

OP-42

GENERAL DESCRIPTION *Continued*

common-mode rejection of 88dB minimum over a $\pm 11V$ input voltage range is exceptional for a high-speed amplifier. High CMR combined with a minimum 500V/mV gain into 10k Ω load ensure excellent linearity in both noninverting and inverting gain configurations. The low input bias and offset currents provided by the JFET input stage suit the OP-42 for use in high-speed sample and hold circuits, peak detectors, and log amplifiers. Excellent radiation hardness characteristics make the OP-42 ideal for military and aerospace applications.

The OP-42 conforms to the standard 741 pinout with nulling to V₋. The OP-42 upgrades the performance of circuits using the AD544, AD611, AD711, and LF400 by direct replacement. In circuits without nulling, the OP-42 offers an upgrade for designs using the OP-16, OP-17, LT1022, LT1056, and HA2510.

ABSOLUTE MAXIMUM RATINGS (Note 1)

Supply Voltage	$\pm 20V$
Input Voltage (Note 2)	$\pm 20V$
Differential Input Voltage (Note 2)	40V
Output Short-Circuit Duration	Undefined

Storage Temperature Range -65°C to +175°C

Operating Temperature Range

OP42A (J, Z) -55°C to +125°C

OP42E, F (J, Z) -25°C to +85°C

OP42G -40°C to +85°C

Junction Temperature -65°C to +175°C

Lead Temperature Range (Soldering, 60 sec.) +300°C

PACKAGE TYPE	θ_{JA} (NOTE 3)	θ_{JC}	UNITS
TO-99 (J)	150	18	°C/W
8-Pin Hermetic DIP (Z)	148	16	°C/W
8-Pin Plastic DIP (P)	103	43	°C/W
20-Contact LCC (RC, TC)	98	38	°C/W
8-Pin SO (S)	158	43	°C/W

NOTES:

1. Absolute maximum ratings apply to both DICE and packaged parts, unless otherwise noted.
2. For supply voltages less than $\pm 20V$, the absolute maximum input voltage is equal to the supply voltage.
3. θ_{JA} is specified for worst case mounting conditions, i.e., θ_{JA} is specified for device in socket for TO, CERDIP, P-DIP, and LCC packages; θ_{JA} is specified for device soldered to printed circuit board for SO package.

ELECTRICAL CHARACTERISTICS at V_S = $\pm 15V$, T_A = +25°C, unless otherwise noted.

PARAMETER	SYMBOL	CONDITIONS	OP-42E			OP-42F			OP-42G			UNITS
			MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
Offset Voltage	V _{OS}		-	0.3	0.75	-	0.4	1.5	-	1.5	5.0	mV
Input Bias Current	I _B	V _{CM} = 0V T _J = 25°C	-	80	200	-	130	250	-	130	250	pA
Input Offset Current	I _{OS}	V _{CM} = 0V T _J = 25°C	-	4	40	-	6	50	-	6	50	pA
Input Voltage Range	IVR	(Note 1)	± 11	+12.5 -12.0	-	± 11	+12.5 -12.0	-	± 11	+12.5 -12.0	-	V
Common-Mode Rejection	CMR	V _{CM} = $\pm 11V$	88	98	-	80	92	-	80	92	-	dB
Power-Supply Rejection Ratio	PSRR	V _S = $\pm 10V$ to $\pm 20V$	-	9	40	-	12	50	-	12	50	$\mu V/V$
Large-Signal Voltage Gain	A _{VO}	R _L = 10k Ω	500	900	-	500	900	-	500	900	-	V/mV
		R _L = 2k Ω	200	260	-	200	260	-	200	260	-	
		R _L = 1k Ω	100	170	-	100	170	-	100	170	-	
Output Voltage Swing	V _O	R _L = 1k Ω	± 11.5	+12.5 -11.9	-	± 11.5	+12.5 -11.9	-	± 11.5	+12.5 -11.9	-	V
Short-Circuit Current Limit	I _{SC}	Output Shorted to Ground	± 20	+33 -28	± 60	± 20	+33 -28	± 60	± 20	+33 -28	± 60	mA
Supply Current	I _{SY}	No Load V _O = 0V	-	5.1	6.0	-	5.1	6.5	-	5.1	6.5	mA
Slew Rate	SR		50	58	-	40	50	-	40	50	-	V/ μs
Full-Power Bandwidth	BW _p	(Note 2)	750	900	-	600	800	-	600	800	-	kHz
Gain-Bandwidth Product	GBW	f _O = 10kHz	-	10	-	-	10	-	-	10	-	MHz
Settling Time	t _s	10V Step 0.01% (Note 3)	-	0.8	1.0	-	0.9	1.2	-	0.9	1.2	μs
Overload Recovery Time	t _{OR}		-	700	-	-	700	-	-	700	-	ns
Phase Margin	ϕ_o	0db Gain	-	47	-	-	47	-	-	47	-	degrees
Gain Margin	A ₁₈₀	180° Open-Loop Phase Shift	-	9	-	-	9	-	-	9	-	dB
Capacitive Load Drive Capability	C _L	Unity-Gain Stable (Note 4)	100	300	-	100	300	-	100	300	-	pF

ELECTRICAL CHARACTERISTICS at $V_S = \pm 15V$, $T_A = +25^\circ C$, unless otherwise noted. *Continued*

PARAMETER	SYMBOL	CONDITIONS	OP-42E			OP-42F			OP-42G			UNITS
			MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
Differential Input Impedance	Z_{IN}		-	$10^{12} 6$	-	-	$10^{12} 6$	-	-	$10^{12} 6$	-	ΩpF
Open-Loop Output Resistance	R_O		-	50	-	-	50	-	-	50	-	Ω
Voltage Noise	$e_{n\ p-p}$	0.1Hz to 10Hz	-	2	-	-	2	-	-	2	-	μV_{p-p}
Voltage Noise Density	e_n	$f_O = 10Hz$	-	38	-	-	38	-	-	38	-	nV/\sqrt{Hz}
		$f_O = 100Hz$	-	16	-	-	16	-	-	16	-	
		$f_O = 1kHz$	-	13	-	-	13	-	-	13	-	
		$f_O = 10kHz$	-	12	-	-	12	-	-	12	-	
Current Noise Density	i_n	$f_O = 1kHz$	-	0.007	-	-	0.007	-	-	0.007	-	pA/\sqrt{Hz}
External V_{OS} Trim Range	$R_{pot} = 20k\Omega$		-	4	-	-	4	-	-	4	-	mV
Long-Term V_{OS} Drift			-	5	-	-	5	-	-	5	-	$\mu V/month$
Supply Voltage Range	V_S		± 8	± 15	± 20	± 8	± 15	± 20	± 8	± 15	± 20	V

NOTES:

- Guaranteed by CMR test.
- Guaranteed by slew-rate test and formula $BW_p = SR/(2\pi 10V_{PEAK})$.
- Settling-time is sample tested for A and E grades. Test circuit is shown in Figure 4. Settling-time for F grade is guaranteed but not tested.
- Guaranteed but not tested.

ELECTRICAL CHARACTERISTICS at $V_S = \pm 15V$, $T_A = +25^\circ C$, unless otherwise noted.

