# Digital Step Attenuator 50Ω DC-4000 MHz

31.5 dB, 0.5 dB Step 6 Bit, Parallel Control Interface, Single Supply Voltage

#### **Product Features**

- Immune to latch up
- Excellent accuracy, 0.1 dB Typ
- Low Insertion Loss
- High IP3, +52 dBm Typ
- Very low DC power consumption
- Excellent return loss, 20 dB Typ
- Small size 4.0 x 4.0 mm



CASE STYLE: DG983-2

for RoHS Compliance methodologies and qualifications

# **Typical Applications**

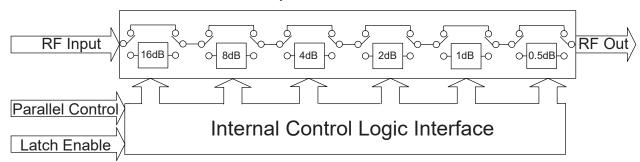
- Base Station Infrastructure
- Portable Wireless
- CATV & DBS
- MMDS & Wireless LAN
- Wireless Local Loop
- UNII & Hiper LAN
- · Power amplifier distortion canceling loops

#### +RoHS Compliant The +Suffix identifies RoHS Compliance. See our web site

# **General Description**

The DAT-31R5A-PP+ is a 50 $\Omega$  RF digital step attenuator that offers an attenuation range up to 31.5 dB in 0.5 dB steps. The control is a 6-bit parallel interface, operating on single (positive) supply voltage. The DAT-31R5A-PP+ is produced using a unique CMOS process on silicon, offering the performance of GaAs, with the advantages of conventional CMOS devices.

#### Simplified Schematic





# RF Electrical Specifications, DC-4000 MHz, T<sub>AMB</sub>=25°C, V<sub>DD</sub>=+3V

Parameter	Freq. Range (GHz)	Min.	Тур.	Max.	Units
	DC-1	_	0.03	0.1	
Accuracy @ 0.5 dB Attenuation Setting	1-2.4	_	0.05	0.15	dB
	2.4-4	_	0.07	0.2	
	DC-1	_	0.02	0.1	
Accuracy @ 1 dB Attenuation Setting	1-2.4	_	0.05	0.15	dB
	2.4-4		0.1	0.25	
	DC-1	_	0.05	0.15	
Accuracy @ 2 dB Attenuation Setting	1-2.4	_	0.15	0.25	dB
	2.4-4		0.15	0.35	
	DC-1	_	0.07	0.2	
Accuracy @ 4 dB Attenuation Setting	1-2.4	_	0.15	0.25	dB
	2.4-4		0.23	0.5	
	DC-1	_	0.03	0.2	dB
Accuracy @ 8 dB Attenuation Setting	1-2.4	_	0.15	0.5	
	2.4-4		0.6	0.8	
	DC-1	_	0.1	0.3	dB
Accuracy @ 16 dB Attenuation Setting	1-2.4	_	0.15	0.7	
	2.4-4		1.1	1.45	
	DC-1	_	1.3	1.9	
Insertion Loss (note 2) @ all attenuator set to 0dB	1-2.4	_	1.6	2.4	dB
	2.4-4	_	2.1	3.0	
Input IP3 (note 3) (at Min. and Max. Attenuation)	DC-4	_	+52	_	dBm
Input Power @ 0.2dB Compression (Note 3) (at Min. and Max. Attenuation)	DC-4	_	+24	_	dBm
Input Operating Power	10 kHz to 50 MHz	_	_	See Fig. 1	dBm
Imput Operating Fower	>50 MHz	_		+24	QDIII
	DC-1	_	1.2	1.5	
VSWR	1-2.4	_	1.2	1.6	:1
	2.4-4	_	1.4	1.9	

#### Notes:

- 1. Tested on Evaluation Board TB-334, See Figure 3.
- 2. Insertion loss values are de-embedded from test board Loss (test board's Insertion Loss: 0.10dB @100MHz, 0.35dB @1000MHz, 0.60dB @2400MHz, 0.75dB @4000MHz).

  3. Input IP3 and 1dB compression degrade below 1 MHz. Input power not to exceed max operating specification for continuous operation.

## **DC Electrical Specifications**

Parameter	Min.	Тур.	Max.	Units
VDD, Supply Voltage	2.3	3	3.6 <sup>(Note 4)</sup>	V
IDD Supply Current	_	_	200	μΑ
Control Input Low	-0.3	_	+0.6	V
Control Input High	1.17	_	3.6	V
Control Current	_	_	20 <sup>(Note 5)</sup>	μΑ

- 4. For operation above +3.6V, see Application Note AN-70-006
- 5. Except, 30µA typ for C0.5, C16, PUP1 at +3.6V

# Absolute Maximum Ratings(Note 6,7)

Parameter	Ratings
Operating Temperature	-40°C to 105°C
Storage Temperature	-65°C to 150°C
V <sub>DD</sub>	-0.3V Min., 5.5V Max.
Voltage on any control input	-0.3V Min., 3.6V Max.
Input Power	+30dBm
Thermal Resistance	37°C/W

<sup>6.</sup> Permanent damage may occur if any of these limits are exceeded.

