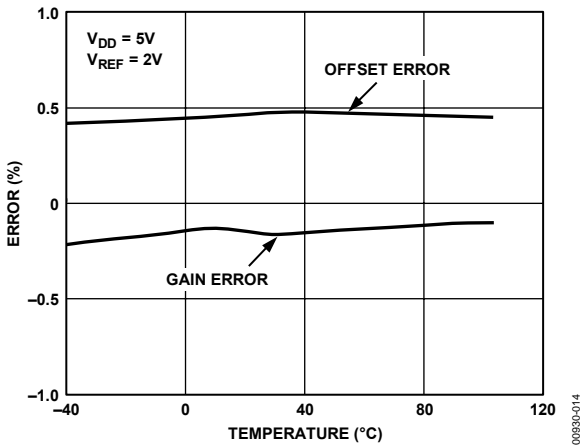


Figure 12. AD5305 Offset Error and Gain Error vs. Temperature

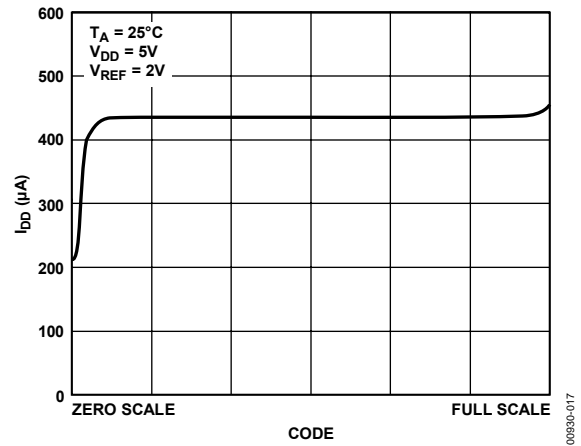


Figure 15. Supply Current vs. DAC Code

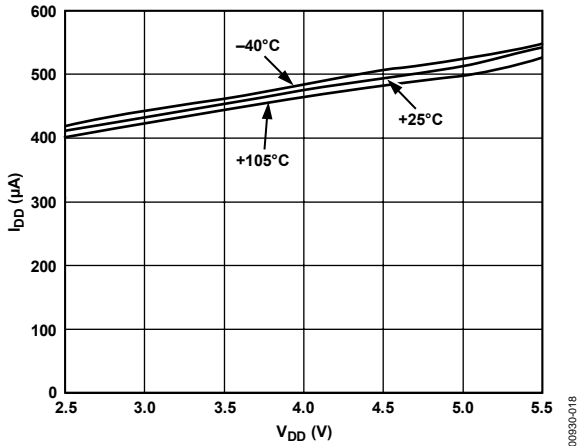


Figure 16. Supply Current vs. Supply Voltage

00930-018

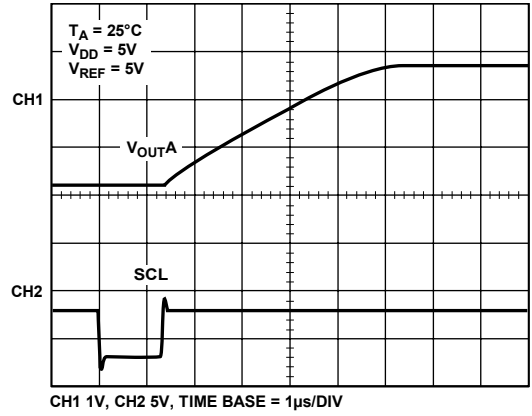


Figure 19. Half-Scale Settling (1/4 to 3/4 Scale Code Change)

00930-021

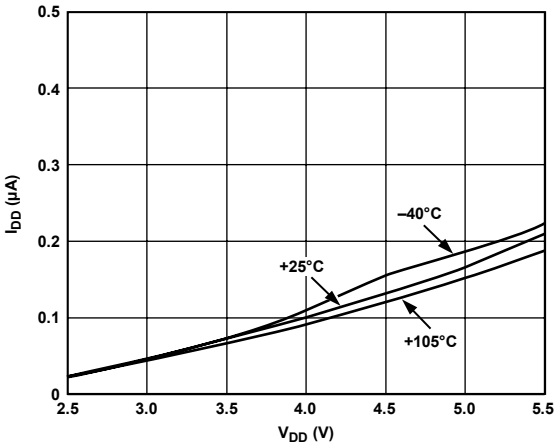


Figure 17. Power-Down Current vs. Supply Voltage

00930-019

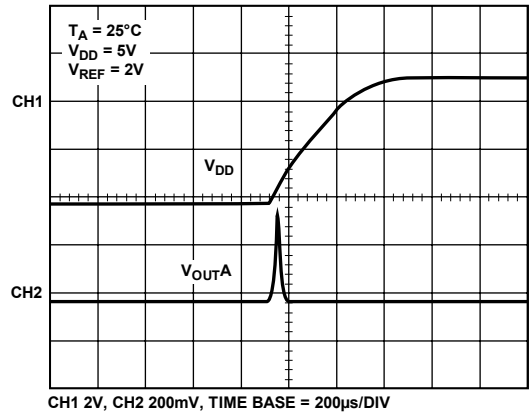


Figure 20. Power-On Reset to 0V

00930-022

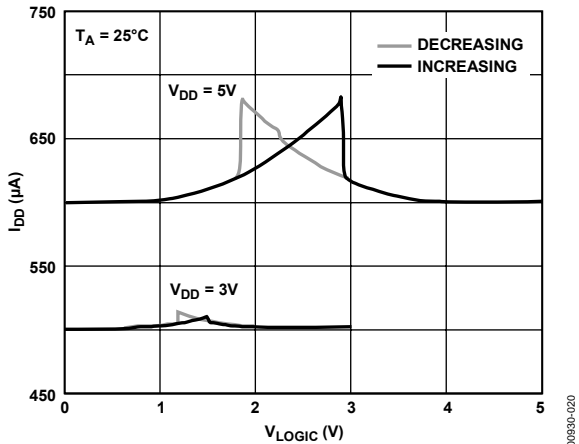


Figure 18. Supply Current vs. Logic Input Voltage for SDA and SCL Voltage Increasing and Decreasing