PARAMETER	SYMBOL	CONDITIONS	OP-42A			UNITS
			MIN	TYP	MAX	
Offset Voltage	V_{OS}		-	0.3	1.0	mV
Input Bias Current	I_B	$V_{CM} = 0V$ $T_J = 25^\circ C$	-	80	200	μA
Input Offset Current	I_{OS}	$V_{CM} = 0V$ $T_J = 25^\circ C$	-	4	40	μA
Input Voltage Range	IVR	(Note 1)	± 11	+12.5 -12.0	-	V
Common-Mode Rejection	CMR	$V_{CM} = \pm 11V$	86	96	-	dB
Power-Supply Rejection Ratio	PSRR	$V_S = \pm 10V$ to $\pm 20V$	-	9	40	$\mu V/V$
Large-Signal Voltage Gain	A_{VO}	$R_L = 10k\Omega$	500	900	-	V/mV
		$R_L = 2k\Omega$	200	260	-	
		$R_L = 1k\Omega$	100	170	-	
Output Voltage Swing	V_O	$R_L = 1k\Omega$	± 11.5	+12.5 -11.9	-	V
Short-Circuit Current Limit	I_{SC}	Output Shorted to Ground	± 20	+33 -28	± 60	mA
Supply Current	I_{SY}	No Load $V_O = 0V$	-	5.1	6.0	mA
Slew Rate	SR		45	52	-	V/ μs
Full-Power Bandwidth	BW_p	(Note 2)	700	850	-	kHz
Gain-Bandwidth Product	GBW	$f_O = 10kHz$	-	10	-	MHz
Settling -Time	t_s	10V Step 0.01% (Note 3)	-	0.8	1.0	μs
Overload Recovery Time	t_{OR}		-	700	-	ns
Phase Margin	ϕ_o	0db Gain	-	47	-	degrees

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ELECTRICAL CHARACTERISTICS at $V_S = \pm 15V$, $T_A = 25^\circ C$, unless otherwise noted. *Continued*

PARAMETER	SYMBOL	CONDITIONS	MIN	OP-42A TYP	MAX	UNITS
Gain Margin	A_{180}	180° Open-Loop Phase Shift	–	9	–	dB
Capacitive Load Drive Capability	C_L	Unity-Gain Stable (Note 4)	100	300	–	pF
Differential Input Impedance	Z_{IN}		–	$10^{12} 6$	–	ΩpF
Open-Loop Output Resistance	R_O		–	50	–	Ω
Voltage Noise	$e_{n\ p-p}$	0.1Hz to 10Hz	–	2	–	μV_{p-p}
Voltage Noise Density	e_n	$f_o = 10Hz$	–	38	–	nV/\sqrt{Hz}
		$f_o = 100Hz$	–	16	–	
		$f_o = 1kHz$	–	13	–	
		$f_o = 10kHz$	–	12	–	
Current Noise Density	i_n	$f_o = 1kHz$	–	0.007	–	pA/\sqrt{Hz}
External V_{OS} Trim Range		$R_{pot} = 20k\Omega$	–	4	–	mV
Long-Term V_{OS} Drift			–	5	–	$\mu V/month$
Supply Voltage Range	V_S		± 8	± 15	± 20	V

NOTES:

1. Guaranteed by CMR test.
2. Guaranteed by slew-rate test and formula $BW_p = SR/(2\pi 10V_{PEAK})$.

3. Settling-time is sample tested for A and E grades. Test circuit is shown in Figure 4. Settling-time for F grade is guaranteed but not tested.
4. Guaranteed but not tested.

ELECTRICAL CHARACTERISTICS at $V_S = \pm 15V$, $-25^\circ C \leq T_A \leq 85^\circ C$ for E/F grades, and $-40^\circ C \leq T_A \leq +85^\circ C$ for G grade, unless otherwise noted.

PARAMETER	SYMBOL	CONDITIONS	OP-42E			OP-42F			OP-42G			UNITS
			MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
Offset Voltage	V_{OS}		–	0.4	1.2	–	0.6	2.5	–	2.0	6.0	mV
Offset Voltage Temperature Coefficient	TCV_{OS}		–	4	10	–	8	–	–	8	–	$\mu V/^\circ C$
Input Bias Current	I_B	(Note 1)	–	0.5	1.2	–	0.6	2.0	–	0.6	2.0	nA
Input Offset Current	I_{OS}	(Note 1)	–	0.05	0.2	–	0.06	0.4	–	0.06	0.4	nA
Input Voltage Range	IVR	(Note 2)	± 11	+12.5 –12.0	–	± 11	+12.5 –12.0	–	± 11	+12.5 –12.0	–	V
Common-Mode Rejection	CMR	$V_{CM} = \pm 11V$	86	96	–	80	94	–	80	94	–	dB
Power-Supply Rejection Ratio	PSRR	$V_S = \pm 10V$ to $\pm 20V$	–	2	40	–	6	50	–	6	50	$\mu V/V$
Large-Signal Voltage Gain	A_{VO}	$R_L = 10k\Omega$ (Note 1) $R_L = 2k\Omega$ $V_O = \pm 10V$	200	500	–	200	500	–	200	500	–	V/mV
			100	160	–	100	160	–	100	160	–	
Output Voltage Swing	V_O	$R_L = 2k\Omega$	± 11.0	+12.3 –11.8	–	± 11.0	+12.3 –11.8	–	± 11.0	+12.3 –11.8	–	V
Short-Circuit Current Limit	I_{SC}	Output Shorted to Ground	± 8	–	± 60	± 8	–	± 60	± 8	–	± 60	mA
Supply Current	I_{SY}	No Load $V_O = 0V$	–	5.1	6.0	–	5.1	6.5	–	5.1	6.5	mA
Slew Rate	SR	$R_L = 2k\Omega$	45	57	–	40	50	–	40	50	–	V/ μs
Capacitive Load Drive Capability	C_L	Unity-Gain Stable (Note 3)	100	250	–	100	250	–	100	250	–	pF

NOTES:

1. $T_j = 85^\circ C$ for E/F/G Grades; $T_j = 125^\circ C$ for A grade.

2. Guaranteed by CMR test.
3. Guaranteed but not tested.

ELECTRICAL CHARACTERISTICS at $V_S = \pm 15V$, $-55^\circ C \leq T_A \leq 125^\circ C$ for A grade, unless otherwise noted.

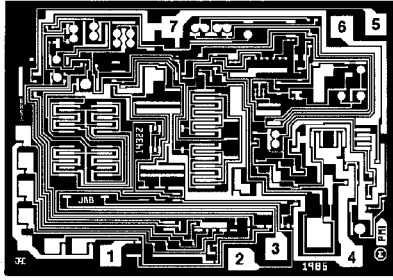
PARAMETER	SYMBOL	CONDITIONS	OP-42A			UNITS
			MIN	TYP	MAX	
Offset Voltage	V_{OS}		-	0.5	2.0	mV
Offset Voltage Temperature Coefficient	TCV_{OS}		-	4	10	$\mu V/^\circ C$
Input Bias Current	I_B	(Note 1)	-	6	20	nA
Input Offset Current	I_{OS}	(Note 1)	-	0.2	1.0	nA
Input Voltage Range	IVR	(Note 2)	± 11	+12.5 -12.0	-	V
Common-Mode Rejection	CMR	$V_{CM} = \pm 11V$	80	94	-	dB
Power-Supply Rejection Ratio	PSRR	$V_S = \pm 10V$ to $\pm 20V$	-	10	50	$\mu V/V$
Large-Signal Voltage Gain	A_{VO}	$R_L = 10k\Omega$ (Note 1) $R_L = 2k\Omega$ $V_O = \pm 10V$	160 80	350 110	-	V/mV
Output Voltage Swing	V_O	$R_L = 2k\Omega$	± 11.0	+12.3 -11.8	-	V
Short-Circuit Current Limit	I_{sc}	Output Shorted to Ground	± 8	-	± 60	mA
Supply Current	I_{SY}	No Load $V_O = 0V$	-	5.1	6.0	mA
Slew Rate	SR	$R_L = 2k\Omega$	40	52	-	V/ μs
Capacitive Load Drive Capability	C_L	Unity-Gain Stable (Note 3)	100	250	-	pF

NOTES:

- $T_j = 85^\circ C$ for E/F Grades; $T_j = 125^\circ C$ for A grade.
- Guaranteed by CMR test.
- Guaranteed but not tested.

