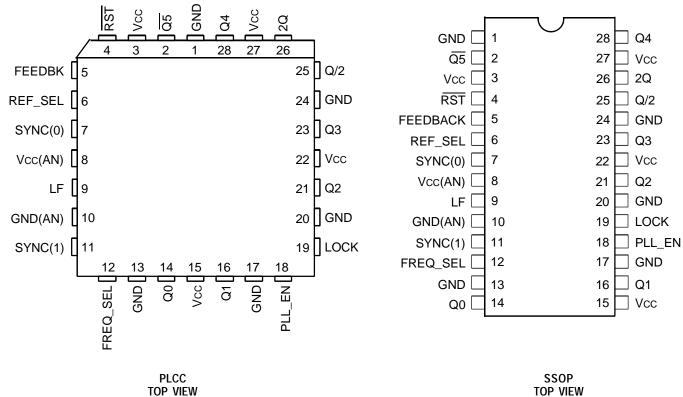
PINCONFIGURATIONS



TOP VIEW

PINDESCRIPTION

Pin Name	I/O	Description
SYNC(0)	I	Reference clock input
SYNC(1)	I	Reference clock input
REF_SEL	I	Chooses reference between SYNC (0) & SYNC (1) (refer to functional block diagram)
FREQ_SEL	I	Selects between ÷ 1 and ÷ 2 frequency options (refer to functional block diagram)
FEEDBACK	I	Feedback input to phase detector
LF	I	Input for external loop filter connection
Q0-Q4	0	Clock outputs
Q5	0	Inverted clock output
20	0	Clock output (2 x Q frequency)
Q/2	0	Clock output (Q frequency ÷ 2)
LOCK	0	Indicates phase lock has been achieved (HIGH when locked)
RST		Asynchronous reset (active LOW)
PLL_EN		Disables phase-lock for low frequency testing (refer to functional block diagram)

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ABSOLUTE MAXIMUM RATINGS(1)

Symbol	Description	Max.	Unit
VTERM ⁽²⁾	Terminal Voltage with Respect to GND	–0.5 to 7	V
VTERM ⁽³⁾	Terminal Voltage with Respect to GND	-0.5 to Vcc+0.5	V
TA	OperatingTemperature	0 to +70	°C
TBIAS	Temperature Under Bias	-55 to +125	°C
Tstg	StorageTemperature	-55 to +125	°C
Ιουτ	DC Output Current	-60 to 120	mA

NOTES:

 Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability. No terminal voltage may exceed Vcc by +0.5V unless otherwise noted.

2. Input and Vcc terminals.

3. Outputs and I/O terminals.

CAPACITANCE (TA = +25°C, f = 1.0MHz)

Symbol	Parameter ⁽¹⁾	Conditions	Тур.	Max.	Unit
CIN	Input Capacitance	VIN = 0V	4.5	6	pF
Соит	Output Capacitance	Vout = 0V	5.5	8	pF

NOTE:

1. This parameter is measured at characterization but not tested.

SYNC INPUT TIMING REQUIREMENTS

Symbol	Parameter	Min.	Max.	Unit
TRISE/FALL	Rise/Fall Times, SYNC inputs	-	3	ns
	(0.8V to 2.0V)			
Frequency	Input Frequency, SYNC Inputs	10	2Q fmax	MHz
Duty Cycle	Input Duty Cycle, SYNC Inputs	25%	75%	—

DC ELECTRICAL CHARACTERISTICS OVER OPERATING RANGE

Following Conditions Apply Unless Otherwise Specified: Commercial: TA = 0° C to 70° C, Vcc = 5.0V ±5%

Symbol	Parameter	Test Conditi	ons ⁽¹⁾	Min.	Тур. ⁽²⁾	Max.	Unit
Vih	Input HIGH Level	Guaranteed Logic HIGH Level		2	—	-	V
VIL	Input LOW Level	Guaranteed Logic LOW Level		_	—	0.8	V
Ін	Input HIGH Current	Vcc = Max. VI = Vcc			—	±1	μA
lı.	Input LOW Current		VI = GND	_	—	±1	μA
Vik	Clamp Diode Voltage	VCC = Min., IIN = -18mA	Vcc = Min., IIN = -18mA			-1.2	V
Vih	Input Hysteresis	_	_		100	_	mV
Vон	Output HIGH Voltage	Vcc = Min.	Iон = –15mA	2.4	3.5	_	V
Vol	Output LOW Voltage	Vcc = Min.	IOL = 64mA	_	0.2	0.55	V
ICCL ICCH	Quiescent Power Supply Current	Vcc = Max., Vin = GND or Vcc (Test mode, LF connected to GND)		_	2	4	mA

NOTES:

1. For conditions shown as Min. or Max., use appropriate value specified under Electrical Characteristics for the applicable device type.