00930-020

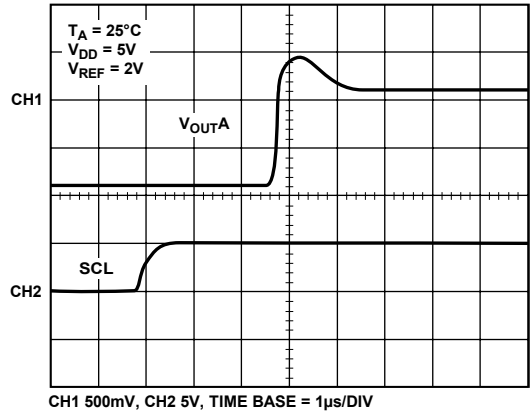


Figure 21. Exiting Power-Down to Midscale

00930-023

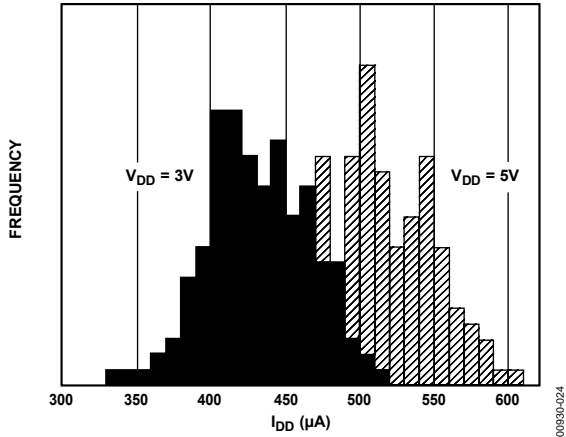


Figure 22.  $I_{DD}$  Histogram with  $V_{DD} = 3\text{ V}$  and  $V_{DD} = 5\text{ V}$

00930-024

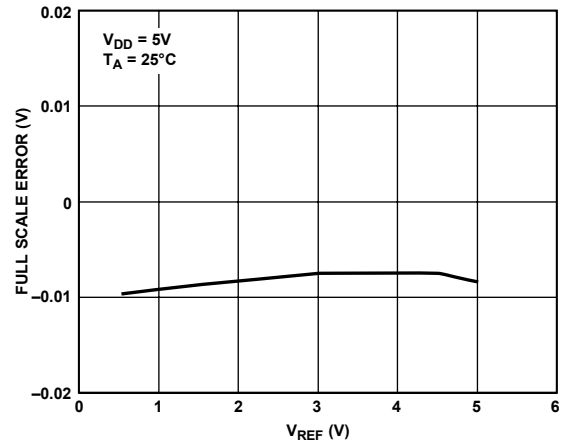


Figure 25. Full-Scale Error vs.  $V_{REF}$

00930-027

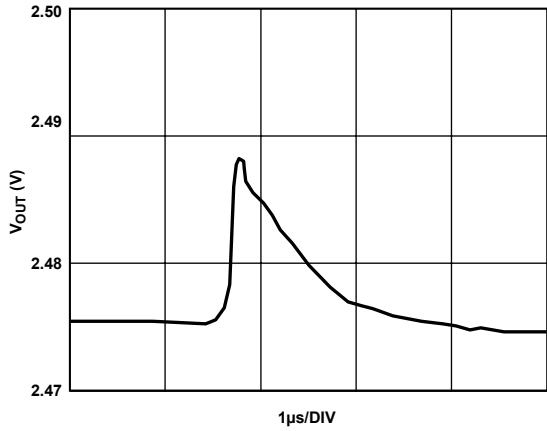


Figure 23. AD5325 Major-Code Transition Glitch Energy

00930-025

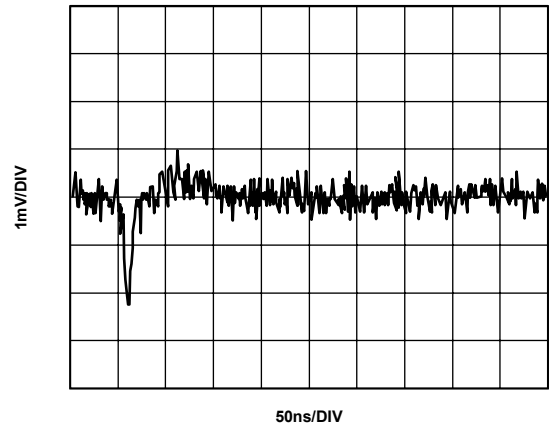


Figure 26. DAC-to-DAC Crosstalk

00930-028

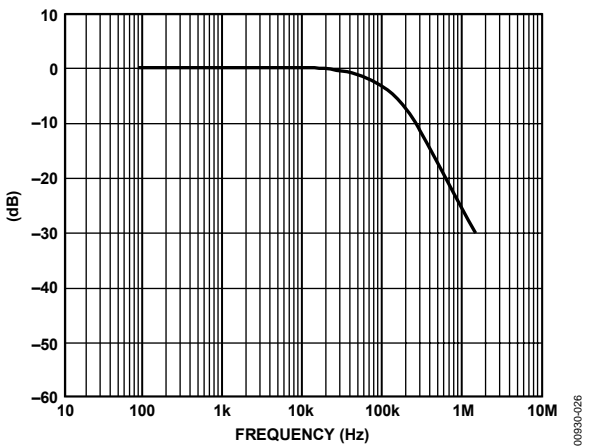


Figure 24. Multiplying Bandwidth (Small-Signal Frequency Response)

00930-026

## TERMINOLOGY

### Relative Accuracy

For the DAC, relative accuracy or integral nonlinearity (INL) is a measure of the maximum deviation, in LSB, from a straight line passing through the endpoints of the DAC transfer function. Typical INL versus code plots can be seen in Figure 4, Figure 5, and Figure 6.