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DICE CHARACTERISTICS



1. OFFSET VOLTAGE NULL
2. INVERTING INPUT
3. NONINVERTING INPUT
4. NEGATIVE SUPPLY
5. OFFSET VOLTAGE NULL
6. AMPLIFIER OUTPUT
7. POSITIVE SUPPLY

DIE SIZE 0.098 × 0.070 inch, 6860 sq. mils
(2.49 × 1.78 mm, 4.43 sq. mm)

WAFER TEST LIMITS at $V_S = \pm 15V$, $T_j = 25^\circ C$, unless otherwise noted.

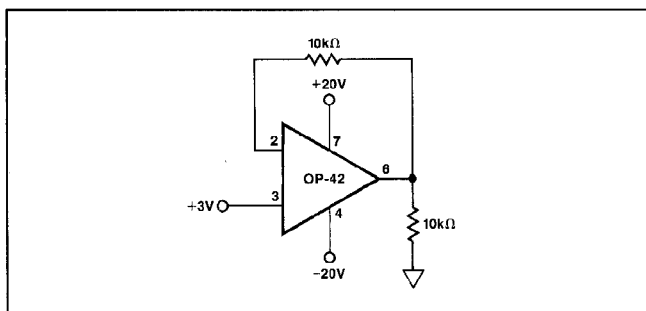
PARAMETER	SYMBOL	CONDITIONS	OP-42N LIMIT	UNITS
Offset Voltage	V_{OS}		1.5	mV MAX
Input Bias Current	I_B	$V_{CM} = 0V$	250	pA MAX
Input Offset Current	I_{OS}	$V_{CM} = 0V$	50	pA MAX
Input Voltage Range	IVR	(Note 1)	± 11	V MIN
Common-Mode Rejection	CMR	$V_{CM} = \pm 11V$	80	dB MIN
Power-Supply Rejection Ratio	PSRR	$V_S = \pm 10V$ to $\pm 20V$	50	$\mu V/V$ MAX
Large-Signal Voltage Gain	A_{VO}	$R_L = 10k\Omega$	500	V/mV MIN
		$R_L = 2k\Omega$	200	
		$R_L = 1k\Omega$	100	
Output Voltage Swing	V_O	$R_L = 1k\Omega$	± 11.5	V MIN
Short-Circuit Current Limit	I_{SC}	Output Shorted to Ground	$\pm 20/\pm 60$	mA MIN/MAX
Supply Current	I_{SY}	No Load $V_O = 0V$	6.5	mA MAX
Slew Rate	SR		40	V/ μs MIN
Capacitive Load Drive Capability	C_L	Unity-Gain Stable (Note 2)	100	pF MIN

NOTES:

1. Guaranteed by CMR test.
2. Guaranteed but not tested.

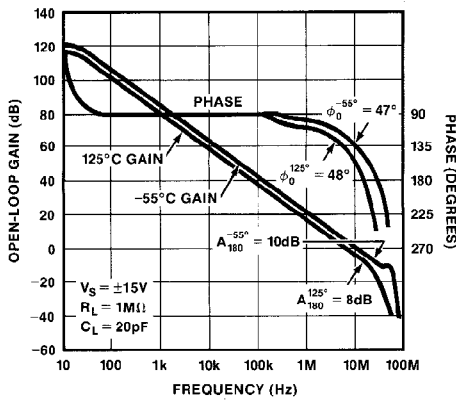
Electrical tests are performed at wafer probe to the limits shown. Due to variations in assembly methods and normal yield loss, yield after packaging is not guaranteed for standard product dice. Consult factory to negotiate specifications based on dice lot qualification through sample lot assembly and testing.