# **Switching Specifications**

<u> </u>				
Parameter	Min.	Тур.	Max.	Units
Switching Speed, 50% Control to 0.5dB of Attenuation Value	_	1.0	_	μSec
Switching Control Frequency	_	_	25	kHz

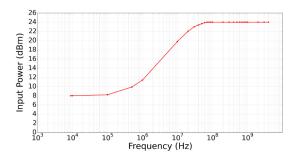


Figure 1. Max Input Operating Power vs Frequency



Operation between max operating and absolute max input power will result in reduced reliability.

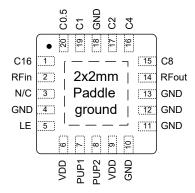
# **Pin Description**

Function	Pin Number	Description
C16	1	Control for Attenuation bit, 16dB (Note 3, 7)
RF in	2	RF in port (Note 1)
N/C	3	Not connected (Note 4)
GND	4	Ground connection
LE	5	Latch Enable Input (Note 2)
$V_{DD}$	6	Positive Supply Voltage
PUP1	7	Power-up selection (Note 7)
PUP2	8	Power-up selection
$V_{DD}$	9	Positive Supply Voltage
GND	10	Ground connection
GND	11	Ground connection
GND	12	Ground connection (Note 6)
GND	13	Ground connection
RF out	14	RF out port (Note 1)
C8	15	Control for attenuation bit, 8 dB
C4	16	Control for attenuation bit, 4 dB
C2	17	Control for attenuation bit, 2 dB
GND	18	Ground Connection
C1	19	Control for attenuation bit, 1 dB
C0.5	20	Control for attenuation bit, 0.5 dB (Note 7)
GND	Paddle	Paddle ground (Note 5)

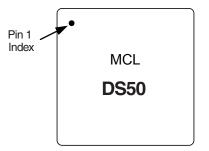
#### Notes

- 1. Both RF ports must be held at 0VDC or DC blocked with an external series capacitor.
- 2. Latch Enable (LE) has an internal 2M  $\!\Omega$  to internal positive supply voltage.
- 3. Place a 10K  $\!\Omega\!$  resistor in series, as close to pin as possible to avoid freq. resonance.
- 4. Place a shunt  $10 \text{K}\Omega$  resistor to GND
- The exposed solder pad on the bottom of the package (See Pin configuration) must be grounded for proper device operation.
- 6. Ground must be less than 80 mil (0.08") from Pin 12 for proper device operation.
- 7. This pin has an internal 200  $k\Omega$  resistor to ground.

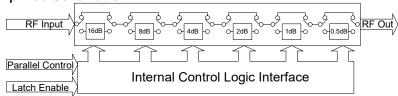
# Pin Configuration (Top View)



# **Device Marking**



**Simplified Schematic** 



The DAT-31R5A-PP+ parallel interface consists of 6 control bits that select the desired attenuation state, as shown in Table 1: Truth Table

Table 1. Truth Table						
Attenuation State	C16	C8	C4	C2	C1	C0.5
Reference	0	0	0	0	0	0
0.5 (dB)	0	0	0	0	0	1
1 (dB)	0	0	0	0	1	0
2 (dB)	0	0	0	1	0	0
4 (dB)	0	0	1	0	0	0
8 (dB)	0	1	0	0	0	0
16 (dB)	1	0	0	0	0	0
31.5 (dB)	1	1	1	1	1	1
Note: Not all 64 possible combinations of C0.5 - C16 are shown in table						

The parallel interface timing requirements are defined by Figure 2 (Parallel Interface Timing Diagram) and Table 2 (Parallel Interface AC Characteristics), and switching speed.

For latched parallel programming the Latch Enable (LE) should be held LOW while changing attenuation state control values, then pulse LE HIGH to LOW (per Figure 1) to latch new attenuation state into device.

For direct parallel programming, the Latch Enable (LE) line should be pulled HIGH. Changing attenuation state control values will change device state to new attenuation. Direct mode is ideal for manual control of the device (using hardwire, switches, or jumpers).

Figure 2: Parallel Interface Timing Diagram

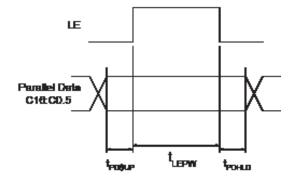


Table 2. Parallel Interface AC Characteristics				
Symbol	Parameter Min. Max.		Max.	Units
t <sub>LEPW</sub>	LE minimum pulse width	10		ns
t <sub>PDSUP</sub>	Data set-up time before clock rising edge of LE		ns	
t <sub>PDHLD</sub>	Data hold time after clock falling edge of LE	10		ns