### Differential Nonlinearity

Differential nonlinearity (DNL) is the difference between the measured change and the ideal 1 LSB change between any two adjacent codes. A specified differential nonlinearity of  $\pm 1$  LSB maximum ensures monotonicity. This DAC is guaranteed monotonic by design. Typical DNL vs. code plots can be seen in Figure 7, Figure 8, and Figure 9.

### Offset Error

This is a measure of the offset error of the DAC and the output amplifier. It is expressed as a percentage of the full-scale range.

### Gain Error

This is a measure of the span error of the DAC. It is the deviation in slope of the actual DAC transfer characteristic from the ideal expressed as a percentage of the full-scale range.

### Offset Error Drift

This is a measure of the change in offset error with changes in temperature. It is expressed in (ppm of full-scale range)/ $^{\circ}\text{C}$ .

### Gain Error Drift

This is a measure of the change in gain error with changes in temperature. It is expressed in (ppm of full-scale range)/ $^{\circ}\text{C}$ .

### Power Supply Rejection Ratio (PSRR)

This indicates how the output of the DAC is affected by changes in the supply voltage. PSRR is the ratio of the change in  $V_{\text{OUT}}$  to a change in  $V_{\text{DD}}$  for full-scale output of the DAC. It is measured in dB.  $V_{\text{REF}}$  is held at 2 V and  $V_{\text{DD}}$  is varied  $\pm 10\%$ .

### DC Crosstalk

This is the dc change in the output level of one DAC at midscale in response to a full-scale code change (all 0s to all 1s and vice versa) and output change of another DAC. It is expressed in  $\mu\text{V}$ .

### Reference Feedthrough

This is the ratio of the amplitude of the signal at the DAC output to the reference input when the DAC output is not being updated. It is expressed in dB.

### Major-Code Transition Glitch Energy

Major-code transition glitch energy is the energy of the impulse injected into the analog output when the code in the DAC register changes state. It is normally specified as the area of the glitch in nV-s and is measured when the digital code is changed by 1 LSB at the major carry transition (011 . . . 11 to 100 . . . 00, or 100 . . . 00 to 011 . . . 11).

### Digital Feedthrough

Digital feedthrough is a measure of the impulse injected into the analog output of the DAC from the digital input pins of the device when the DAC output is not being updated. It is specified in nV-s and is measured with a worst-case change on the digital input pins, for example, from all 0s to all 1s or vice versa.

### Digital Crosstalk

This is the glitch impulse transferred to the output of one DAC at midscale in response to a full-scale code change (all 0s to all 1s and vice versa) in the input register of another DAC. It is expressed in nV-s.

### DAC-to-DAC Crosstalk

This is the glitch impulse transferred to the output of one DAC due to a digital code change and subsequent output change of another DAC. This includes both digital and analog crosstalk. It is measured by loading one of the DACs with a full-scale code change (all 0s to all 1s and vice versa) with the  $\overline{\text{LDAC}}$  bit set low and monitoring the output of another DAC. The energy of the glitch is expressed in nV-s.

### Multiplying Bandwidth

The amplifiers within the DAC have a finite bandwidth. The multiplying bandwidth is a measure of this. A sine wave on the reference (with full-scale code loaded to the DAC) appears on the output. The multiplying bandwidth is the frequency at which the output amplitude falls to 3 dB below the input.

### Total Harmonic Distortion (THD)

This is the difference between an ideal sine wave and its attenuated version using the DAC. The sine wave is used as the reference for the DAC and the THD is a measure of the harmonics present on the DAC output. It is measured in dB.

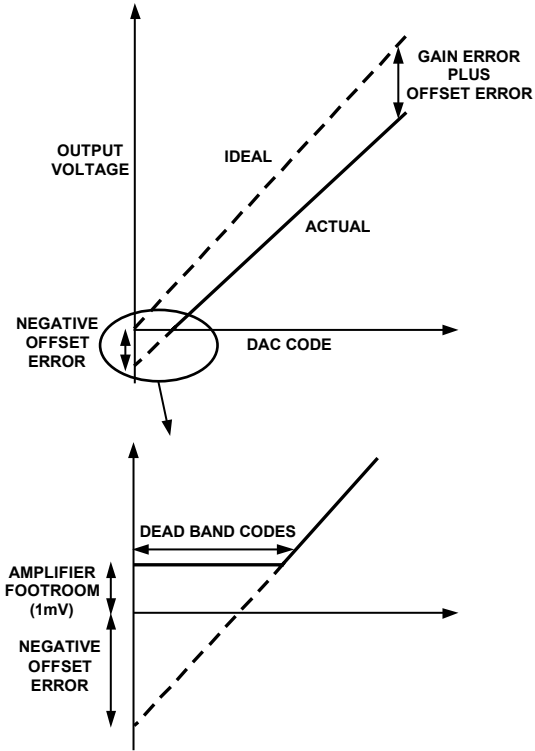


Figure 27. Transfer Function with Negative Offset

00930-004

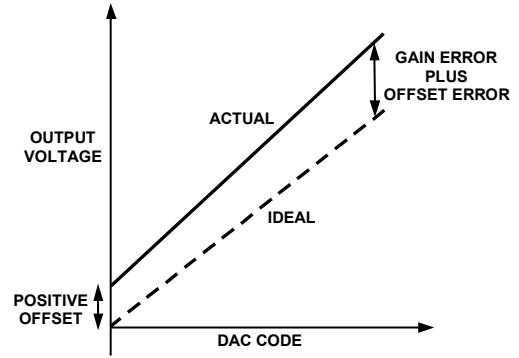


Figure 28. Transfer Function with Positive Offset

00930-005

## FUNCTIONAL DESCRIPTION

The AD5305/AD5315/AD5325 are quad resistor-string DACs fabricated on a CMOS process with resolutions of 8, 10, and 12 bits, respectively. Each contains four output buffer amplifiers and is written to via a 2-wire serial interface. They operate from single supplies of 2.5 V to 5.5 V, and the output buffer amplifiers provide rail-to-rail output swing with a slew rate of 0.7 V/ $\mu$ s. The four DACs share a single reference input pin. The devices have three programmable power-down modes, in which all DACs can be turned off completely with a high impedance output, or the outputs can be pulled low by on-chip resistors.