BURN-IN CIRCUIT

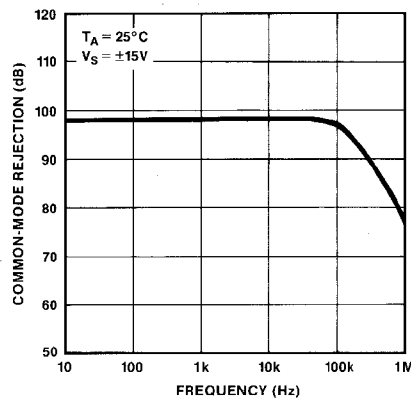


TYPICAL PERFORMANCE CHARACTERISTICS

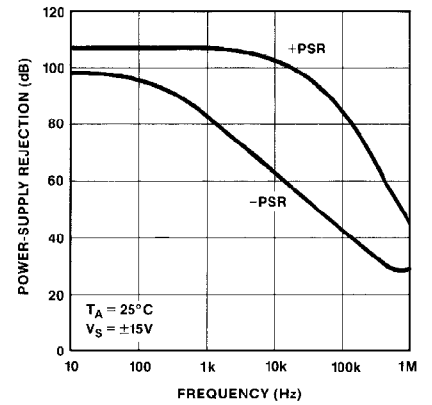
OPEN-LOOP GAIN, PHASE vs FREQUENCY



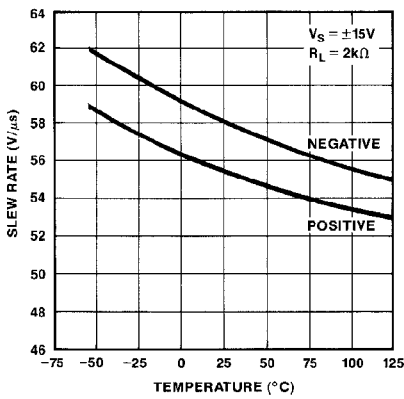
COMMON-MODE REJECTION vs FREQUENCY



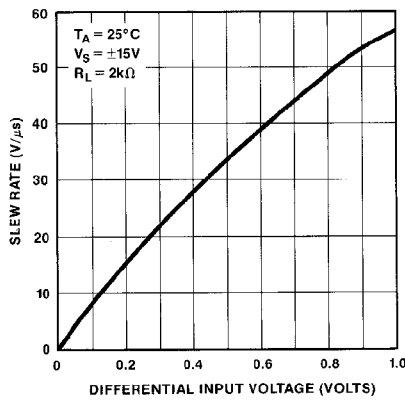
POWER-SUPPLY REJECTION vs FREQUENCY



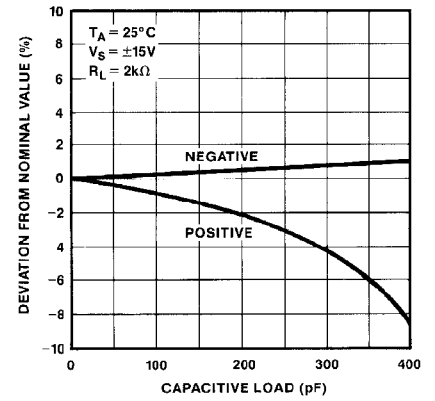
SLEW RATE vs TEMPERATURE



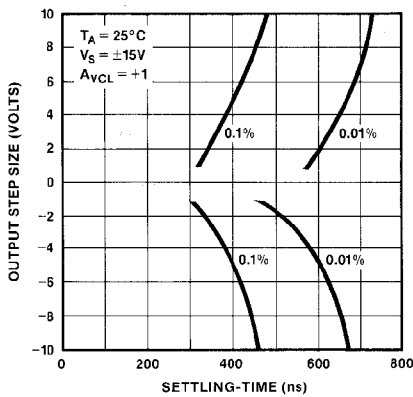
SLEW RATE vs DIFFERENTIAL INPUT VOLTAGE



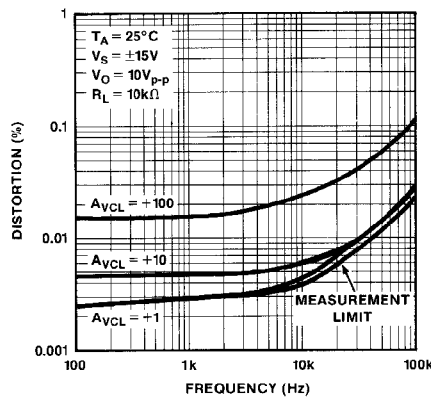
SLEW RATE vs CAPACITIVE LOAD



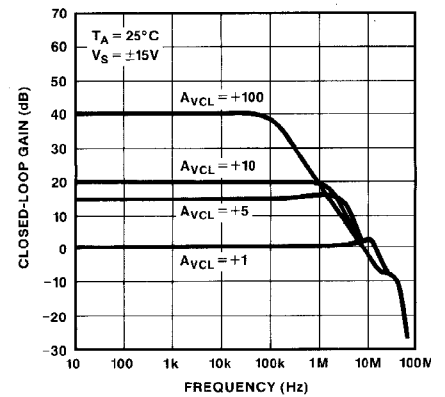
SETTLING-TIME vs STEP SIZE



DISTORTION vs FREQUENCY



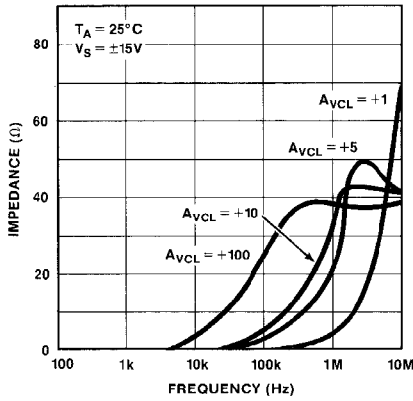
CLOSED-LOOP GAIN vs FREQUENCY



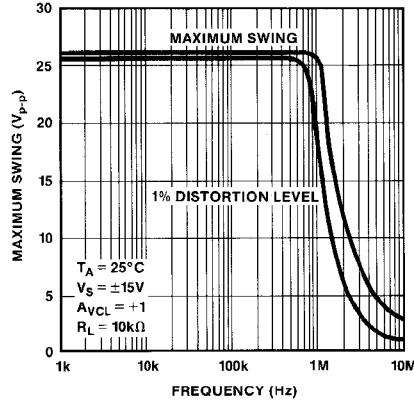
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TYPICAL PERFORMANCE CHARACTERISTICS

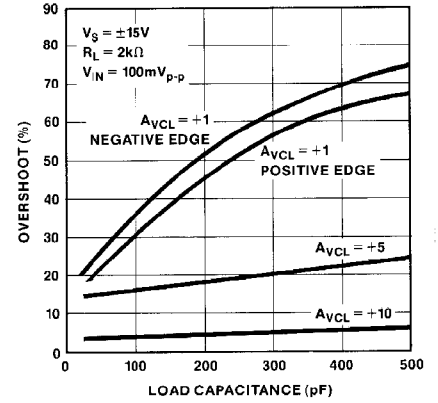
CLOSED-LOOP OUTPUT IMPEDANCE vs FREQUENCY



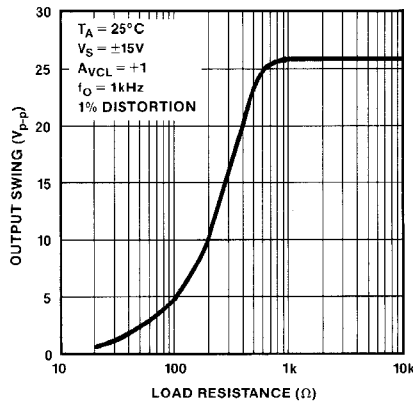
MAXIMUM OUTPUT SWING vs FREQUENCY



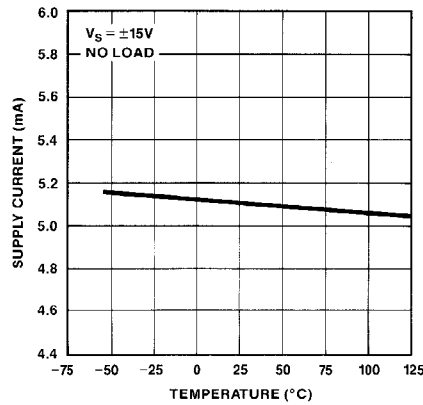
SMALL-SIGNAL OVERSHOOT vs LOAD CAPACITANCE