2. Typical values are at Vcc = 5.0V, +25°C ambient.

3. Not more than one output should be tested at one time. Duration of the test should not exceed one second.

POWER SUPPLY CHARACTERISTICS

Symbol	Parameter	Test Conditions ⁽¹⁾		Min.	Typ. ⁽²⁾	Max.	Unit
∆lcc	Quiescent Power Supply Current	Vcc = Max.		-	0.5	1.5	mA
	TTL Inputs HIGH	$VIN = VCC - 2.1V^{(3)}$					
ICCD	Dynamic Power Supply	Vcc = Max.	VIN = VCC	-	0.5	0.7	mA/
	Current ⁽⁴⁾	All Outputs Open	Vin = GND				MHz
Cpd	Power Dissipation Capacitance	50% Duty Cycle		-	25	40	pF
Ic	Total Power Supply Current ^(5,6)	Vcc = Max.		-	65	80	mA
		PLL_EN = 1, LOCK = 1, FEEDBACK	PLL_EN = 1, LOCK = 1, FEEDBACK = Q4				
		SYNC frequency = 50MHz. Q4 loaded	l with 50pF.				
		All other outputs open.					
		Vcc = Max.		_	_	_	mA
		PLL_EN = 1, LOCK = 1, FEEDBACK	= Q4				
		SYNC frequency = 50MHz. Q4 loaded	SYNC frequency = 50MHz. Q4 loaded with 50Ω				
		Thevenin termination. All other outputs open.					
PD1	Power Dissipation	50Ω Thevenin termination @ 33MHz		—	120	_	mW
PD2	Power Dissipation	50Ω Paralell termination to GND @ 33	MHz	-	300	_	mW

NOTES:

1. For conditions shown as Min. or Max., use appropriate value specified under Electrical Characteristics.

2. Typical values are at Vcc = 5.0V, +25°C ambient.

3. Per TTL driven input; all other inputs at Vcc or GND.

4. This parameter is not directly testable, but is derived for use in Total Power Supply Calculations. It is derived with Q frequency as the reference.

5. Values for these conditions are examples of the Icc formula. These limits are guaranteed but not tested.

6. IC = IQUIESCENT + INPUTS + IDYNAMIC

 $IC = ICC + \Delta ICC DHNT + ICCD (f) + ILOAD$

Icc = Quiescent Current (IccL, IccH and Iccz)

 ΔIcc = Power Supply Current for a TTL High Input

DH = Duty Cycle for TTL Inputs High

 $N \tau$ = Number of TTL Inputs at $D \ensuremath{\mathsf{H}}$

ICCD = Dynamic Current Caused by an Input Transition Pair (HLH or LHL)

f = 2Q frequency

ILOAD = Dynamic Current due to load.

OUTPUT FREQUENCY SPECIFICATIONS

			Max. ⁽²⁾				
Symbol	Parameter	Min.	55	70	100	133	Unit
f2Q	Operating frequency 2Q Output	40	55	70	100	133	MHz
fQ	Operating frequency Q0-Q4, $\overline{Q5}$ Outputs	20	27.5	35	50	66.7	MHz
fQ/2	Operating frequency Q/2 Output	10	13.75	17.5	25	33.3	MHz

NOTES:

1. Note 8 in "General AC Specification Notes" and Figure 2 describes this specification and its actual limits depending on the feedback connection.