### DIGITAL-TO-ANALOG SECTION

The architecture of one DAC channel consists of a resistor-string DAC followed by an output buffer amplifier. The voltage at the REFIN pin provides the reference voltage for the DAC. Figure 29 shows a block diagram of the DAC architecture. Because the input coding to the DAC is straight binary, the ideal output voltage is given by

$$V_{OUT} = \frac{V_{REF} \times D}{2^N}$$

where:

$D$  = decimal equivalent of the binary code, which is loaded to the DAC register:

0 to 255 for AD5305 (8 bits)

0 to 1023 for AD5315 (10 bits)

0 to 4095 for AD5325 (12 bits)

$N$  = DAC resolution

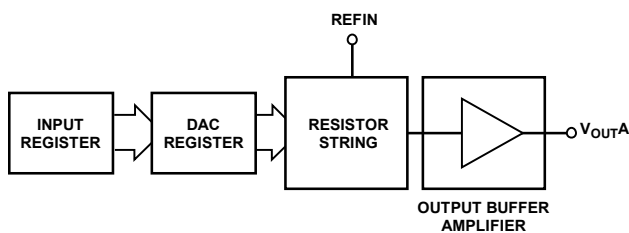


Figure 29. DAC Channel Architecture

### RESISTOR STRING

The resistor string section is shown in Figure 30. It is simply a string of resistors, each of value  $R$ . The digital code loaded to the DAC register determines at what node on the string the voltage is tapped off to be fed into the output amplifier. The voltage is tapped off by closing one of the switches connecting the string to the amplifier. Because it is a string of resistors, it is guaranteed monotonic.

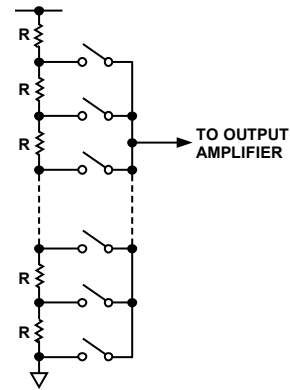


Figure 30. Resistor String

### DAC REFERENCE INPUTS

There is a single reference input pin for the four DACs. The reference input is unbuffered. The user can have a reference voltage as low as 0.25 V and as high as  $V_{DD}$  because there is no restriction due to headroom and footroom of any reference amplifier.

It is recommended to use a buffered reference in the external circuit (for example, REF192). The input impedance is typically 45 k $\Omega$ .

### OUTPUT AMPLIFIER

The output buffer amplifier is capable of generating rail-to-rail voltages on its output, which gives an output range of 0 V to  $V_{DD}$  when the reference is  $V_{DD}$ . It is capable of driving a load of 2 k $\Omega$  to GND or  $V_{DD}$ , in parallel with 500 pF to GND or  $V_{DD}$ . The source and sink capabilities of the output amplifier can be seen in the plot in Figure 14.

The slew rate is 0.7 V/ $\mu$ s with a half-scale settling time to  $\pm 0.5$  LSB (at eight bits) of 6  $\mu$ s.

### POWER-ON RESET

The AD5305/AD5315/AD5325 are provided with a power-on reset function, so that they power up in a defined state. The power-on state is

- Normal operation
- Output voltage set to 0 V

Both input and DAC registers are filled with zeros and remain so until a valid write sequence is made to the device. This is particularly useful in applications where it is important to know the state of the DAC outputs while the device is powering up.

# AD5305/AD5315/AD5325

## SERIAL INTERFACE

The AD5305/AD5315/AD5325 are controlled via an I<sup>2</sup>C compatible serial bus. The DACs are connected to this bus as slave devices (that is, no clock is generated by the AD5305/AD5315/AD5325 DACs). This interface is SMBus compatible at  $V_{DD} < 3.6$  V.

The AD5305/AD5315/AD5325 have a 7-bit slave address. The 6 MSB are 000110 and the LSB is determined by the state of the A0 pin. The facility to make hardwired changes to A0 allows the user to use up to two of these devices on one bus. The 2-wire serial bus protocol operates as follows:

1. The master initiates data transfer by establishing a start condition, which is when a high-to-low transition on the SDA line occurs while SCL is high. The following byte is the address byte, which consists of the 7-bit slave address followed by an  $\overline{R/\overline{W}}$  bit (this bit determines whether data is read from or written to the slave device).

The slave whose address corresponds to the transmitted address responds by pulling SDA low during the ninth clock pulse (this is termed the acknowledge bit). At this stage, all other devices on the bus remain idle while the selected device waits for data to be written to or read from its shift register.

2. Data is transmitted over the serial bus in sequences of nine clock pulses (eight data bits followed by an acknowledge bit). The transitions on the SDA line must occur during the low period of SCL and remain stable during the high period of SCL.
3. When all data bits have been read or written, a stop condition is established. In write mode, the master pulls the SDA line high during the 10<sup>th</sup> clock pulse to establish a stop condition. In read mode, the master issues a No Acknowledge for the ninth clock pulse (that is, the SDA line remains high). The master then brings the SDA line low before the 10<sup>th</sup> clock pulse and then high during the 10<sup>th</sup> clock pulse to establish a stop condition.

## READ/WRITE SEQUENCE

In the case of the AD5305/AD5315/AD5325, all write access sequences and most read sequences begin with the device address (with  $\overline{R/\overline{W}} = 0$ ) followed by the pointer byte. This pointer byte specifies the data format and determines which DAC is being accessed in the subsequent read/write operation (see Figure 31). In a write operation, the data follows immediately. In a read operation, the address is resent with  $\overline{R/\overline{W}} = 1$  and then the data is read back. However, it is also possible to perform a read operation by sending only the address with  $\overline{R/\overline{W}} = 1$ . The previously loaded pointer settings are then used for the readback operation. See Figure 32 for a graphical explanation of the interface.