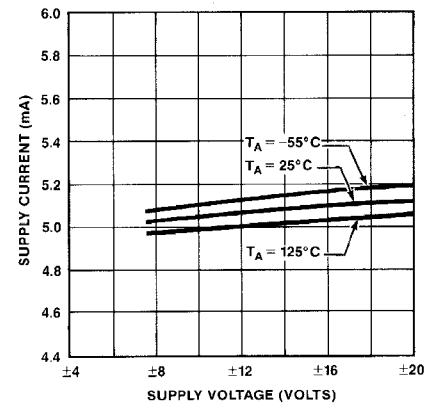
OUTPUT SWING vs LOAD RESISTANCE



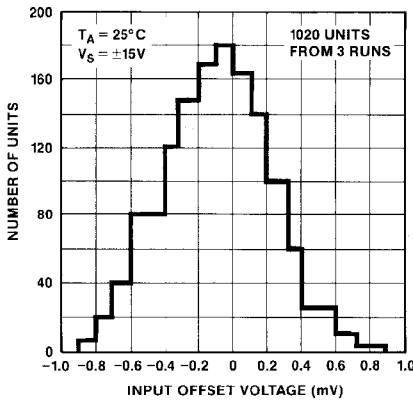
SUPPLY CURRENT vs TEMPERATURE



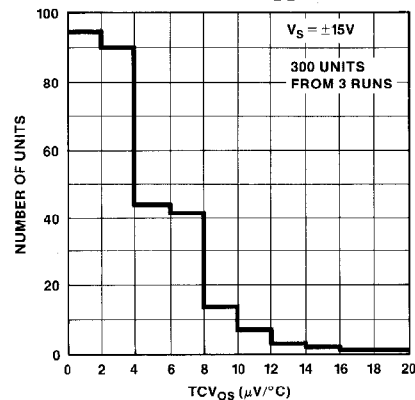
SUPPLY CURRENT vs SUPPLY VOLTAGE



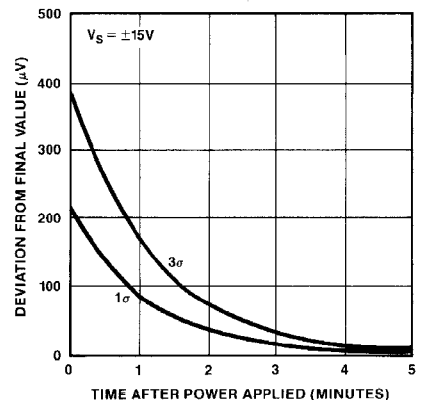
TYPICAL DISTRIBUTION OF INPUT OFFSET VOLTAGE



TYPICAL DISTRIBUTION OF TCV_{OS}

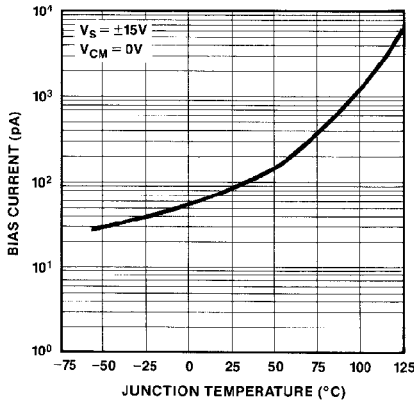


OFFSET VOLTAGE WARM-UP DRIFT

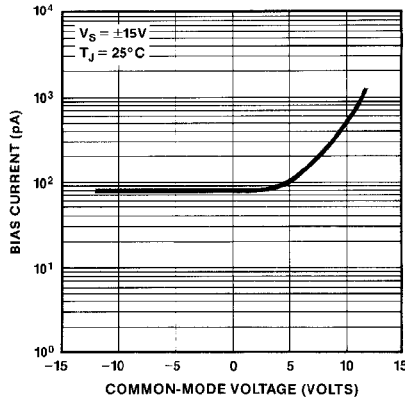


TYPICAL PERFORMANCE CHARACTERISTICS

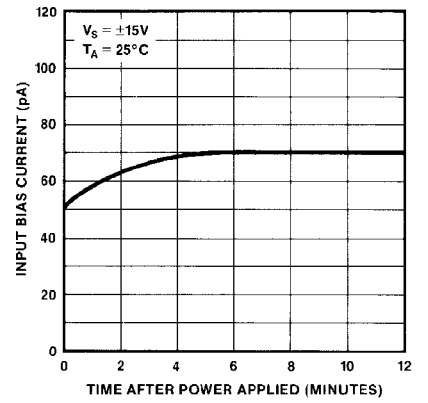
BIAS CURRENT vs JUNCTION TEMPERATURE



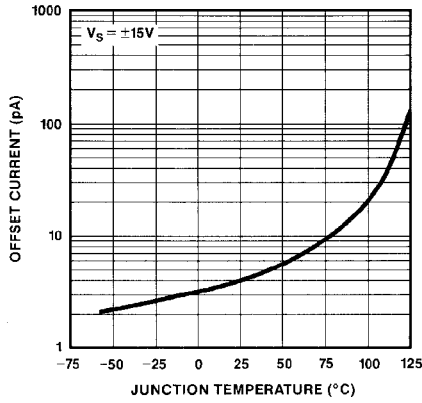
BIAS CURRENT vs COMMON-MODE VOLTAGE



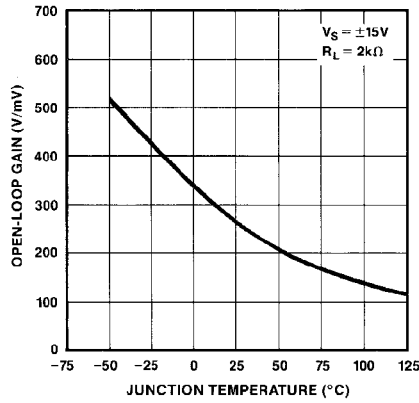
BIAS CURRENT WARM-UP DRIFT



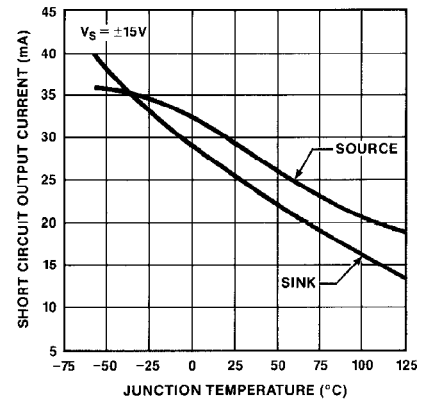
OFFSET CURRENT vs JUNCTION TEMPERATURE



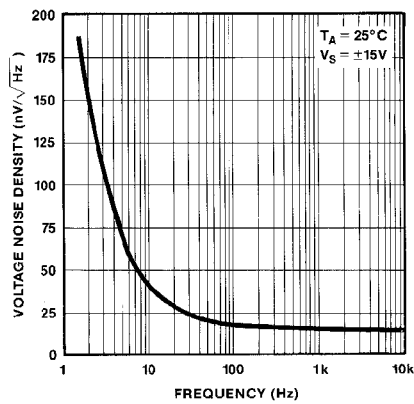
OPEN-LOOP GAIN vs JUNCTION TEMPERATURE



SHORT CIRCUIT OUTPUT CURRENT vs JUNCTION TEMPERATURE



VOLTAGE NOISE DENSITY vs FREQUENCY



OP-42

APPLICATIONS INFORMATION

The OP-42 combines speed with a high level of input precision usually found only with slower devices. Well-behaved AC performance in the form of clean transient response, symmetrical slew-rates and a high degree of forgiveness to supply decoupling are the hallmarks of this amplifier. AC gain and phase response are quite independent of temperature or supply voltage. Figure 1 shows the OP-42's small-signal response. Even with 75pF loads, there is minimal ringing in the output waveform. Large-signal response is shown in Figure 2. This figure clearly shows the OP-42's exceptionally close matching between positive and negative slew-rates. Slew-rate symmetry decreases the DC offset a system encounters when processing high-frequency signals, and thus reduces the DC current necessary for load driving.

FIGURE 1: Small-Signal Transient Response,
 $Z_L = 2k\Omega || 75pF$

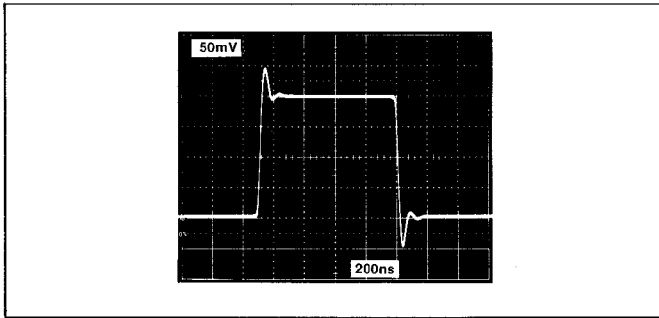
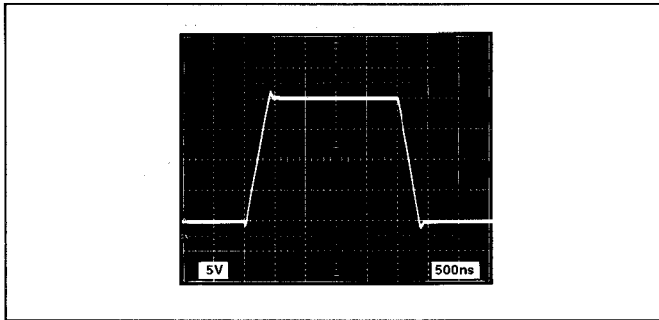


FIGURE 2: Large-Signal Transient Response,
 $Z_L = 2k\Omega || 75pF$



As with most JFET-input amplifiers, the output of the OP-42 may undergo phase inversion if either input exceeds the specified input voltage range. Phase inversion will not damage the amplifier, nor will it cause an internal latch-up.

Supply decoupling should be used to overcome inductance and resistance associated with supply lines to the amplifier.