2. Maximum operating frequency is guaranteed with the part in a phase locked condition and all outputs loaded with 50pF.

SWITCHING CHARACTERISTICS OVER OPERATING RANGE

Symbol	Parameter	Condition ⁽¹⁾	Min.	Max.	Unit
trise/fall	Rise/Fall Time	CL = 50pF	1 ⁽²⁾	2.5	ns
AllOutputs	(between 0.2 Vcc and 0.8 Vcc)	RL = 500Ω			
trise/fall	Rise/Fall Time	CL = 20pF &	0.5 ⁽²⁾	1.6	ns
2Q Output ⁽³⁾	(between 0.8V and 2.0V)	termination ⁽⁷⁾			
TPULSE WIDTH	Output Pulse Width	CL = 50pF	0.5tcycle-0.5 ⁽⁵⁾	0.5tcycle + 0.5 ⁽⁵⁾	ns
Q, \overline{Q} , Q/2 Outputs ⁽³⁾	Q0-Q4, Q5, Q/2 @ Vcc/2				
TPULSE WIDTH	Output Pulse Width	CL = 50pF	0.5tcycle – 1 ⁽⁵⁾	0.5tcycle + 1 ⁽⁵⁾	ns
2Q Output ⁽³⁾	2Q Output @ Vcc/2				
TPULSE WIDTH	Output Pulse Width	Termination as in	0.5tcycle – 0.5 ⁽⁵⁾	0.5tcycle + 0.5 ⁽⁵⁾	ns
2Q Output ⁽³⁾	2Q @ 1.5V	note 7			
t PD	SYNC input to FEEDBACK delay	Load = 50Ω to Vcc/2,	-0.5	+0.5	ns
SYNC-FEEDBACK ⁽³⁾	(measured at SYNC0 or 1 and FEEDBACK	CL = 20pF			
	inputpins)	0.1MF from LF to Analog GND ⁽⁹⁾			
tSKEWr	Output to Output Skew between outputs 2Q,	CL = 50pF	—	500	ps
(rising) ^(3, 4)	Q0-Q4,Q/2 (rising edges only)				
tskewf	Output to Output Skew between outputs 2Q,		—	500	ps
(falling) ^(3, 4)	Q0-Q4 (falling edges only)				
tskewall ^(3, 4)	Output to Output Skew		_	500	ps
	2Q, Q/2, Q0-Q4 rising, $\overline{Q5}$ falling				
tlock ⁽⁶⁾	Time required to acquire Phase-Lock from time		1 ⁽²⁾	10	ms
	SYNC input signal is received				
trst	Propagation Delay, RST (HIGH-to-LOW) to any		1.5 ⁽²⁾	8	ns
Reset – Q	Output (HIGH-to-LOW)				
trec ⁽¹⁰⁾	Reset Recovery Time		9	_	ns
	Rising RST edge to falling SYNC edge				
tw ⁽¹⁰⁾	Minimum Pulse Width RST input LOW		5	_	ns

GENERAL AC SPECIFICATION NOTES:

1. See test circuit and waveforms.

2. Minimum limits are guaranteed but not tested.

3. These specifications are guaranteed but not production tested.

4. Under equally loaded conditions, CL = 50pF (±2pF), and at a fixed temperature and voltage.

5. tcycle = 1/frequency at which each output (Q, \overline{Q} , Q/2 or 2Q) is expected to run.

6. With Vcc fully powered-on and an output properly connected to the FEEDBACK pin. tLOCK Max. is with C1 = 0.1µF, tLOCK Min. is with C1 = 0.01µF (where C1 is loop filter capacitor shown in Figure 2).

7. These two specs (trise/FALL and tPULSE WIDTH 2Q output) guarantee that the FCT88915TT meets 68040 P-Clock input specification. For these two specs to be guaranteed by IDT, the termination scheme shown in Figure 1 must be used:

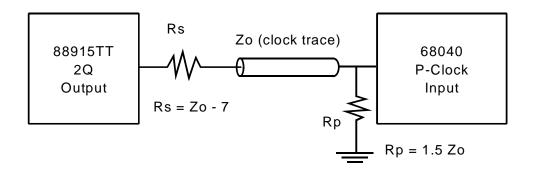


Figure 1. MC68040 P-Clock Input Termination Scheme

IDT74FCT88915TT LOW SKEW PLL-BASED CMOS CLOCK DRIVER

GENERAL AC SPECIFICATION NOTES, CONTINUED

8. The wiring diagrams and written explanations of Figures 4a-4c demonstrate the input and output frequency relationships for various possible feedback configurations. The allowable SYNC input range to stay in the phase-locked condition is also indicated. There are two allowable SYNC frequency ranges, depending on whether FREQ_SEL is HIGH or LOW. Also, it is possible to feed back the Q5 output, thus creating a 180° phase shift between the SYNC input and the Q outputs. The table below summarizes the allowable SYNC frequency range for each possible configuration:

FREQ_SEL Level	Feedback Output	Allowable SYNC Input Frequency Range (MHz)	Corresponding 2Q Output Frequency Range	Phase Relationship of the Q Outputs to Rising SYNC Edge
HIGH	Q/2	10 to (2Q fmax Spec)/4	40 to (2Q fMAX Spec)	0°
HIGH	Any Q (Q0-Q4)	20 to (2Q fmax Spec)/2	40 to (2Q fMAX Spec)	0°
HIGH	<u>Q5</u>	20 to (2Q fmax Spec)/2	40 to (2Q fMAX Spec)	180°
HIGH	2Q	40 to (2Q fmax Spec)	40 to (2Q fMAX Spec)	0°
LOW	Q/2	5 to (2Q fMAX Spec)/8	20 to (2Q fMAX Spec)/2	0°
LOW	Any Q (Q0-Q4)	10 to (2Q fmax Spec)/4	20 to (2Q fMAX Spec)/2	0°
LOW	<u>Q5</u>	10 to (2Q fmax Spec)/4	20 to (2Q fMAX Spec)/2	180°
LOW	2Q	20 to (2Q fmax Spec)/2	20 to (2Q fMAX Spec)/2	0°

9. The tPD spec describes how the phase offset between the SYNC input and the output connected to the FEEDBACK input varies with process, temperature, and voltage. The phase measurements were made at 1.5V. The Q/2 output was terminated at the FEEDBACK input with 100Ω to Vcc and 100Ω to ground. tPD measurements were made with the loop filter connection shown in Figure 2 below:

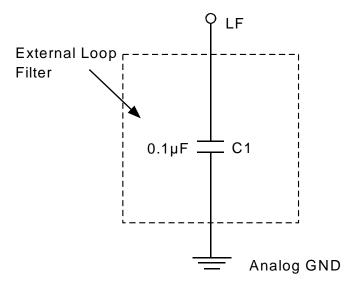


Figure 2. Loop Filter Connection

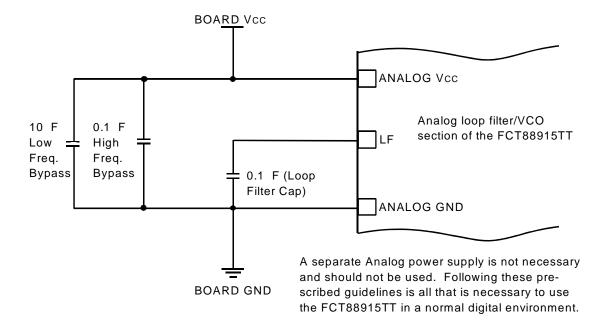


Figure 3. Recommended Loop Filter and Analog Isloation Scheme for the FCT88915TT

NOTES:

- 1. Figure 3 shows a loop filter and analog isolation scheme which will be effective in most applications. The following guidelines should be followed to ensure stable and jitter-free operation:
 - a. All loop filter and analog isolation components should be tied as close to the package as possible. Stray current passing through the parasitics of long traces can cause undesirable voltage transients at the LF pin.
 - b. The 10µF low frequency bypass capacitor and the 0.1µF high frequency bypass capacitor form a wide bandwidth filter that will minimize the 88915TT's sensitivity to voltage transients from the system digital Vcc supply and ground planes.

If good bypass techniques are used on a board design near components which may cause digital Vcc and ground noise, Vcc step deviations should not occur at the 88915TT's digital Vcc supply. The purpose of the bypass filtering scheme shown in Figure 3 is to give the 88915TT additional protection from the power supply and ground plane transients that can occur in a high frequency, high speed digital system.

- c. The loop filter capacitor (0.1µF) can be a ceramic chip capacitor, the same as a standard bypass capacitor.
- 2. In addition to the bypass capacitors used in the analog filter of Figure 3, there should be a 0.1µF bypass capacitor between each of the other (digital) four Vcc pins and the board ground plane. This will reduce output switching noise caused by the 88915TT outputs, in addition to reducing potential for noise in the "analog" section of the chip. These bypass capacitors should also be tied as close to the 88915TT package as possible.