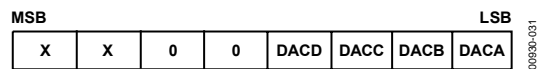


Figure 31. Pointer Byte

## POINTER BYTE BITS

Table 6 explains the individual bits that make up the pointer byte.

Table 6. Individual Bits of the Pointer Byte

Bit	Description
X	Don't care bits.
0	Reserved bits. Must be set to 0.
DACD	[1] The following data bytes are for DAC D.
DACC	[1] The following data bytes are for DAC C.
DACB	[1] The following data bytes are for DAC B.
DACA	[1] The following data bytes are for DAC A.

## INPUT SHIFT REGISTER

The input shift register is 16 bits wide. Data is loaded into the device as two data bytes on the serial data line, SDA, under the control of the serial clock input, SCL. The timing diagram for this operation is shown in Figure 2. The two data bytes consist of four control bits followed by 8, 10, or 12 bits of DAC data, depending on the device type. The first two bits loaded are the PD1 and PD0 bits that control the mode of operation of the device. See the Power-Down Modes section for a complete description. Bit 13 is  $\overline{CLR}$ , Bit 12 is  $\overline{LDAC}$ , and the remaining bits are left justified DAC data bits, starting with the MSB. See Figure 32.

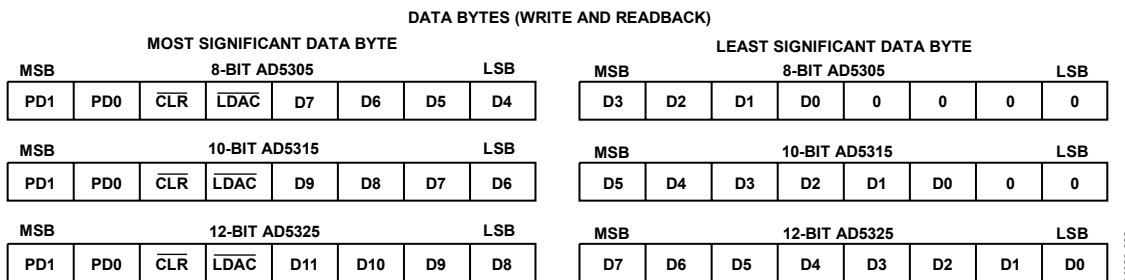


Figure 32. Data Formats for Write and Readback

Table 7.  $\overline{\text{CLR}}$  and  $\overline{\text{LDAC}}$  Bit Descriptions

Bit	Description
$\overline{\text{CLR}}$	[0] All DAC registers and input registers are filled with 0s on completion of the write sequence. [1] Normal operation.
$\overline{\text{LDAC}}$	[0] All four DAC registers and, therefore, all DAC outputs, are simultaneously updated on completion of the write sequence. [1] Only addressed input register is updated. There is no change in the contents of the DAC registers.

**DEFAULT READBACK CONDITION**

All pointer byte bits power up to 0. Therefore, if the user initiates a readback without writing to the pointer byte first, no single DAC channel has been specified. In this case, the default readback bits are all 0, except for the  $\overline{\text{CLR}}$  bit, which is a 1.

**MULTIPLE-DAC WRITE SEQUENCE**

Because there are individual bits in the pointer byte for each DAC, it is possible to simultaneously write the same data and control bits to 2, 3, or 4 DACs by setting the relevant bits to 1.

**MULTIPLE-DAC READBACK SEQUENCE**

If the user attempts to read back data from more than one DAC at a time, the part reads back the default, power-on reset conditions, that is, all 0s except for  $\overline{\text{CLR}}$ , which is 1.

**WRITE OPERATION**

When writing to the AD5305/AD5315/AD5325 DACs, the user must begin with an address byte ( $R/\overline{W} = 0$ ), after which the DAC acknowledges that it is prepared to receive data by pulling SDA low. This address byte is followed by the pointer byte, which is also acknowledged by the DAC. Two bytes of data are then written to the DAC, as shown in Figure 33. A stop condition follows.

**READ OPERATION**

When reading data back from the AD5305/AD5315/AD5325 DACs, the user begins with an address byte ( $R/\overline{W} = 0$ ), after which the DAC acknowledges that it is prepared to receive data by pulling SDA low. This address byte is usually followed by the pointer byte, which is also acknowledged by the DAC. Following this, there is a repeated start condition by the master and the address is resent with  $R/\overline{W} = 1$ . This is acknowledged by the DAC indicating that it is prepared to transmit data. Two bytes of data are then read from the DAC, as shown in Figure 34. A stop condition follows.

However, if the master sends an ACK and continues clocking SCL (no STOP is sent), the DAC retransmits the same two bytes of data on SDA. This allows continuous readback of data from the selected DAC register.

Alternatively, the user can send a start followed by the address with  $R/\overline{W} = 1$ . In this case, the previously loaded pointer settings are used and readback of data can commence immediately.