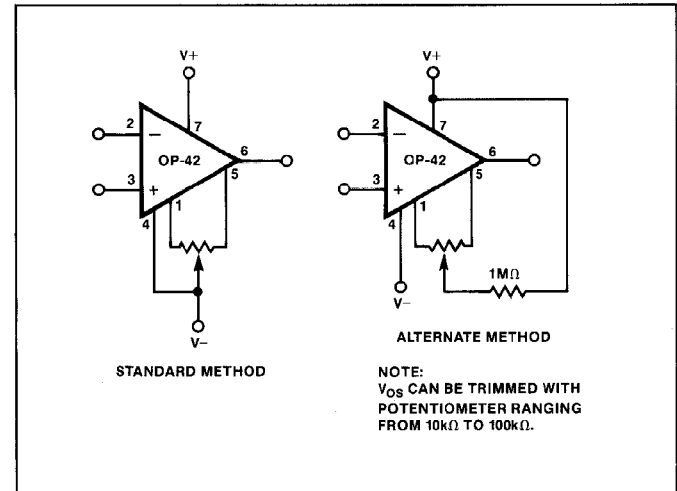
For most applications a 0.1 μ F to 0.01 μ F capacitor should be placed between each supply pin and ground.

The OP-42 displays excellent resistance to radiation. Radiation hardness data is available by contacting the factory.

OFFSET VOLTAGE ADJUSTMENT

Offset voltage is adjusted with a 10k Ω to 100k Ω potentiometer as shown in Figure 3. The potentiometer should be connected between pins 1 and 5 with its wiper connected to the V⁻ supply. Nulling V_{OS} in this manner changes TCV_{OS} by no more than 5 μ V/ $^{\circ}$ C per millivolt of V_{OS} change. Alternately, V_{OS} may be nulled by attaching the potentiometer wiper through a 1M Ω resistor to the positive supply rail.

FIGURE 3: Input Offset Voltage Nulling



SETTLING-TIME

Guaranteed fast-settling is assured by sample-testing during production. The OP-42 is configured as a unity-gain follower in the test circuit of Figure 4. This test method has advantages over false-sum-node techniques in that the actual output of the amplifier is measured, instead of an error-voltage at the sum node. Common-mode settling effects are exercised in this circuit, in addition to the slew-rate and bandwidth effects measured by the false-sum-node method. A reasonably flat-top pulse is required as a stimulus.

The output waveform of the OP-42 being tested is clamped by Schottky diodes and buffered by the JFET source-follower. The signal is amplified by a factor of ten by the fast amplifier IC1, then Schottky-clamped before being output. The OP-41 provides overall offset nulling. Analysis of the waveform using a digitizing oscilloscope determines the op amp's settling-time.

FIGURE 4: Settling-Time Test Fixture

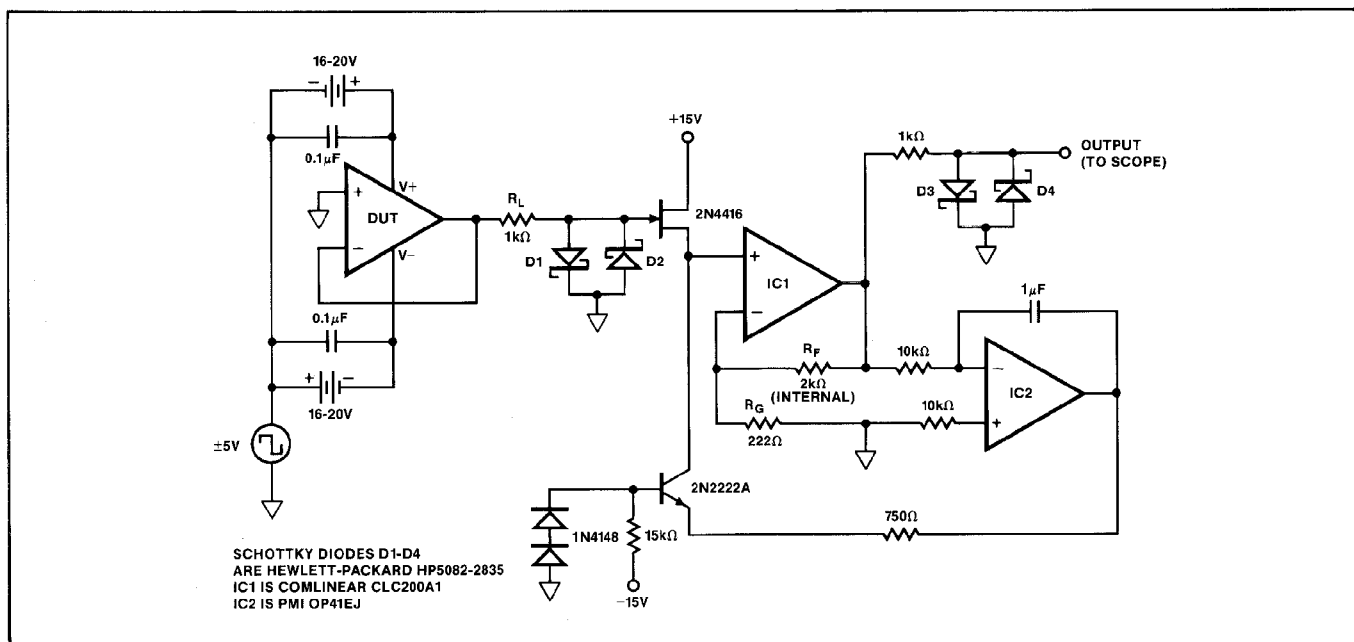
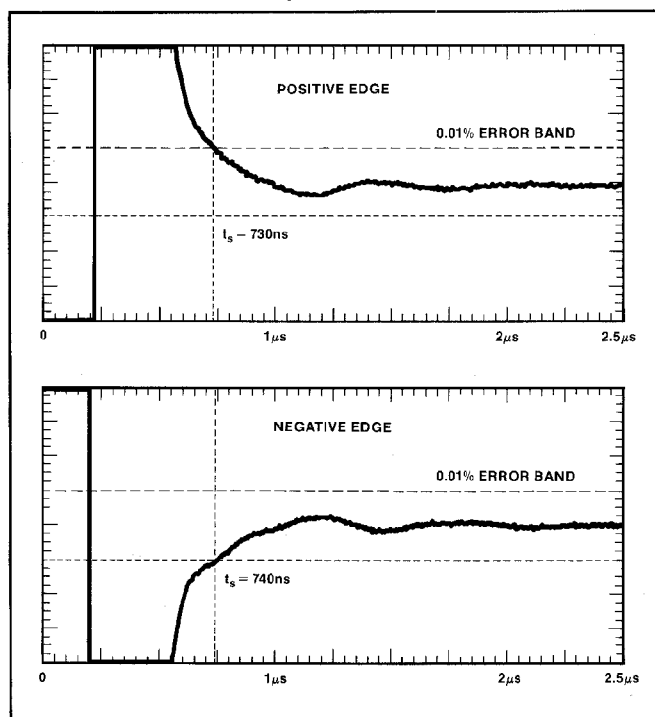


FIGURE 5: OP-42 Settling-Characteristics

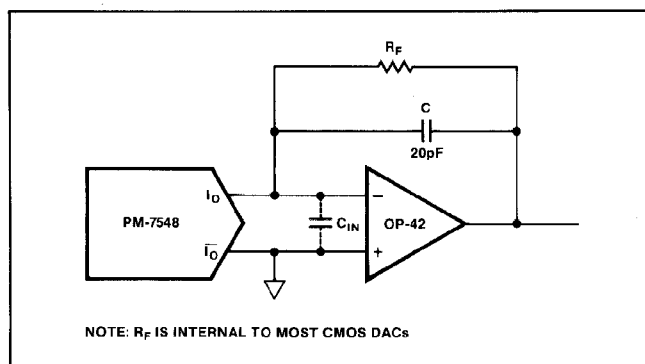


DAC OUTPUT AMPLIFIER

The OP-42 is an excellent choice for a DAC output amplifier, since its high speed and fast settling-time allow quick transitions between codes, even for full-scale changes in output level. The DAC output capacitance appears at the operational amplifier inputs, and must be compensated to ensure

optimal settling speed. Compensation is achieved with capacitor C in Figure 6. C must be adjusted to account for the DAC's output capacitance, the op amp's input capacitance, and any stray capacitance at the inputs. With a bipolar DAC, an additional shunt resistor may be used to optimize response. This technique is described in PMI's application note AN-24.