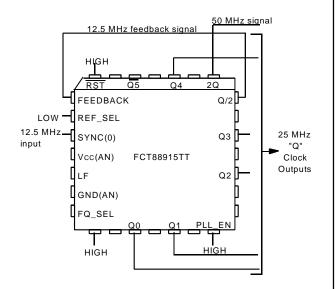
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COMMERCIALTEMPERATURERANGE

The frequency relationship shown here is applicable to all Q outputs (Q0, Q1, Q2, Q3 and Q4).

1:2 INPUT TO "Q" OUTPUT FREQUENCY RELATIONSHIP

In this application, the Q/2 output is connected to the FEEDBACK input. The internal PLL will line up the positive edges of Q/2 and SYNC. Thus the Q/2 frequency will equal the SYNC frequency. The Q outputs (Q0-Q4, $\overline{\text{Q5}}$) will always run at 2X the Q/2 frequency, and the 2Q output will run at 4X the Q/2 frequency.

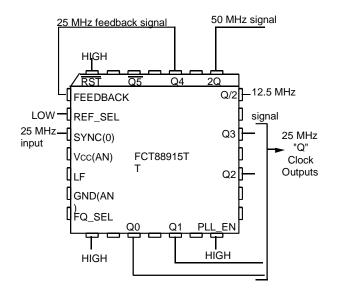


Allowable Input Frequency Range: 10MHz to (f2Q FMAX Spec)/4 (for FREQ_SEL HIGH) 5MHz to (f2Q FMAX Spec)/8 (for FREQ_SEL LOW)

Figure 4a. Wiring Diagram and Frequency Relationships with Q/2 Output Feedback

1:1 INPUT TO "Q" OUTPUT FREQUENCY RELATIONSHIP

In this application, the Q4 output is connected to the FEEDBACK input. The internal PLL will line up the positive edges of Q4 and SYNC. Thus the Q4 frequency (and the rest of the "Q" outputs) will equal the SYNC frequency. The Q/2 output will always run at 1/2 the Q frequency, and the 2Q output will run at 2X the Q frequency.

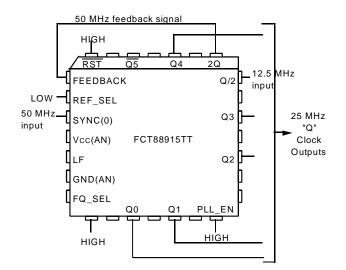


Allowable Input Frequency Range: 20MHz to (f2Q FMAX Spec)/2 (for FREQ_SEL HIGH) 10MHz to (f2Q FMAX Spec)/4 (for FREQ_SEL LOW)

Figure 4b. Wiring Diagram and Frequency Relationships with Q4 Output Feedback

2:1 INPUT TO "Q" OUTPUT FREQUENCY RELATIONSHIP

In this application, the 2Q output is connected to the FEEDBACK input. The internal PLL will line up the positive edges of 2Q and SYNC. Thus the 2Q frequency will equal the SYNC frequency. The Q/2 output will always run at 1/4 the 2Q frequency, and the Q output will run at 1/2 the 2Q frequency.



Allowable Input Frequency Range: 40MHz to (f2Q FMAX Spec) (for FREQ_SEL HIGH) 20MHz to (f2Q FMAX Spec)/2 (for FREQ_SEL LOW)

Figure 4c. Wiring Diagram and Frequency Relationships with 2Q Output Feedback

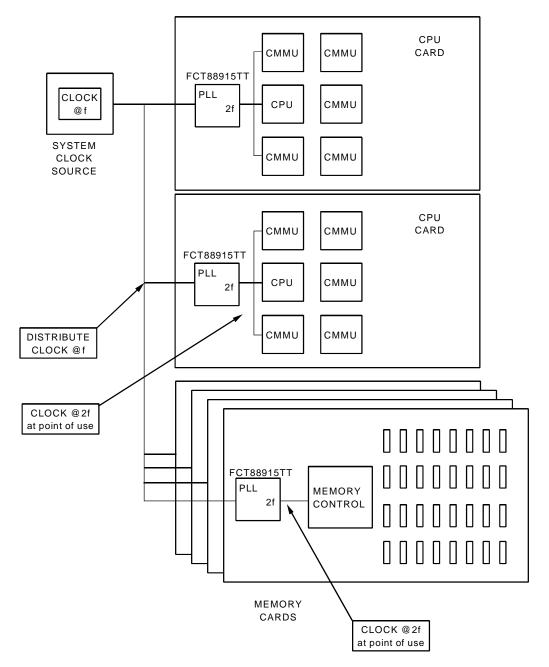


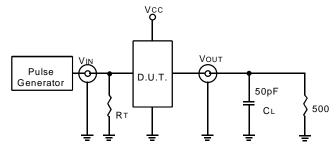
Figure 5. Multiprocessing Application Using the FCT88915 for Frequency Multiplication and Low Board-to-Board skew