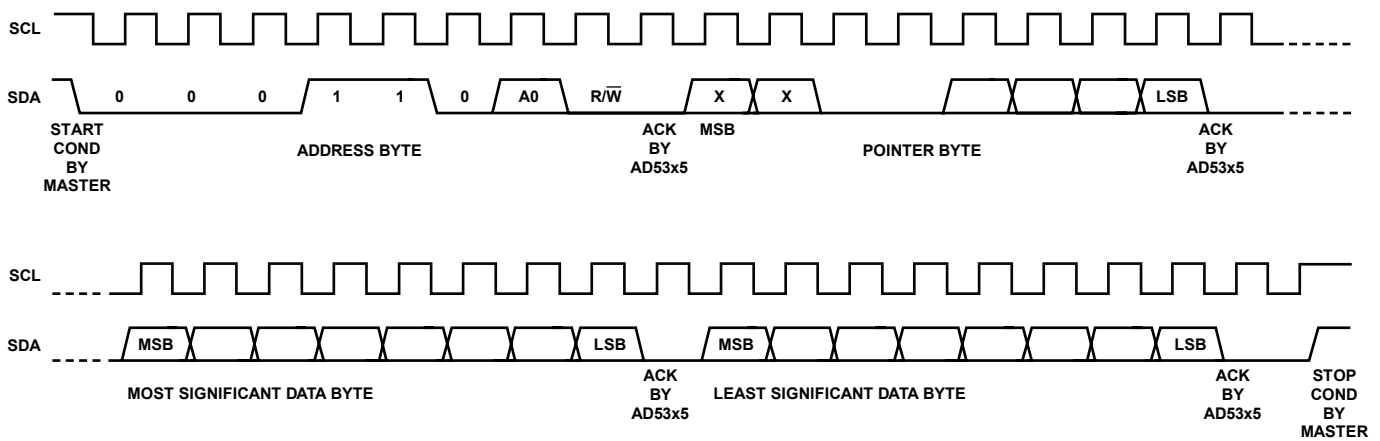
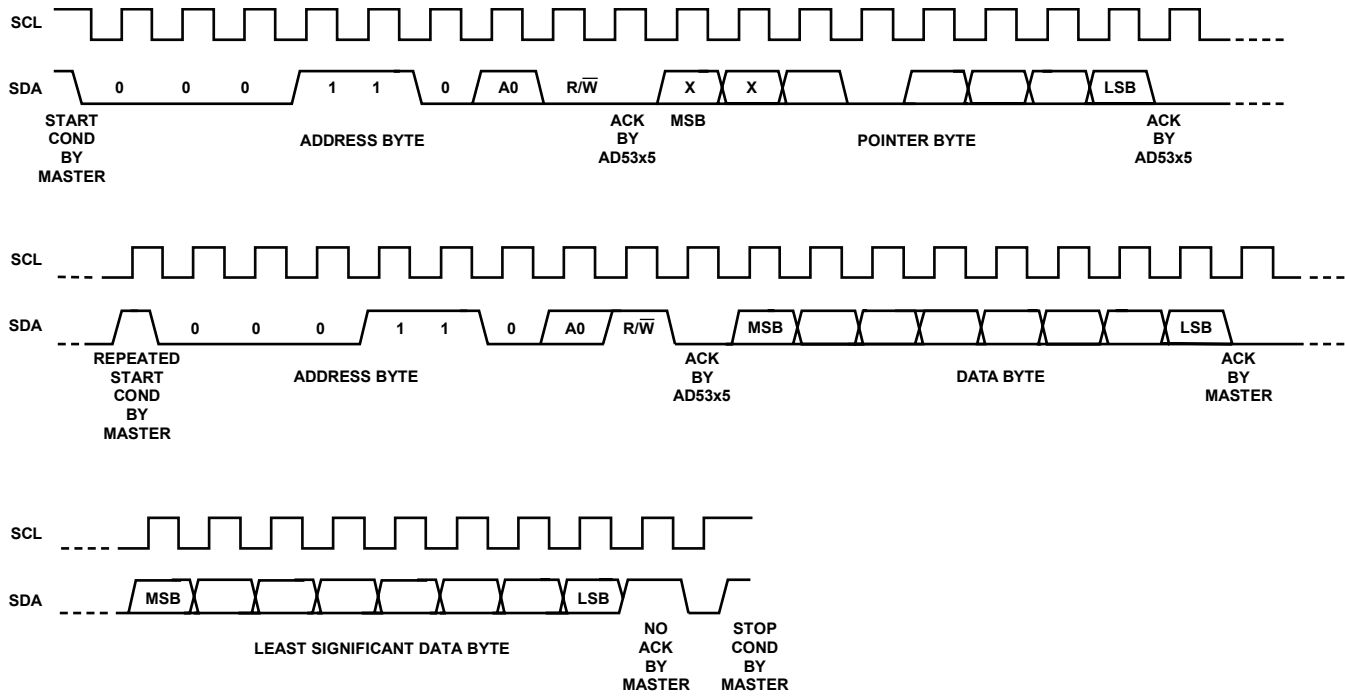


Figure 33. Write Sequence

009340-033



# AD5305/AD5315/AD5325



NOTE: DATA BYTES ARE THE SAME AS THOSE IN THE WRITE SEQUENCE EXCEPT THAT DON'T CARES ARE READ BACK AS 0s.

Figure 34. Readback Sequence

009340-034

## DOUBLE-BUFFERED INTERFACE

The AD5305/AD5315/AD5325 DACs have double-buffered interfaces consisting of two banks of registers—input registers and DAC registers. The input register is directly connected to the input shift register and the digital code is transferred to the relevant input register on completion of a valid write sequence. The DAC register contains the digital code used by the resistor string.

Access to the DAC register is controlled by the  $\overline{\text{LDAC}}$  bit. When the  $\overline{\text{LDAC}}$  bit is set high, the DAC register is latched and, therefore, the input register can change state without affecting the contents of the DAC register. However, when the  $\overline{\text{LDAC}}$  bit is set low, the DAC register becomes transparent and the contents of the input register are transferred to it.

This is useful if the user requires simultaneous updating of all DAC outputs. The user can write to three of the input registers individually and then, by setting the  $\overline{\text{LDAC}}$  bit low when writing to the remaining DAC input register, all outputs update simultaneously.

These parts contain an extra feature whereby the DAC register is not updated unless its input register has been updated since the last time that  $\overline{\text{LDAC}}$  was brought low. Normally, when  $\overline{\text{LDAC}}$  is brought low, the DAC registers are filled with the contents of the input registers. In the case of the AD5305/AD5315/AD5325, the part updates the DAC register only if the input register has been changed since the last time the DAC register was updated, thereby removing unnecessary digital crosstalk.