FIGURE 6: DAC Output Amplifier Circuit



Highest speed is achieved using bipolar DACs such as PMI's DAC-08, DAC-10 or DAC-312. The output capacitances of these converters are up to an order of magnitude lower than their CMOS counterparts, resulting in substantially faster settling-times. The high output impedance of bipolar DACs allows the output amplifier to operate in a true current-to-voltage mode, with a noise gain of unity, thereby retaining the amplifier's full bandwidth. Offset voltage has minimal effect on linearity with bipolar converters.

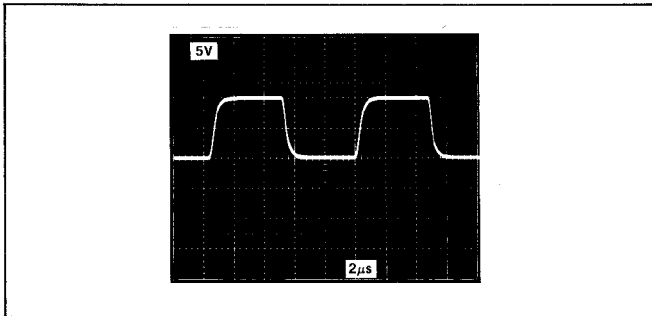
CMOS digital-to-analog converters have higher output capacitances and lower output resistances than bipolar DACs.

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This results in slower settling-times, higher sensitivity to offset voltages and a reduction in the output amplifier's bandwidth. These trade-offs must be balanced against the CMOS DAC's advantages in terms of interfacing capability, power dissipation, accuracy levels and cost. Using the internal feedback resistor which is present on most CMOS converters, the gain applied to offset voltage varies between 4/3 and 2, depending upon output code. Contributions to linearity error will be as much as $2/3V_{OS}$. In a 10-volt 12-bit system, this may add up to an additional 1/5LSB DNL with the OP-42E. Amplifier bandwidth is reduced by the same gain factor applied to offset voltage, however the OP-42's 10MHz gain-bandwidth product results in no reduction of the CMOS converter's multiplying bandwidth.

Individual DAC data-sheets should be consulted for more complete descriptions of the converters and their circuit applications.

FIGURE 7: DAC Output Amplifier Response (PM-7545 DAC)



DRIVING A HIGH-SPEED ADC

The OP-42's open-loop output resistance is approximately 50Ω. When feedback is applied around the amplifier, output resistance decreases in proportion to open-loop gain divided by closed-loop gain (A_{VOL}/A_{VCL}). Output impedance increases as open-loop gain rolls-off with frequency. High-speed analog-to-digital converters require low source impedances at high frequency. Output impedance at 1MHz is typically 5Ω for an OP-42 operating at unity-gain. If lower output impedances are required, an output buffer may be placed at the output of the OP-42.

HIGH-CURRENT OUTPUT BUFFER

The circuit in Figure 8 shows a high-current output stage for the OP-42. Output current is limited by R1 and R2. For good tracking between the output transistors Q1, Q2 and their biasing diodes D1 and D2, thermal contact must be maintained between the transistor and its associated diode. If good thermal contact is not maintained, R1 and R2 must be increased to 5-6Ω in order to prevent thermal runaway. Using 5Ω resistors, the circuit easily drives a 75Ω load (Figure 9). Output resistance is decreased and heavier loads may be driven by decreasing R1 and R2.

Base current and biasing for Q1 and Q2 are provided by two current sources, the MAT-02 and the JFET. The 2kΩ potentiometer in the JFET current source should be trimmed for optimum transient performance. The case of the MAT-02 should be connected to V^- , and decoupled to ground with a

0.1μF capacitor. Compensation for the OP-42's input capacitance is provided by C_C . The circuit may be operated at any gain, in the usual op amp configurations.

FIGURE 8: High-Current Output Buffer

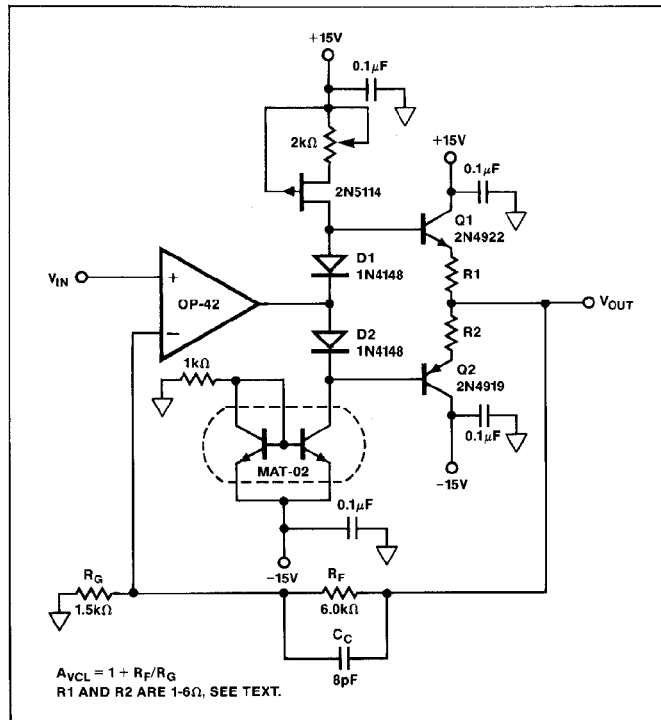
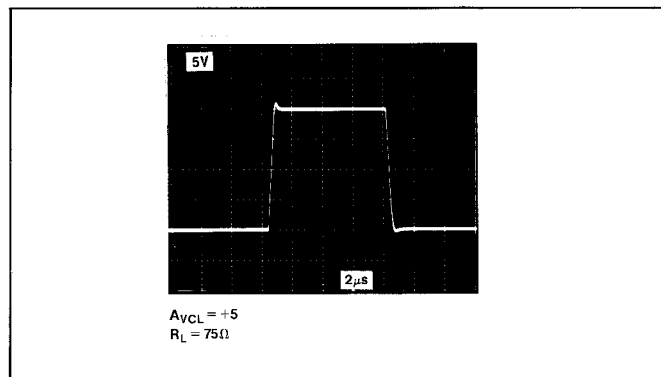


FIGURE 9: Output Buffer Large-Signal Response



DRIVING CAPACITIVE LOADS

Best performance will always be achieved by minimizing input and load capacitances around any high-speed amplifier. However, the OP-42 is guaranteed capable of driving a 100pF capacitive load over its full operating temperature range while operating at any gain including unity. Typically, an OP-42 will drive more than 250pF at any temperature. Supply decoupling does affect capacitive load driving ability. Extra care should be given to ensure good decoupling when driving capacitive loads, and a larger decoupling capacitor between 1μF and 10μF should be placed in parallel with the usual decoupling capacitor on each supply.