FCT88915 SYSTEM LEVEL TESTING FUNCTIONALITY

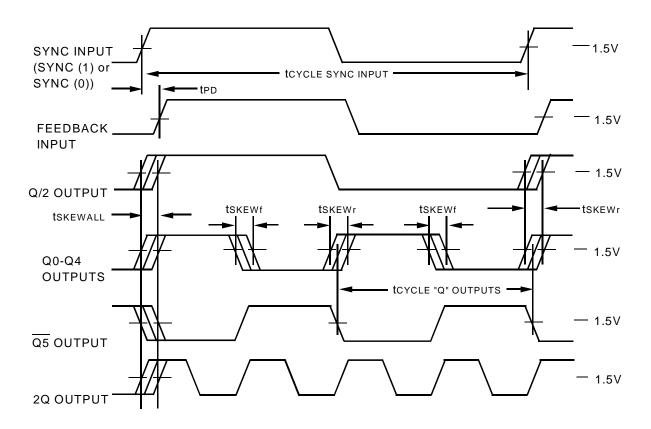
When the PLL_EN pin is LOW, the PLL is bypassed and the FCT88915TT is in low frequency "test mode". In test mode (with FREQ_SEL HIGH), the 2Q output is inverted from the selected SYNC input, and the Q outputs are divideby-2 (negative edge triggered) of the SYNC input, and the Q/2 output is divideby-4 (negative edge triggered). With FREQ_SEL LOW the 2Q output is divideby-2 of the SYNC, the Q outputs divide-by-4, and the Q/2 output divide-by-8. These relationships can be seen in the block diagram. A recommended test configuration would be to use SYNC0 or SYNC1 as the test clock input, and tie PLL_EN and REF_SEL together and connect them to the test select logic.

This functionality is needed since most board-level testers run at 1 MHz or below, and the FCT88915TT cannot lock onto that low of an input frequency. In the test mode described above, any test frequency test can be used.

TEST CIRCUITS AND WAVEFORMS



Test Circuits For All Outputs



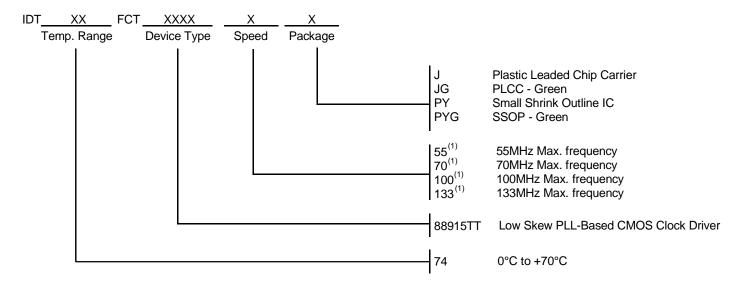
Propagation Delay, Output Skew

(These waveforms represent the configuration shown in Figure 4a)

NOTES:

- 1. The FCT88915TT aligns rising edges of the FEEDBACK input and SYNC input. Therefore, the SYNC input does not require a 50% duty cycle.
- 2. All skew specs are measured between the Vcc/2 crossing point of the appropriate output edges. All skews are specified as "windows", not as ± deviation around a center point. 3. If a Q output is connected to the FEEDBACK input (this situation is not shown), the Q output frequency would match the SYNC input frequency, the 2Q output would run at twice
- the SYNC frequency, and the Q/2 output would run at half the SYNC frequency.

ORDERING INFORMATION



NOTE:

1. When ordering GREEN packages, replace this numeric value with the equivalent letter below.

- A= 55 MHz
- B= 70 MHz
- C= 100 MHz
- D= 133 MHz

For example, to order a 133MHz version, Green PLCC, the nomenclature would be 74FCT88915TTDPYG.

	REVISION HISTORY SHEET						
Rev	Rev Table Page Description of Change Date						
A		1	PDN - Product Discontinuance Notice	5/21/13			

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