## POWER-DOWN MODES

The AD5305/AD5315/AD5325 have very low power consumption, dissipating typically 1.5 mW with a 3 V supply and 3 mW with a 5 V supply. Power consumption can be further reduced when the DACs are not in use by putting them into one of three power-down modes, which are selected by Bit 15 and Bit 14 (PD1 and PD0) of the data byte. Table 8 shows how the state of the bits corresponds to the mode of operation of the DAC.

Table 8. PD1/PD0 Operating Modes

PD1	PD0	Operating Mode
0	0	Normal Operation
0	1	Power-Down (1 k $\Omega$ load to GND)
1	0	Power-Down (100 k $\Omega$ load to GND)
1	1	Power-Down (three-state output)

When both bits are set to 0, the DAC works normally with its normal power consumption of 600  $\mu\text{A}$  at 5 V. However, for the three power-down modes, the supply current falls to 200 nA at 5 V (80 nA at 3 V). Not only does the supply current drop, but the output stage is also internally switched from the output of the amplifier to a resistor network of known values. This has an advantage because the output impedance of the part is known while the part is in power-down mode and provides a defined input condition for whatever is connected to the output of the DAC amplifier. There are three different options. The output is connected internally to GND through a 1 k $\Omega$  resistor, a 100 k $\Omega$  resistor, or it is left open-circuited (three-state). Resistor tolerance =  $\pm 20\%$ . The output stage is illustrated in Figure 35.

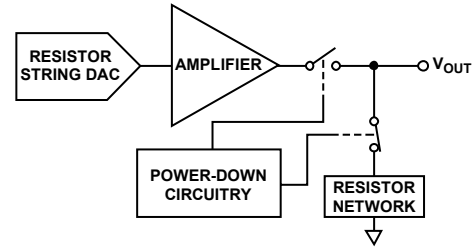


Figure 35. Output Stage During Power-Down

The bias generator, the output amplifiers, the resistor string, and all other associated linear circuitry are shut down when the power-down mode is activated. However, the contents of the DAC registers are unchanged when in power-down. The time to exit power-down is typically 2.5  $\mu\text{s}$  for  $V_{\text{DD}} = 5 \text{ V}$  and 5  $\mu\text{s}$  when  $V_{\text{DD}} = 3 \text{ V}$ . This is the time from the rising edge of the eighth SCL pulse to when the output voltage deviates from its power-down voltage. See Figure 21 for a plot.

## APPLICATIONS

### TYPICAL APPLICATION CIRCUIT

The AD5305/AD5315/AD5325 can be used with a wide range of reference voltages where the devices offer full, one-quadrant multiplying capability over a reference range of 0 V to  $V_{DD}$ . More typically, these devices are used with a fixed, precision reference voltage. Suitable references for 5 V operation are the AD780 and REF192 (2.5 V references). For 2.5 V operation, a suitable external reference is the AD589, a 1.23 V band gap reference. Figure 36 shows a typical setup for the AD5305/AD5315/AD5325 when using an external reference. Note that A0 can be high or low.

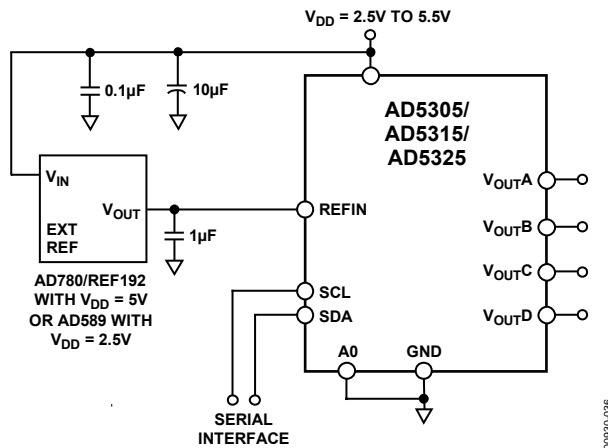


Figure 36. AD5305/AD5315/AD5325 Using External Reference

If an output range of 0 V to  $V_{DD}$  is required, the simplest solution is to connect the reference input to  $V_{DD}$ . As this supply may not be very accurate and may be noisy, the AD5305/AD5315/AD5325 can be powered from the reference voltage; for example, using a 5 V reference such as the REF195. The REF195 outputs a steady supply voltage for the AD5305/AD5315/AD5325. The typical current required from the REF195 is 600  $\mu$ A supply current and approximately 112  $\mu$ A into the reference input. This is with no load on the DAC outputs. When the DAC outputs are loaded, the REF195 also needs to supply the current to the loads. The total current required (with a 10 k $\Omega$  load on each output) is

$$712 \mu\text{A} + 4(5 \text{ V}/10 \text{ k}\Omega) = 2.70 \text{ mA}$$

The load regulation of the REF195 is typically 2 ppm/mA, which results in an error of 5.4 ppm (27  $\mu$ V) for the 2.7 mA current drawn from it. This corresponds to a 0.0014 LSB error at eight bits and 0.022 LSB error at 12 bits.

### BIPOLAR OPERATION

The AD5305/AD5315/AD5325 have been designed for single supply operation, but a bipolar output range is also possible using the circuit in Figure 37. This circuit gives an output voltage range of 5 V. Rail-to-rail operation at the amplifier output is achievable using an AD820 or an OP295 as the output amplifier.