Large capacitive loads may be driven utilizing the circuit shown in Figure 10. R1 and C1 introduce a small amount of feedforward compensation around the amplifier to counteract the phase lag induced by the output impedance and load capacitance. At DC and low frequencies, R1 is contained within the feedback loop. At higher frequencies, feedforward compensation becomes increasingly dominant, and R1's effect on output impedance will become more noticeable.

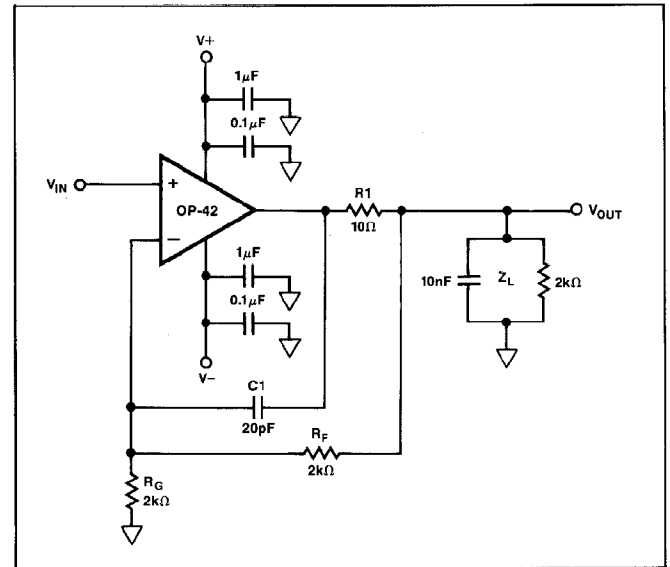
When driving very large capacitances, slew-rate will be limited by the short-circuit current limit. Although the unloaded slew-rate is insensitive to variations in temperature, the output current limit has a negative temperature coefficient, and is asymmetrical with regards to sourcing and sinking current. Therefore, slew-rate into excessive capacities will decrease with increasing temperature, and will lose symmetry.

COMPUTER SIMULATIONS

Many electronic design and analysis programs include models for op amps which calculate AC performance from the location of poles and zeros. As an aid to designers utilizing such a program, major poles and zeros of the OP-42 are listed below. Their location will vary slightly between production lots. Typically, they will be within $\pm 15\%$ of the frequency listed. Use of this data will enable the designer to evaluate gross circuit performance quickly, but should not supplant rigorous characterization of a breadboarded circuit.

POLES	ZEROS
20Hz	1MHz
300kHz	
3MHz	

FIGURE 10: Compensation for Large Capacitive Loads

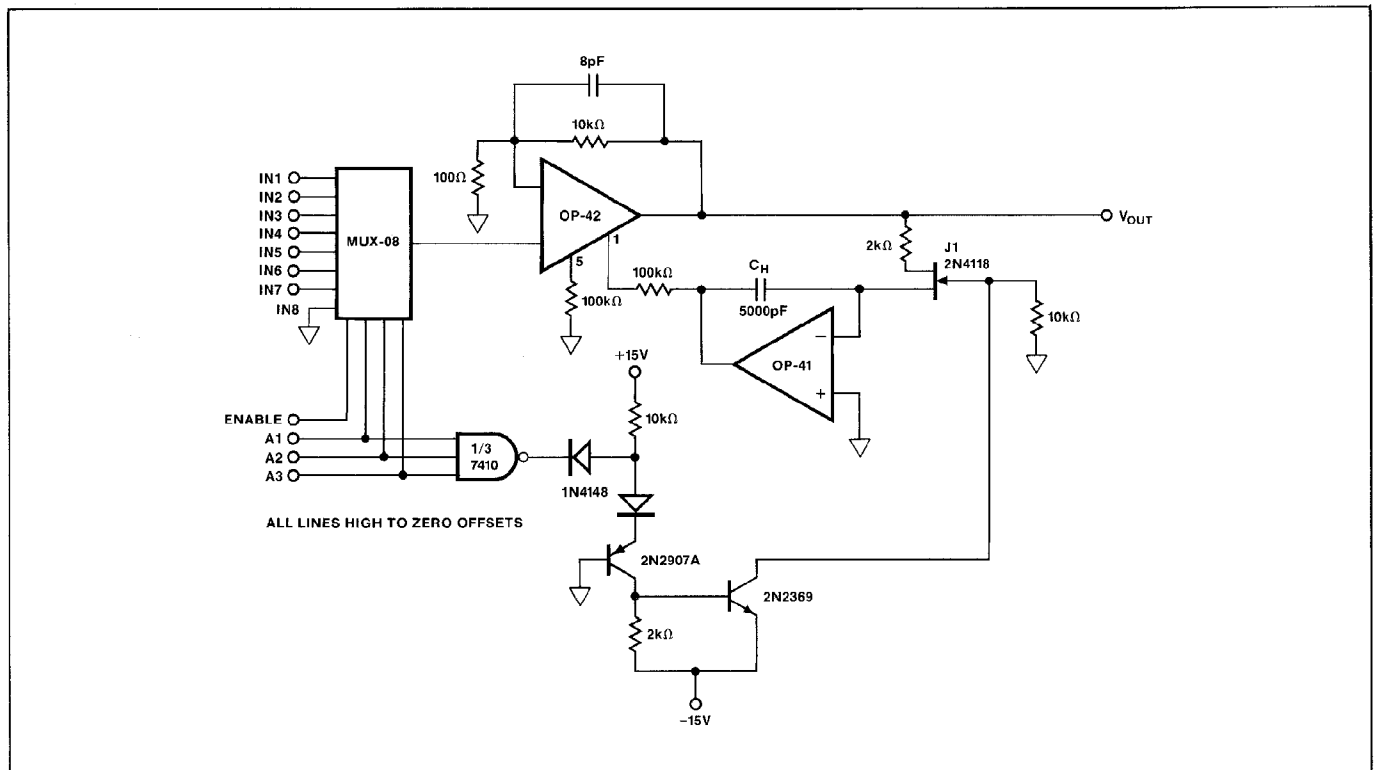


AUTOZEROING OFFSET VOLTAGE

Figure 11 describes a circuit for automatic offset voltage and drift correction. The OP-41 is used in a servo loop to force the OP-42 output equal to the OP-41's offset voltage. Thus, the OP-42's effective input offset is held below $10\mu V$ ($1mV/A_{VCL} = 100$) despite any temperature variations. This circuit will be most advantageous in high-gain applications.

Feedback is accomplished using the OP-42's null pins, leaving both inputs free for other purposes. In the application

FIGURE 11: OP-41 Servo Amplifier Provides Offset Correction



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shown, the OP-42 has seven multiplexed inputs, while the eighth input provides a ground reference. Nulling is accomplished by addressing the grounded channel. This address should be held for at least $200\mu\text{s}$. After this time, the address may be changed to another channel. The MUX-08 ENABLE pin must be high during the entire nulling cycle. During this time, JFET switch J1 turns on, completing feedback around

the OP-41 servo amplifier. A charge is developed across C_H to compensate for the OP-42's offset voltage. When another channel is addressed, J1 turns off, and the correction charge is maintained across C_H by the OP-41. Droop is exceptionally low — only $1.3\mu\text{V/s}$ at 25°C . A correction range of more than 4mV allows nulling of minor system offsets as well as the OP-42's offset voltage.

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