# **Power-up Control Settings**

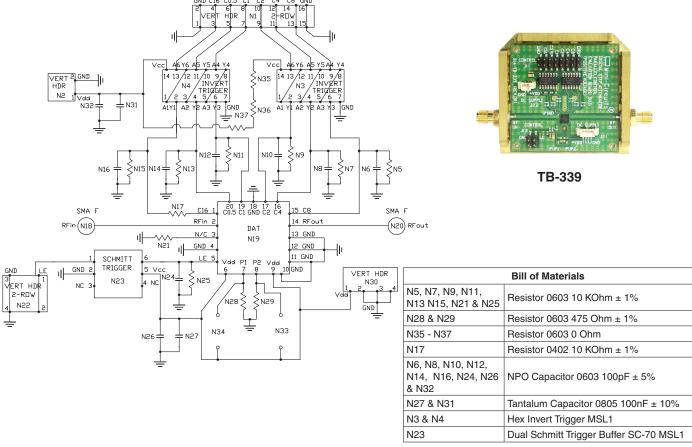
The DAT-31R5A-PP+ always assumes a specifiable attenuation setting on power-up, allowing a known attenuation state to be established before an initial parallel control word is provided.

When the attenuator powers up with LE=0, the control bits are automatically set to one of four possible values .These four values are selected by the two power-up control bits,PUP1 and PUP2 ,as shown in Table 3: (Power-Up Truth Table, Parallel Mode).

Table 3. Power-Up Truth Table, Parallel Mode				
Attenuation State	PUP1	PUP2	LE	
Reference	0	0	0	
8 (dB)	0	1	0	
16 (dB)	1	0	0	
31.5 (dB)	1	1	0	
Defined by C0.5-C16 (See Table 1-Truth Table)	X (Note 1)	X (Note 1)	1	

Note 1: PUP1 and PUP2 Connection may be 0, 1, GROUND, or not connect, without effect on attenuation state.

Power-Up with LE=1 provides normal parallel operation with C0.5-C16, and PUP1 and PUP2 are not active.



#### Notes

- 1. Both RF ports must be held at 0VDC or DC blocked with an external series capacitor.
- 2. Test Board TB-339 is designed for operation for VDD=2.3 to 3.6V. For operation over 3.6V to 5.2V, See Application Note AN-70-006
- 3. VDD=Vdo

Fig 3. Evaluation Board Schematic, TB-339, used for characterization (DUT not soldered on TB-339)

#### **Test Equipment**

# For Insertion Loss, Isolation and Return Loss:

Agilent's E5071C Network Analyzer & E3631A Power Supply.

#### For Compression:

Agilent's N9020A Signal Analyzer, E8247C RF Generator, E3631A Power Supply & U2004A Power Sensor.

#### For Input IP3:

Agilent's N9020A Signal Analyzer, N5181A

Signal Generators, E3631A Power Supply, U2004A Power Sensor.

# For Spurs:

Agilent N5181A Signal Generator, E4440A Spectrum Analyzer.

## For Switching Time:

Agilent's N5181A Signal Generator, 81110A Pulse Generator, 54832B Oscilloscope, E3631A Power Supply.

#### For Max Control Frequency:

Agilent's N5181A Signal Generator, N9020A Signal Analyzer, E3631A Power Supply, 81110A Pulse Generator.

#### **Measurement Conditions**

# For Insertion Loss, Isolation and Return Loss:

VDD=+2.3/+3/+5.5V &Pin=0dBm

For Compression: Pin=0/+24dBm. VDD=+3V

#### For Input IP3: Pin=+10dBm/tone.

Tone spacing: 0.1 MHz to 1 MHz RF Freq and 1 MHz to 4200 MHz RF Freq,

VDD=+3V

For Spurs: RF IN at 1000MHz and -20dBm. VDD=+3V

#### For Switching Time:

RF Freq=501MHz/0dBm, Pulse for LE=1Hz/0/+3.4V, Delay=500ms, Width=500ms. VDD=+3V

#### For Max Control Frequency:

RF Freq=501MHz, 0dBm. VDD=+3V



Additional Detailed Technical Information additional information is available on our dash board. To access this information click here			
Data Table			
Performance Data	Swept Graphs		
	S-Parameter (S2P Files) Data Set (.zip file)		
Case Style	DG983-2 Plastic package, exposed paddle, lead finish: NiPdAu		
Tape & Reel	F87		
Standard quantities available on reel	7" reels with 20, 50, 100 or 200 devices 13" reels with 3K devices		
Suggested Layout for PCB Design PL-180			
Evaluation Board	TB-339		
Environmental Ratings	ENV33T1		

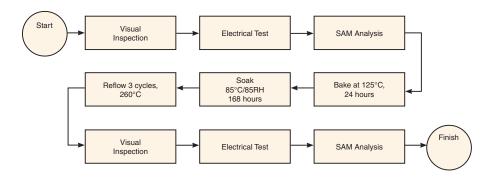
# **ESD Rating**

Human Body Model (HBM): Class 1C (1000 to <2000V) in accordance with MIL-STD-883 method 3015

# **MSL Rating**

Moisture Sensitivity: MSL1 in accordance with IPC/JEDEC J-STD-020D

# **MSL Test Flow Chart**



#### **Additional Notes**

- A. Performance and quality attributes and conditions not expressly stated in this specification document are intended to be excluded and do not form a part of this specification document.
- B. Electrical specifications and performance data contained in this specification document are based on Mini-Circuit's applicable established test performance criteria and measurement instructions.
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