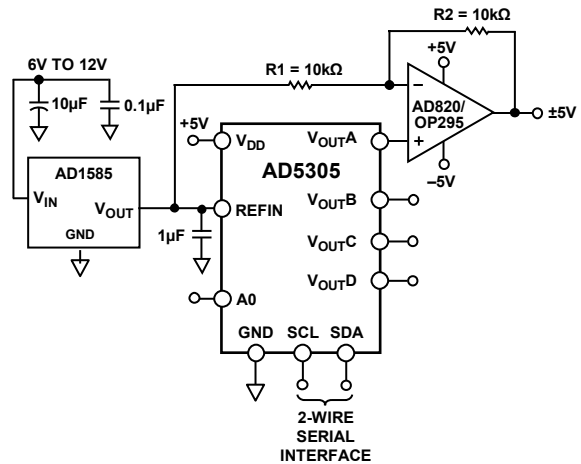


Figure 37. Bipolar Operation with the AD5305

The output voltage for any input code can be calculated as follows:

$$V_{OUT} = \left[ \frac{(REFIN \times (D/2^N)) \times (R1 + R2)}{R1} - REFIN \times (R2/R1) \right]$$

where:

$D$  is the decimal equivalent of the code loaded to the DAC.

$N$  is the DAC resolution.

$REFIN$  is the reference voltage input.

with

$$REFIN = 5 \text{ V}, R1 = R2 = 10 \text{ k}\Omega, V_{OUT} (10 \times D/2^N) - 5 \text{ V}$$

### MULTIPLE DEVICES ON ONE BUS

Figure 38 shows two AD5305 devices on the same serial bus. Each has a different slave address because the state of the A0 pin is different. This allows each of eight DACs to be written to or read from independently.

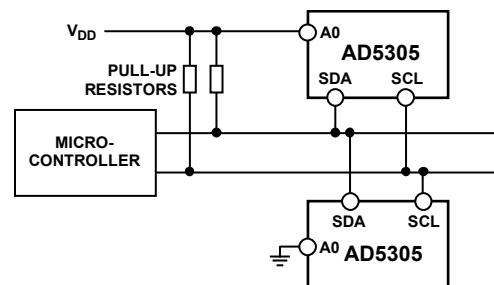


Figure 38. Multiple AD5305 Devices on One Bus



# AD5305/AD5315/AD5325

Table 9. Overview of All AD53xx Serial Devices

Part No.	Resolution	No. of DACs	DNL	Interface	Settling Time ( $\mu$ s)	Package	Pins
<b>SINGLES</b>							
AD5300	8	1	$\pm 0.25$	SPI <sup>®</sup>	4	SOT-23, MSOP	6, 8
AD5310	10	1	$\pm 0.5$	SPI	6	SOT-23, MSOP	6, 8
AD5320	12	1	$\pm 1.0$	SPI	8	SOT-23, MSOP	6, 8
AD5301	8	1	$\pm 0.25$	2-Wire	6	SOT-23, MSOP	6, 8
AD5311	10	1	$\pm 0.5$	2-Wire	7	SOT-23, MSOP	6, 8
AD5321	12	1	$\pm 1.0$	2-Wire	8	SOT-23, MSOP	6, 8
<b>DUALS</b>							
AD5302	8	2	$\pm 0.25$	SPI	6	MSOP	8
AD5312	10	2	$\pm 0.5$	SPI	7	MSOP	8
AD5322	12	2	$\pm 1.0$	SPI	8	MSOP	8
AD5303	8	2	$\pm 0.25$	SPI	6	TSSOP	16
AD5313	10	2	$\pm 0.5$	SPI	7	TSSOP	16
AD5323	12	2	$\pm 1.0$	SPI	8	TSSOP	16
<b>QUADS</b>							
AD5304	8	4	$\pm 0.25$	SPI	6	MSOP	10
AD5314	10	4	$\pm 0.5$	SPI	7	MSOP	10
AD5324	12	4	$\pm 1.0$	SPI	8	MSOP	10
AD5305	8	4	$\pm 0.25$	2-Wire	6	MSOP	10
AD5315	10	4	$\pm 0.5$	2-Wire	7	MSOP	10
AD5325	12	4	$\pm 1.0$	2-Wire	8	MSOP	10
AD5306	8	4	$\pm 0.25$	2-Wire	6	TSSOP	16
AD5316	10	4	$\pm 0.5$	2-Wire	7	TSSOP	16
AD5326	12	4	$\pm 1.0$	2-Wire	8	TSSOP	16
AD5307	8	4	$\pm 0.25$	SPI	6	TSSOP	16
AD5317	10	4	$\pm 0.5$	SPI	7	TSSOP	16
AD5327	12	4	$\pm 1.0$	SPI	8	TSSOP	16
<b>OCTALS</b>							
AD5308	8	8	$\pm 0.25$	SPI	6	TSSOP	16
AD5318	10	8	$\pm 0.5$	SPI	7	TSSOP	16
AD5328	12	8	$\pm 1.0$	SPI	8	TSSOP	16

Table 10. Overview of AD53xx Parallel Devices

Part No.	Resolution	DNL	V <sub>REF</sub> Pins	Settling Time ( $\mu$ s)	Additional Pin Functions				Package	Pins
					BUF	GAIN	HBEN	CLR		
<b>SINGLES</b>										
AD5330	8	$\pm 0.25$	1	6	✓	✓		✓	TSSOP	20
AD5331	10	$\pm 0.5$	1	7		✓		✓	TSSOP	20
AD5340	12	$\pm 1.0$	1	8	✓	✓		✓	TSSOP	24
AD5341	12	$\pm 1.0$	1	8	✓	✓	✓	✓	TSSOP	20
<b>DUALS</b>										
AD5332	8	$\pm 0.25$	2	6				✓	TSSOP	20
AD5333	10	$\pm 0.5$	2	7	✓	✓		✓	TSSOP	24
AD5342	12	$\pm 1.0$	2	8	✓	✓		✓	TSSOP	28
AD5343	12	$\pm 1.0$	1	8			✓	✓	TSSOP	20
<b>QUADS</b>										
AD5334	8	$\pm 0.25$	2	6		✓		✓	TSSOP	24
AD5335	10	$\pm 0.5$	2	7			✓	✓	TSSOP	24
AD5336	10	$\pm 0.5$	4	7		✓		✓	TSSOP	28
AD5344	12	$\pm 1.0$	4	8					TSSOP	28



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